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Chapter 1. Introduction

Modern processor architectures have embraced parallelism as an important pathway to increased performance. Facing technical challenges with higher clock speeds in a fixed power envelope, Central Processing Units (CPUs) now improve performance by adding multiple cores. Graphics Processing Units (GPUs) have also evolved from fixed function rendering devices into programmable parallel processors. As today's computer systems often include highly parallel CPUs, GPUs and other types of processors, it is important to enable software developers to take full advantage of these heterogeneous processing platforms.

Creating applications for heterogeneous parallel processing platforms is challenging as traditional programming approaches for multi-core CPUs and GPUs are very different. CPU-based parallel programming models are typically based on standards but usually assume a shared address space and do not encompass vector operations. General purpose GPU programming models address complex memory hierarchies and vector operations but are traditionally platform-, vendor- or hardware-specific. These limitations make it difficult for a developer to access the compute power of heterogeneous CPUs, GPUs and other types of processors from a single, multi-platform source code base. More than ever, there is a need to enable software developers to effectively take full advantage of heterogeneous processing platforms from high performance compute servers, through desktop computer systems to handheld devices - that include a diverse mix of parallel CPUs, GPUs and other processors such as DSPs and the Cell/B.E. processor.

OpenCL (Open Computing Language) is an open royalty-free standard for general purpose parallel programming across CPUs, GPUs and other processors, giving software developers portable and efficient access to the power of these heterogeneous processing platforms.

OpenCL supports a wide range of applications, ranging from embedded and consumer software to HPC solutions, through a low-level, high-performance, portable abstraction. By creating an efficient, close-to-the-metal programming interface, OpenCL will form the foundation layer of a parallel computing ecosystem of platform-independent tools, middleware and applications. OpenCL is particularly suited to play an increasingly significant role in emerging interactive graphics applications that combine general parallel compute algorithms with graphics rendering pipelines.

OpenCL consists of an API for coordinating parallel computation across heterogeneous processors, a cross-platform programming language, and a cross-platform intermediate language with a well-specified computation environment. The OpenCL standard:

- Supports both data- and task-based parallel programming models
- Supports kernels written using a subset of ISO C99 with extensions for parallel execution
- Supports kernels represented by a portable and self-contained intermediate language (e.g. SPIR-V) with support for parallel execution
- Defines consistent numerical requirements based on IEEE 754
- Defines a configuration profile for handheld and embedded devices
- Supports efficient interop with OpenGL, OpenGL ES and other APIs

This document begins with an overview of basic concepts and the architecture of OpenCL, followed by a detailed description of its execution model, memory model and synchronization support. It
then discusses the OpenCL platform and runtime API. Some examples are given that describe sample compute use-cases and how they would be written in OpenCL. The specification is divided into a core specification that any OpenCL compliant implementation must support; a handheld/embedded profile which relaxes the OpenCL compliance requirements for handheld and embedded devices; and a set of optional extensions that are likely to move into the core specification in later revisions of the OpenCL specification.

1.1. Normative References

Normative references are references to external documents or resources to which implementers of OpenCL must comply with all, or specified portions of, as described in this specification.


1.2. Version Numbers

The OpenCL version number follows a major.minor-revision scheme. When this version number is used within the API it generally only includes the major.minor components of the version number.

A difference in the major or minor version number indicates that some amount of new functionality has been added to the specification, and may also include behavior changes and bug fixes. Functionality may also be deprecated or removed when the major or minor version changes.

A difference in the revision number indicates small changes to the specification, typically to fix a bug or to clarify language. When the revision number changes there may be an impact on the behavior of existing functionality, but this should not affect backwards compatibility. Functionality should not be added or removed when the revision number changes.

1.3. Unified Specification

This document specifies all versions of the OpenCL API.

There are three ways that an OpenCL feature may be described in terms of what versions of OpenCL support that feature.

• Missing before major.minor: Features that were introduced in version major.minor. Implementations of an earlier version of OpenCL will not provide these features.
• Deprecated by major.minor: Features that were deprecated in version major.minor, see the definition of deprecation in the glossary.
• Universal: Features that have no mention of what version they are missing before or deprecated by are available in all versions of OpenCL.
Chapter 2. Glossary

Application
The combination of the program running on the host and OpenCL devices.

Acquire semantics
One of the memory order semantics defined for synchronization operations. Acquire semantics apply to atomic operations that load from memory. Given two units of execution, A and B, acting on a shared atomic object M, if A uses an atomic load of M with acquire semantics to synchronize-with an atomic store to M by B that used release semantics, then A's atomic load will occur before any subsequent operations by A. Note that the memory orders release, sequentially consistent, and acquire_release all include release semantics and effectively pair with a load using acquire semantics.

Acquire release semantics
A memory order semantics for synchronization operations (such as atomic operations) that has the properties of both acquire and release memory orders. It is used with read-modify-write operations.

Atomic operations
Operations that at any point, and from any perspective, have either occurred completely, or not at all. Memory orders associated with atomic operations may constrain the visibility of loads and stores with respect to the atomic operations (see relaxed semantics, acquire semantics, release semantics or acquire_release semantics).

Blocking and Non-Blocking Enqueue API calls
A non-blocking enqueue API call places a command on a command-queue and returns immediately to the host. The blocking-mode enqueue API calls do not return to the host until the command has completed.

Barrier
There are three types of barriers a command-queue barrier, a work-group barrier, and a sub-group barrier.

• The OpenCL API provides a function to enqueue a command-queue barrier command. This barrier command ensures that all previously enqueued commands to a command-queue have finished execution before any following commands enqueued in the command-queue can begin execution.

• The OpenCL kernel execution model provides built-in work-group barrier functionality. This barrier built-in function can be used by a kernel executing on a device to perform synchronization between work-items in a work-group executing the kernel. All the work-items of a work-group must execute the barrier construct before any are allowed to continue execution beyond the barrier.

• The OpenCL kernel execution model provides built-in sub-group barrier functionality. This barrier built-in function can be used by a kernel executing on a device to perform synchronization between work-items in a sub-group executing the kernel. All the work-items of a sub-group must execute the barrier construct before any are allowed to continue
execution beyond the barrier.

**Buffer Object**
A memory object that stores a linear collection of bytes. Buffer objects are accessible using a pointer in a *kernel* executing on a *device*. Buffer objects can be manipulated by the host using OpenCL API calls. A *buffer object* encapsulates the following information:

- Size in bytes.
- Properties that describe usage information and which region to allocate from.
- Buffer data.

**Built-in Kernel**
A *built-in kernel* is a *kernel* that is executed on an OpenCL *device* or *custom device* by fixed-function hardware or in firmware. Applications can query the *built-in kernels* supported by a *device* or *custom device*. A *program object* can only contain *kernels* written in OpenCL C or *built-in kernels* but not both. See also *Kernel* and *Program*.

**Child kernel**
See *Device-side enqueue*.

**Command**
The OpenCL operations that are submitted to a *command-queue* for execution. For example, OpenCL commands issue kernels for execution on a compute device, manipulate memory objects, etc.

**Command-queue**
An object that holds *commands* that will be executed on a specific *device*. The *command-queue* is created on a specific *device* in a *context*. *Commands* to a *command-queue* are queued in-order but may be executed in-order or out-of-order. Refer to *In-order Execution* and *Out-of-order Execution*.

**Command-queue Barrier**
See *Barrier*.

**Command synchronization**
Constraints on the order that commands are launched for execution on a device defined in terms of the synchronization points that occur between commands in host command-queues and between commands in device-side command-queues. See *synchronization points*.

**Complete**
The final state in the six state model for the execution of a command. The transition into this state occurs is signaled through event objects or callback functions associated with a command.

**Compute Device Memory**
This refers to one or more memories attached to the compute device.

**Compute Unit**
An OpenCL *device* has one or more *compute units*. A *work-group* executes on a single *compute unit*. A *compute unit* is composed of one or more *processing elements* and *local memory*. A
compute unit may also include dedicated texture filter units that can be accessed by its processing elements.

Concurrency
A property of a system in which a set of tasks in a system can remain active and make progress at the same time. To utilize concurrent execution when running a program, a programmer must identify the concurrency in their problem, expose it within the source code, and then exploit it using a notation that supports concurrency.

Constant Memory
A region of global memory that remains constant during the execution of a kernel. The host allocates and initializes memory objects placed into constant memory.

Context
The environment within which the kernels execute and the domain in which synchronization and memory management is defined. The context includes a set of devices, the memory accessible to those devices, the corresponding memory properties and one or more command-queues used to schedule execution of a kernel(s) or operations on memory objects.

Control flow
The flow of instructions executed by a work-item. Multiple logically related work-items may or may not execute the same control flow. The control flow is said to be converged if all the work-items in the set execute the same stream of instructions. In a diverged control flow, the work-items in the set execute different instructions. At a later point, if a diverged control flow becomes converged, it is said to be a re-converged control flow.

Converged control flow
See Control flow.

Custom Device
An OpenCL device that fully implements the OpenCL Runtime but does not support programs written in OpenCL C. A custom device may be specialized non-programmable hardware that is very power efficient and performant for directed tasks or hardware with limited programmable capabilities such as specialized DSPs. Custom devices are not OpenCL conformant. Custom devices may support an online compiler. Programs for custom devices can be created using the OpenCL runtime APIs that allow OpenCL programs to be created from source (if an online compiler is supported) and/or binary, or from built-in kernels supported by the device. See also Device.

Data Parallel Programming Model
Traditionally, this term refers to a programming model where concurrency is expressed as instructions from a single program applied to multiple elements within a set of data structures. The term has been generalized in OpenCL to refer to a model wherein a set of instructions from a single program are applied concurrently to each point within an abstract domain of indices.

Data race
The execution of a program contains a data race if it contains two actions in different work-items or host threads where (1) one action modifies a memory location and the other action
reads or modifies the same memory location, and (2) at least one of these actions is not atomic, or the corresponding memory scopes are not inclusive, and (3) the actions are global actions unordered by the global-happens-before relation or are local actions unordered by the local-happens-before relation.

**Deprecation**

Existing features are marked as deprecated if their usage is not recommended as that feature is being de-emphasized, superseded and may be removed from a future version of the specification.

**Device**

A *device* is a collection of *compute units*. A *command-queue* is used to queue *commands* to a *device*. Examples of *commands* include executing *kernels*, or reading and writing *memory objects*. OpenCL devices typically correspond to a GPU, a multi-core CPU, and other processors such as DSPs and the Cell/B.E. processor.

**Device-side enqueue**

A mechanism whereby a kernel-instance is enqueued by a kernel-instance running on a device without direct involvement by the host program. This produces *nested parallelism*; i.e. additional levels of concurrency are nested inside a running kernel-instance. The kernel-instance executing on a device (the *parent kernel*) enqueues a kernel-instance (the *child kernel*) to a device-side command-queue. Child and parent kernels execute asynchronously though a parent kernel does not complete until all of its child-kernels have completed.

**Diverged control flow**

See *Control flow*.

**Ended**

The fifth state in the six state model for the execution of a command. The transition into this state occurs when execution of a command has ended. When a Kernel-enqueue command ends, all of the work-groups associated with that command have finished their execution.

**Event Object**

An *event object* encapsulates the status of an operation such as a *command*. It can be used to synchronize operations in a context.

**Event Wait List**

An *event wait list* is a list of *event objects* that can be used to control when a particular *command* begins execution.

**Fence**

A memory ordering operation without an associated atomic object. A fence can use the *acquire semantics*, *release semantics*, or *acquire release semantics*.

**Framework**

A software system that contains the set of components to support software development and execution. A *framework* typically includes libraries, APIs, runtime systems, compilers, etc.
Generic address space
An address space that include the *private*, *local*, and *global* address spaces available to a device. The generic address space supports conversion of pointers to and from private, local and global address spaces, and hence lets a programmer write a single function that at compile time can take arguments from any of the three named address spaces.

Global-happens-before
See *Happens-before*.

Global ID
A *global ID* is used to uniquely identify a *work-item* and is derived from the number of *global work-items* specified when executing a *kernel*. The *global ID* is a N-dimensional value that starts at (0, 0, … 0). See also *Local ID*.

Global Memory
A memory region accessible to all *work-items* executing in a *context*. It is accessible to the *host* using *commands* such as read, write and map. *Global memory* is included within the *generic address space* that includes the private and local address spaces.

GL share group
A *GL share group* object manages shared OpenGL or OpenGL ES resources such as textures, buffers, framebuffers, and renderbuffers and is associated with one or more GL context objects. The *GL share group* is typically an opaque object and not directly accessible.

Handle
An opaque type that references an *object* allocated by OpenCL. Any operation on an *object* occurs by reference to that object’s handle. Each object must have a unique handle value during the course of its lifetime. Handle values may be, but are not required to be, re-used by an implementation.

Happens-before
An ordering relationship between operations that execute on multiple units of execution. If an operation A happens-before operation B then A must occur before B; in particular, any value written by A will be visible to B. We define two separate happens-before relations: *global-happens-before* and *local-happens-before*. These are defined in Memory Ordering Rules.

Host
The *host* interacts with the *context* using the OpenCL API.

Host-thread
The unit of execution that executes the statements in the host program.

Host pointer
A pointer to memory that is in the virtual address space on the *host*.

Illegal
Behavior of a system that is explicitly not allowed and will be reported as an error when encountered by OpenCL.
Image Object

A *memory object* that stores a two- or three-dimensional structured array. Image data can only be accessed with read and write functions. The read functions use a *sampler*.

The *image object* encapsulates the following information:

- Dimensions of the image.
- Description of each element in the image.
- Properties that describe usage information and which region to allocate from.
- Image data.

The elements of an image are selected from a list of predefined image formats.

Implementation-Defined

Behavior that is explicitly allowed to vary between conforming implementations of OpenCL. An OpenCL implementor is required to document the implementation-defined behavior.

Independent Forward Progress

If an entity supports independent forward progress, then if it is otherwise not dependent on any actions due to be performed by any other entity (for example it does not wait on a lock held by, and thus that must be released by, any other entity), then its execution cannot be blocked by the execution of any other entity in the system (it will not be starved). Work-items in a sub-group, for example, typically do not support independent forward progress, so one work-item in a sub-group may be completely blocked (starved) if a different work-item in the same sub-group enters a spin loop.

In-order Execution

A model of execution in OpenCL where the *commands* in a *command-queue* are executed in order of submission with each *command* running to completion before the next one begins. See *Out-of-order Execution*.

Intermediate Language

A lower-level language that may be used to create programs. SPIR-V is a required intermediate language (IL) for OpenCL 2.1 and 2.2 devices. Other OpenCL devices may optionally support SPIR-V or other ILs.

Kernel

A *kernel* is a function declared in a *program* and executed on an OpenCL *device*. A *kernel* is identified by the *__kernel* or *kernel* qualifier applied to any function defined in a *program*.

Kernel-instance

The work carried out by an OpenCL program occurs through the execution of kernel-instances on devices. The kernel instance is the *kernel object*, the values associated with the arguments to the kernel, and the parameters that define the *ND-range* index space.

Kernel Object

A *kernel object* encapsulates a specific *kernel* function declared in a *program* and the argument
values to be used when executing this kernel function.

**Kernel Language**
A language that is used to represent source code for kernel. Kernels may be directly created from OpenCL C kernel language source strings. Other kernel languages may be supported by compiling to SPIR-V, another supported Intermediate Language, or to a device-specific program binary format.

**Launch**
The transition of a command from the submitted state to the ready state. See Ready.

**Local ID**
A local ID specifies a unique work-item ID within a given work-group that is executing a kernel. The local ID is a N-dimensional value that starts at (0, 0, ... 0). See also Global ID.

**Local Memory**
A memory region associated with a work-group and accessible only by work-items in that work-group. Local memory is included within the generic address space that includes the private and global address spaces.

**Marker**
A command queued in a command-queue that can be used to tag all commands queued before the marker in the command-queue. The marker command returns an event which can be used by the application to queue a wait on the marker event i.e. wait for all commands queued before the marker command to complete.

**Memory Consistency Model**
Rules that define which values are observed when multiple units of execution load data from any shared memory plus the synchronization operations that constrain the order of memory operations and define synchronization relationships. The memory consistency model in OpenCL is based on the memory model from the ISO C11 programming language.

**Memory Objects**
A memory object is a handle to a reference counted region of Global Memory. Also see Buffer Object and Image Object.

**Memory Regions (or Pools)**
A distinct address space in OpenCL. Memory regions may overlap in physical memory though OpenCL will treat them as logically distinct. The memory regions are denoted as private, local, constant, and global.

**Memory Scopes**
These memory scopes define a hierarchy of visibilities when analyzing the ordering constraints of memory operations. They are defined by the values of the memory_scope enumeration constant. Current values are memory_scope_work_item (memory constraints only apply to a single work-item and in practice apply only to image operations), memory_scope_sub_group (memory-ordering constraints only apply to work-items executing in a sub-group), memory_scope_work_group (memory-ordering constraints only apply to work-items executing
in a work-group), **memory_scope_device** (memory-ordering constraints only apply to work-items executing on a single device) and **memory_scope_all_svm_devices** or equivalently **memory_scope_all_devices** (memory-ordering constraints only apply to work-items executing across multiple devices and when using shared virtual memory).

**Modification Order**

All modifications to a particular atomic object M occur in some particular *total order*, called the **modification order** of M. If A and B are modifications of an atomic object M, and A happens-before B, then A shall precede B in the modification order of M. Note that the modification order of an atomic object M is independent of whether M is in local or global memory.

**Nested Parallelism**

*See device-side enqueue.*

**Object**

Objects are abstract representation of the resources that can be manipulated by the OpenCL API. Examples include **program objects**, **kernel objects**, and **memory objects**.

**Out-of-order Execution**

A model of execution in which commands placed in the **work queue** may begin and complete execution in any order consistent with constraints imposed by **event wait lists** and **command-queue barrier**. *See In-order Execution.*

**Parent device**

The OpenCL **device** which is partitioned to create **sub-devices**. Not all **parent devices** are **root devices**. A **root device** might be partitioned and the **sub-devices** partitioned again. In this case, the first set of **sub-devices** would be **parent devices** of the second set, but not the **root devices**. Also see **Device**, **parent device** and **root device**.

**Parent kernel**

*see Device-side enqueue.*

**Pipe**

The **pipe** memory object conceptually is an ordered sequence of data items. A pipe has two endpoints: a write endpoint into which data items are inserted, and a read endpoint from which data items are removed. At any one time, only one kernel instance may write into a pipe, and only one kernel instance may read from a pipe. To support the producer consumer design pattern, one kernel instance connects to the write endpoint (the producer) while another kernel instance connects to the reading endpoint (the consumer).

**Platform**

The **host** plus a collection of **devices** managed by the OpenCL **framework** that allow an application to share **resources** and execute **kernels** on **devices** in the **platform**.

**Private Memory**

A region of memory private to a **work-item**. Variables defined in one **work-items private memory** are not visible to another **work-item**.
Processing Element
A virtual scalar processor. A work-item may execute on one or more processing elements.

Program
An OpenCL program consists of a set of kernels. Programs may also contain auxiliary functions called by the kernel functions and constant data.

Program Object
A program object encapsulates the following information:

- A reference to an associated context.
- A program source or binary.
- The latest successfully built program executable, the list of devices for which the program executable is built, the build options used and a build log.
- The number of kernel objects currently attached.

Queued
The first state in the six state model for the execution of a command. The transition into this state occurs when the command is enqueued into a command-queue.

Ready
The third state in the six state model for the execution of a command. The transition into this state occurs when pre-requisites constraining execution of a command have been met; i.e. the command has been launched. When a kernel-enqueue command is launched, work-groups associated with the command are placed in a devices work-pool from which they are scheduled for execution.

Re-converged Control Flow
see Control flow.

Reference Count
The life span of an OpenCL object is determined by its reference count, an internal count of the number of references to the object. When you create an object in OpenCL, its reference count is set to one. Subsequent calls to the appropriate retain API (such as clRetainContext, clRetainCommandQueue) increment the reference count. Calls to the appropriate release API (such as clReleaseContext, clReleaseCommandQueue) decrement the reference count. Implementations may also modify the reference count, e.g. to track attached objects or to ensure correct operation of in-progress or scheduled activities. The object becomes inaccessible to host code when the number of release operations performed matches the number of retain operations plus the allocation of the object. At this point the reference count may be zero but this is not guaranteed.

Relaxed Consistency
A memory consistency model in which the contents of memory visible to different work-items or commands may be different except at a barrier or other explicit synchronization points.
Relaxed Semantics

A memory order semantics for atomic operations that implies no order constraints. The operation is \textit{atomic} but it has no impact on the order of memory operations.

Release Semantics

One of the memory order semantics defined for synchronization operations. Release semantics apply to atomic operations that store to memory. Given two units of execution, \textbf{A} and \textbf{B}, acting on a shared atomic object \textbf{M}, if \textbf{A} uses an atomic store of \textbf{M} with release semantics to synchronize-with an atomic load to \textbf{M} by \textbf{B} that used acquire semantics, then \textbf{A}'s atomic store will occur \textit{after} any prior operations by \textbf{A}. Note that the memory orders \textit{acquire}, \textit{sequentially consistent}, and \textit{acquire_release} all include \textit{acquire semantics} and effectively pair with a store using release semantics.

Remainder work-groups

When the work-groups associated with a kernel-instance are defined, the sizes of a work-group in each dimension may not evenly divide the size of the ND-range in the corresponding dimensions. The result is a collection of work-groups on the boundaries of the ND-range that are smaller than the base work-group size. These are known as \textit{remainder work-groups}.

Running

The fourth state in the six state model for the execution of a command. The transition into this state occurs when the execution of the command starts. When a Kernel-enqueue command starts, one or more work-groups associated with the command start to execute.

Root device

A \textit{root device} is an OpenCL \textit{device} that has not been partitioned. Also see \textit{Device}, \textit{Parent device} and \textit{Root device}.

Resource

A class of \textit{objects} defined by OpenCL. An instance of a \textit{resource} is an \textit{object}. The most common \textit{resources} are the \textit{context}, \textit{command-queue}, \textit{program objects}, \textit{kernel objects}, and \textit{memory objects}. Computational resources are hardware elements that participate in the action of advancing a program counter. Examples include the \textit{host}, \textit{devices}, \textit{compute units} and \textit{processing elements}.

Retain, Release

The action of incrementing (retain) and decrementing (release) the reference count using an OpenCL \textit{object}. This is a book keeping functionality to make sure the system doesn't remove an \textit{object} before all instances that use this \textit{object} have finished. Refer to \textit{Reference Count}.

Sampler

An \textit{object} that describes how to sample an image when the image is read in the \textit{kernel}. The image read functions take a \textit{sampler} as an argument. The \textit{sampler} specifies the image addressing-mode i.e. how out-of-range image coordinates are handled, the filter mode, and whether the input image coordinate is a normalized or unnormalized value.

Scope inclusion

Two actions \textbf{A} and \textbf{B} are defined to have an inclusive scope if they have the same scope \textbf{P} such that: (1) if \textbf{P} is \textit{memory_scope_sub_group}, and \textbf{A} and \textbf{B} are executed by work-items within the
same sub-group, or (2) if $P$ is `memory_scope_work_group`, and $A$ and $B$ are executed by work-items within the same work-group, or (3) if $P$ is `memory_scope_device`, and $A$ and $B$ are executed by work-items on the same device, or (4) if $P$ is `memory_scope_all_svm_devices` or `memory_scope_all_devices`, if $A$ and $B$ are executed by host threads or by work-items on one or more devices that can share SVM memory with each other and the host process.

**Sequenced before**

A relation between evaluations executed by a single unit of execution. Sequenced-before is an asymmetric, transitive, pair-wise relation that induces a partial order between evaluations. Given any two evaluations $A$ and $B$, if $A$ is sequenced-before $B$, then the execution of $A$ shall precede the execution of $B$.

**Sequential consistency**

Sequential consistency interleaves the steps executed by each unit of execution. Each access to a memory location sees the last assignment to that location in that interleaving.

**Sequentially consistent semantics**

One of the memory order semantics defined for synchronization operations. When using sequentially-consistent synchronization operations, the loads and stores within one unit of execution appear to execute in program order (i.e., the sequenced-before order), and loads and stores from different units of execution appear to be simply interleaved.

**Shared Virtual Memory (SVM)**

An address space exposed to both the host and the devices within a context. SVM causes addresses to be meaningful between the host and all of the devices within a context and therefore supports the use of pointer based data structures in OpenCL kernels. It logically extends a portion of the global memory into the host address space therefore giving work-items access to the host address space. There are three types of SVM in OpenCL:

- **Coarse-Grained buffer SVM**
  Sharing occurs at the granularity of regions of OpenCL buffer memory objects.

- **Fine-Grained buffer SVM**
  Sharing occurs at the granularity of individual loads/stores into bytes within OpenCL buffer memory objects.

- **Fine-Grained system SVM**
  Sharing occurs at the granularity of individual loads/stores into bytes occurring anywhere within the host memory.

**SIMD**

Single Instruction Multiple Data. A programming model where a `kernel` is executed concurrently on multiple `processing elements` each with its own data and a shared program counter. All `processing elements` execute a strictly identical set of instructions.

**Specialization constants**

Specialization constants are special constant objects that do not have known constant values in an intermediate language (e.g. SPIR-V). Applications may provide updated values for the
specialization constants before a program is built. Specialization constants that do not receive a value from an application shall use the default specialization constant value.

SPMD
Single Program Multiple Data. A programming model where a kernel is executed concurrently on multiple processing elements each with its own data and its own program counter. Hence, while all computational resources run the same kernel they maintain their own instruction counter and due to branches in a kernel, the actual sequence of instructions can be quite different across the set of processing elements.

Sub-device
An OpenCL device can be partitioned into multiple sub-devices. The new sub-devices alias specific collections of compute units within the parent device, according to a partition scheme. The sub-devices may be used in any situation that their parent device may be used. Partitioning a device does not destroy the parent device, which may continue to be used along side and intermingled with its child sub-devices. Also see Device, Parent device and Root device.

Sub-group
Sub-groups are an implementation-dependent grouping of work-items within a work-group. The size and number of sub-groups is implementation-defined.

Sub-group Barrier
See Barrier.

Submitted
The second state in the six state model for the execution of a command. The transition into this state occurs when the command is flushed from the command-queue and submitted for execution on the device. Once submitted, a programmer can assume a command will execute once its prerequisites have been met.

SVM Buffer
A memory allocation enabled to work with Shared Virtual Memory (SVM). Depending on how the SVM buffer is created, it can be a coarse-grained or fine-grained SVM buffer. Optionally it may be wrapped by a Buffer Object. See Shared Virtual Memory (SVM).

Synchronization
Synchronization refers to mechanisms that constrain the order of execution and the visibility of memory operations between two or more units of execution.

Synchronization operations
Operations that define memory order constraints in a program. They play a special role in controlling how memory operations in one unit of execution (such as work-items or, when using SVM a host thread) are made visible to another. Synchronization operations in OpenCL include atomic operations and fences.

Synchronization point
A synchronization point between a pair of commands (A and B) assures that results of command A happens-before command B is launched (i.e. enters the ready state).
Synchronizes with
A relation between operations in two different units of execution that defines a memory order constraint in global memory (global-synchronizes-with) or local memory (local-synchronizes-with).

Task Parallel Programming Model
A programming model in which computations are expressed in terms of multiple concurrent tasks executing in one or more command-queues. The concurrent tasks can be running different kernels.

Thread-safe
An OpenCL API call is considered to be thread-safe if the internal state as managed by OpenCL remains consistent when called simultaneously by multiple host threads. OpenCL API calls that are thread-safe allow an application to call these functions in multiple host threads without having to implement mutual exclusion across these host threads i.e. they are also re-entrant-safe.

Undefined
The behavior of an OpenCL API call, built-in function used inside a kernel or execution of a kernel that is explicitly not defined by OpenCL. A conforming implementation is not required to specify what occurs when an undefined construct is encountered in OpenCL.

Unit of execution
A generic term for a process, OS managed thread running on the host (a host-thread), kernel-instance, host program, work-item or any other executable agent that advances the work associated with a program.

Valid Object
An OpenCL object is considered valid if it meets all of the following criteria:

- The object was created by a successful call to an OpenCL API function.
- The object has a strictly positive application-owned reference count.
- The object has not had its backing memory changed outside of normal usage by the OpenCL implementation (e.g. corrupted by the application, a library it uses, the implementation itself, or any other agent that can access the object’s backing memory).

An object is only valid in the platform where it was created.

An OpenCL implementation must check for a NULL object to determine if an object is valid. The behavior for all other invalid objects is implementation-defined.

Work-group
A collection of related work-items that execute on a single compute unit. The work-items in the group execute the same kernel-instance and share local memory and work-group functions.

Work-group Barrier
See Barrier.
**Work-group Function**

A function that carries out collective operations across all the work-items in a work-group. Available collective operations are a barrier, reduction, broadcast, prefix sum, and evaluation of a predicate. A work-group function must occur within a *converged control flow*; i.e. all work-items in the work-group must encounter precisely the same work-group function.

**Work-group Synchronization**

Constraints on the order of execution for work-items in a single work-group.

**Work-pool**

A logical pool associated with a device that holds commands and work-groups from kernel-instances that are ready to execute. OpenCL does not constrain the order that commands and work-groups are scheduled for execution from the work-pool; i.e. a programmer must assume that they could be interleaved. There is one work-pool per device used by all command-queues associated with that device. The work-pool may be implemented in any manner as long as it assures that work-groups placed in the pool will eventually execute.

**Work-item**

One of a collection of parallel executions of a *kernel* invoked on a *device* by a *command*. A *work-item* is executed by one or more *processing elements* as part of a *work-group* executing on a *compute unit*. A *work-item* is distinguished from other work-items by its *global ID* or the combination of its *work-group ID* and its *local ID* within a *work-group*. 
Chapter 3. The OpenCL Architecture

OpenCL is an open industry standard for programming a heterogeneous collection of CPUs, GPUs and other discrete computing devices organized into a single platform. It is more than a language. OpenCL is a framework for parallel programming and includes a language, API, libraries and a runtime system to support software development. Using OpenCL, for example, a programmer can write general purpose programs that execute on GPUs without the need to map their algorithms onto a 3D graphics API such as OpenGL or DirectX.

The target of OpenCL is expert programmers wanting to write portable yet efficient code. This includes library writers, middleware vendors, and performance oriented application programmers. Therefore OpenCL provides a low-level hardware abstraction plus a framework to support programming and many details of the underlying hardware are exposed.

To describe the core ideas behind OpenCL, we will use a hierarchy of models:

- Platform Model
- Memory Model
- Execution Model
- Programming Model

3.1. Platform Model

The Platform model for OpenCL is defined below. The model consists of a host connected to one or more OpenCL devices. An OpenCL device is divided into one or more compute units (CUs) which are further divided into one or more processing elements (PEs). Computations on a device occur within the processing elements.

An OpenCL application is implemented as both host code and device kernel code. The host code portion of an OpenCL application runs on a host processor according to the models native to the host platform. The OpenCL application host code submits the kernel code as commands from the host to OpenCL devices. An OpenCL device executes the commands computation on the processing elements within the device.

An OpenCL device has considerable latitude on how computations are mapped onto the devices processing elements. When processing elements within a compute unit execute the same sequence of statements across the processing elements, the control flow is said to be converged. Hardware optimized for executing a single stream of instructions over multiple processing elements is well suited to converged control flows. When the control flow varies from one processing element to another, it is said to be diverged. While a kernel always begins execution with a converged control flow, due to branching statements within a kernel, converged and diverged control flows may occur within a single kernel. This provides a great deal of flexibility in the algorithms that can be implemented with OpenCL.
Figure 1. Platform Model ... one host plus one or more compute devices each with one or more compute units composed of one or more processing elements.

Programmers may provide programs in the form of OpenCL C source strings, the SPIR-V intermediate language, or as implementation-defined binary objects. An OpenCL platform provides a compiler to translate programs of these forms into executable program objects. The device code compiler may be online or offline. An online compiler is available during host program execution using standard APIs. An offline compiler is invoked outside of host program control, using platform-specific methods. The OpenCL runtime allows developers to get a previously compiled device program executable and be able to load and execute a previously compiled device program executable.

OpenCL defines two kinds of platform profiles: a full profile and a reduced-functionality embedded profile. A full profile platform must provide an online compiler for all its devices. An embedded platform may provide an online compiler, but is not required to do so.

A device may expose special purpose functionality as a built-in kernel. The platform provides APIs for enumerating and invoking the built-in kernels offered by a device, but otherwise does not define their construction or semantics. A custom device supports only built-in kernels, and cannot be programmed via a kernel language.

Built-in kernels and custom devices are missing before version 1.2.

All device types support the OpenCL execution model, the OpenCL memory model, and the APIs used in OpenCL to manage devices.

The platform model is an abstraction describing how OpenCL views the hardware. The relationship between the elements of the platform model and the hardware in a system may be a fixed property of a device or it may be a dynamic feature of a program dependent on how a compiler optimizes code to best utilize physical hardware.

3.2. Execution Model

The OpenCL execution model is defined in terms of two distinct units of execution: kernels that execute on one or more OpenCL devices and a host program that executes on the host. With regard to OpenCL, the kernels are where the “work” associated with a computation occurs. This work occurs through work-items that execute in groups (work-groups).

A kernel executes within a well-defined context managed by the host. The context defines the
environment within which kernels execute. It includes the following resources:

- **Devices**: One or more devices exposed by the OpenCL platform.
- **Kernel Objects**: The OpenCL functions with their associated argument values that run on OpenCL devices.
- **Program Objects**: The program source and executable that implement the kernels.
- **Memory Objects**: Variables visible to the host and the OpenCL devices. Instances of kernels operate on these objects as they execute.

The host program uses the OpenCL API to create and manage the context. Functions from the OpenCL API enable the host to interact with a device through a *command-queue*. Each command-queue is associated with a single device. The commands placed into the command-queue fall into one of three types:

- **Kernel-enqueue commands**: Enqueue a kernel for execution on a device.
- **Memory commands**: Transfer data between the host and device memory, between memory objects, or map and unmap memory objects from the host address space.
- **Synchronization commands**: Explicit synchronization points that define order constraints between commands.

In addition to commands submitted from the host command-queue, a kernel running on a device can enqueue commands to a device-side command-queue. This results in *child kernels* enqueued by a kernel executing on a device (the *parent kernel*). Regardless of whether the command-queue resides on the host or a device, each command passes through six states:

1. **Queued**: The command is enqueued to a command-queue. A command may reside in the queue until it is flushed either explicitly (a call to `clFlush`) or implicitly by some other command.

2. **Submitted**: The command is flushed from the command-queue and submitted for execution on the device. Once flushed from the command-queue, a command will execute after any prerequisites for execution are met.

3. **Ready**: All prerequisites constraining execution of a command have been met. The command, or for a kernel-enqueue command the collection of work-groups associated with a command, is placed in a device work-pool from which it is scheduled for execution.

4. **Running**: Execution of the command starts. For the case of a kernel-enqueue command, one or more work-groups associated with the command start to execute.

5. **Ended**: Execution of a command ends. When a Kernel-enqueue command ends, all of the work-groups associated with that command have finished their execution. *Immediate side effects*, i.e. those associated with the kernel but not necessarily with its child kernels, are visible to other units of execution. These side effects include updates to values in global memory.

6. **Complete**: The command and its child commands have finished execution and the status of the event object, if any, associated with the command is set to `CL_COMPLETE`.

The execution states and the transitions between them are summarized below. These states and the concept of a device work-pool are conceptual elements of the execution model. An implementation of OpenCL has considerable freedom in how these are exposed to a program. Five of the transitions,
however, are directly observable through a profiling interface. These *profiled states* are shown below.

![Diagram of states and transitions](image)

*Figure 2. The states and transitions between states defined in the OpenCL execution model. A subset of these transitions is exposed through the profiling interface.*

Commands communicate their status through *Event objects*. Successful completion is indicated by setting the event status associated with a command to `CL_COMPLETE`. Unsuccessful completion results in abnormal termination of the command which is indicated by setting the event status to a negative value. In this case, the command-queue associated with the abnormally terminated command and all other command-queues in the same context may no longer be available and their behavior is implementation-defined.

A command submitted to a device will not launch until prerequisites that constrain the order of commands have been resolved. These prerequisites have three sources:

- They may arise from commands submitted to a command-queue that constrain the order in which commands are launched. For example, commands that follow a command-queue barrier will not launch until all commands prior to the barrier are complete.

- The second source of prerequisites is dependencies between commands expressed through events. A command may include an optional list of events. The command will wait and not launch until all the events in the list are in the state `CL_COMPLETE`. By this mechanism, event objects define order constraints between commands and coordinate execution between the host and one or more devices.

- The third source of prerequisites can be the presence of non-trivial C initializers or C++ constructors for program scope global variables. In this case, OpenCL C/C++ compiler shall
Program initialization and clean-up kernels are missing before version 2.2.

Note that C initializers, C++ constructors, or C++ destructors for program scope variables cannot use pointers to coarse grain and fine grain SVM allocations.

A command may be submitted to a device and yet have no visible side effects outside of waiting on and satisfying event dependences. Examples include markers, kernels executed over ranges of no work-items or copy operations with zero sizes. Such commands may pass directly from the ready state to the ended state.

Command execution can be blocking or non-blocking. Consider a sequence of OpenCL commands. For blocking commands, the OpenCL API functions that enqueue commands don’t return until the command has completed. Alternatively, OpenCL functions that enqueue non-blocking commands return immediately and require that a programmer defines dependencies between enqueued commands to ensure that enqueued commands are not launched before needed resources are available. In both cases, the actual execution of the command may occur asynchronously with execution of the host program.

Commands within a single command-queue execute relative to each other in one of two modes:

- **In-order Execution**: Commands and any side effects associated with commands appear to the OpenCL application as if they execute in the same order they are enqueued to a command-queue.

- **Out-of-order Execution**: Commands execute in any order constrained only by explicit synchronization points (e.g. through command-queue barriers) or explicit dependencies on events.

Multiple command-queues can be present within a single context. Multiple command-queues execute commands independently. Event objects visible to the host program can be used to define synchronization points between commands in multiple command-queues. If such synchronization points are established between commands in multiple command-queues, an implementation must assure that the command-queues progress concurrently and correctly account for the dependencies established by the synchronization points. For a detailed explanation of synchronization points, see the execution model **Synchronization** section.

The core of the OpenCL execution model is defined by how the kernels execute. When a kernel-enqueue command submits a kernel for execution, an index space is defined. The kernel, the argument values associated with the arguments to the kernel, and the parameters that define the
index space define a *kernel-instance*. When a kernel-instance executes on a device, the kernel function executes for each point in the defined index space. Each of these executing kernel functions is called a *work-item*. The work-items associated with a given kernel-instance are managed by the device in groups called *work-groups*. These work-groups define a coarse grained decomposition of the Index space. Work-groups are further divided into *sub-groups*, which provide an additional level of control over execution.

Sub-groups are missing before version 2.1.

Work-items have a global ID based on their coordinates within the Index space. They can also be defined in terms of their work-group and the local ID within a work-group. The details of this mapping are described in the following section.

### 3.2.1. Mapping Work-items Onto an Nd-range

The index space supported by OpenCL is called an ND-range. An ND-range is an N-dimensional index space, where N is one, two or three. The ND-range is decomposed into work-groups forming blocks that cover the Index space. An ND-range is defined by three integer arrays of length N:

- The extent of the index space (or global size) in each dimension.
- An offset index F indicating the initial value of the indices in each dimension (zero by default).
- The size of a work-group (local size) in each dimension.

Each work-items global ID is an N-dimensional tuple. The global ID components are values in the range from F, to F plus the number of elements in that dimension minus one.

Unless a kernel comes from a source that disallows it, e.g. OpenCL C 1.x or using `-cl-uniform-work-group-size`, the size of work-groups in an ND-range (the local size) need not be the same for all work-groups. In this case, any single dimension for which the global size is not divisible by the local size will be partitioned into two regions. One region will have work-groups that have the same number of work-items as was specified for that dimension by the programmer (the local size). The other region will have work-groups with less than the number of work items specified by the local size parameter in that dimension (the *remainder work-groups*). Work-group sizes could be non-uniform in multiple dimensions, potentially producing work-groups of up to 4 different sizes in a 2D range and 8 different sizes in a 3D range.

Non-uniform work-group sizes are missing before version 2.0.

Each work-item is assigned to a work-group and given a local ID to represent its position within the work-group. A work-item's local ID is an N-dimensional tuple with components in the range from zero to the size of the work-group in that dimension minus one.

Work-groups are assigned IDs similarly. The number of work-groups in each dimension is not directly defined but is inferred from the local and global ND-ranges provided when a kernel-instance is enqueued. A work-group's ID is an N-dimensional tuple with components in the range 0 to the ceiling of the global size in that dimension divided by the local size in the same dimension. As a result, the combination of a work-group ID and the local-ID within a work-group uniquely defines a work-item. Each work-item is identifiable in two ways; in terms of a global index, and in terms of
a work-group index plus a local index within a work-group.

For example, consider the 2-dimensional index space shown below. We input the index space for the work-items \((G_x, G_y)\), the size of each work-group \((S_x, S_y)\) and the global ID offset \((F_x, F_y)\). The global indices define an \(G_x\) by \(G_y\) index space where the total number of work-items is the product of \(G_x\) and \(G_y\). The local indices define an \(S_x\) by \(S_y\) index space where the number of work-items in a single work-group is the product of \(S_x\) and \(S_y\). Given the size of each work-group and the total number of work-items we can compute the number of work-groups. A 2-dimensional index space is used to uniquely identify a work-group. Each work-item is identified by its global ID \((g_x, g_y)\) or by the combination of the work-group ID \((w_x, w_y)\), the size of each work-group \((S_x, S_y)\) and the local ID \((s_x, s_y)\) inside the work-group such that

\[
(g_x, g_y) = (w_x \times S_x + s_x + F_x, w_y \times S_y + s_y + F_y)
\]

The number of work-groups can be computed as:

\[
(W_x, W_y) = (\text{ceil}(G_x / S_x), \text{ceil}(G_y / S_y))
\]

Given a global ID and the work-group size, the work-group ID for a work-item is computed as:

\[
(w_x, w_y) = (\frac{(g_x - s_x - F_x)}{S_x}, \frac{(g_y - s_y - F_y)}{S_y})
\]

Figure 3. An example of an ND-range index space showing work-items, their global IDs and their mapping onto the pair of work-group and local IDs. In this case, we assume that in each dimension, the size of the work-group evenly divides the global ND-range size (i.e. all work-groups have the same size) and that the offset is equal to zero.

Within a work-group work-items may be divided into sub-groups. The mapping of work-items to sub-groups is implementation-defined and may be queried at runtime. While sub-groups may be used in multi-dimensional work-groups, each sub-group is 1-dimensional and any given work-item may query which sub-group it is a member of.
Sub-groups are missing before version 2.1.

Work-items are mapped into sub-groups through a combination of compile-time decisions and the parameters of the dispatch. The mapping to sub-groups is invariant for the duration of a kernels execution, across dispatches of a given kernel with the same work-group dimensions, between dispatches and query operations consistent with the dispatch parameterization, and from one work-group to another within the dispatch (excluding the trailing edge work-groups in the presence of non-uniform work-group sizes). In addition, all sub-groups within a work-group will be the same size, apart from the sub-group with the maximum index which may be smaller if the size of the work-group is not evenly divisible by the size of the sub-groups.

In the degenerate case, a single sub-group must be supported for each work-group. In this situation all sub-group scope functions are equivalent to their work-group level equivalents.

### 3.2.2. Execution of Kernel-instances

The work carried out by an OpenCL program occurs through the execution of kernel-instances on compute devices. To understand the details of OpenCL's execution model, we need to consider how a kernel object moves from the kernel-enqueue command, into a command-queue, executes on a device, and completes.

A kernel object is defined as a function within the program object and a collection of arguments connecting the kernel to a set of argument values. The host program enqueues a kernel object to the command-queue along with the ND-range and the work-group decomposition. These define a kernel-instance. In addition, an optional set of events may be defined when the kernel is enqueued. The events associated with a particular kernel-instance are used to constrain when the kernel-instance is launched with respect to other commands in the queue or to commands in other queues within the same context.

A kernel-instance is submitted to a device. For an in-order command-queue, the kernel instances appear to launch and then execute in that same order; where we use the term appear to emphasize that when there are no dependencies between commands and hence differences in the order that commands execute cannot be observed in a program, an implementation can reorder commands even in an in-order command-queue. For an out-of-order command-queue, kernel-instances wait to be launched until:

- Synchronization commands enqueued prior to the kernel-instance are satisfied.
- Each of the events in an optional event list defined when the kernel-instance was enqueued are set to **CL_COMPLETE**.

Once these conditions are met, the kernel-instance is launched and the work-groups associated with the kernel-instance are placed into a pool of ready to execute work-groups. This pool is called a work-pool. The work-pool may be implemented in any manner as long as it assures that work-groups placed in the pool will eventually execute. The device schedules work-groups from the work-pool for execution on the compute units of the device. The kernel-enqueue command is complete when all work-groups associated with the kernel-instance end their execution, updates to global memory associated with a command are visible globally, and the device signals successful completion by setting the event associated with the kernel-enqueue command to **CL_COMPLETE**.
While a command-queue is associated with only one device, a single device may be associated with multiple command-queues all feeding into the single work-pool. A device may also be associated with command-queues associated with different contexts within the same platform, again all feeding into the single work-pool. The device will pull work-groups from the work-pool and execute them on one or several compute units in any order; possibly interleaving execution of work-groups from multiple commands. A conforming implementation may choose to serialize the work-groups so a correct algorithm cannot assume that work-groups will execute in parallel. There is no safe and portable way to synchronize across the independent execution of work-groups since once in the work-pool, they can execute in any order.

The work-items within a single sub-group execute concurrently but not necessarily in parallel (i.e. they are not guaranteed to make independent forward progress). Therefore, only high-level synchronization constructs (e.g. sub-group functions such as barriers) that apply to all the work-items in a sub-group are well defined and included in OpenCL.

Sub-groups are missing before version 2.1.

Sub-groups execute concurrently within a given work-group and with appropriate device support (see Querying Devices), may make independent forward progress with respect to each other, with respect to host threads and with respect to any entities external to the OpenCL system but running on an OpenCL device, even in the absence of work-group barrier operations. In this situation, sub-groups are able to internally synchronize using barrier operations without synchronizing with each other and may perform operations that rely on runtime dependencies on operations other sub-groups perform.

The work-items within a single work-group execute concurrently but are only guaranteed to make independent progress in the presence of sub-groups and device support. In the absence of this capability, only high-level synchronization constructs (e.g. work-group functions such as barriers) that apply to all the work-items in a work-group are well defined and included in OpenCL for synchronization within the work-group.

In the absence of synchronization functions (e.g. a barrier), work-items within a sub-group may be serialized. In the presence of sub-group functions, work-items within a sub-group may be serialized before any given sub-group function, between dynamically encountered pairs of sub-group functions and between a work-group function and the end of the kernel.

In the absence of independent forward progress of constituent sub-groups, work-items within a work-group may be serialized before, after or between work-group synchronization functions.

3.2.3. Device-Side Enqueue

Device-side enqueue is missing before version 2.0.

Algorithms may need to generate additional work as they execute. In many cases, this additional work cannot be determined statically; so the work associated with a kernel only emerges at runtime as the kernel-instance executes. This capability could be implemented in logic running within the host program, but involvement of the host may add significant overhead and/or complexity to the application control flow. A more efficient approach would be to nest kernel-
enqueue commands from inside other kernels. This nested parallelism can be realized by supporting the enqueuing of kernels on a device without direct involvement by the host program; so-called device-side enqueue.

Device-side kernel-enqueue commands are similar to host-side kernel-enqueue commands. The kernel executing on a device (the parent kernel) enqueues a kernel-instance (the child kernel) to a device-side command-queue. This is an out-of-order command-queue and follows the same behavior as the out-of-order command-queues exposed to the host program. Commands enqueued to a device-side command-queue generate and use events to enforce order constraints just as for the command-queue on the host. These events, however, are only visible to the parent kernel running on the device. When these prerequisite events take on the value CL_COMPLETE, the work-groups associated with the child kernel are launched into the devices work pool. The device then schedules them for execution on the compute units of the device. Child and parent kernels execute asynchronously. However, a parent will not indicate that it is complete by setting its event to CL_COMPLETE until all child kernels have ended execution and have signaled completion by setting any associated events to the value CL_COMPLETE. Should any child kernel complete with an event status set to a negative value (i.e. abnormally terminate), the parent kernel will abnormally terminate and propagate the childs negative event value as the value of the parents event. If there are multiple children that have an event status set to a negative value, the selection of which childs negative event value is propagated is implementation-defined.

3.2.4. Synchronization

Synchronization refers to mechanisms that constrain the order of execution between two or more units of execution. Consider the following three domains of synchronization in OpenCL:

- Work-group synchronization: Constraints on the order of execution for work-items in a single work-group
- Sub-group synchronization: Constraints on the order of execution for work-items in a single sub-group. Note: Sub-groups are missing before version 2.1
- Command synchronization: Constraints on the order of commands launched for execution

Synchronization across all work-items within a single work-group is carried out using a work-group function. These functions carry out collective operations across all the work-items in a work-group. Available collective operations are: barrier, reduction, broadcast, prefix sum, and evaluation of a predicate. A work-group function must occur within a converged control flow; i.e. all work-items in the work-group must encounter precisely the same work-group function. For example, if a work-group function occurs within a loop, the work-items must encounter the same work-group function in the same loop iterations. All the work-items of a work-group must execute the work-group function and complete reads and writes to memory before any are allowed to continue execution beyond the work-group function. Work-group functions that apply between work-groups are not provided in OpenCL since OpenCL does not define forward-progress or ordering relations between work-groups, hence collective synchronization operations are not well defined.

Synchronization across all work-items within a single sub-group is carried out using a sub-group function. These functions carry out collective operations across all the work-items in a sub-group. Available collective operations are: barrier, reduction, broadcast, prefix sum, and evaluation of a predicate. A sub-group function must occur within a converged control flow; i.e. all work-items in
the sub-group must encounter precisely the same sub-group function. For example, if a work-group function occurs within a loop, the work-items must encounter the same sub-group function in the same loop iterations. All the work-items of a sub-group must execute the sub-group function and complete reads and writes to memory before any are allowed to continue execution beyond the sub-group function. Synchronization between sub-groups must either be performed using work-group functions, or through memory operations. Using memory operations for sub-group synchronization should be used carefully as forward progress of sub-groups relative to each other is only supported optionally by OpenCL implementations.

Command synchronization is defined in terms of distinct synchronization points. The synchronization points occur between commands in host command-queues and between commands in device-side command-queues. The synchronization points defined in OpenCL include:

- **Launching a command**: A kernel-instance is launched onto a device after all events that kernel is waiting-on have been set to CL_COMPLETE.

- **Ending a command**: Child kernels may be enqueued such that they wait for the parent kernel to reach the end state before they can be launched. In this case, the ending of the parent command defines a synchronization point.

- **Completion of a command**: A kernel-instance is complete after all of the work-groups in the kernel and all of its child kernels have completed. This is signaled to the host, a parent kernel or other kernels within command-queues by setting the value of the event associated with a kernel to CL_COMPLETE.

- **Blocking Commands**: A blocking command defines a synchronization point between the unit of execution that calls the blocking API function and the enqueued command reaching the complete state.

- **Command-queue barrier**: The command-queue barrier ensures that all previously enqueued commands have completed before subsequently enqueued commands can be launched.

- **clFinish**: This function blocks until all previously enqueued commands in the command-queue have completed after which clFinish defines a synchronization point and the clFinish function returns.

A synchronization point between a pair of commands (A and B) assures that results of command A happens-before command B is launched. This requires that any updates to memory from command A complete and are made available to other commands before the synchronization point completes. Likewise, this requires that command B waits until after the synchronization point before loading values from global memory. The concept of a synchronization point works in a similar fashion for commands such as a barrier that apply to two sets of commands. All the commands prior to the barrier must complete and make their results available to following commands. Furthermore, any commands following the barrier must wait for the commands prior to the barrier before loading values and continuing their execution.

These happens-before relationships are a fundamental part of the OpenCL 2.x memory model. When applied at the level of commands, they are straightforward to define at a language level in terms of ordering relationships between different commands. Ordering memory operations inside different commands, however, requires rules more complex than can be captured by the high level concept of a synchronization point. These rules are described in detail in Memory Ordering Rules.
3.2.5. Categories of Kernels

The OpenCL execution model supports three types of kernels:

- **OpenCL kernels** are managed by the OpenCL API as kernel objects associated with kernel functions within program objects. OpenCL program objects are created and built using OpenCL APIs. The OpenCL API includes functions to query the kernel languages and intermediate languages that may be used to create OpenCL program objects for a device.

- **Native kernels** are accessed through a host function pointer. Native kernels are queued for execution along with OpenCL kernels on a device and share memory objects with OpenCL kernels. For example, these native kernels could be functions defined in application code or exported from a library. The ability to execute native kernels is optional within OpenCL and the semantics of native kernels are implementation-defined. The OpenCL API includes functions to query capabilities of a device to determine if this capability is supported.

- **Built-in kernels** are tied to particular device and are not built at runtime from source code in a program object. The common use of built in kernels is to expose fixed-function hardware or firmware associated with a particular OpenCL device or custom device. The semantics of a built-in kernel may be defined outside of OpenCL and hence are implementation-defined. Note: Built-in kernels are missing before version 1.2.

All three types of kernels are manipulated through the OpenCL command-queues and must conform to the synchronization points defined in the OpenCL execution model.

3.3. Memory Model

The OpenCL memory model describes the structure, contents, and behavior of the memory exposed by an OpenCL platform as an OpenCL program runs. The model allows a programmer to reason about values in memory as the host program and multiple kernel-instances execute.

An OpenCL program defines a context that includes a host, one or more devices, command-queues, and memory exposed within the context. Consider the units of execution involved with such a program. The host program runs as one or more host threads managed by the operating system running on the host (the details of which are defined outside of OpenCL). There may be multiple devices in a single context which all have access to memory objects defined by OpenCL. On a single device, multiple work-groups may execute in parallel with potentially overlapping updates to memory. Finally, within a single work-group, multiple work-items concurrently execute, once again with potentially overlapping updates to memory.

The memory model must precisely define how the values in memory as seen from each of these units of execution interact so a programmer can reason about the correctness of OpenCL programs. We define the memory model in four parts.

- Memory regions: The distinct memories visible to the host and the devices that share a context.
- Memory objects: The objects defined by the OpenCL API and their management by the host and devices.
- Shared Virtual Memory: A virtual address space exposed to both the host and the devices within a context. Note: SVM is missing before version 2.0.
• Consistency Model: Rules that define which values are observed when multiple units of execution load data from memory plus the atomic/fence operations that constrain the order of memory operations and define synchronization relationships.

### 3.3.1. Fundamental Memory Regions

Memory in OpenCL is divided into two parts.

- **Host Memory**: The memory directly available to the host. The detailed behavior of host memory is defined outside of OpenCL. Memory objects move between the Host and the devices through functions within the OpenCL API or through a shared virtual memory interface.

- **Device Memory**: Memory directly available to kernels executing on OpenCL devices.

Device memory consists of four named address spaces or **memory regions**:

- **Global Memory**: This memory region permits read/write access to all work-items in all work-groups running on any device within a context. Work-items can read from or write to any element of a memory object. Reads and writes to global memory may be cached depending on the capabilities of the device.

- **Constant Memory**: A region of global memory that remains constant during the execution of a kernel-instance. The host allocates and initializes memory objects placed into constant memory.

- **Local Memory**: A memory region local to a work-group. This memory region can be used to allocate variables that are shared by all work-items in that work-group.

- **Private Memory**: A region of memory private to a work-item. Variables defined in one work-item's private memory are not visible to another work-item.

The **memory regions** and their relationship to the OpenCL Platform model are summarized below. Local and private memories are always associated with a particular device. The global and constant memories, however, are shared between all devices within a given context. An OpenCL device may include a cache to support efficient access to these shared memories.

To understand memory in OpenCL, it is important to appreciate the relationships between these named address spaces. The four named address spaces available to a device are disjoint meaning they do not overlap. This is a logical relationship, however, and an implementation may choose to let these disjoint named address spaces share physical memory.

Programmers often need functions callable from kernels where the pointers manipulated by those functions can point to multiple named address spaces. This saves a programmer from the error-prone and wasteful practice of creating multiple copies of functions; one for each named address space. Therefore the global, local and private address spaces belong to a single **generic address space**. This is closely modeled after the concept of a generic address space used in the embedded C standard (ISO/IEC 9899:1999). Since they all belong to a single generic address space, the following properties are supported for pointers to named address spaces in device memory:

- A pointer to the generic address space can be cast to a pointer to a global, local or private address space

- A pointer to a global, local or private address space can be cast to a pointer to the generic
address space.

- A pointer to a global, local or private address space can be implicitly converted to a pointer to the generic address space, but the converse is not allowed.

The constant address space is disjoint from the generic address space.

The generic address space is **missing before** version 2.0.

The addresses of memory associated with memory objects in Global memory are not preserved between kernel instances, between a device and the host, and between devices. In this regard global memory acts as a global pool of memory objects rather than an address space. This restriction is relaxed when shared virtual memory (SVM) is used.

Shared virtual memory is **missing before** version 2.0.

SVM causes addresses to be meaningful between the host and all of the devices within a context hence supporting the use of pointer based data structures in OpenCL kernels. It logically extends a portion of the global memory into the host address space giving work-items access to the host address space. On platforms with hardware support for a shared address space between the host and one or more devices, SVM may also provide a more efficient way to share data between devices and the host. Details about SVM are presented in **Shared Virtual Memory.**
Figure 4. The named address spaces exposed in an OpenCL Platform. Global and Constant memories are shared between the one or more devices within a context, while local and private memories are associated with a single device. Each device may include an optional cache to support efficient access to their view of the global and constant address spaces.

A programmer may use the features of the memory consistency model to manage safe access to global memory from multiple work-items potentially running on one or more devices. In addition, when using shared virtual memory (SVM), the memory consistency model may also be used to ensure that host threads safely access memory locations in the shared memory region.

3.3.2. Memory Objects

The contents of global memory are memory objects. A memory object is a handle to a reference counted region of global memory. Memory objects use the OpenCL type `cl_mem` and fall into three distinct classes.

- **Buffer**: A memory object stored as a block of contiguous memory and used as a general purpose object to hold data used in an OpenCL program. The types of the values within a buffer may be any of the built in types (such as int, float), vector types, or user-defined structures. The buffer can be manipulated through pointers much as one would with any block of memory in C.

- **Image**: An image memory object holds one, two or three dimensional images. The formats are based on the standard image formats used in graphics applications. An image is an opaque data structure managed by functions defined in the OpenCL API. To optimize the manipulation of images stored in the texture memories found in many GPUs, OpenCL kernels have traditionally been disallowed from both reading and writing a single image. In OpenCL 2.0, however, we have relaxed this restriction by providing synchronization and fence operations that let
programmers properly synchronize their code to safely allow a kernel to read and write a single image.

- **Pipe**: The *pipe* memory object conceptually is an ordered sequence of data items. A pipe has two endpoints: a write endpoint into which data items are inserted, and a read endpoint from which data items are removed. At any one time, only one kernel instance may write into a pipe, and only one kernel instance may read from a pipe. To support the producer consumer design pattern, one kernel instance connects to the write endpoint (the producer) while another kernel instance connects to the reading endpoint (the consumer). Note: The *pipe* memory object is missing before version 2.0.

Memory objects are allocated by host APIs. The host program can provide the runtime with a pointer to a block of continuous memory to hold the memory object when the object is created (*CL_MEM_USE_HOST_PTR*). Alternatively, the physical memory can be managed by the OpenCL runtime and not be directly accessible to the host program.

Allocation and access to memory objects within the different memory regions varies between the host and work-items running on a device. This is summarized in the *Memory Regions* table, which describes whether the kernel or the host can allocate from a memory region, the type of allocation (static at compile time vs. dynamic at runtime) and the type of access allowed (i.e. whether the kernel or the host can read and/or write to a memory region).

**Table 1. Memory Regions**

<table>
<thead>
<tr>
<th></th>
<th>Global</th>
<th>Constant</th>
<th>Local</th>
<th>Private</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Host</strong></td>
<td>Allocation</td>
<td>Dynamic</td>
<td>Dynamic</td>
<td>None</td>
</tr>
<tr>
<td></td>
<td>Read/Write to Buffers and Images, but not Pipes</td>
<td>Read/Write</td>
<td>None</td>
<td>None</td>
</tr>
<tr>
<td><strong>Kernel</strong></td>
<td>Allocation</td>
<td>Static (program scope variables)</td>
<td>Static for parent kernel, Dynamic for child kernels</td>
<td>Static</td>
</tr>
<tr>
<td></td>
<td>Read/Write</td>
<td>Read-only</td>
<td>Read/Write, No access to child kernel memory</td>
<td>Read/Write</td>
</tr>
</tbody>
</table>

The *Memory Regions* table shows the different memory regions in OpenCL and how memory objects are allocated and accessed by the host and by an executing instance of a kernel. For kernels, we distinguish between the behavior of local memory for a parent kernel and its child kernels.

Once allocated, a memory object is made available to kernel-instances running on one or more devices. In addition to *Shared Virtual Memory*, there are three basic ways to manage the contents of buffers between the host and devices.

- **Read/Write/Fill commands**: The data associated with a memory object is explicitly read and written between the host and global memory regions using commands enqueued to an OpenCL command-queue. Note: Fill commands are missing before version 1.2.
• **Map/Unmap commands**: Data from the memory object is mapped into a contiguous block of memory accessed through a host accessible pointer. The host program enqueues a *map* command on block of a memory object before it can be safely manipulated by the host program. When the host program is finished working with the block of memory, the host program enqueues an *unmap* command to allow a kernel-instance to safely read and/or write the buffer.

• **Copy commands**: The data associated with a memory object is copied between two buffers, each of which may reside either on the host or on the device.

With Read/Write/Map, the commands can be blocking or non-blocking operations. The OpenCL function call for a blocking memory transfer returns once the command (memory transfer) has completed. At this point the associated memory resources on the host can be safely reused, and following operations on the host are guaranteed that the transfer has already completed. For a non-blocking memory transfer, the OpenCL function call returns as soon as the command is enqueued.

Memory objects are bound to a context and hence can appear in multiple kernel-instances running on more than one physical device. The OpenCL platform must support a large range of hardware platforms including systems that do not support a single shared address space in hardware; hence the ways memory objects can be shared between kernel-instances is restricted. The basic principle is that multiple read operations on memory objects from multiple kernel-instances that overlap in time are allowed, but mixing overlapping reads and writes into the same memory objects from different kernel instances is only allowed when fine grained synchronization is used with Shared Virtual Memory.

When global memory is manipulated by multiple kernel-instances running on multiple devices, the OpenCL runtime system must manage the association of memory objects with a given device. In most cases the OpenCL runtime will implicitly associate a memory object with a device. A kernel instance is naturally associated with the command-queue to which the kernel was submitted. Since a command-queue can only access a single device, the queue uniquely defines which device is involved with any given kernel-instance; hence defining a clear association between memory objects, kernel-instances and devices. Programmers may anticipate these associations in their programs and explicitly manage association of memory objects with devices in order to improve performance.

### 3.3.3. Lifetime of Shared Direct3D Memory Objects

This section refers to similar Direct3D 10 and Direct3D 11 objects and concepts such as resources, reference counts, and devices.

Sharing is accomplished by creating an OpenCL context via the context create parameters `CL_CONTEXT_D3D10_DEVICE_KHR` (for Direct3D 10, if the `cl_khr_d3d10_sharing` extension is supported) or `CL_CONTEXT_D3D11_DEVICE_KHR` (for Direct3D 11, if the `cl_khr_d3d11_sharing` extension is supported).

An OpenCL memory object created from a Direct3D resource remains valid as long as the corresponding Direct3D resource has not been deleted. If the Direct3D resource is deleted through the Direct3D API, subsequent use of the OpenCL memory object will result in undefined behavior, including but not limited to possible OpenCL errors, data corruption, and program termination.

The successful creation of a `cl_context` against a Direct3D device will increment the internal Direct3D reference count on the specified device. The internal Direct3D reference count on that
Direct3D device will be decremented when the OpenCL reference count on the returned OpenCL context drops to zero.

The OpenCL context and corresponding command-queues are dependent on the existence of the Direct3D device from which the OpenCL context was created. If the Direct3D device is deleted through the Direct3D API, subsequent use of the OpenCL context will result in undefined behavior, including but not limited to possible OpenCL errors, data corruption, and program termination.

3.3.3.1. Lifetime of Shared EGLImage Objects

An OpenCL memory object created from an EGL EGLImage object remains valid according to the lifetime behavior as described in the EGL_KHR_image_base extension.

Any EGLImage siblings exist in any client API context

For OpenCL this means that while the application retains a reference on the cl_mem (the EGL sibling), the image remains valid.

3.3.4. Lifetime of Shared OpenCL/OpenGL Memory Objects

An OpenCL memory object created from an OpenGL object (hereinafter referred to as a “shared OpenCL/OpenGL object”) remains valid as long as the corresponding OpenGL object has not been deleted. If the OpenGL object is deleted through the OpenGL API (e.g. glDeleteBuffers, glDeleteTextures, or glDeleteRenderbuffers), subsequent use of the OpenCL buffer or image object will result in undefined behavior, including but not limited to possible OpenCL errors and data corruption, but may not result in program termination.

The OpenCL context and corresponding command-queues are dependent on the existence of the OpenGL share group object, or the share group associated with the OpenGL context from which the OpenCL context is created. If the OpenGL share group object or all OpenGL contexts in the share group are destroyed, any use of the OpenCL context or command-queue(s) will result in undefined behavior, which may include program termination. Applications should destroy the OpenCL command-queue(s) and OpenCL context before destroying the corresponding OpenGL share group or contexts.

3.3.5. Shared Virtual Memory

Shared virtual memory is missing before version 2.0.

OpenCL extends the global memory region into the host memory region through a shared virtual memory (SVM) mechanism. There are three types of SVM in OpenCL:

- **Coarse-Grained buffer SVM**: Sharing occurs at the granularity of regions of OpenCL buffer memory objects. Consistency is enforced at synchronization points and with map/unmap commands to drive updates between the host and the device. This form of SVM is similar to non-SVM use of memory; however, it lets kernel-instances share pointer-based data structures (such as linked-lists) with the host program. Program scope global variables are treated as per-device coarse-grained SVM for addressing and sharing purposes.

- **Fine-Grained buffer SVM**: Sharing occurs at the granularity of individual loads/stores into
bytes within OpenCL buffer memory objects. Loads and stores may be cached. This means consistency is guaranteed at synchronization points. If the optional OpenCL atomics are supported, they can be used to provide fine-grained control of memory consistency.

- **Fine-Grained system SVM**: Sharing occurs at the granularity of individual loads/stores into bytes occurring anywhere within the host memory. Loads and stores may be cached so consistency is guaranteed at synchronization points. If the optional OpenCL atomics are supported, they can be used to provide fine-grained control of memory consistency.

### Table 2. A summary of shared virtual memory (SVM) options in OpenCL

<table>
<thead>
<tr>
<th>Granularity of sharing</th>
<th>Memory Allocation</th>
<th>Mechanisms to enforce Consistency</th>
<th>Explicit updates between host and device</th>
</tr>
</thead>
<tbody>
<tr>
<td>Non-SVM buffers</td>
<td>OpenCL Memory objects (buffer)</td>
<td><code>clCreateBuffer</code> <code>clCreateBufferWithProperties</code></td>
<td>Host synchronization points on the same or between devices</td>
</tr>
<tr>
<td>Coarse-Grained buffer SVM</td>
<td>OpenCL Memory objects (buffer)</td>
<td><code>clSVMAlloc</code></td>
<td>Host synchronization points between devices</td>
</tr>
<tr>
<td>Fine-Grained buffer SVM</td>
<td>Bytes within OpenCL Memory objects (buffer)</td>
<td><code>clSVMAlloc</code></td>
<td>Synchronization points plus atomics (if supported)</td>
</tr>
<tr>
<td>Fine-Grained system SVM</td>
<td>Bytes within Host memory (system)</td>
<td>Host memory allocation mechanisms (e.g. malloc)</td>
<td>Synchronization points plus atomics (if supported)</td>
</tr>
</tbody>
</table>

Coarse-Grained buffer SVM is a required feature for OpenCL 2.0, 2.1, or 2.2 devices and an optional feature for OpenCL 3.0 or newer devices. Fine-Grained SVM is an optional feature for all OpenCL devices. The various SVM mechanisms to access host memory from the work-items associated with a kernel instance are summarized above.

### 3.3.6. Memory Consistency Model for OpenCL 1.x

This memory consistency model is deprecated by version 2.0.

OpenCL 1.x uses a relaxed consistency memory model; i.e. the state of memory visible to a work-item is not guaranteed to be consistent across the collection of work-items at all times.

Within a work-item memory has load / store consistency. Local memory is consistent across work-items in a single work-group at a work-group barrier. Global memory is consistent across work-items in a single work-group at a work-group barrier, but there are no guarantees of memory consistency between different work-groups executing a kernel.
Memory consistency for memory objects shared between enqueued commands is enforced at a synchronization point.

### 3.3.7. Memory Consistency Model for OpenCL 2.x

This memory consistency model is missing before version 2.0.

The OpenCL 2.x memory model tells programmers what they can expect from an OpenCL 2.x implementation; which memory operations are guaranteed to happen in which order and which memory values each read operation will return. The memory model tells compiler writers which restrictions they must follow when implementing compiler optimizations; which variables they can cache in registers and when they can move reads or writes around a barrier or atomic operation. The memory model also tells hardware designers about limitations on hardware optimizations; for example, when they must flush or invalidate hardware caches.

The memory consistency model in OpenCL 2.x is based on the memory model from the ISO C11 programming language. To help make the presentation more precise and self-contained, we include modified paragraphs taken verbatim from the ISO C11 international standard. When a paragraph is taken or modified from the C11 standard, it is identified as such along with its original location in the C11 standard.

For programmers, the most intuitive model is the *sequential consistency* memory model. Sequential consistency interleaves the steps executed by each of the units of execution. Each access to a memory location sees the last assignment to that location in that interleaving. While sequential consistency is relatively straightforward for a programmer to reason about, implementing sequential consistency is expensive. Therefore, OpenCL 2.x implements a relaxed memory consistency model; i.e. it is possible to write programs where the loads from memory violate sequential consistency. Fortunately, if a program does not contain any races and if the program only uses atomic operations that utilize the sequentially consistent memory order (the default memory ordering for OpenCL 2.x), OpenCL programs appear to execute with sequential consistency.

Programmers can to some degree control how the memory model is relaxed by choosing the memory order for synchronization operations. The precise semantics of synchronization and the memory orders are formally defined in Memory Ordering Rules. Here, we give a high level description of how these memory orders apply to atomic operations on atomic objects shared between units of execution. OpenCL 2.x memory_order choices are based on those from the ISO C11 standard memory model. They are specified in certain OpenCL functions through the following enumeration constants:

- **memory_order_relaxed**: implies no order constraints. This memory order can be used safely to increment counters that are concurrently incremented, but it doesn’t guarantee anything about the ordering with respect to operations to other memory locations. It can also be used, for example, to do ticket allocation and by expert programmers implementing lock-free algorithms.

- **memory_order_acquire**: A synchronization operation (fence or atomic) that has acquire semantics "acquires" side-effects from a release operation that synchronizes with it: if an acquire synchronizes with a release, the acquiring unit of execution will see all side-effects preceding that release (and possibly subsequent side-effects.) As part of carefully-designed
protocols, programmers can use an "acquire" to safely observe the work of another unit of execution.

- **memory_order_release**: A synchronization operation (fence or atomic operation) that has release semantics "releases" side effects to an acquire operation that synchronises with it. All side effects that precede the release are included in the release. As part of carefully-designed protocols, programmers can use a "release" to make changes made in one unit of execution visible to other units of execution.

In general, no acquire must *always* synchronise with any particular release. However, synchronisation can be forced by certain executions. See the description of Fence Operations for detailed rules for when synchronisation must occur.

- **memory_order_acq_rel**: A synchronization operation with acquire-release semantics has the properties of both the acquire and release memory orders. It is typically used to order read-modify-write operations.

- **memory_order_seq_cst**: The loads and stores of each unit of execution appear to execute in program (i.e., sequenced-before) order, and the loads and stores from different units of execution appear to be simply interleaved.

Regardless of which memory_order is specified, resolving constraints on memory operations across a heterogeneous platform adds considerable overhead to the execution of a program. An OpenCL platform may be able to optimize certain operations that depend on the features of the memory consistency model by restricting the scope of the memory operations. Distinct memory scopes are defined by the values of the memory_scope enumeration constant:

- **memory_scope_work_item**: memory-ordering constraints only apply within the work-item
- **memory_scope_sub_group**: memory-ordering constraints only apply within the sub-group.
- **memory_scope_work_group**: memory-ordering constraints only apply to work-items executing within a single work-group.
- **memory_scope_device**: memory-ordering constraints only apply to work-items executing on a single device
- **memory_scope_all_svm_devices**: memory-ordering constraints apply to work-items executing across multiple devices and (when using SVM) the host. A release performed with memory_scope_all_svm_devices to a buffer that does not have the CL_MEM_SVM_ATOMICS flag set will commit to at least memory_scope_device visibility, with full synchronization of the buffer at a queue synchronization point (e.g. an OpenCL event).
- **memory_scope_all_devices**: an alias for memory_scope_all_svm_devices.

These memory scopes define a hierarchy of visibilities when analyzing the ordering constraints of memory operations. For example if a programmer knows that a sequence of memory operations will only be associated with a collection of work-items from a single work-group (and hence will run on a single device), the implementation is spared the overhead of managing the memory orders across other devices within the same context. This can substantially reduce overhead in a program. All memory scopes are valid when used on global memory or local memory. For local memory, all visibility is constrained to within a given work-group and scopes wider than memory_scope_work_group carry no additional meaning.
In the following subsections (leading up to OpenCL Framework), we will explain the synchronization constructs and detailed rules needed to use OpenCL’s 2.x relaxed memory models. It is important to appreciate, however, that many programs do not benefit from relaxed memory models. Even expert programmers have a difficult time using atomics and fences to write correct programs with relaxed memory models. A large number of OpenCL programs can be written using a simplified memory model. This is accomplished by following these guidelines.

- Write programs that manage safe sharing of global memory objects through the synchronization points defined by the command-queues.
- Restrict low level synchronization inside work-groups to the work-group functions such as barrier.
- If you want sequential consistency behavior with system allocations or fine-grain SVM buffers with atomics support, use only `memory_order_seq_cst` operations with the scope `memory_scope_all_svm_devices`.
- If you want sequential consistency behavior when not using system allocations or fine-grain SVM buffers with atomics support, use only `memory_order_seq_cst` operations with the scope `memory_scope_device` or `memory_scope_all_svm_devices`.
- Ensure your program has no races.

If these guidelines are followed in your OpenCL programs, you can skip the detailed rules behind the relaxed memory models and go directly to OpenCL Framework.

### 3.3.8. Overview of Atomic and Fence Operations

OpenCL 2.x has a number of synchronization operations that are used to define memory order constraints in a program. They play a special role in controlling how memory operations in one unit of execution (such as work-items or, when using SVM a host thread) are made visible to another. There are two types of synchronization operations in OpenCL; atomic operations and fences.

Atomic operations are indivisible. They either occur completely or not at all. These operations are used to order memory operations between units of execution and hence they are parameterized with the memory_order and memory_scope parameters defined by the OpenCL memory consistency model. The atomic operations for OpenCL kernel languages are similar to the corresponding operations defined by the C11 standard.

The OpenCL 2.x atomic operations apply to variables of an atomic type (a subset of those in the C11 standard) including atomic versions of the int, uint, long, ulong, float, double, half, intptr_t, uintptr_t, size_t, and ptrdiff_t types. However, support for some of these atomic types depends on support for the corresponding regular types.

An atomic operation on one or more memory locations is either an acquire operation, a release operation, or both an acquire and release operation. An atomic operation without an associated memory location is a fence and can be either an acquire fence, a release fence, or both an acquire and release fence. In addition, there are relaxed atomic operations, which do not have synchronization properties, and atomic read-modify-write operations, which have special characteristics. [C11 standard, Section 5.1.2.4, paragraph 5, modified.]
The orders `memory_order_acquire` (used for reads), `memory_order_release` (used for writes), and `memory_order_acq_rel` (used for read-modify-write operations) are used for simple communication between units of execution using shared variables. Informally, executing a `memory_order_release` on an atomic object A makes all previous side effects visible to any unit of execution that later executes a `memory_order_acquire` on A. The orders `memory_order_acquire`, `memory_order_release`, and `memory_order_acq_rel` do not provide sequential consistency for race-free programs because they will not ensure that atomic stores followed by atomic loads become visible to other threads in that order.

The fence operation is `atomic_work_item_fence`, which includes a memory_order argument as well as the memory_scope and cl_mem_fence_flags arguments. Depending on the memory_order argument, this operation:

- has no effects, if `memory_order_relaxed`;
- is an acquire fence, if `memory_order_acquire`;
- is a release fence, if `memory_order_release`;
- is both an acquire fence and a release fence, if `memory_order_acq_rel`;
- is a sequentially-consistent fence with both acquire and release semantics, if `memory_order_seq_cst`.

If specified, the cl_mem_fence_flags argument must be `CLK_IMAGE_MEM_FENCE`, `CLK_GLOBAL_MEM_FENCE`, `CLK_LOCAL_MEM_FENCE`, or `CLK_GLOBAL_MEM_FENCE | CLK_LOCAL_MEM_FENCE`.

The `atomic_work_item_fence(CLK_IMAGE_MEM_FENCE, …)` built-in function must be used to make sure that sampler-less writes are visible to later reads by the same work-item. Without use of the `atomic_work_item_fence` function, write-read coherence on image objects is not guaranteed: if a work-item reads from an image to which it has previously written without an intervening `atomic_work_item_fence`, it is not guaranteed that those previous writes are visible to the work-item.

The synchronization operations in OpenCL 2.x can be parameterized by a memory_scope. Memory scopes control the extent that an atomic operation or fence is visible with respect to the memory model. These memory scopes may be used when performing atomic operations and fences on global memory and local memory. When used on global memory visibility is bounded by the capabilities of that memory. When used on a fine-grained non-atomic SVM buffer, a coarse-grained SVM buffer, or a non-SVM buffer, operations parameterized with `memory_scope_all_svm_devices` will behave as if they were parameterized with `memory_scope_device`. When used on local memory, visibility is bounded by the work-group and, as a result, memory_scope with wider visibility than `memory_scope_work_group` will be reduced to `memory_scope_work_group`.

Two actions A and B are defined to have an inclusive scope if they have the same scope P such that:

- P is `memory_scope_sub_group` and A and B are executed by work-items within the same sub-group.
- P is `memory_scope_work_group` and A and B are executed by work-items within the same work-group.
- P is `memory_scope_device` and A and B are executed by work-items on the same device when
A and B apply to an SVM allocation or A and B are executed by work-items in the same kernel or one of its children when A and B apply to a cl_mem buffer.

- P is memory_scope_all_svm_devices if A and B are executed by host threads or by work-items on one or more devices that can share SVM memory with each other and the host process.

### 3.3.9. Memory Ordering Rules

Fundamentally, the issue in a memory model is to understand the orderings in time of modifications to objects in memory. Modifying an object or calling a function that modifies an object are side effects, i.e. changes in the state of the execution environment. Evaluation of an expression in general includes both value computations and initiation of side effects. Value computation for an lvalue expression includes determining the identity of the designated object. [C11 standard, Section 5.1.2.3, paragraph 2, modified.]

We assume that the OpenCL kernel language and host programming languages have a sequenced-before relation between the evaluations executed by a single unit of execution. This sequenced-before relation is an asymmetric, transitive, pair-wise relation between those evaluations, which induces a partial order among them. Given any two evaluations A and B, if A is sequenced-before B, then the execution of A shall precede the execution of B. (Conversely, if A is sequenced-before B, then B is sequenced-after A.) If A is not sequenced-before or sequenced-after B, then A and B are unsequenced. Evaluations A and B are indeterminately sequenced when A is either sequenced-before or sequenced-after B, but it is unspecified which. [C11 standard, Section 5.1.2.3, paragraph 3, modified.]

Sequenced-before is a partial order of the operations executed by a single unit of execution (e.g. a host thread or work-item). It generally corresponds to the source program order of those operations, and is partial because of the undefined argument evaluation order of the OpenCL C kernel language.

In an OpenCL kernel language, the value of an object visible to a work-item W at a particular point is the initial value of the object, a value stored in the object by W, or a value stored in the object by another work-item or host thread, according to the rules below. Depending on details of the host programming language, the value of an object visible to a host thread may also be the value stored in that object by another work-item or host thread. [C11 standard, Section 5.1.2.4, paragraph 2, modified.]

Two expression evaluations conflict if one of them modifies a memory location and the other one reads or modifies the same memory location. [C11 standard, Section 5.1.2.4, paragraph 4.]

All modifications to a particular atomic object M occur in some particular total order, called the modification order of M. If A and B are modifications of an atomic object M, and A happens-before B, then A shall precede B in the modification order of M, which is defined below. Note that the modification order of an atomic object M is independent of whether M is in local or global memory. [C11 standard, Section 5.1.2.4, paragraph 7, modified.]

A release sequence begins with a release operation A on an atomic object M and is the maximal contiguous sub-sequence of side effects in the modification order of M, where the first operation is A and every subsequent operation either is performed by the same work-item or host thread that...
performed the release or is an atomic read-modify-write operation. [C11 standard, Section 5.1.2.4, paragraph 10, modified.]

OpenCL’s local and global memories are disjoint. Kernels may access both kinds of memory while host threads may only access global memory. Furthermore, the flags argument of OpenCL’s work_group_barrier function specifies which memory operations the function will make visible: these memory operations can be, for example, just the ones to local memory, or the ones to global memory, or both. Since the visibility of memory operations can be specified for local memory separately from global memory, we define two related but independent relations, global-synchronizes-with and local-synchronizes-with. Certain operations on global memory may global-synchronize-with other operations performed by another work-item or host thread. An example is a release atomic operation in one work-item that global-synchronizes-with an acquire atomic operation in a second work-item. Similarly, certain atomic operations on local objects in kernels can local-synchronize-with other atomic operations on those local objects. [C11 standard, Section 5.1.2.4, paragraph 11, modified.]

We define two separate happens-before relations: global-happens-before and local-happens-before.

A global memory action \( A \) global-happens-before a global memory action \( B \) if

- \( A \) is sequenced before \( B \), or
- \( A \) global-synchronizes-with \( B \), or
- For some global memory action \( C \), \( A \) global-happens-before \( C \) and \( C \) global-happens-before \( B \).

A local memory action \( A \) local-happens-before a local memory action \( B \) if

- \( A \) is sequenced before \( B \), or
- \( A \) local-synchronizes-with \( B \), or
- For some local memory action \( C \), \( A \) local-happens-before \( C \) and \( C \) local-happens-before \( B \).

An OpenCL 2.x implementation shall ensure that no program execution demonstrates a cycle in either the local-happens-before relation or the global-happens-before relation.

The global- and local-happens-before relations are critical to defining what values are read and when data races occur. The global-happens-before relation, for example, defines what global memory operations definitely happen before what other global memory operations. If an operation \( A \) global-happens-before operation \( B \) then \( A \) must occur before \( B \); in particular, any write done by \( A \) will be visible to \( B \). The local-happens-before relation has similar properties for local memory. Programmers can use the local- and global-happens-before relations to reason about the order of program actions.

A visible side effect \( A \) on a global object \( M \) with respect to a value computation \( B \) of \( M \) satisfies the conditions:

- \( A \) global-happens-before \( B \), and
- there is no other side effect \( X \) to \( M \) such that \( A \) global-happens-before \( X \) and \( X \) global-happens-before \( B \).
We define visible side effects for local objects $M$ similarly. The value of a non-atomic scalar object $M$, as determined by evaluation $B$, shall be the value stored by the visible side effect $A$. [C11 standard, Section 5.1.2.4, paragraph 19, modified.]

The execution of a program contains a data race if it contains two conflicting actions $A$ and $B$ in different units of execution, and

- (1) at least one of $A$ or $B$ is not atomic, or $A$ and $B$ do not have inclusive memory scope, and
- (2) the actions are global actions unordered by the global-happens-before relation or are local actions unordered by the local-happens-before relation.

Any such data race results in undefined behavior. [C11 standard, Section 5.1.2.4, paragraph 25, modified.]

We also define the visible sequence of side effects on local and global atomic objects. The remaining paragraphs of this subsection define this sequence for a global atomic object $M$; the visible sequence of side effects for a local atomic object is defined similarly by using the local-happens-before relation.

The visible sequence of side effects on a global atomic object $M$, with respect to a value computation $B$ of $M$, is a maximal contiguous sub-sequence of side effects in the modification order of $M$, where the first side effect is visible with respect to $B$, and for every side effect, it is not the case that $B$ global-happens-before it. The value of $M$, as determined by evaluation $B$, shall be the value stored by some operation in the visible sequence of $M$ with respect to $B$. [C11 standard, Section 5.1.2.4, paragraph 22, modified.]

If an operation $A$ that modifies an atomic object $M$ global-happens-before an operation $B$ that modifies $M$, then $A$ shall be earlier than $B$ in the modification order of $M$. This requirement is known as write-write coherence.

If a value computation $A$ of an atomic object $M$ global-happens-before a value computation $B$ of $M$, and $A$ takes its value from a side effect $X$ on $M$, then the value computed by $B$ shall either equal the value stored by $X$, or be the value stored by a side effect $Y$ on $M$, where $Y$ follows $X$ in the modification order of $M$. This requirement is known as read-read coherence. [C11 standard, Section 5.1.2.4, paragraph 22, modified.]

If a value computation $A$ of an atomic object $M$ global-happens-before an operation $B$ on $M$, then $A$ shall take its value from a side effect $X$ on $M$, where $X$ precedes $B$ in the modification order of $M$. This requirement is known as read-write coherence.

If a side effect $X$ on an atomic object $M$ global-happens-before a value computation $B$ of $M$, then the evaluation $B$ shall take its value from $X$ or from a side effect $Y$ that follows $X$ in the modification order of $M$. This requirement is known as write-read coherence.

### 3.3.9.1. Atomic Operations

This and following sections describe how different program actions in kernel C code and the host program contribute to the local- and global-happens-before relations. This section discusses ordering rules for OpenCL 2.x atomic operations.
Device-side enqueue defines the enumerated type memory_order.

- For memory_order_relaxed, no operation orders memory.
- For memory_order_release, memory_order_acq_rel, and memory_order_seq_cst, a store operation performs a release operation on the affected memory location.
- For memory_order_acquire, memory_order_acq_rel, and memory_order_seq_cst, a load operation performs an acquire operation on the affected memory location. [C11 standard, Section 7.17.3, paragraphs 2-4, modified.]

Certain built-in functions synchronize with other built-in functions performed by another unit of execution. This is true for pairs of release and acquire operations under specific circumstances. An atomic operation \( A \) that performs a release operation on a global object \( M \) global-synchronizes-with an atomic operation \( B \) that performs an acquire operation on \( M \) and reads a value written by any side effect in the release sequence headed by \( A \). A similar rule holds for atomic operations on objects in local memory: an atomic operation \( A \) that performs a release operation on a local object \( M \) local-synchronizes-with an atomic operation \( B \) that performs an acquire operation on \( M \) and reads a value written by any side effect in the release sequence headed by \( A \). [C11 standard, Section 5.1.2.4, paragraph 11, modified.]

- Atomic operations specifying memory_order_relaxed are relaxed only with respect to memory ordering. Implementations must still guarantee that any given atomic access to a particular atomic object be indivisible with respect to all other atomic accesses to that object.

There shall exist a single total order \( S \) for all memory_order_seq_cst operations that is consistent with the modification orders for all affected locations, as well as the appropriate global-happens-before and local-happens-before orders for those locations, such that each memory_order_seq_cst operation \( B \) that loads a value from an atomic object \( M \) in global or local memory observes one of the following values:

- the result of the last modification \( A \) of \( M \) that precedes \( B \) in \( S \), if it exists, or
- if \( A \) exists, the result of some modification of \( M \) in the visible sequence of side effects with respect to \( B \) that is not memory_order_seq_cst and that does not happen before \( A \), or
- if \( A \) does not exist, the result of some modification of \( M \) in the visible sequence of side effects with respect to \( B \) that is not memory_order_seq_cst. [C11 standard, Section 7.17.3, paragraph 6, modified.]

Let \( X \) and \( Y \) be two memory_order_seq_cst operations. If \( X \) local-synchronizes-with or global-synchronizes-with \( Y \) then \( X \) both local-synchronizes-with \( Y \) and global-synchronizes-with \( Y \).

If the total order \( S \) exists, the following rules hold:

- For an atomic operation \( B \) that reads the value of an atomic object \( M \), if there is a memory_order_seq_cst fence \( X \) sequenced-before \( B \), then \( B \) observes either the last memory_order_seq_cst modification of \( M \) preceding \( X \) in the total order \( S \) or a later modification of \( M \) in its modification order. [C11 standard, Section 7.17.3, paragraph 9.]
- For atomic operations \( A \) and \( B \) on an atomic object \( M \), where \( A \) modifies \( M \) and \( B \) takes its value,
if there is a `memory_order_seq_cst` fence X such that A is sequenced-before X and B follows X in S, then B observes either the effects of A or a later modification of M in its modification order. [C11 standard, Section 7.17.3, paragraph 10.]

- For atomic operations A and B on an atomic object M, where A modifies M and B takes its value, if there are `memory_order_seq_cst` fences X and Y such that A is sequenced-before X, Y is sequenced-before B, and X precedes Y in S, then B observes either the effects of A or a later modification of M in its modification order. [C11 standard, Section 7.17.3, paragraph 11.]

- For atomic operations A and B on an atomic object M, if there are `memory_order_seq_cst` fences X and Y such that A is sequenced-before X, Y is sequenced-before B, and X precedes Y in S, then B occurs later than A in the modification order of M.

`memory_order_seq_cst` ensures sequential consistency only for a program that is (1) free of data races, and (2) exclusively uses `memory_order_seq_cst` synchronization operations. Any use of weaker ordering will invalidate this guarantee unless extreme care is used. In particular, `memory_order_seq_cst` fences ensure a total order only for the fences themselves. Fences cannot, in general, be used to restore sequential consistency for atomic operations with weaker ordering specifications.

Atomic read-modify-write operations should always read the last value (in the modification order) stored before the write associated with the read-modify-write operation. [C11 standard, Section 7.17.3, paragraph 12.]

Implementations should ensure that no "out-of-thin-air" values are computed that circularly depend on their own computation.

Note: Under the rules described above, and independent to the previously footnoted C++ issue, it is known that `x == y == 42` is a valid final state in the following problematic example:

```c
global atomic_int x = ATOMIC_VAR_INIT(0);
local atomic_int y = ATOMIC_VAR_INIT(0);

unit_of_execution_1:
... [execution not reading or writing x or y, leading up to:]
int t = atomic_load_explicit(&y, memory_order_acquire);
atomic_store_explicit(&x, t, memory_order_release);

unit_of_execution_2:
... [execution not reading or writing x or y, leading up to:]
int t = atomic_load_explicit(&x, memory_order_acquire);
atomic_store_explicit(&y, t, memory_order_release);
```

This is not useful behavior and implementations should not exploit this phenomenon. It should be expected that in the future this may be disallowed by appropriate updates to the memory model description by the OpenCL committee.

Implementations should make atomic stores visible to atomic loads within a reasonable amount of
As long as the following conditions are met, a host program sharing SVM memory with a kernel executing on one or more OpenCL 2.x devices may use atomic and synchronization operations to ensure that its assignments, and those of the kernel, are visible to each other:

1. Either fine-grained buffer or fine-grained system SVM must be used to share memory. While coarse-grained buffer SVM allocations may support atomic operations, visibility on these allocations is not guaranteed except at map and unmap operations.

2. The optional OpenCL 2.x SVM atomic-controlled visibility specified by provision of the `CL_MEM_SVM_ATOMICS` flag must be supported by the device and the flag provided to the SVM buffer on allocation.

3. The host atomic and synchronization operations must be compatible with those of an OpenCL kernel language. This requires that the size and representation of the data types that the host atomic operations act on be consistent with the OpenCL kernel language atomic types.

If these conditions are met, the host operations will apply at all_svm_devices scope.

### 3.3.9.2. Fence Operations

This section describes how the OpenCL 2.x fence operations contribute to the local- and global-happens-before relations.

Earlier, we introduced synchronization primitives called fences. Fences can utilize the acquire memory Order, release memory Order, or both. A fence with acquire semantics is called an acquire fence; a fence with release semantics is called a release fence. The overview of atomic and fence operations section describes the memory orders that result in acquire and release fences.

A global release fence A global-synchronizes-with a global acquire fence B if there exist atomic operations X and Y, both operating on some global atomic object M, such that A is sequenced-before X, X modifies M, Y is sequenced-before B, Y reads the value written by X or a value written by any side effect in the hypothetical release sequence X would head if it were a release operation, and that the scopes of A, B are inclusive. [C11 standard, Section 7.17.4, paragraph 2, modified.]

A global release fence A global-synchronizes-with an atomic operation B that performs an acquire operation on a global atomic object M if there exists an atomic operation X such that A is sequenced-before X, X modifies M, B reads the value written by X or a value written by any side effect in the hypothetical release sequence X would head if it were a release operation, and the scopes of A and B are inclusive. [C11 standard, Section 7.17.4, paragraph 3, modified.]

An atomic operation A that is a release operation on a global atomic object M global-synchronizes-with a global acquire fence B if there exists some atomic operation X on M such that X is sequenced-before B and reads the value written by A or a value written by any side effect in the release sequence headed by A, and the scopes of A and B are inclusive. [C11 standard, Section 7.17.4, paragraph 4, modified.]

A local release fence A local-synchronizes-with a local acquire fence B if there exist atomic operations X and Y, both operating on some local atomic object M, such that A is sequenced-before X, X modifies M, Y is sequenced-before B, and Y reads the value written by X or a value written by
any side effect in the hypothetical release sequence $X$ would head if it were a release operation, and the scopes of $A$ and $B$ are inclusive. [C11 standard, Section 7.17.4, paragraph 2, modified.]

A local release fence $A$ local-synchronizes-with an atomic operation $B$ that performs an acquire operation on a local atomic object $M$ if there exists an atomic operation $X$ such that $A$ is sequenced-before $X$, $X$ modifies $M$, and $B$ reads the value written by $X$ or a value written by any side effect in the hypothetical release sequence $X$ would head if it were a release operation, and the scopes of $A$ and $B$ are inclusive. [C11 standard, Section 7.17.4, paragraph 3, modified.]

An atomic operation $A$ that is a release operation on a local atomic object $M$ local-synchronizes-with a local acquire fence $B$ if there exists some atomic operation $X$ on $M$ such that $X$ is sequenced-before $B$ and reads the value written by $A$ or a value written by any side effect in the release sequence headed by $A$, and the scopes of $A$ and $B$ are inclusive. [C11 standard, Section 7.17.4, paragraph 4, modified.]

Let $X$ and $Y$ be two work-item fences that each have both the $CLK\_GLOBAL\_MEM\_FENCE$ and $CLK\_LOCAL\_MEM\_FENCE$ flags set. $X$ global-synchronizes-with $Y$ and $X$ local synchronizes with $Y$ if the conditions required for $X$ to global-synchronize with $Y$ are met, the conditions required for $X$ to local-synchronize-with $Y$ are met, or both sets of conditions are met.

### 3.3.9.3. Work-Group Functions

The OpenCL kernel execution model includes collective operations across the work-items within a single work-group. These are called work-group functions, and include functions such as barriers, scans, reductions, and broadcasts. We will first discuss the work-group barrier function. Other work-group functions are discussed afterwards.

The barrier function provides a mechanism for a kernel to synchronize the work-items within a single work-group: informally, each work-item of the work-group must execute the barrier before any are allowed to proceed. It also orders memory operations to a specified combination of one or more address spaces such as local memory or global memory, in a similar manner to a fence.

To precisely specify the memory ordering semantics for barrier, we need to distinguish between a dynamic and a static instance of the call to a barrier. A call to a barrier can appear in a loop, for example, and each execution of the same static barrier call results in a new dynamic instance of the barrier that will independently synchronize a work-groups work-items.

A work-item executing a dynamic instance of a barrier results in two operations, both fences, that are called the entry and exit fences. These fences obey all the rules for fences specified elsewhere in this chapter as well as the following:

- The entry fence is a release fence with the same flags and scope as requested for the barrier.
- The exit fence is an acquire fence with the same flags and scope as requested for the barrier.
- For each work-item the entry fence is sequenced before the exit fence.
- If the flags have $CLK\_GLOBAL\_MEM\_FENCE$ set then for each work-item the entry fence global-synchronizes-with the exit fence of all other work-items in the same work-group.
- If the flags have $CLK\_LOCAL\_MEM\_FENCE$ set then for each work-item the entry fence local-synchronizes-with the exit fence of all other work-items in the same work-group.
Other work-group functions include such functions as scans, reductions, and broadcasts, and are described in the kernel language and IL specifications. The use of these work-group functions implies sequenced-before relationships between statements within the execution of a single work-item in order to satisfy data dependencies. For example, a work-item that provides a value to a work-group function must behave as if it generates that value before beginning execution of that work-group function. Furthermore, the programmer must ensure that all work-items in a work-group must execute the same work-group function call site, or dynamic work-group function instance.

### 3.3.9.4. Sub-Group Functions

Sub-group functions are missing before version 2.1. Also see cl_khr_subgroups.

The OpenCL kernel execution model includes collective operations across the work-items within a single sub-group. These are called sub-group functions. We will first discuss the sub-group barrier. Other sub-group functions are discussed afterwards.

The barrier function provides a mechanism for a kernel to synchronize the work-items within a single sub-group: informally, each work-item of the sub-group must execute the barrier before any are allowed to proceed. It also orders memory operations to a specified combination of one or more address spaces such as local memory or global memory, in a similar manner to a fence.

To precisely specify the memory ordering semantics for barrier, we need to distinguish between a dynamic and a static instance of the call to a barrier. A call to a barrier can appear in a loop, for example, and each execution of the same static barrier call results in a new dynamic instance of the barrier that will independently synchronize the work-items in a sub-group.

A work-item executing a dynamic instance of a barrier results in two operations, both fences, that are called the entry and exit fences. These fences obey all the rules for fences specified elsewhere in this chapter as well as the following:

- The entry fence is a release fence with the same flags and scope as requested for the barrier.
- The exit fence is an acquire fence with the same flags and scope as requested for the barrier.
- For each work-item the entry fence is sequenced before the exit fence.
- If the flags have `CLK_GLOBAL_MEM_FENCE` set then for each work-item the entry fence globally synchronizes with the exit fence of all other work-items in the same sub-group.
- If the flags have `CLK_LOCAL_MEM_FENCE` set then for each work-item the entry fence locally synchronizes with the exit fence of all other work-items in the same sub-group.

Other sub-group functions include such functions as scans, reductions, and broadcasts, and are described in the kernel languages and IL specifications. The use of these sub-group functions implies sequenced-before relationships between statements within the execution of a single work-item in order to satisfy data dependencies. For example, a work-item that provides a value to a sub-group function must behave as if it generates that value before beginning execution of that sub-group function. Furthermore, the programmer must ensure that all work-items in a sub-group must execute the same sub-group function call site, or dynamic sub-group function instance.
3.3.9.5. Host-Side and Device-Side Commands

This section describes how the OpenCL API functions associated with command-queues contribute to happens-before relations. There are two types of command-queues and associated API functions in OpenCL 2.x; *host command-queues* and *device command-queues*. The interaction of these command-queues with the memory model are for the most part equivalent. In a few cases, the rules only applies to the host command-queue. We will indicate these special cases by specifically denoting the host command-queue in the memory ordering rule. SVM memory consistency in such instances is implied only with respect to synchronizing host commands.

Memory ordering rules in this section apply to all memory objects (buffers, images and pipes) as well as to SVM allocations where no earlier, and more fine-grained, rules apply.

In the remainder of this section, we assume that each command \( C \) enqueued onto a command-queue has an associated event object \( E \) that signals its execution status, regardless of whether \( E \) was returned to the unit of execution that enqueued \( C \). We also distinguish between the API function call that enqueues a command \( C \) and creates an event \( E \), the execution of \( C \), and the completion of \( C \)(which marks the event \( E \) as complete).

The ordering and synchronization rules for API commands are defined as following:

1. If an API function call \( X \) enqueues a command \( C \), then \( X \) global-synchronizes-with \( C \). For example, a host API function to enqueue a kernel global-synchronizes-with the start of that kernel-instances execution, so that memory updates sequenced-before the enqueue kernel function call will global-happen-before any kernel reads or writes to those same memory locations. For a device-side enqueue, global memory updates sequenced before \( X \) happens-before \( C \) reads or writes to those memory locations only in the case of fine-grained SVM.

2. If \( E \) is an event upon which a command \( C \) waits, then \( E \) global-synchronizes-with \( C \). In particular, if \( C \) waits on an event \( E \) that is tracking the execution status of the command \( C_1 \), then memory operations done by \( C_1 \) will global-happen-before memory operations done by \( C \). As an example, assume we have an OpenCL program using coarse-grain SVM sharing that enqueues a kernel to a host command-queue to manipulate the contents of a region of a buffer that the host thread then accesses after the kernel completes. To do this, the host thread can call \texttt{clEnqueueMapBuffer} to enqueue a blocking-mode map command to map that buffer region, specifying that the map command must wait on an event signaling the kernels completion. When \texttt{clEnqueueMapBuffer} returns, any memory operations performed by the kernel to that buffer region will global-happen-before subsequent memory operations made by the host thread.

3. If a command \( C \) has an event \( E \) that signals its completion, then \( C \) global-synchronizes-with \( E \).

4. For a command \( C \) enqueued to a host-side command-queue, if \( C \) has an event \( E \) that signals its completion, then \( E \) global-synchronizes-with an API call \( X \) that waits on \( E \). For example, if a host thread or kernel-instance calls the wait-for-events function on \( E \) (e.g. the \texttt{clWaitForEvents} function called from a host thread), then \( E \) global-synchronizes-with that wait-for-events function call.

5. If commands \( C \) and \( C_1 \) are enqueued in that sequence onto an in-order command-queue, then the event (including the event implied between \( C \) and \( C_1 \) due to the in-order queue) signaling \( C \)'s completion global-synchronizes-with \( C_1 \). Note that in OpenCL 2.x, only a host command-
queue can be configured as an in-order queue.

6. If an API call enqueues a marker command $C$ with an empty list of events upon which $C$ should wait, then the events of all commands enqueued prior to $C$ in the command-queue global-synchronize-with $C$.

7. If a host API call enqueues a command-queue barrier command $C$ with an empty list of events on which $C$ should wait, then the events of all commands enqueued prior to $C$ in the command-queue global-synchronize-with $C$. In addition, the event signaling the completion of $C$ global-synchronizes-with all commands enqueued after $C$ in the command-queue.

8. If a host thread executes a `clFinish` call $X$, then the events of all commands enqueued prior to $X$ in the command-queue global-synchronize-with $X$.

9. The start of a kernel-instance $K$ global-synchronizes-with all operations in the work-items of $K$. Note that this includes the execution of any atomic operations by the work-items in a program using fine-grain SVM.

10. All operations of all work-items of a kernel-instance $K$ global-synchronizes-with the event signaling the completion of $K$. Note that this also includes the execution of any atomic operations by the work-items in a program using fine-grain SVM.

11. If a callback procedure $P$ is registered on an event $E$, then $E$ global-synchronizes-with all operations of $P$. Note that callback procedures are only defined for commands within host command-queues.

12. If $C$ is a command that waits for an event $E$'s completion, and API function call $X$ sets the status of a user event $E$'s status to `CL_COMPLETE` (for example, from a host thread using a `clSetUserEventStatus` function), then $X$ global-synchronizes-with $C$.

13. If a device enqueues a command $C$ with the `CLK_ENQUEUE_FLAGS_WAIT_KERNEL` flag, then the end state of the parent kernel instance global-synchronizes with $C$.

14. If a work-group enqueues a command $C$ with the `CLK_ENQUEUE_FLAGS_WAIT_WORK_GROUP` flag, then the end state of the work-group global-synchronizes with $C$.

When using an out-of-order command-queue, a wait on an event or a marker or command-queue barrier command can be used to ensure the correct ordering of dependent commands. In those cases, the wait for the event or the marker or barrier command will provide the necessary global-synchronizes-with relation.

In this situation:

- access to shared locations or disjoint locations in a single `cl_mem` object when using atomic operations from different kernel instances enqueued from the host such that one or more of the atomic operations is a write is implementation-defined and correct behavior is not guaranteed except at synchronization points.

- access to shared locations or disjoint locations in a single `cl_mem` object when using atomic operations from different kernel instances consisting of a parent kernel and any number of child kernels enqueued by that kernel is guaranteed under the memory ordering rules described earlier in this section.

- access to shared locations or disjoint locations in a single program scope global variable, coarse-grained SVM allocation or fine-grained SVM allocation when using atomic operations from
different kernel instances enqueued from the host to a single device is guaranteed under the memory ordering rules described earlier in this section.

If fine-grain SVM is used but without support for the OpenCL 2.x atomic operations, then the host and devices can concurrently read the same memory locations and can concurrently update non-overlapping memory regions, but attempts to update the same memory locations are undefined. Memory consistency is guaranteed at the OpenCL synchronization points without the need for calls to `clEnqueueMapBuffer` and `clEnqueueUnmapMemObject`. For fine-grained SVM buffers it is guaranteed that at synchronization points only values written by the kernel will be updated. No writes to fine-grained SVM buffers can be introduced that were not in the original program.

In the remainder of this section, we discuss a few points regarding the ordering rules for commands with a host command-queue.

---

In an OpenCL 1.x implementation a synchronization point is a kernel-instance or host program location where the contents of memory visible to different work-items or command-queue commands are the same. It also says that waiting on an event and a command-queue barrier are synchronization points between commands in command-queues. Four of the rules listed above (2, 4, 7, and 8) cover these OpenCL synchronization points.

A map operation (`clEnqueueMapBuffer` or `clEnqueueMapImage`) performed on a non-SVM buffer or a coarse-grained SVM buffer is allowed to overwrite the entire target region with the latest runtime view of the data as seen by the command with which the map operation synchronizes, whether the values were written by the executing kernels or not. Any values that were changed within this region by another kernel or host thread while the kernel synchronizing with the map operation was executing may be overwritten by the map operation.

Access to non-SVM `cl_mem` buffers and coarse-grained SVM allocations is ordered at synchronization points between host commands. In the presence of an out-of-order command-queue or a set of command-queues mapped to the same device, multiple kernel instances may execute concurrently on the same device.

### 3.4. The OpenCL Framework

The OpenCL framework allows applications to use a host and one or more OpenCL devices as a single heterogeneous parallel computer system. The framework contains the following components:

- **OpenCL Platform layer**: The platform layer allows the host program to discover OpenCL devices and their capabilities and to create contexts.

- **OpenCL Runtime**: The runtime allows the host program to manipulate contexts once they have been created.

- **OpenCL Compiler**: The OpenCL compiler creates program executables that contain OpenCL kernels. The OpenCL compiler may build program executables from OpenCL C source strings, the SPIR-V intermediate language, or device-specific program binary objects, depending on the capabilities of a device. Other kernel languages or intermediate languages may be supported by
3.4.1. Mixed Version Support

Mixed version support **missing before** version 1.1.

OpenCL supports devices with different capabilities under a single platform. This includes devices which conform to different versions of the OpenCL specification. There are three version identifiers to consider for an OpenCL system: the platform version, the version of a device, and the version(s) of the kernel language or IL supported on a device.

The platform version indicates the version of the OpenCL runtime that is supported. This includes all of the APIs that the host can use to interact with resources exposed by the OpenCL runtime; including contexts, memory objects, devices, and command-queues.

The device version is an indication of the device’s capabilities separate from the runtime and compiler as represented by the device info returned by `clGetDeviceInfo`. Examples of attributes associated with the device version are resource limits (e.g., minimum size of local memory per compute unit) and extended functionality (e.g., list of supported KHR extensions). The version returned corresponds to the highest version of the OpenCL specification for which the device is conformant, but is not higher than the platform version.

The language version for a device represents the OpenCL programming language features a developer can assume are supported on a given device. The version reported is the highest version of the language supported.

3.4.2. Backwards Compatibility

Backwards compatibility is an important goal for the OpenCL standard. Backwards compatibility is expected such that a device will consume earlier versions of the OpenCL C programming languages and the SPIR-V intermediate language with the following minimum requirements:

- An OpenCL 1.x device must support at least one 1.x version of the OpenCL C programming language.
- An OpenCL 2.0 device must support all the requirements of an OpenCL 1.2 device in addition to the OpenCL C 2.0 programming language. If multiple language versions are supported, the compiler defaults to using the OpenCL C 1.2 language version. To utilize the OpenCL 2.0 Kernel programming language, a programmer must specifically pass the appropriate compiler build option (`-cl-std=CL2.0`). The language version must not be higher than the platform version, but may exceed the device version.
- An OpenCL 2.1 device must support all the requirements of an OpenCL 2.0 device in addition to the SPIR-V intermediate language at version 1.0 or above. Intermediate language versioning is encoded as part of the binary object and no flags are required to be passed to the compiler.
- An OpenCL 2.2 device must support all the requirements of an OpenCL 2.0 device in addition to the SPIR-V intermediate language at version 1.2 or above. Intermediate language versioning is encoded as a part of the binary object and no flags are required to be passed to the compiler.
- OpenCL 3.0 is designed to enable any OpenCL implementation supporting OpenCL 1.2 or newer.
to easily support and transition to OpenCL 3.0, by making many features in OpenCL 2.0, 2.1, or 2.2 optional. This means that OpenCL 3.0 is backwards compatible with OpenCL 1.2, but is not necessarily backwards compatible with OpenCL 2.0, 2.1, or 2.2.

An OpenCL 3.0 platform must implement all OpenCL 3.0 APIs, but some APIs may return an error code unconditionally when a feature is not supported by any devices in the platform. Whenever a feature is optional, it will be paired with a query to determine whether the feature is supported. The queries will enable correctly written applications to selectively use all optional features without generating any OpenCL errors, if desired.

OpenCL 3.0 also adds a new version of the OpenCL C programming language, which makes many features in OpenCL C 2.0 optional. The new version of OpenCL C is backwards compatible with OpenCL C 1.2, but is not backwards compatible with OpenCL C 2.0. The new version of OpenCL C must be explicitly requested via the `-cl-std=` build option, otherwise a program will continue to be compiled using the highest OpenCL C 1.x language version supported for the device.

Whenever an OpenCL C feature is optional in the new version of the OpenCL C programming language, it will be paired with a feature macro, such as `__opencl_c_<feature_name>`, and a corresponding API query. If a feature macro is defined then the feature is supported by the OpenCL C compiler, otherwise the optional feature is not supported.

In order to allow future versions of OpenCL to support new types of devices, minor releases of OpenCL may add new profiles where some features that are currently required for all OpenCL devices become optional. All features that are required for an OpenCL profile will also be required for that profile in subsequent minor releases of OpenCL, thereby guaranteeing backwards compatibility for applications targeting specific profiles. It is therefore strongly recommended that applications query the profile supported by the OpenCL device they are running on in order to remain robust to future changes.

### 3.4.3. Versioning

The OpenCL specification is regularly updated with bug fixes and clarifications. Occasionally new functionality is added to the core and extensions. In order to indicate to developers how and when these changes are made to the specification, and to provide a way to identify each set of changes, the OpenCL API, C language, intermediate languages and extensions maintain a version number. Built-in kernels are also versioned.

#### 3.4.3.1. Version Numbers

A version number comprises three logical fields:

- The **major** version indicates a significant change. Backwards compatibility may break across major versions.
- The **minor** version indicates the addition of new functionality with backwards compatibility for any existing profiles.
- The **patch** version indicates bug fixes, clarifications and general improvements.

Version numbers are represented using the `cl_version` type that is an alias for a 32-bit integer. The
fields are packed as follows:

- The major version is a 10-bit integer packed into bits 31-22.
- The minor version is a 10-bit integer packed into bits 21-12.
- The patch version is a 12-bit integer packed into bits 11-0.

This enables versions to be ordered using standard C/C++ operators.

A number of convenience macros are provided by the OpenCL Headers to make working with version numbers easier.

- CL_VERSION_MAJOR extracts the major version from a packed cl_version.
- CL_VERSION_MINOR extracts the minor version from a packed cl_version.
- CL_VERSION_PATCH extracts the patch version from a packed cl_version.
- CL_MAKE_VERSION returns a packed cl_version from a major, minor and patch version.
- CL_VERSION_MAJOR_BITS, CL_VERSION_MINOR_BITS, and CL_VERSION_PATCH_BITS are the number of bits in the corresponding field.
- CL_VERSION_MAJOR_MASK, CL_VERSION_MINOR_MASK, and CL_VERSION_PATCH_MASK are bitmasks used to extract the corresponding packed fields from the version number.

```c
typedef cl_uint cl_version;

#define CL_VERSION_MAJOR_BITS (10)
#define CL_VERSION_MINOR_BITS (10)
#define CL_VERSION_PATCH_BITS (12)

#define CL_VERSION_MAJOR(version) \
    ((version) >> (CL_VERSION_MINOR_BITS + CL_VERSION_PATCH_BITS))

#define CL_VERSION_MINOR(version) \
    (((version) >> CL_VERSION_PATCH_BITS) & CL_VERSION_MINOR_MASK)

#define CL_VERSION_PATCH(version) ((version) & CL_VERSION_PATCH_MASK)

#define CL_MAKE_VERSION(major, minor, patch) \
    (((major) & CL_VERSION_MAJOR_MASK) << \
        (CL_VERSION_MINOR_BITS + CL_VERSION_PATCH_BITS)) | \
    (((minor) & CL_VERSION_MINOR_MASK) << \
        CL_VERSION_PATCH_BITS) | \
    ((patch) & CL_VERSION_PATCH_MASK)
```
3.4.3.2. Version-Name Pairing

The `cl_name_version` structure describes a version number and a corresponding entity (e.g. extension or built-in kernel) name:

```c
// Provided by CL_VERSION_3_0
typedef struct cl_name_version {
    cl_version version;
    char name[CL_NAME_VERSION_MAX_NAME_SIZE];
} cl_name_version;
```

- `version` is a Version Number.
- `name` is an array of `CL_NAME_VERSION_MAX_NAME_SIZE` characters containing a null-terminated string, whose maximum length is therefore `CL_NAME_VERSION_MAX_NAME_SIZE` minus one.

3.4.4. Valid Usage and Undefined Behavior

The OpenCL specification describes valid usage and how to use the API correctly. For some conditions where an API is used incorrectly, behavior is well-defined, such as returning an error code. For other conditions, behavior is undefined, and may include program termination. However, OpenCL implementations must always ensure that incorrect usage by an application does not affect the integrity of the operating system, the OpenCL implementation, or other OpenCL client applications in the system. In particular, any guarantees made by an operating system about whether memory from one process can be visible to another process or not must not be violated by an OpenCL implementation for any memory allocation. OpenCL implementations are not required to make additional security or integrity guarantees beyond those provided by the operating system unless explicitly directed by the application’s use of a particular feature or extension.

For instance, if an operating system guarantees that data in all its memory allocations are set to zero when newly allocated, the OpenCL implementation must make the same guarantees for any allocations it controls.

Similarly, if an operating system guarantees that use-after-free of host allocations will not result in values written by another process becoming visible, the same guarantees must be made by the OpenCL implementation for memory accessible to an OpenCL device.

[1] This value for memory_scope can only be used with atomic_work_item_fence with flags set to `CLK_IMAGE_MEM_FENCE`. 
Chapter 4. The OpenCL Platform Layer

This section describes the OpenCL platform layer which implements platform-specific features that allow applications to query OpenCL devices, device configuration information, and to create OpenCL contexts using one or more devices.

4.1. Querying Platform Info

The list of platforms available can be obtained with the function:

```
// Provided by CL_VERSION_1_0
cl_int clGetPlatformIDs(
    cl_uint num_entries,
    cl_platform_id* platforms,
    cl_uint* num_platforms);
```

- `num_entries` is the number of `cl_platform_id` entries that can be added to `platforms`. If `platforms` is not `NULL`, `num_entries` must be greater than zero.

- `platforms` returns a list of OpenCL platforms found. The `cl_platform_id` values returned in `platforms` can be used to identify a specific OpenCL platform. If `platforms` is `NULL`, this argument is ignored. The number of OpenCL platforms returned is the minimum of the value specified by `num_entries` or the number of OpenCL platforms available.

- `num_platforms` returns the number of OpenCL platforms available. If `num_platforms` is `NULL`, this argument is ignored.

`clGetPlatformIDs` returns `CL_SUCCESS` if the function is executed and, if the `cl_khr_icd` extension is supported, there are a non-zero number of platforms available. Otherwise, it returns one of the following errors:

- `CL_PLATFORM_NOT_FOUND_KHR` if the `cl_khr_icd` extension is supported and zero platforms are available.

- `CL_INVALID_VALUE` if `num_entries` is equal to zero and `platforms` is not `NULL` or if both `num_platforms` and `platforms` are `NULL`.

- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

To obtain the list of platforms accessible through the Khronos ICD Loader, call the function:

```
// Provided by cl_khr_icd
cl_int clIcdGetPlatformIDsKHR(
    cl_uint num_entries,
    cl_platform_id* platforms,
    cl_uint* num_platforms);
```
clIcdGetPlatformIDsKHR is provided by the cl_khr_icd extension.

- `num_entries` is the number of `cl_platform_id` entries that can be added to `platforms`. If `platforms` is not `NULL`, then `num_entries` must be greater than zero.

- `platforms` returns a list of OpenCL platforms available for access through the Khronos ICD Loader. The `cl_platform_id` values returned in `platforms` are ICD compatible and can be used to identify a specific OpenCL platform. If the `platforms` argument is `NULL`, then this argument is ignored. The number of OpenCL platforms returned is the minimum of the value specified by `num_entries` or the number of OpenCL platforms available.

- `num_platforms` returns the number of OpenCL platforms available. If `num_platforms` is `NULL`, then this argument is ignored.

cIcdGetPlatformIDsKHR returns `CL_SUCCESS` if the function is executed successfully and there are a non zero number of platforms available. Otherwise, it returns one of the following errors:

- `CL_PLATFORM_NOT_FOUND_KHR` if zero platforms are available.
- `CL_INVALID_VALUE` if `num_entries` is equal to zero and `platforms` is not `NULL` or if both `num_platforms` and `platforms` are `NULL`.

Specific information about an OpenCL platform can be obtained with the function:

```c
// Provided by CL_VERSION_1_0
cl_int clGetPlatformInfo(  
    cl_platform_id platform,  
    cl_platform_info param_name,  
    size_t param_value_size,  
    void* param_value,  
    size_t* param_value_size_ret);
```

- `platform` refers to the platform ID returned by `clGetPlatformIDs` or can be `NULL`. If `platform` is `NULL`, the behavior is implementation-defined.

- `param_name` is an enumeration constant that identifies the platform information being queried. It can be one of the following values as specified in the Platform Queries table.

- `param_value` is a pointer to memory location where appropriate values for a given `param_name`, as specified in the Platform Queries table, will be returned. If `param_value` is `NULL`, it is ignored.

- `param_value_size` specifies the size in bytes of memory pointed to by `param_value`. This size in bytes must be ≥ size of return type specified in the Platform Queries table.

- `param_value_size_ret` returns the actual size in bytes of data being queried by `param_name`. If `param_value_size_ret` is `NULL`, it is ignored.

The information that can be queried using `clGetPlatformInfo` is specified in the Platform Queries table.

**Table 3. List of supported param_names by clGetPlatformInfo**

<table>
<thead>
<tr>
<th>Platform Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_PLATFORM_PROFILE [1]</td>
<td>char[] [2]</td>
<td>OpenCL profile string. Returns the profile name supported by the implementation. The profile name returned can be one of the following strings:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>FULL_PROFILE - if the implementation supports the OpenCL specification (functionality defined as part of the core specification and does not require any extensions to be supported).</td>
</tr>
<tr>
<td></td>
<td></td>
<td>EMBEDDED_PROFILE - if the implementation supports the OpenCL embedded profile. The embedded profile is defined to be a subset for each version of OpenCL. The embedded profile for OpenCL is described in <a href="https://www.khronos.org_OpenCL_Files/Specs/OpenCL_EmbProfile.pdf">OpenCL Embedded Profile</a>.</td>
</tr>
<tr>
<td>CL_PLATFORM_VERSION</td>
<td>char[]</td>
<td>OpenCL version string. Returns the OpenCL version supported by the implementation. This version string has the following format:</td>
</tr>
<tr>
<td></td>
<td></td>
<td><code>OpenCL &lt;space&gt; &lt;major_version.minor_version&gt; &lt;space&gt; &lt;platform-specific information&gt;</code></td>
</tr>
<tr>
<td></td>
<td></td>
<td>The <code>major_version.minor_version</code> value returned will be one of 1.0, 1.1, 1.2, 2.0, 2.1, 2.2 or 3.0.</td>
</tr>
<tr>
<td>CL_PLATFORM_NUMERIC_VERSION</td>
<td>cl_version</td>
<td>Returns the detailed (major, minor, patch) version supported by the platform. The major and minor version numbers returned must match those returned via <code>CL_PLATFORM_VERSION</code>.</td>
</tr>
<tr>
<td>missing before version 3.0</td>
<td>cl_version_khr</td>
<td></td>
</tr>
<tr>
<td>or</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_PLATFORM_NUMERIC_VERSION_</td>
<td></td>
<td></td>
</tr>
<tr>
<td>KHR</td>
<td></td>
<td></td>
</tr>
<tr>
<td>provided by the</td>
<td></td>
<td></td>
</tr>
<tr>
<td>cl_khr_extended_versioning</td>
<td></td>
<td></td>
</tr>
<tr>
<td>extension.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_PLATFORM_NAME</td>
<td>char[]</td>
<td>Platform name string.</td>
</tr>
<tr>
<td>CL_PLATFORM_VENDOR</td>
<td>char[]</td>
<td>Platform vendor string.</td>
</tr>
<tr>
<td>Platform Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>---------------------------------------------------</td>
<td>----------------</td>
<td>---------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td><strong>CL_PLATFORM_EXTENSIONS</strong></td>
<td>char[]</td>
<td>Returns a space separated list of extension names (the extension names themselves do not contain any spaces) supported by the platform. Each extension that is supported by all devices associated with this platform must be reported here.</td>
</tr>
<tr>
<td><strong>CL_PLATFORM_EXTENSIONS_WITH_VERSION</strong></td>
<td>cl_name_version[] or cl_name_version_khr[]</td>
<td>Returns an array of description (name and version) structures that lists all the extensions supported by the platform. The same extension name must not be reported more than once. The list of extensions reported must match the list reported via <strong>CL_PLATFORM_EXTENSIONS</strong>.</td>
</tr>
<tr>
<td><strong>CL_PLATFORM_HOST_TIMER_RESOLUTION</strong></td>
<td>cl_ulong</td>
<td>Returns the resolution of the host timer in nanoseconds as used by <strong>clGetDeviceAndHostTimer</strong>. Support for device and host timer synchronization is required for platforms supporting OpenCL 2.1 or 2.2. This value must be 0 for devices that do not support device and host timer synchronization.</td>
</tr>
<tr>
<td>Platform Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>------------------------------------------------------------</td>
<td>-------------------------------------------------</td>
<td>-----------------------------------------------------------------------------</td>
</tr>
<tr>
<td><strong>CL_PLATFORM_COMMAND_BUFFER_CAPABILITIES_KHR</strong></td>
<td><code>cl_platform_command_buffer_capabilities_khr</code></td>
<td>Describes platform command-buffer capabilities, encoded as bits in a bitfield. Supported capabilities are:</td>
</tr>
<tr>
<td>provided by the <code>cl_khr_command_buffer_multi_device</code> extension.</td>
<td></td>
<td><strong>CL_COMMAND_BUFFER_PLATFORM_UNIVERSAL_SYNC_KHR</strong> - Platform supports the ability to synchronize all commands in a command-buffer using sync-points, irrespective of the queue the individual commands are recorded to.</td>
</tr>
<tr>
<td><strong>CL_COMMAND_BUFFER_PLATFORM_UNIVERSAL_SYNC_KHR</strong></td>
<td></td>
<td>provided by the <code>cl_khr_command_buffer_multi_device</code> extension.</td>
</tr>
<tr>
<td><strong>CL_COMMAND_BUFFER_PLATFORM_REMAP_QUEUES_KHR</strong></td>
<td></td>
<td><strong>CL_COMMAND_BUFFER_PLATFORM_REMAP_QUEUES_KHR</strong> - Platform supports the ability to create a deep copy of an existing command-buffer with the commands explicitly remapped to different, potentially incompatible, queues.</td>
</tr>
<tr>
<td>provided by the <code>cl_khr_command_buffer_multi_device</code> extension.</td>
<td></td>
<td>provided by the <code>cl_khr_command_buffer_multi_device</code> extension.</td>
</tr>
<tr>
<td><strong>CL_COMMAND_BUFFER_PLATFORM_AUTOMATIC_REMAP_KHR</strong></td>
<td></td>
<td><strong>CL_COMMAND_BUFFER_PLATFORM_AUTOMATIC_REMAP_KHR</strong> - Platform supports the ability to create a remapped command-buffer where the mapping of commands to queues is done by the OpenCL runtime in a way it determines as optimal. If <code>CL_COMMAND_BUFFER_PLATFORM_AUTOMATIC_REMAP_KHR</code> is reported, <code>CL_COMMAND_BUFFER_PLATFORM_REMAP_QUEUES_KHR</code> must also be reported.</td>
</tr>
<tr>
<td>provided by the <code>cl_khr_command_buffer_multi_device</code> extension.</td>
<td></td>
<td>provided by the <code>cl_khr_command_buffer_multi_device</code> extension.</td>
</tr>
<tr>
<td><strong>CL_PLATFORM_EXTERNAL_MEMORY_IMPORT_HANDLE_TYPES_KHR</strong></td>
<td><code>cl_external_memory_handle_type_khr[]</code></td>
<td>Returns the list of importable external memory handle types supported by all devices in <code>platform</code>.</td>
</tr>
<tr>
<td>provided by the <code>cl_khr_external_memory</code> extension.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>CL_PLATFORM_SEMAPHORE_TYPES_KHR</strong></td>
<td><code>cl_semaphore_type_khr[]</code></td>
<td>Returns the list of the semaphore types supported all devices in <code>platform</code>.</td>
</tr>
<tr>
<td>provided by the <code>cl_khr_semaphore</code> extension.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Platform Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>---------------</td>
<td>-------------</td>
<td>-------------</td>
</tr>
<tr>
<td>CL_PLATFORM_SEMAPHORE_IMPORT_HANDLE_TYPES_KHR</td>
<td>cl_external_semaphore_handle_type_khr[]</td>
<td>Returns the list of importable external semaphore handle types supported by all devices in platform.</td>
</tr>
<tr>
<td>provided by the cl_khr_external_semaphore extension.</td>
<td></td>
<td>The size of this query may be 0 if no importable external semaphore handle types are supported by all devices in platform.</td>
</tr>
<tr>
<td>CL_PLATFORM_SEMAPHORE_EXPORT_HANDLE_TYPES_KHR</td>
<td>cl_external_semaphore_handle_type_khr[]</td>
<td>Returns the list of exportable external semaphore handle types supported by all devices in the platform.</td>
</tr>
<tr>
<td>provided by the cl_khr_external_semaphore extension.</td>
<td></td>
<td>This size of this query may be 0 if no exportable external semaphore handle types are supported by all devices in platform.</td>
</tr>
<tr>
<td>CL_PLATFORM_ICD_SUFFIX_KHR</td>
<td>char[]</td>
<td>The function name suffix used to identify extension functions to be directed to this platform by the ICD Loader.</td>
</tr>
<tr>
<td>provided by the cl_khr_icd extension.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

clGetPlatformInfo returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors [3]:

- CL_INVALID_PLATFORM if platform is not a valid platform.
- CL_INVALID_VALUE if param_name is not one of the supported values or if size in bytes specified by param_value_size is < size of return type as specified in the OpenCL Platform Queries table, and param_value is not a NULL value.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 4.2. Querying Devices

The list of devices available on a platform can be obtained using the function [4]:

```c
// Provided by CL_VERSION_1_0
cl_int clGetDeviceIDs(
    cl_platform_id platform,
    cl_device_type device_type,
    cl_uint num_entries,
    cl_device_id* devices,
    cl_uint* num_devices);
```

- platform refers to the platform ID returned by clGetPlatformIDs or can be NULL. If platform is NULL, the behavior is implementation-defined.
- device_type is a bitfield that identifies the type of OpenCL device. The device_type can be used to
query specific OpenCL devices or all OpenCL devices available. The valid values for `device_type` are specified in the Device Types table.

- `num_entries` is the number of `cl_device_id` entries that can be added to `devices`. If `devices` is not `NULL`, the `num_entries` must be greater than zero.

- `devices` returns a list of OpenCL devices found. The `cl_device_id` values returned in `devices` can be used to identify a specific OpenCL device. If `devices` is `NULL`, this argument is ignored. The number of OpenCL devices returned is the minimum of the value specified by `num_entries` or the number of OpenCL devices whose type matches `device_type`.

- `num_devices` returns the number of OpenCL devices available that match `device_type`. If `num_devices` is `NULL`, this argument is ignored.

<table>
<thead>
<tr>
<th>Device Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_DEVICE_TYPE_CPU</td>
<td>An OpenCL device similar to a traditional CPU (Central Processing Unit). The host processor that executes OpenCL host code may also be considered a CPU OpenCL device.</td>
</tr>
<tr>
<td>CL_DEVICE_TYPE_GPU</td>
<td>An OpenCL device similar to a GPU (Graphics Processing Unit). Many systems include a dedicated processor for graphics or rendering that may be considered a GPU OpenCL device.</td>
</tr>
<tr>
<td>CL_DEVICE_TYPE_ACCELERATOR</td>
<td>Dedicated devices that may accelerate OpenCL programs, such as FPGAs (Field Programmable Gate Arrays), DSPs (Digital Signal Processors), or AI (Artificial Intelligence) processors.</td>
</tr>
<tr>
<td>CL_DEVICE_TYPE_CUSTOM</td>
<td>Specialized devices that implement some of the OpenCL runtime APIs but do not support all of the required OpenCL functionality.</td>
</tr>
<tr>
<td>CL_DEVICE_TYPE_DEFAULT</td>
<td>The default OpenCL device in the platform. One device in the platform must be returned as the CL_DEVICE_TYPE_DEFAULT device when passed as the device_type to clGetDeviceIDs. CL_DEVICE_TYPE_DEFAULT is only used to query OpenCL devices using clGetDeviceIDs or to create OpenCL contexts using clCreateContextFromType, and will never be returned in CL_DEVICE_TYPE for any OpenCL device. The default OpenCL device must not be a CL_DEVICE_TYPE_CUSTOM device.</td>
</tr>
</tbody>
</table>
## Device Type

<table>
<thead>
<tr>
<th>Device Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_DEVICE_TYPE_ALL</td>
<td>All OpenCL devices available in the platform, except for CL_DEVICE_TYPE_CUSTOM devices. CL_DEVICE_TYPE_ALL is only used to query OpenCL devices using <code>clGetDeviceIDs</code> or to create OpenCL contexts using <code>clCreateContextFromType</code>, and will never be returned in CL_DEVICE_TYPE for any OpenCL device.</td>
</tr>
</tbody>
</table>

### `clGetDeviceIDs` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_PLATFORM** if `platform` is not a valid platform.
- **CL_INVALID_DEVICE_TYPE** if `device_type` is not a valid value.
- **CL_INVALID_VALUE** if `num_entries` is equal to zero and `devices` is not `NULL` or if both `num_devices` and `devices` are `NULL`.
- **CL_DEVICE_NOT_FOUND** if no OpenCL devices that matched `device_type` were found.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

The application can query specific capabilities of the OpenCL device(s) returned by `clGetDeviceIDs`. This can be used by the application to determine which device(s) to use.

To get specific information about an OpenCL device, call the function:

```c
// Provided by CL_VERSION_1_0
cl_int clGetDeviceInfo(
    cl_device_id device,
    cl_device_info param_name,
    size_t param_value_size,
    void* param_value,
    size_t* param_value_size_ret);
```

- **device** may be a device returned by `clGetDeviceIDs` or a sub-device created by `clCreateSubDevices`. If `device` is a sub-device, the specific information for the sub-device will be returned. The information that can be queried using `clGetDeviceInfo` is specified in the Device Queries table.

- **param_name** is an enumeration constant that identifies the device information being queried. It can be one of the following values as specified in the Device Queries table.

- **param_value** is a pointer to memory location where appropriate values for a given `param_name`, as specified in the Device Queries table, will be returned. If `param_value` is `NULL`, it is ignored.
• `param_value_size` specifies the size in bytes of memory pointed to by `param_value`. This size in bytes must be ≥ size of return type specified in the Device Queries table.

• `param_value_size_ret` returns the actual size in bytes of data being queried by `param_name`. If `param_value_size_ret` is NULL, it is ignored.

The device queries described in the Device Queries table should return the same information for a root-level device i.e. a device returned by clGetDeviceIDs and any sub-devices created from this device except for the following queries:

- `CL_DEVICE_GLOBAL_MEM_CACHE_SIZE`
- `CL_DEVICE_BUILT_IN_KERNELS`
- `CL_DEVICE_PARENT_DEVICE`
- `CL_DEVICE_PARTITION_TYPE`
- `CL_DEVICE_REFERENCE_COUNT`

Table 5. List of supported `param_names` by `clGetDeviceInfo`

<table>
<thead>
<tr>
<th>Device Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>CL_DEVICE_TYPE</code></td>
<td><code>cl_device_type</code></td>
<td>The type of the OpenCL device. The device type is purely informational and has no semantic meaning. The device must report a single device type, which must not be <code>CL_DEVICE_TYPE_DEFAULT</code> or <code>CL_DEVICE_TYPE_ALL</code>. Please see the Device Types table for supported device types and device type descriptions.</td>
</tr>
<tr>
<td><code>CL_DEVICE_VENDOR_ID</code>[^5]</td>
<td><code>cl_uint</code></td>
<td>A unique device vendor identifier. If the vendor has a PCI vendor ID, the low 16 bits must contain that PCI vendor ID, and the remaining bits must be set to zero. Otherwise, the value returned must be a valid Khronos vendor ID represented by type <code>cl_khronos_vendor_id</code>. Khronos vendor IDs are allocated starting at 0x10000, to distinguish them from the PCI vendor ID namespace.</td>
</tr>
<tr>
<td><code>CL_DEVICE_MAX_COMPUTE_UNITS</code></td>
<td><code>cl_uint</code></td>
<td>The number of parallel compute units on the OpenCL device. A work-group executes on a single compute unit. The minimum value is 1.</td>
</tr>
<tr>
<td><code>CL_DEVICE_MAX_WORK_ITEM_DIMENSIONS</code></td>
<td><code>cl_uint</code></td>
<td>Maximum dimensions that specify the global and local work-item IDs used by the data parallel execution model. (Refer to clEnqueueNDRangeKernel). The minimum value is 3 for devices that are not of type <code>CL DEVICE_TYPE CUSTOM</code>.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>--------------------------------------------------------</td>
<td>-------------</td>
<td>------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_DEVICE_MAX_WORK_ITEM_SIZES</td>
<td>size_t[]</td>
<td>Maximum number of work-items that can be specified in each dimension of the work-group to clEnqueueNDRangeKernel. Returns ( n ) size_t entries, where ( n ) is the value returned by the query for CL_DEVICE_MAX_WORK_ITEM_DIMENSIONS. The minimum value is (1, 1, 1) for devices that are not of type CL_DEVICE_TYPE_CUSTOM.</td>
</tr>
<tr>
<td>CL_DEVICE_MAX_WORK_GROUP_SIZE</td>
<td>size_t</td>
<td>Maximum number of work-items in a work-group that a device is capable of executing on a single compute unit, for any given kernel-instance running on the device. (Refer also to clEnqueueNDRangeKernel and CL_KERNEL_WORK_GROUP_SIZE). The minimum value is 1. The returned value is an upper limit and will not necessarily maximize performance. This maximum may be larger than supported by a specific kernel (refer to the CL_KERNEL_WORK_GROUP_SIZE query of clGetKernelWorkGroupInfo).</td>
</tr>
<tr>
<td>CL_DEVICE_PREFERRED_VECTOR_WIDTH_CHAR</td>
<td>cl_uint</td>
<td>Preferred native vector width size for built-in scalar types that can be put into vectors. The vector width is defined as the number of scalar elements that can be stored in the vector. If double precision is not supported, CL_DEVICE_PREFERRED_VECTOR_WIDTH_DOUBLE must return 0.</td>
</tr>
<tr>
<td>CL_DEVICE_PREFERRED_VECTOR_WIDTH_SHORT</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_PREFERRED_VECTOR_WIDTH_INT</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_PREFERRED_VECTOR_WIDTH_LONG</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_PREFERRED_VECTOR_WIDTH_FLOAT</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_PREFERRED_VECTOR_WIDTH_DOUBLE</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_PREFERRED_VECTOR_WIDTH_HALF</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_PREFERRED_VECTOR_WIDTH_HALF is missing before version 1.1.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>-------------------------------------------------</td>
<td>-------------</td>
<td>-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_DEVICE_NATIVE_VECTOR_WIDTH_CHAR</td>
<td>cl_uint</td>
<td>Returns the native ISA vector width. The vector width is defined as the number of scalar elements that can be stored in the vector. If double precision is not supported, CL_DEVICE_NATIVE_VECTOR_WIDTH_DOUBLE must return 0. If the cl_khr_fp16 extension is not supported, CL_DEVICE_NATIVE_VECTOR_WIDTH_HALF must return 0.</td>
</tr>
<tr>
<td>CL_DEVICE_NATIVE_VECTOR_WIDTH_SHORT</td>
<td>cl_uint</td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_NATIVE_VECTOR_WIDTH_INT</td>
<td>cl_uint</td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_NATIVE_VECTOR_WIDTH_LONG</td>
<td>cl_uint</td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_NATIVE_VECTOR_WIDTH_FLOAT</td>
<td>cl_uint</td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_NATIVE_VECTOR_WIDTH_DOUBLE</td>
<td>cl_uint</td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_NATIVE_VECTOR_WIDTH_HALF</td>
<td>cl_uint</td>
<td></td>
</tr>
<tr>
<td>missing before version 1.1.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_MAX_CLOCK_FREQUENCY</td>
<td>cl_uint</td>
<td>Clock frequency of the device in MHz. The meaning of this value is implementation-defined. For devices with multiple clock domains, the clock frequency for any of the clock domains may be returned. For devices that dynamically change frequency for power or thermal reasons, the returned clock frequency may be any valid frequency. Note: This definition is missing before version 2.2. Maximum configured clock frequency of the device in MHz. Note: This definition is deprecated by version 2.2.</td>
</tr>
<tr>
<td>CL_DEVICE_ADDRESS_BITS</td>
<td>cl_uint</td>
<td>The default compute device address space size of the global address space specified as an unsigned integer value in bits. Currently supported values are 32 or 64 bits.</td>
</tr>
<tr>
<td>CL_DEVICE_MAX_MEM_ALLOC_SIZE</td>
<td>cl_ulong</td>
<td>Max size of memory object allocation in bytes. The minimum value is max(min(1024 × 1024 × 1024, 1/4th of CL_DEVICE_GLOBAL_MEM_SIZE), 32 × 1024 × 1024) for devices that are not of type CL_DEVICE_TYPE_CUSTOM.</td>
</tr>
<tr>
<td>CL_DEVICE_IMAGE_SUPPORT</td>
<td>cl_bool</td>
<td>Is CL_TRUE if images are supported by the OpenCL device and CL_FALSE otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_MAX_READ_IMAGE_ARGS</td>
<td>cl_uint</td>
<td>Max number of image objects arguments of a kernel declared with the read_only qualifier. The minimum value is 128 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>------------------------------------------------------</td>
<td>-------------</td>
<td>-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_DEVICE_MAX_WRITE_IMAGE_ARGS</td>
<td>cl_uint</td>
<td>Max number of image objects arguments of a kernel declared with the write_only qualifier. The minimum value is 64 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_MAX_READ_WRITE_IMAGE_ARGS</td>
<td>cl_uint</td>
<td>Max number of image objects arguments of a kernel declared with the write_only or read_write qualifier. Support for read-write image arguments is required for an OpenCL 2.0, 2.1, or 2.2 device if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE. The minimum value is 64 if the device supports read-write images arguments, and must be 0 for devices that do not support read-write images.</td>
</tr>
<tr>
<td>CL_DEVICE_IL_VERSION</td>
<td>char[]</td>
<td>The intermediate languages that can be supported by clCreateProgramWithIL for this device. Returns a space-separated list of IL version strings of the form &lt;IL_Prefix&gt;_&lt;Major_Version&gt;.&lt;Minor_Version&gt;</td>
</tr>
<tr>
<td>or CL_DEVICE_IL_VERSION_KHR</td>
<td></td>
<td>For an OpenCL 2.1 or 2.2 device, SPIR-V is a required IL prefix. If the device does not support intermediate language programs, the value must be &quot;&quot; (an empty string). A device that supports the cl_khr_il_program extension must support the &quot;SPIR-V&quot; IL prefix.</td>
</tr>
<tr>
<td>CL_DEVICE_IALS_WITH_VERSION</td>
<td>cl_name_version[] or cl_name_version_khr[]</td>
<td>Returns an array of descriptions (name and version) for all supported intermediate languages. Intermediate languages with the same name may be reported more than once but each name and major/minor version combination may only be reported once. The list of intermediate languages reported must match the list reported via CL_DEVICE_IL_VERSION. For an OpenCL 2.1 or 2.2 device, at least one version of SPIR-V must be reported.</td>
</tr>
<tr>
<td>missing before version 2.0.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>missing before version 2.1.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>or CL_DEVICE_IALS_WITH_VERSION_KHR</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>-------------------------------------------------</td>
<td>-------------</td>
<td>-----------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_DEVICE_IMAGE2D_MAX_WIDTH</td>
<td>size_t</td>
<td>Max width of 2D image or 1D image not created from a buffer object in pixels.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The minimum value is 16384 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_IMAGE2D_MAX_HEIGHT</td>
<td>size_t</td>
<td>Max height of 2D image in pixels.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The minimum value is 16384 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_IMAGE3D_MAX_WIDTH</td>
<td>size_t</td>
<td>Max width of 3D image in pixels.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The minimum value is 2048 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_IMAGE3D_MAX_HEIGHT</td>
<td>size_t</td>
<td>Max height of 3D image in pixels.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The minimum value is 2048 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_IMAGE3D_MAX_DEPTH</td>
<td>size_t</td>
<td>Max depth of 3D image in pixels.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The minimum value is 2048 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_IMAGE_MAX_BUFFER_SIZE</td>
<td>size_t</td>
<td>Max number of pixels for a 1D image created from a buffer object.</td>
</tr>
<tr>
<td>missing before version 1.2.</td>
<td></td>
<td>The minimum value is 65536 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_IMAGE_MAX_ARRAY_SIZE</td>
<td>size_t</td>
<td>Max number of images in a 1D or 2D image array.</td>
</tr>
<tr>
<td>missing before version 1.2.</td>
<td></td>
<td>The minimum value is 2048 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_MAX_SAMPLERS</td>
<td>cl_uint</td>
<td>Maximum number of samplers that can be used in a kernel.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The minimum value is 16 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>-------------------------------------------------</td>
<td>-------------</td>
<td>---------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td><strong>CL_DEVICE_IMAGE_PITCH_ALIGNMENT</strong></td>
<td><strong>cl_uint</strong></td>
<td>The row pitch alignment size in pixels for 2D images created from a buffer. The value returned must be a power of 2.</td>
</tr>
<tr>
<td>missing before version 2.0.</td>
<td></td>
<td>Support for 2D images created from a buffer is required for an OpenCL 2.0, 2.1, or 2.2 device if <strong>CL_DEVICE_IMAGE_SUPPORT</strong> is <strong>CL_TRUE</strong>.</td>
</tr>
<tr>
<td>The equivalent <strong>CL_DEVICE_IMAGE_PITCH_ALIGNMENT_KHR</strong> may be used if the <strong>cl_khr_image2d_from_buffer</strong> extension is supported.</td>
<td></td>
<td>This value must be 0 for devices that do not support 2D images created from a buffer.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_IMAGE_BASE_ADDRESS_ALIGNMENT</strong></td>
<td><strong>cl_uint</strong></td>
<td>This query specifies the minimum alignment in pixels of the host_ptr specified to <strong>clCreateBuffer</strong> or <strong>clCreateBufferWithProperties</strong> when a 2D image is created from a buffer which was created using <strong>CL_MEM_USE_HOST_PTR</strong>. The value returned must be a power of 2.</td>
</tr>
<tr>
<td>missing before version 2.0.</td>
<td></td>
<td>Support for 2D images created from a buffer is required for an OpenCL 2.0, 2.1, or 2.2 device if <strong>CL_DEVICE_IMAGE_SUPPORT</strong> is <strong>CL_TRUE</strong>.</td>
</tr>
<tr>
<td>The equivalent <strong>CL_DEVICE_IMAGE_BASE_ADDRESS_ALIGNMENT_KHR</strong> may be used if the <strong>cl_khr_image2d_from_buffer</strong> extension is supported.</td>
<td></td>
<td>This value must be 0 for devices that do not support 2D images created from a buffer.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_MAX_PIPE_ARGS</strong></td>
<td><strong>cl_uint</strong></td>
<td>The maximum number of pipe objects that can be passed as arguments to a kernel. The minimum value is 16 for devices supporting pipes, and must be 0 for devices that do not support pipes.</td>
</tr>
<tr>
<td>missing before version 2.0.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>CL_DEVICE_PIPE_MAX_ACTIVE_RESERVATIONS</strong></td>
<td><strong>cl_uint</strong></td>
<td>The maximum number of reservations that can be active for a pipe per work-item in a kernel. A work-group reservation is counted as one reservation per work-item. The minimum value is 1 for devices supporting pipes, and must be 0 for devices that do not support pipes.</td>
</tr>
<tr>
<td>missing before version 2.0.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>CL_DEVICE_PIPE_MAX_PACKET_SIZE</strong></td>
<td><strong>cl_uint</strong></td>
<td>The maximum size of pipe packet in bytes.</td>
</tr>
<tr>
<td>missing before version 2.0.</td>
<td></td>
<td>Support for pipes is required for an OpenCL 2.0, 2.1, or 2.2 device. The minimum value is 1024 bytes if the device supports pipes, and must be 0 for devices that do not support pipes.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>-------------------------------------------------</td>
<td>-------------</td>
<td>-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_DEVICE_MAX_PARAMETER_SIZE</td>
<td>size_t</td>
<td>Max size in bytes of all arguments that can be passed to a kernel. The minimum value is 1024 for devices that are not of type CL_DEVICE_TYPE_CUSTOM. For this minimum value, only a maximum of 128 arguments can be passed to a kernel. For all other values, a maximum of 255 arguments can be passed to a kernel.</td>
</tr>
<tr>
<td>CL_DEVICE_MEM_BASE_ADDR_ALIGN</td>
<td>cl_uint</td>
<td>Alignment requirement (in bits) for sub-buffer offsets. The minimum value is the size (in bits) of the largest OpenCL built-in data type supported by the device (long16 in FULL profile, long16 or int16 in EMBEDDED profile) for devices that are not of type CL_DEVICE_TYPE_CUSTOM.</td>
</tr>
<tr>
<td>CL_DEVICE_MIN_DATA_TYPE_ALIGN_SIZE</td>
<td>cl_uint</td>
<td>The minimum value is the size (in bytes) of the largest OpenCL data type supported by the device (long16 in FULL profile, long16 or int16 in EMBEDDED profile).</td>
</tr>
</tbody>
</table>

**Deprecated by version 1.2.**
<table>
<thead>
<tr>
<th>Device Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_DEVICE_SINGLE_FP_CONFIG</td>
<td>cl_device_fp_config</td>
<td>Describes single precision floating-point capability of the device. This is a bit-field that describes one or more of the following values:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>- CL_FP_DENORM - denoms are supported</td>
</tr>
<tr>
<td></td>
<td></td>
<td>- CL_FP_INF_NAN - INF and quiet NaNs are supported</td>
</tr>
<tr>
<td></td>
<td></td>
<td>- CL_FP_ROUND_TO_NEAREST - round to nearest even rounding mode supported</td>
</tr>
<tr>
<td></td>
<td></td>
<td>- CL_FP_ROUND_TO_ZERO - round to zero rounding mode supported</td>
</tr>
<tr>
<td></td>
<td></td>
<td>- CL_FP_ROUND_TO_INF - round to positive and negative infinity rounding modes supported</td>
</tr>
<tr>
<td></td>
<td></td>
<td>- CL_FP_FMA - IEEE754-2008 fused multiply-add is supported</td>
</tr>
<tr>
<td></td>
<td></td>
<td>- CL_FP_CORRECTLY_ROUNDED_DIVIDE_SQRT - divide and sqrt are correctly rounded as defined by the IEEE754 specification</td>
</tr>
<tr>
<td></td>
<td></td>
<td>- CL_FP_SOFT_FLOAT - Basic floating-point operations (such as addition, subtraction, multiplication) are implemented in software</td>
</tr>
<tr>
<td></td>
<td></td>
<td>For the full profile, the mandated minimum floating-point capability for devices that are not of type CL_DEVICE_TYPE_CUSTOM is:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>- CL_FP_ROUND_TO_NEAREST</td>
</tr>
<tr>
<td></td>
<td></td>
<td>For the embedded profile, see the dedicated table.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>-------------</td>
<td>-------------</td>
<td>-------------</td>
</tr>
</tbody>
</table>
| `CL_DEVICE_DOUBLE_FP_CONFIG`[^7] | `cl_device_fp_config` | Describes double precision floating-point capability of the OpenCL device. This is a bit-field that describes one or more of the following values:  
  - `CL_FP_DENORM` - denorms are supported  
  - `CL_FP_INF_NAN` - INF and NaNs are supported  
  - `CL_FP_ROUND_TOНЕAREST` - round to nearest even rounding mode supported  
  - `CL_FP_ROUND_TO_ZERO` - round to zero rounding mode supported  
  - `CL_FP_ROUND_TO_INF` - round to positive and negative infinity rounding modes supported  
  - `CL_FP_FMA` - IEEE754-2008 fused multiply-add is supported  
  - `CL_FP_SOFT_FLOAT` - Basic floating-point operations (such as addition, subtraction, multiplication) are implemented in software  
  
  Double precision is an optional feature so the mandated minimum double precision floating-point capability is 0.  
  
  If double precision is supported by the device, then the minimum double precision floating-point capability for OpenCL 2.0 or newer devices is:  
  
  `CL_FP_FMA | CL_FP_ROUND_TO_NEAREST | CL_FP_INF_NAN | CL_FP_DENORM`.  
  
  or for OpenCL 1.0, OpenCL 1.1 or OpenCL 1.2 devices:  
  
  `CL_FP_FMA | CL_FP_ROUND_TO_NEAREST | CL_FP_ROUND_TO_INFINITY | CL_FP_ROUND_TO_INF | CL_FP_INF_NAN | CL_FP_DENORM`.  

<p>| CL_DEVICE_GLOBAL_MEM_CACHE_TYPE | cl_device_mem_cache_type | Type of global memory cache supported. Valid values are: <code>CL_NONE</code>, <code>CL_READ_ONLY_CACHE</code>, and <code>CL_READ_WRITE_CACHE</code>. |</p>
<table>
<thead>
<tr>
<th>Device Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_DEVICE_GLOBAL_MEM_CACHELINE_SIZE</td>
<td>cl_uint</td>
<td>Size of global memory cache line in bytes.</td>
</tr>
<tr>
<td>CL_DEVICE_GLOBAL_MEM_CACHE_SIZE</td>
<td>cl_ulong</td>
<td>Size of global memory cache in bytes.</td>
</tr>
<tr>
<td>CL_DEVICE_GLOBAL_MEM_SIZE</td>
<td>cl_ulong</td>
<td>Size of global device memory in bytes.</td>
</tr>
<tr>
<td>CL_DEVICE_MAX_CONSTANT_BUFFER_SIZE</td>
<td>cl_ulong</td>
<td>Max size in bytes of a constant buffer allocation. The minimum value is 64 KB for devices that are not of type CL_DEVICE_TYPE_CUSTOM.</td>
</tr>
<tr>
<td>CL_DEVICE_MAX_CONSTANT_ARGS</td>
<td>cl_uint</td>
<td>Max number of arguments declared with the __constant qualifier in a kernel. The minimum value is 8 for devices that are not of type CL_DEVICE_TYPECUSTOM.</td>
</tr>
<tr>
<td>CL_DEVICE_MAX_GLOBAL_VARIABLE_SIZE</td>
<td>size_t</td>
<td>The maximum number of bytes of storage that may be allocated for any single variable in program scope or inside a function in an OpenCL kernel language declared in the global address space. Support for program scope global variables is required for an OpenCL 2.0, 2.1, or 2.2 device. The minimum value is 64 KB if the device supports program scope global variables, and must be 0 for devices that do not support program scope global variables.</td>
</tr>
<tr>
<td>CL_DEVICE_GLOBAL_VARIABLE_PREFERRED_TOTAL_SIZE</td>
<td>size_t</td>
<td>Maximum preferred total size, in bytes, of all program variables in the global address space. This is a performance hint. An implementation may place such variables in storage with optimized device access. This query returns the capacity of such storage. The minimum value is 0.</td>
</tr>
<tr>
<td>CL_DEVICE_LOCAL_MEM_TYPE</td>
<td>cl_device_local_mem_type</td>
<td>Type of local memory supported. This can be set to CL_LOCAL implying dedicated local memory storage such as SRAM, or CL_GLOBAL. For custom devices, CL_NONE can also be returned indicating no local memory support.</td>
</tr>
<tr>
<td>CL_DEVICE_LOCAL_MEM_SIZE</td>
<td>cl_ulong</td>
<td>Size of local memory region in bytes. The minimum value is 32 KB for devices that are not of type CL_DEVICE_TYPE_CUSTOM.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>-------------------------------------------------------</td>
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<td>---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_DEVICE_ERROR_CORRECTION_SUPPORT</td>
<td>cl_bool</td>
<td>Is CL_TRUE if the device implements error correction for all accesses to compute device memory (global and constant). Is CL_FALSE if the device does not implement such error correction.</td>
</tr>
<tr>
<td>CL_DEVICE_HOST_UNIFIED_MEMORY</td>
<td>cl_bool</td>
<td>Is CL_TRUE if the device and the host have a unified memory subsystem and is CL_FALSE otherwise. Missing before version 1.1 and deprecated by version 2.0.</td>
</tr>
<tr>
<td>CL_DEVICE_PROFILING_TIMER_RESOLUTION</td>
<td>size_t</td>
<td>Describes the resolution of device timer. This is measured in nanoseconds. Refer to Profiling Operations for details.</td>
</tr>
<tr>
<td>CL_DEVICE_ENDIAN_LITTLE</td>
<td>cl_bool</td>
<td>Is CL_TRUE if the OpenCL device is a little endian device and CL_FALSE otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_AVAILABLE</td>
<td>cl_bool</td>
<td>Is CL_TRUE if the device is available and CL_FALSE otherwise. A device is considered to be available if the device can be expected to successfully execute commands enqueued to the device.</td>
</tr>
<tr>
<td>CL_DEVICE_COMPILER_AVAILABLE</td>
<td>cl_bool</td>
<td>Is CL_FALSE if the implementation does not have a compiler available to compile the program source.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Is CL_TRUE if the compiler is available. This can be CL_FALSE for the embedded platform profile only.</td>
</tr>
<tr>
<td>CL_DEVICE_LINKER_AVAILABLE</td>
<td>cl_bool</td>
<td>Is CL_FALSE if the implementation does not have a linker available. Is CL_TRUE if the linker is available.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>This can be CL_FALSE for the embedded platform profile only.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>This must be CL_TRUE if CL_DEVICE_COMPILER_AVAILABLE is CL_TRUE.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>--------------------------------</td>
<td>------------------------------------------</td>
<td>-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL DEVICE EXECUTION CAPABILITIES</td>
<td>cl_device_exec_capabilities</td>
<td>Describes the execution capabilities of the device. This is a bit-field that describes one or more of the following values:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_EXEC_KERNEL - The OpenCL device can execute OpenCL kernels.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_EXEC_NATIVE_KERNEL - The OpenCL device can execute native kernels.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The mandated minimum capability is: CL_EXEC_KERNEL.</td>
</tr>
<tr>
<td>CL_DEVICE_QUEUE_PROPERTIES</td>
<td>cl_command_queue_properties</td>
<td>See description of CL DEVICE QUEUE ON HOST PROPERTIES.</td>
</tr>
<tr>
<td>deprecated by version 2.0.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL DEVICE QUEUE ON HOST PROPERTIES</td>
<td>cl_command_queue_properties</td>
<td>Describes the on host command-queue properties supported by the device. This is a bit-field that describes one or more of the following values:</td>
</tr>
<tr>
<td>missing before version 2.0.</td>
<td></td>
<td>CL_QUEUE_OUT_OF_ORDER_EXEC_MODE_ENABLE</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_QUEUE_PROFILING_ENABLE</td>
</tr>
<tr>
<td></td>
<td></td>
<td>These properties are described in the Queue Properties table.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The mandated minimum capability is: CL_QUEUE_PROFILING_ENABLE.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>-------------</td>
<td>-------------</td>
<td>-------------</td>
</tr>
</tbody>
</table>
| **CL_DEVICE_QUEUE_ON_DEVICE_PROPERTIES** | **cl_command_queue_properties** | Describes the on device command-queue properties supported by the device. This is a bit-field that describes one or more of the following values:  

- `CL_QUEUE_OUT_OF_ORDER_EXEC_MODE_ENABLE`  
- `CL_QUEUE_PROFILING_ENABLE`  

These properties are described in the Queue Properties table.  

Support for on-device queues is required for an OpenCL 2.0, 2.1, or 2.2 device. When on-device queues are supported, the mandated minimum capability is:  

- `CL_QUEUE_OUT_OF_ORDER_EXEC_MODE_ENABLE | CL_QUEUE_PROFILING_ENABLE`.  

Must be 0 for devices that do not support on-device queues. |
| **CL_DEVICE_QUEUE_ON_DEVICE_PREFERRED_SIZE** | **cl_uint** | The preferred size of the device queue, in bytes. Applications should use this size for the device queue to ensure good performance.  

The minimum value is 16 KB for devices supporting on-device queues, and must be 0 for devices that do not support on-device queues. |
| **CL_DEVICE_QUEUE_ON_DEVICE_MAX_SIZE** | **cl_uint** | The maximum size of the device queue in bytes.  

The minimum value is 256 KB for the full profile and 64 KB for the embedded profile for devices supporting on-device queues, and must be 0 for devices that do not support on-device queues. |
| **CL_DEVICE_MAX_ON_DEVICE_QUEUES** | **cl_uint** | The maximum number of device queues that can be created for this device in a single context.  

The minimum value is 1 for devices supporting on-device queues, and must be 0 for devices that do not support on-device queues. |
<table>
<thead>
<tr>
<th>Device Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>CL_DEVICE_MAX_ON_DEVICE_EVENTS</strong></td>
<td><strong>cl_uint</strong></td>
<td>The maximum number of events in use by a device queue. These refer to events returned by the <code>enqueue_</code> built-in functions to a device queue or user events returned by the <code>create_user_event</code> built-in function that have not been released. The minimum value is 1024 for devices supporting on-device queues, and must be 0 for devices that do not support on-device queues.</td>
</tr>
<tr>
<td><strong>missing before</strong> version 2.0.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>CL_DEVICE_BUILT_IN_KERNELS</strong></td>
<td><strong>char[]</strong></td>
<td>A semi-colon separated list of built-in kernels supported by the device. An empty string is returned if no built-in kernels are supported by the device.</td>
</tr>
<tr>
<td><strong>missing before</strong> version 1.2.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>CL_DEVICE_BUILT_IN_KERNELS_WITH_VERSION</strong></td>
<td><strong>cl_name_version[]</strong></td>
<td>Returns an array of descriptions for the built-in kernels supported by the device. Each built-in kernel may only be reported once. The list of reported kernels must match the list returned via <strong>CL_DEVICE_BUILT_IN_KERNELS</strong>.</td>
</tr>
<tr>
<td><strong>missing before</strong> version 3.0.</td>
<td>or <strong>cl_name_version_khr[]</strong></td>
<td></td>
</tr>
<tr>
<td><strong>CL_DEVICE_BUILT_IN_KERNELS_WITH_VERSION_KHR</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>provided by the <strong>cl_khr_extended_versioning</strong> extension.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>CL_DEVICE_PLATFORM</strong></td>
<td><strong>cl_platform_id</strong></td>
<td>The platform associated with this device.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_NAME</strong></td>
<td><strong>char[]</strong></td>
<td>Device name string.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_VENDOR</strong></td>
<td><strong>char[]</strong></td>
<td>Vendor name string.</td>
</tr>
<tr>
<td><strong>CL_DRIVER_VERSION</strong></td>
<td><strong>char[]</strong></td>
<td>OpenCL software driver version string. Follows a vendor-specific format.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_PROFILE</strong></td>
<td><strong>char[]</strong></td>
<td>OpenCL profile string. Returns the profile name supported by the device. The profile name returned can be one of the following strings: FULL_PROFILE - if the device supports the OpenCL specification (functionality defined as part of the core specification and does not require any extensions to be supported). EMBEDDED_PROFILE - if the device supports the OpenCL embedded profile.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>-----------------------------------</td>
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</tr>
<tr>
<td>CL_DEVICE_VERSION</td>
<td>char[]</td>
<td>OpenCL version string. Returns the OpenCL version supported by the device. This version string has the following format: OpenCL &lt;major_version.minor_version&gt;&lt;space&gt;&lt;vendor-specific information&gt; The major_version.minor_version value returned will be one of 1.0, 1.1, 1.2, 2.0, 2.1, 2.2, or 3.0.</td>
</tr>
<tr>
<td>CL_DEVICE_NUMERIC_VERSION</td>
<td>cl_version</td>
<td>Returns the detailed (major, minor, patch) version supported by the device. The major and minor version numbers returned must match those returned via CL_DEVICE_VERSION.</td>
</tr>
<tr>
<td>missing before version 3.0.</td>
<td></td>
<td>or cl_version_khr</td>
</tr>
<tr>
<td>CL_DEVICE_NUMERIC_VERSION_KHR</td>
<td></td>
<td>provided by the cl_khr_extended_versioning extension.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
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<td>-------------</td>
<td>-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_DEVICE_OPENCL_C_VERSION</td>
<td>char[]</td>
<td>Returns the highest fully backwards compatible OpenCL C version supported by the compiler for the device. For devices supporting compilation from OpenCL C source, this will return a version string with the following format:&lt;br&gt;&lt;br&gt;OpenCL &lt; major_version.minor_version &gt; &lt; vendor-specific information &gt;&lt;br&gt;&lt;br&gt;For devices that support compilation from OpenCL C source:&lt;br&gt;&lt;br&gt;Because OpenCL 3.0 is backwards compatible with OpenCL C 1.2, an OpenCL 3.0 device must support at least OpenCL C 1.2. An OpenCL 3.0 device may return an OpenCL C version newer than OpenCL C 1.2 if and only if all optional OpenCL C features are supported by the device for the newer version. Support for OpenCL C 2.0 is required for an OpenCL 2.0, OpenCL 2.1, or OpenCL 2.2 device. Support for OpenCL C 1.2 is required for an OpenCL 1.2 device. Support for OpenCL C 1.1 is required for an OpenCL 1.1 device. Support for either OpenCL C 1.0 or OpenCL C 1.1 is required for an OpenCL 1.0 device. For devices that do not support compilation from OpenCL C source, such as when <code>CL_DEVICE_COMPILER_AVAILABLE</code> is <code>CL_FALSE</code>, this query may return an empty string. This query has been superseded by the <code>CL_DEVICE_OPENCL_C_ALL_VERSIONS</code> query, which returns a set of OpenCL C versions supported by a device.</td>
</tr>
<tr>
<td>missing before version 1.1 and deprecated by version 3.0.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
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<td>--------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_DEVICE_OPENCL_C_ALL_VERSIONS</td>
<td>cl_name_version[]</td>
<td>Returns an array of name, version descriptions listing all the versions of OpenCL C supported by the compiler for the device. In each returned description structure, the name field is required to be &quot;OpenCL C&quot;. The list may include both newer non-backwards compatible OpenCL C versions, such as OpenCL C 3.0, and older OpenCL C versions with mandatory backwards compatibility. The version returned by CL_DEVICE_OPENCL_C_VERSION is required to be present in the list. For devices that support compilation from OpenCL C source: Because OpenCL 3.0 is backwards compatible with OpenCL C 1.2, and OpenCL C 1.2 is backwards compatible with OpenCL C 1.1 and OpenCL C 1.0, support for at least OpenCL C 3.0, OpenCL C 1.2, OpenCL C 1.1, and OpenCL C 1.0 is required for an OpenCL 3.0 device. Support for OpenCL C 2.0, OpenCL C 1.2, OpenCL C 1.1, and OpenCL C 1.0 is required for an OpenCL 2.0, OpenCL 2.1, or OpenCL 2.2 device. Support for OpenCL C 1.2, OpenCL C 1.1, and OpenCL C 1.0 is required for an OpenCL 1.2 device. Support for OpenCL C 1.1 and OpenCL C 1.0 is required for an OpenCL 1.1 device. Support for at least OpenCL C 1.0 is required for an OpenCL 1.0 device. For devices that do not support compilation from OpenCL C source, this query may return an empty array.</td>
</tr>
<tr>
<td>missing before version 3.0.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>----------------------------------------------------------------------------</td>
<td>-------------------</td>
<td>-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td><strong>CL_DEVICE_OPENCL_C_NUMERIC_VERSION_KHR</strong></td>
<td>cl_version_khr</td>
<td>Returns detailed (major, minor, patch) numeric version information. The major and minor version numbers returned must match those returned via <strong>CL_DEVICE_OPENCL_C_VERSION</strong>.</td>
</tr>
<tr>
<td>Provided by the cl_khr_extended_versioning extension.</td>
<td></td>
<td>This query was not promoted to core in OpenCL version 3.0, but the core query <strong>CL_DEVICE_OPENCL_C_ALL_VERSIONS</strong> can be used to obtain equivalent information.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_OPENCL_C_FEATURES</strong> missing before version 3.0.</td>
<td>cl_name_version[]</td>
<td>Returns an array of optional OpenCL C features supported by the compiler for the device alongside the OpenCL C version that introduced the feature macro. For example, if a compiler supports an OpenCL C 3.0 feature, the returned name will be the full name of the OpenCL C feature macro, and the returned version will be 3.0.0.</td>
</tr>
<tr>
<td>For devices that do not support compilation from OpenCL C source, this query may return an empty array.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
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<td>---------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_DEVICE_EXTENSIONS</td>
<td>char[]</td>
<td>Returns a space separated list of extension names (the extension names themselves do not contain any spaces) supported by the device. The list of extension names may include Khronos approved extension names and vendor specified extension names. The following Khronos extension names must be returned by all devices that support OpenCL 1.1:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>cl_khr_byte_addressable_store cl_khr_global_int32_base_atomics cl_khr_global_int32_extended_atomics cl_khr_local_int32_base_atomics cl_khr_local_int32_extended_atomics</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Additionally, the following Khronos extension names must be returned by all devices that support OpenCL 1.2 when and only when the optional feature is supported:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>cl_khr_fp64</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Additionally, the following Khronos extension names must be returned by all devices that support OpenCL 2.0, OpenCL 2.1, or OpenCL 2.2. For devices that support OpenCL 3.0, these extension names must be returned when and only when the optional feature is supported:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>cl_khr_3d_image_writes cl_khr_depth_images cl_khr_image2d_from_buffer</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Please refer to the OpenCL Extension Specification or vendor provided documentation for a detailed description of these extensions.</td>
</tr>
<tr>
<td>Device Info</td>
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<td>Description</td>
</tr>
<tr>
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<td>------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_DEVICE_EXTENSIONS_WITH_VERSION</td>
<td>cl_name_version[]</td>
<td>Returns an array of description (name and version) structures. The same extension name must not be reported more than once. The list of extensions reported must match the list reported via CL_DEVICE_EXTENSIONS.</td>
</tr>
<tr>
<td></td>
<td>or cl_name_version_khr[]</td>
<td></td>
</tr>
<tr>
<td>provided by the cl_khr_extended_versioning extension.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_PRINTF_BUFFER_SIZE</td>
<td>size_t</td>
<td>Maximum size in bytes of the internal buffer that holds the output of printf calls from a kernel. The minimum value for the FULL profile is 1 MB.</td>
</tr>
<tr>
<td>missing before version 1.2.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_PREFERRED_INTEROP_USER_SYNC</td>
<td>cl_bool</td>
<td>Is <strong>CL_TRUE</strong> if the device's preference is for the user to be responsible for synchronization, when sharing memory objects between OpenCL and other APIs such as DirectX, <strong>CL_FALSE</strong> if the device / implementation has a performant path for performing synchronization of memory object shared between OpenCL and other APIs such as DirectX.</td>
</tr>
<tr>
<td>missing before version 1.2.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_PARENT_DEVICE</td>
<td>cl_device_id</td>
<td>Returns the <strong>cl_device_id</strong> of the parent device to which this sub-device belongs. If <strong>device</strong> is a root-level device, a <strong>NULL</strong> value is returned.</td>
</tr>
<tr>
<td>missing before version 1.2.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_PARTITION_MAX_SUB_DEVICES</td>
<td>cl_uint</td>
<td>Returns the maximum number of sub-devices that can be created when a device is partitioned. The value returned cannot exceed <strong>CL_DEVICE_MAX_COMPUTE_UNITS</strong>.</td>
</tr>
<tr>
<td>missing before version 1.2.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
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</tr>
</tbody>
</table>
| `CL_DEVICE_PARTITION_PROPERTIES`<br>missing before version 1.2. | `cl_device_partition_property[]` | Returns the list of partition types supported by device. This is an array of `cl_device_partition_property` values drawn from the following list:  
  - `CL_DEVICE_PARTITION_EQUALLY`
  - `CL_DEVICE_PARTITION_BY_COUNTS`
  - `CL_DEVICE_PARTITION_BY_AFFINITY_DOMAIN`

  If the device cannot be partitioned (i.e. there is no partitioning scheme supported by the device that will return at least two sub-devices), a value of 0 will be returned. |
| `CL_DEVICE_PARTITION_AFFINITY_DOMAIN`<br>missing before version 1.2. | `cl_device_affinity_domain` | Returns the list of supported affinity domains for partitioning the device using `CL_DEVICE_PARTITION_BY_AFFINITY_DOMAIN`. This is a bit-field that describes one or more of the following values:  
  - `CL_DEVICE_AFFINITY_DOMAIN_NUMA`
  - `CL_DEVICE_AFFINITY_DOMAIN_L4_CACHE`
  - `CL_DEVICE_AFFINITY_DOMAIN_L3_CACHE`
  - `CL_DEVICE_AFFINITY_DOMAIN_L2_CACHE`
  - `CL_DEVICE_AFFINITY_DOMAIN_L1_CACHE`
  - `CL_DEVICE_AFFINITY_DOMAIN_NEXT_PARTITIONABLE`

  If the device does not support any affinity domains, a value of 0 will be returned. |
<table>
<thead>
<tr>
<th>Device Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_DEVICE_PARTITION_TYPE</td>
<td>cl_device_partition_property[]</td>
<td>Returns the properties argument specified in clCreateSubDevices if device is a sub-device. In the case where the properties argument to clCreateSubDevices is CL_DEVICE_PARTITION_BY_AFFINITY_DOMAIN, CL_DEVICE_AFFINITY_DOMAIN_NEXT_PARTITIONABLE, the affinity domain used to perform the partition will be returned. This can be one of the following values: CL_DEVICE_AFFINITY_DOMAIN_NUMA CL_DEVICE_AFFINITY_DOMAIN_L4_CACHE CL_DEVICE_AFFINITY_DOMAIN_L3_CACHE CL_DEVICE_AFFINITY_DOMAIN_L2_CACHE CL_DEVICE_AFFINITY_DOMAIN_L1_CACHE Otherwise the implementation may either return a param_value_size_ret of 0 i.e. there is no partition type associated with device or can return a property value of 0 (where 0 is used to terminate the partition property list) in the memory that param_value points to.</td>
</tr>
<tr>
<td>CL_DEVICE_REFERENCE_COUNT</td>
<td>cl_uint</td>
<td>Returns the device reference count. If the device is a root-level device, a reference count of one is returned.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>-------------------------------------------------</td>
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</tr>
<tr>
<td><strong>CL_DEVICE_SVM_CAPABILITIES</strong> missing before version 2.0.</td>
<td><strong>cl_device_svm_capabilities</strong></td>
<td>Describes the various shared virtual memory (SVM) memory allocation types the device supports. This is a bit-field that describes a combination of the following values:</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_DEVICE_SVM_COARSE_GRAIN_BUFFER</strong> - Support for coarse-grain buffer sharing using <code>clSVMAlloc</code>. Memory consistency is guaranteed at synchronization points and the host must use calls to <code>clEnqueueMapBuffer</code> and <code>clEnqueueUnmapMemObject</code>.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_DEVICE_SVM_FINE_GRAIN_BUFFER</strong> - Support for fine-grain buffer sharing using <code>clSVMAlloc</code>. Memory consistency is guaranteed at synchronization points without need for <code>clEnqueueMapBuffer</code> and <code>clEnqueueUnmapMemObject</code>.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_DEVICE_SVM_FINE_GRAIN_SYSTEM</strong> - Support for sharing the host's entire virtual memory including memory allocated using <code>malloc</code>. Memory consistency is guaranteed at synchronization points.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_DEVICE_SVM_ATOMICS</strong> - Support for the OpenCL 2.0 atomic operations that provide memory consistency across the host and all OpenCL devices supporting fine-grain SVM allocations.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The mandated minimum capability for an OpenCL 2.0, 2.1, or 2.2 device is <strong>CL_DEVICE_SVM_COARSE_GRAIN_BUFFER</strong>. For other device versions there is no mandated minimum capability.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_PREFERRED_PLATFORM_ATOMIC_ALIGNMENT</strong> missing before version 2.0.</td>
<td><strong>cl_uint</strong></td>
<td>Returns the value representing the preferred alignment in bytes for OpenCL 2.0 fine-grained SVM atomic types. This query can return 0 which indicates that the preferred alignment is aligned to the natural size of the type.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_PREFERRED_GLOBAL_ATOMIC_ALIGNMENT</strong> missing before version 2.0.</td>
<td><strong>cl_uint</strong></td>
<td>Returns the value representing the preferred alignment in bytes for OpenCL 2.0 atomic types to global memory. This query can return 0 which indicates that the preferred alignment is aligned to the natural size of the type.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
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<td>-------------------------------------------------------</td>
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</tr>
<tr>
<td><code>CL_DEVICE_PREFERRED_LOCAL_ATOMIC_ALIGNMENT</code></td>
<td><code>cl_uint</code></td>
<td>Returns the value representing the preferred alignment in bytes for OpenCL 2.0 atomic types to local memory. This query can return 0 which indicates that the preferred alignment is aligned to the natural size of the type.</td>
</tr>
<tr>
<td>missing before version 2.0.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><code>CL_DEVICE_MAX_NUM_SUB_GROUPS</code></td>
<td><code>cl_uint</code></td>
<td>Maximum number of sub-groups in a work-group that a device is capable of executing on a single compute unit, for any given kernel-instance running on the device.</td>
</tr>
<tr>
<td>missing before version 2.1.</td>
<td></td>
<td>The minimum value is 1 if the device supports sub-groups, and must be 0 for devices that do not support sub-groups. Support for sub-groups is required for an OpenCL 2.1 or 2.2 device.</td>
</tr>
<tr>
<td>(Refer also to <code>clGetKernelSubGroupInfo</code>.)</td>
<td></td>
<td></td>
</tr>
<tr>
<td><code>CL_DEVICE_SUB_GROUP_INDEPENDENT_FORWARD_PROGRESS</code></td>
<td><code>cl_bool</code></td>
<td>Is <code>CL_TRUE</code> if this device supports independent forward progress of sub-groups, <code>CL_FALSE</code> otherwise.</td>
</tr>
<tr>
<td>missing before version 2.1.</td>
<td></td>
<td>This query must return <code>CL_TRUE</code> for devices that support the <code>cl_khr_subgroups</code> extension, and must return <code>CL_FALSE</code> for devices that do not support sub-groups.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
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</tr>
<tr>
<td>CL_DEVICE_ATOMIC_MEMORY_CAPABILITIES</td>
<td>cl_device_atomic_capabilities</td>
<td>Describes the various memory orders and scopes that the device supports for atomic memory operations. This is a bit-field that describes a combination of the following values:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_DEVICE_ATOMIC_ORDER_RELAXED - Support for the relaxed memory order.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_DEVICE_ATOMIC_ORDER_ACQ_REL - Support for the acquire, release, and acquire-release memory orders.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_DEVICE_ATOMIC_ORDER_SEQ_CST - Support for the sequentially consistent memory order.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Because atomic memory orders are hierarchical, a device that supports a strong memory order must also support all weaker memory orders.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_DEVICE_ATOMIC_SCOPE_WORK_ITEM - Support for memory ordering constraints that apply to a single work-item.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_DEVICE_ATOMIC_SCOPE_WORK_GROUP - Support for memory ordering constraints that apply to all work-items in a work-group.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_DEVICE_ATOMIC_SCOPE DEVICE - Support for memory ordering constraints that apply to all work-items executing on the device.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_DEVICE_ATOMIC_SCOPE_ALL_DEVICES - Support for memory ordering constraints that apply to all work-items executing across all devices that can share SVM memory with each other and the host process.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Because atomic scopes are hierarchical, a device that supports a wide scope must also support all narrower scopes, except for the work-item scope, which is a special case.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The mandated minimum capability is:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_DEVICE_ATOMIC_ORDER_RELAXED</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>-------------------------------------------------</td>
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<td>-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_DEVICE_ATOMIC_FENCE_CAPABILITIES</td>
<td>cl_device_atomic_capabilities</td>
<td>Describes the various memory orders and scopes that the device supports for atomic fence operations. This is a bit-field that has the same set of possible values as described for CL_DEVICE_ATOMIC_MEMORY_CAPABILITIES.</td>
</tr>
<tr>
<td>missing before version 3.0.</td>
<td></td>
<td>The mandated minimum capability is:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_DEVICE_ATOMIC_ORDER_RELAXED</td>
</tr>
<tr>
<td>CL_DEVICE_NON_UNIFORM_WORK_GROUP_SUPPORT</td>
<td>cl_bool</td>
<td>Is CL_TRUE if the device supports non-uniform work-groups, and CL_FALSE otherwise.</td>
</tr>
<tr>
<td>missing before version 3.0.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_WORK_GROUP_COLLECTIVE_FUNCTIONS_SUPPORT</td>
<td>cl_bool</td>
<td>Is CL_TRUE if the device supports work-group collective functions e.g. work_group_broadcast, work_group_reduce, and work_group_scan, and CL_FALSE otherwise.</td>
</tr>
<tr>
<td>missing before version 3.0.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_GENERIC_ADDRESS_SPACE_SUPPORT</td>
<td>cl_bool</td>
<td>Is CL_TRUE if the device supports the generic address space and its associated built-in functions, and CL_FALSE otherwise.</td>
</tr>
<tr>
<td>missing before version 3.0.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_DEVICE.Enqueue_Capabilities</td>
<td>cl_device_device_enqueue_capabilities</td>
<td>Describes device-side enqueue capabilities of the device. This is a bit-field that describes one or more of the following values:</td>
</tr>
<tr>
<td>missing before version 3.0.</td>
<td></td>
<td>CL_DEVICE_QUEUE_SUPPORTED - Device supports device-side enqueue and on-device queues.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_DEVICE_QUEUE_REPLACEABLE_DEFAULT - Device supports a replaceable default on-device queue.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>If CL_DEVICE_QUEUE_REPLACEABLE_DEFAULT is set, CL_DEVICE_QUEUE_SUPPORTED must also be set.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Devices that set CL_DEVICE_QUEUE_SUPPORTED for CL_DEVICE_DEVICE.Enqueue_Capabilities must also return CL_TRUE for CL_DEVICE_GENERIC_ADDRESS_SPACE_SUPPORT.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
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</tr>
<tr>
<td>CL_DEVICE_PIPE_SUPPORT</td>
<td>cl_bool</td>
<td>Is CL_TRUE if the device supports pipes, and CL_FALSE otherwise. Devices that return CL_TRUE for CL_DEVICE_PIPE_SUPPORT must also return CL_TRUE for CL_DEVICE_GENERIC_ADDRESS_SPACE_SUPPORT.</td>
</tr>
<tr>
<td>CL_DEVICE_PREFERRED_WORK_GROUP_SIZE_MULTIPLE</td>
<td>size_t</td>
<td>Returns the preferred multiple of work-group size for the given device. This is a performance hint intended as a guide when specifying the local work size argument to <code>clEnqueueNDRangeKernel</code>. (Refer also to <code>clGetKernelWorkGroupInfo</code> where <code>CL_KERNEL_PREFERRED_WORK_GROUP_SIZE_MULTIPLE</code> can return a different value to <code>CL_DEVICE_PREFERRED_WORK_GROUP_SIZE_MULTIPLE</code> which may be more optimal.)</td>
</tr>
<tr>
<td>CL_DEVICE_LATEST_CONFORMANCE_VERSION_PASSED</td>
<td>char[]</td>
<td>Returns the latest version of the conformance test suite that this device has fully passed in accordance with the official conformance process.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
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</tr>
<tr>
<td>CL_DEVICE_COMMAND_BUFFER_CAPABILITIES_KHR</td>
<td>cl_device_command_buffer_capabilitiesKHR</td>
<td>Describes device command-buffer capabilities, encoded as bits in a bitfield. Supported capabilities are:</td>
</tr>
<tr>
<td>provided by the cl_khr_command_buffer extension.</td>
<td></td>
<td>CL_COMMAND_BUFFER_CAPABILITY_KERNEL_PRINTF_KHR Device supports the ability to record commands that execute kernels which contain printf calls.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_command_buffer extension.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_COMMAND_BUFFER_CAPABILITY_DEVICE_SIDE_ENQUEUE_KHR Device supports the ability to record commands that execute kernels which contain device-side kernel-enqueue calls.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_command_buffer extension.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_COMMAND_BUFFER_CAPABILITY_SIMULTANEOUS_USE_KHR Device supports the command-buffers having a Pending Count that exceeds 1.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_command_buffer extension.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_COMMAND_BUFFER_CAPABILITY_OUT_OF_ORDER_KHR Device supports the ability to record command-buffers to out-of-order command-queues.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_command_buffer extension.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_COMMAND_BUFFER_CAPABILITY_MULTIPLE_QUEUE_KHR Device supports the ability to record commands to more than one command-queue associated with device in a single command-buffer.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_command_buffer_multi_device extension.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
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</tr>
<tr>
<td><strong>CL_DEVICE_COMMAND_BUFFER_REQUIRED_QUEUE_PROPERTIES_KHR</strong></td>
<td>cl_command_queue_properties</td>
<td>Bitmask of the minimum properties with which a command-queue must be created to allow a command-buffer to be executed on it. It is valid for a command-queue to be created with extra properties in addition to this base requirement and still be compatible with command-buffer execution.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_COMMAND_BUFFER_NUM_SYNC_DEVICES_KHR</strong></td>
<td>cl_uint</td>
<td>Return the number of root devices listed in <strong>CL_DEVICE_COMMAND_BUFFER_SYNC_DEVICES_KHR</strong> that device can use device-side synchronization with.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_COMMAND_BUFFER_SYNC_DEVICES_KHR</strong></td>
<td>cl_device_id[]</td>
<td>Return the list of root devices device can use device-side synchronization with. A device should list itself only if it has native support for synchronizing commands. Sub-devices are not listed to avoid non-deterministic results as sub-devices are created. Instead if a root device is listed, then any of its partitioned sub-devices can also be natively synchronized with.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
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</tr>
<tr>
<td>CL_DEVICE_MUTABLE_DISPATCH_CAPABILITIES_KHR</td>
<td>cl_mutable_dispatch_fields_khr</td>
<td>Provides device mutable-dispatch capabilities, encoded as bits in a bitfield. Supported capabilities are:</td>
</tr>
<tr>
<td>provided by the cl_khr_command_buffer_mutable_dispatch extension.</td>
<td></td>
<td><strong>CL_MUTABLE_DISPATCH_GLOBAL_OFFSET_KHR</strong> - Device supports the ability to modify the <code>global_work_offset</code> of kernel execution after command recording.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_command_buffer_mutable_dispatch extension.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_MUTABLE_DISPATCH_GLOBAL_SIZE_KHR</strong> - Device supports the ability to modify the <code>global_work_size</code> of kernel execution after command recording.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_command_buffer_mutable_dispatch extension.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_MUTABLE_DISPATCH_LOCAL_SIZE_KHR</strong> - Device supports the ability to modify the <code>local_work_size</code> of kernel execution after command recording.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_command_buffer_mutable_dispatch extension.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_MUTABLE_DISPATCH_ARGUMENTS_KHR</strong> - Device supports the ability to modify arguments set on a kernel after command recording.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_command_buffer_mutable_dispatch extension.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_MUTABLE_DISPATCH_EXEC_INFO_KHR</strong> - Device supports the ability to modify execution information set on a kernel after command recording.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_command_buffer_mutable_dispatch extension.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>-------------------------------------</td>
<td>----------------------</td>
<td>-----------------------------------------------------------------------------</td>
</tr>
<tr>
<td><strong>CL_DEVICE_UUID_KHR</strong></td>
<td>cl_uchar[CL_UUID_SIZE_KHR]</td>
<td>Returns a universally unique identifier (UUID) for the device.</td>
</tr>
<tr>
<td>provided by the cl_khr_device_uuid extension.</td>
<td></td>
<td>Device UUIDs must be immutable for a given device across processes, driver APIs, driver versions, and system reboots.</td>
</tr>
<tr>
<td><strong>CL_DRIVER_UUID_KHR</strong></td>
<td>cl_uchar[CL_UUID_SIZE_KHR]</td>
<td>Returns a universally unique identifier (UUID) for the software driver for the device.</td>
</tr>
<tr>
<td>provided by the cl_khr_device_uuid extension.</td>
<td></td>
<td><strong>CL_UUID_SIZE_KHR</strong> is the size of the UUID, in bytes.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_LUID_VALID_KHR</strong></td>
<td>cl_bool</td>
<td>Returns <strong>CL_TRUE</strong> if the device has a valid LUID and <strong>CL_FALSE</strong> otherwise.</td>
</tr>
<tr>
<td>provided by the cl_khr_device_uuid extension.</td>
<td></td>
<td><strong>CL_DEVICE_LUID_KHR</strong> is provided by the cl_khr_device_uuid extension.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_LUID_KHR</strong></td>
<td>cl_uchar[CL_LUID_SIZE_KHR]</td>
<td>Returns a locally unique identifier (LUID) for the device.</td>
</tr>
<tr>
<td>provided by the cl_khr_device_uuid extension.</td>
<td></td>
<td>It is not an error to query <strong>CL_DEVICE_LUID_KHR</strong> when <strong>CL_DEVICE_LUID_VALID_KHR</strong> returns <strong>CL_FALSE</strong>, but in this case the returned LUID value is undefined.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>When <strong>CL_DEVICE_LUID_VALID_KHR</strong> returns <strong>CL_TRUE</strong>, and the OpenCL device is running on the Windows operating system, the returned LUID value can be cast to an <strong>LUID</strong> object and must be equal to the locally unique identifier of an <strong>IDXGIAdapter1</strong> object that corresponds to the OpenCL device.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_LUID_SIZE_KHR</strong> is the size of the LUID, in bytes.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>-------------</td>
<td>-------------</td>
<td>-------------</td>
</tr>
<tr>
<td>CL_DEVICE_NODE_MASK_KHR provided by the cl_khr_device_uuid extension.</td>
<td>cl_uint</td>
<td>Returns a node mask for the device. It is not an error to query CL_DEVICE_NODE_MASK_KHR when CL_DEVICE_LUID_VALID_KHR returns CL_FALSE, but in this case the returned node mask is undefined. When CL_DEVICE_LUID_VALID_KHR returns CL_TRUE, the returned node mask must contain exactly one bit. If the OpenCL device is running on an operating system that supports the Direct3D 12 API and the OpenCL device corresponds to an individual device in a linked device adapter, the returned node mask identifies the Direct3D 12 node corresponding to the OpenCL device. Otherwise, the returned node mask must be 1.</td>
</tr>
<tr>
<td>CL_DEVICE_EXTERNAL_MEMORY_IMPORT_HANDLE_TYPES_KHR provided by the cl_khr_external_memory extension.</td>
<td>cl_external_memory_handle_type_khr[]</td>
<td>Returns the list of importable external memory handle types supported by device. Must return a non-empty list of external memory handle types for at least one of the devices in the platform.</td>
</tr>
<tr>
<td>CL_DEVICE_EXTERNAL_MEMORY_IMPORT_ASSUME_LINEAR_IMAGES_HANDLE_TYPES_KHR provided by the cl_khr_external_memory extension.</td>
<td>cl_external_memory_handle_type_khr[]</td>
<td>Returns the list of importable external memory handle types supported by device, that are assumed to apply linear layout to imported images when no other tiling information is provided. This list contains a subset of CL_DEVICE_EXTERNAL_MEMORY_IMPORT_HANDLE_TYPES_KHR. The returned list may be empty. External memory handle types not in CL_DEVICE_EXTERNAL_MEMORY_IMPORT_ASSUME_LINEAR_IMAGES_HANDLE_TYPES_KHR may have any memory layout. The layout interpretation of images imported with these handle types is implementation defined.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>---------------------------------</td>
<td>-------------------</td>
<td>---------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_DEVICE_HALF_FP_CONFIG</td>
<td>cl_device_fp_config</td>
<td>Describes half-precision floating-point capability of the OpenCL device. This is a bit-field that describes one or more of the following values:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_FP_DENORM - denoms are supported</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_FP_INF_NAN - INF and NaNs are supported</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_FP_ROUND_TO_NEAREST - round to nearest even rounding mode supported</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_FP_ROUND_TO_ZERO - round to zero rounding mode supported</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_FP_ROUND_TO_INF - round to positive and negative infinity rounding modes supported</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_FP_FMA - IEEE754-2008 fused multiply-add is supported</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_FP_SOFT_FLOAT - Basic floating-point operations (such as addition, subtraction, multiplication) are implemented in software</td>
</tr>
<tr>
<td></td>
<td></td>
<td>If half-precision is supported by the device, then the minimum half-precision floating-point capability for OpenCL 2.0 or newer devices is:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_FP_ROUND_TO_ZERO</td>
</tr>
<tr>
<td></td>
<td></td>
<td>or</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_FP_ROUND_TO_NEAREST</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>-------------------------------------------------</td>
<td>--------------------------------------------------</td>
<td>---------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td><strong>CL_DEVICE_INTEGER_DOT_PRODUCT_CAPABILITIES_KHR</strong> provided by the cl_khr_integer_dot_product extension.</td>
<td><strong>cl_device_integer_dot_product_capabilities_khr</strong></td>
<td>Returns the integer dot product capabilities supported by the device. <strong>CL_DEVICE_INTEGER_DOT_PRODUCT_INPUT_4x8BIT_PACKED_KHR</strong> is always set, indicating that all implementations that support <strong>cl_khr_integer_dot_product</strong> must support dot product built-in functions and, when SPIR-V is supported, SPIR-V instructions that take four-component vectors of 8-bit integers packed into 32-bit integers as input. <strong>CL_DEVICE_INTEGER_DOT_PRODUCT_INPUT_4x8BIT_KHR</strong> is set when dot product built-in functions and, when SPIR-V is supported, SPIR-V instructions that take four-component of 8-bit elements as input are supported. <strong>NOTE:</strong> <strong>CLDEVICEINTEGERDOTPRODUCTINPUT4X8BIT_KHR</strong> must be set in version 2.x of the extension.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_INTEGER_DOT_PRODUCT_ACCELERATION_PROPERTIES_8BIT_KHR</strong> provided by the cl_khr_integer_dot_product extension.</td>
<td><strong>cl_device_integer_dot_product_acceleration_properties_khr</strong></td>
<td>Returns a structure describing the exact 8-bit dot product combinations that are accelerated on the device. Each member is <strong>CL_TRUE</strong> if the combination it corresponds to is accelerated, <strong>CL_FALSE</strong> otherwise. <strong>NOTE:</strong> <strong>CLDEVICEINTEGERDOTPRODUCTACCELERATIONPROPERTIES8BIT_KHR</strong> is missing before version 2.0 of the extension.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_INTEGER_DOT_PRODUCT_ACCELERATION_PROPERTIES_4x8BIT_PACKED_KHR</strong> provided by the cl_khr_integer_dot_product extension.</td>
<td><strong>cl_device_integer_dot_product_acceleration_properties_khr</strong></td>
<td>Returns a structure describing the exact 4x8-bit packed dot product combinations that are accelerated on the device. Each member is <strong>CL_TRUE</strong> if the combination it corresponds to is accelerated, <strong>CL_FALSE</strong> otherwise. <strong>NOTE:</strong> <strong>CLDEVICEINTEGERDOTPRODUCTACCELERATIONPROPERTIES4X8BIT_PACKED_KHR</strong> is missing before version 2.0 of the extension.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>-------------</td>
<td>-------------</td>
<td>-------------</td>
</tr>
<tr>
<td><strong>CL_DEVICE_KERNEL_CLOCK_CAPABILITIES_KHR</strong> provided by the <code>cl_khr_kernel_clock</code> extension.</td>
<td>cl_device_kernel_clock_capabilities_khr</td>
<td>Returns the kernel clock capabilities of the device.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_DEVICE_KERNEL_CLOCK_SCOPE_DEVICE_KHR</strong> is set when kernels are allowed to call the <code>clock_read_device</code> and <code>clock_read_hilo_device</code> OpenCL-C functions.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_DEVICE_KERNEL_CLOCK_SCOPE_WORK_GROUP_KHR</strong> is set when kernels are allowed to call the <code>clock_read_work_group</code> and <code>clock_read_hilo_work_group</code> OpenCL-C functions.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_DEVICE_KERNEL_CLOCK_SCOPE_SUB_GROUP_KHR</strong> is set when kernels are allowed to call the <code>clock_read_sub_group</code> and <code>clock_read_hilo_sub_group</code> OpenCL-C functions.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_PCI_BUS_INFO_KHR</strong> provided by the <code>cl_khr_pci_bus_info</code> extension.</td>
<td>cl_device_pci_bus_info_khr</td>
<td>Returns PCI bus information for the device.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The PCI bus information is returned as a single structure that includes the PCI bus domain, the PCI bus identifier, the PCI device identifier, and the PCI device function identifier.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_SEMAPHORE_TYPES_KHR</strong> provided by the <code>cl_khr_semaphore</code> extension.</td>
<td>cl_semaphore_type_khr[]</td>
<td>Returns the list of the semaphore types supported by <code>device</code>.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Must return a non-empty list for at least one of the devices in the platform, meeting the minimum requirements described for <code>cl_semaphore_type_khr</code>.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_SEMAPHORE_IMPORT_HANDLE_TYPES_KHR</strong> provided by the <code>cl_khr_external_semaphore</code> extension.</td>
<td>cl_external_semaphore_handle_type_khr[]</td>
<td>Returns the list of importable external semaphore handle types supported by <code>device</code>.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>This size of this query may be 0 indicating that the device does not support importing semaphores.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_SEMAPHORE_EXPORT_HANDLE_TYPES_KHR</strong> provided by the <code>cl_khr_external_semaphore</code> extension.</td>
<td>cl_external_semaphore_handle_type_khr[]</td>
<td>Returns the list of exportable external semaphore handle types supported by <code>device</code>.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>This size of this query may be 0 indicating that the device does not support exporting semaphores.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>-------------------------------------------------</td>
<td>-------------</td>
<td>-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td><strong>CL_DEVICE_SPIR_VERSIONS</strong></td>
<td>char[]</td>
<td>A space separated list of SPIR versions supported by the device.</td>
</tr>
<tr>
<td>provided by the cl_khr_spir extension.</td>
<td></td>
<td>For example, returning &quot;1.2&quot; in this query implies that SPIR version 1.2 is supported by the implementation.</td>
</tr>
<tr>
<td><strong>CL_DEVICE_MAX_NAMED_BARRIER_COUNT_KHR</strong></td>
<td>cl_uint</td>
<td>Maximum number of named barriers in a work-group for any given kernel-instance running on the device. The minimum value is 8.</td>
</tr>
<tr>
<td>provided by the cl_khr_subgroup_named_barrier extension.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>CL_DEVICE_TERMINATE_CAPABILITY_KHR</strong></td>
<td>cl_device_terminate_capability_khr</td>
<td>Describes the termination capability of the OpenCL device. This is a bit-field, where the following values are currently supported: CL_DEVICE_TERMINATE_CAPABILITY_CONTEXT_KHR - Indicates that context termination is supported.</td>
</tr>
<tr>
<td>provided by the cl_khrTerminateContext extension.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

OpenCL 3 devices must report the following feature macros via **CL_DEVICE_OPENCL_C_FEATURES** when the corresponding bit is set in the bitfield returned for **CL_DEVICE_INTEGER_DOT_PRODUCT_CAPABILITIES_KHR**:

<table>
<thead>
<tr>
<th>Feature Bit</th>
<th>Feature Macro</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>CL_DEVICE_INTEGER_DOT_PRODUCT_INPUT_4x8BIT_PACKED_KHR</strong></td>
<td>__opencl_c_integer_dot_product_input_4x8bit_packed</td>
</tr>
<tr>
<td><strong>CL_DEVICE_INTEGER_DOT_PRODUCT_INPUT_4x8BIT_KHR</strong></td>
<td>__opencl_c_integer_dot_product_input_4x8bit</td>
</tr>
</tbody>
</table>

OpenCL 3 devices must report the following feature macros via **CL_DEVICE_OPENCL_C_FEATURES** when the corresponding bit is set in the bitfield returned for **CL_DEVICE_KERNEL_CLOCK_CAPABILITIES_KHR**:

<table>
<thead>
<tr>
<th>Feature Bit</th>
<th>Feature Macro</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>CL_DEVICE_KERNEL_CLOCK_SCOPE_DEVICE_KHR</strong></td>
<td>__opencl_c_kernel_clock_scope_device</td>
</tr>
<tr>
<td><strong>CL_DEVICE_KERNEL_CLOCK_SCOPE_WORK_GROUP_KHR</strong></td>
<td>__opencl_c_kernel_clock_scope_work_group</td>
</tr>
<tr>
<td><strong>CL_DEVICE_KERNEL_CLOCK_SCOPE_SUB_GROUP_KHR</strong></td>
<td>__opencl_c_kernel_clock_scope_sub_group</td>
</tr>
</tbody>
</table>

One of the two queries **CL_DEVICE_SEMAPHORE_IMPORT_HANDLE_TYPES_KHR** and **CL_DEVICE_SEMAPHORE_EXPORT_HANDLE_TYPES_KHR** must return a non-empty list indicating support for at least one of the valid semaphore handle types either for import, for export, or both.

**Note**
While **CL_DEVICE_UUID_KHR** is specified to remain consistent across driver versions and system reboots, it is not intended to be usable as a serializable persistent identifier for a device. It may change when a device is physically added to,
removed from, or moved to a different connector in a system while that system is
powered down. Further, there is no reasonable way to verify with conformance
testing that a given device retains the same UUID in a given system across all
driver versions supported in that system. While implementations should make
every effort to report consistent device UUIDs across driver versions, applications
should avoid relying on the persistence of this value for uses other than
identifying compatible devices for external object sharing purposes.

clGetDeviceInfo returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns
one of the following errors:

- CL_INVALID_DEVICE if device is not a valid device.
- CL_INVALID_VALUE if param_name is not one of the supported values or if size in bytes specified
  by param_value_size is < size of return type as specified in the Device Queries table and
  param_value is not a NULL value or if param_name is a value that is available as an extension and
  the corresponding extension is not supported by the device.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL
  implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL
  implementation on the host.

The cl_device_integer_dot_product_acceleration_properties_khr structure describes the exact dot
product operations that are accelerated on the device:

// Provided by cl_khr_integer_dot_product
typedef struct cl_device_integer_dot_product_acceleration_properties_khr {
    cl_bool signed_accelerated;
    cl_bool unsigned_accelerated;
    cl_bool mixed_signedness_accelerated;
    cl_bool accumulating_saturating_signed_accelerated;
    cl_bool accumulating_saturating_unsigned_accelerated;
    cl_bool accumulating_saturating_mixed_signedness_accelerated;
} cl_device_integer_dot_product_acceleration_properties_khr;

- signed_accelerated is CL_TRUE when signed dot product operations are accelerated, CL_FALSE
  otherwise.
- unsigned_accelerated is CL_TRUE when unsigned dot product operations are accelerated, CL_FALSE
  otherwise.
- mixed_signedness_accelerated is CL_TRUE when mixed signedness dot product operations are
  accelerated, CL_FALSE otherwise.
- accumulating_saturating_signed_accelerated is CL_TRUE when accumulating saturating signed dot
  product operations are accelerated, CL_FALSE otherwise.
- accumulating_saturating_unsigned_accelerated is CL_TRUE when accumulating saturating
  unsigned dot product operations are accelerated, CL_FALSE otherwise.
- accumulating_saturating_mixed_signedness_accelerated is CL_TRUE when accumulating saturating
mixed signedness dot product operations are accelerated, \texttt{CL\_FALSE} otherwise.

A dot product operation is deemed accelerated if its implementation provides a performance advantage over application-provided code composed from elementary instructions and/or other dot product instructions, either because the implementation uses optimized machine code sequences whose generation from application-provided code cannot be guaranteed or because it uses hardware features that cannot otherwise be targeted from application-provided code.

The \texttt{cl\_device\_pci\_bus\_info\_khr} structure describes PCI bus information for a device:

```c
// Provided by cl\_khr\_pci\_bus\_info
typedef struct cl\_device\_pci\_bus\_info\_khr {
    cl\_uint pci\_domain;
    cl\_uint pci\_bus;
    cl\_uint pci\_device;
    cl\_uint pci\_function;
} cl\_device\_pci\_bus\_info\_khr;
```

- \textit{pci\_domain} is the PCI bus domain of the device.
- \textit{pci\_bus} is the PCI bus identified of the device.
- \textit{pci\_device} is the PCI device identifier of the device.
- \textit{pci\_function} is the PCI device function identifier of the device.

To query device and host timestamps, call the function:

```c
// Provided by CL\_VERSION\_2\_1
c\_int cl\_GetDeviceAndHostTimer(
    cl\_device\_id device,
    cl\_ulong* device\_timestamp,
    cl\_ulong* host\_timestamp);
```

\textbf{⚠️} \texttt{cl\_GetDeviceAndHostTimer} is missing before version 2.1.

- \textit{device} is a device returned by \texttt{cl\_GetDevice\_IDs}.
- \textit{device\_timestamp} will be updated with the value of the device timer in nanoseconds. The resolution of the timer is the same as the device profiling timer returned by \texttt{cl\_GetDevice\_Info} and the \texttt{CL\_DEVICE\_PROFILING\_TIMER\_RESOLUTION} query.
- \textit{host\_timestamp} will be updated with the value of the host timer in nanoseconds at the closest possible point in time to that at which \textit{device\_timestamp} was returned. The resolution of the timer may be queried via \texttt{cl\_GetPlatform\_Info} and the flag \texttt{CL\_PLATFORM\_HOST\_TIMER\_RESOLUTION}.

\texttt{cl\_GetDeviceAndHostTimer} returns a reasonably synchronized pair of timestamps from the device timer and the host timer as seen by \textit{device}. Implementations may need to execute this query with a high latency in order to provide reasonable synchronization of the timestamps. The host timestamp and device timestamp returned by this function and \texttt{cl\_GetHost\_Timer} each have an
implementation-defined timebase. The timestamps will always be in their respective timebases regardless of which query function is used. The timestamp returned from `clGetEventProfilingInfo` for an event on a device and a device timestamp queried from the same device will always be in the same timebase.

`clGetDeviceAndHostTimer` will return `CL_SUCCESS` with a time value in `host_timestamp` if provided. Otherwise, it returns one of the following errors:

- `CL_INVALID_DEVICE` if `device` is not a valid device.
- `CL_INVALID_OPERATION` if the platform associated with `device` does not support device and host timer synchronization.
- `CL_INVALID_VALUE` if `host_timestamp` or `device_timestamp` is NULL.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

To query the host clock, call the function:

```
// Provided by CL_VERSION_2_1
cl_int clGetHostTimer(
    cl_device_id device,
    cl_ulong* host_timestamp);
```

`clGetHostTimer` is missing before version 2.1.

- `device` is a device returned by `clGetDeviceIDs`.
- `host_timestamp` will be updated with the value of the current timer in nanoseconds. The resolution of the timer may be queried via `clGetPlatformInfo` and the flag `CL_PLATFORM_HOST_TIMER_RESOLUTION`.

`clGetHostTimer` returns the current value of the host clock as seen by `device`. This value is in the same timebase as the `host_timestamp` returned from `clGetDeviceAndHostTimer`. The implementation will return with as low a latency as possible to allow a correlation with a subsequent application sampled time. The host timestamp and device timestamp returned by this function and `clGetDeviceAndHostTimer` each have an implementation-defined timebase. The timestamps will always be in their respective timebases regardless of which query function is used. The timestamp returned from `clGetEventProfilingInfo` for an event on a device and a device timestamp queried from the same device will always be in the same timebase.

`clGetHostTimer` will return `CL_SUCCESS` with a time value in `host_timestamp` if provided. Otherwise, it returns one of the following errors:

- `CL_INVALID_DEVICE` if `device` is not a valid device.
- `CL_INVALID_OPERATION` if the platform associated with `device` does not support device and host timer synchronization.
• **CL_INVALID_VALUE** if `host_timestamp` is NULL.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 4.2.1. Sharing DirectX9 Media Surfaces With OpenCL Images

This section discusses OpenCL functions that allow applications to use media surfaces as OpenCL memory objects. This allows efficient sharing of data between OpenCL and media surface APIs. The OpenCL API may be used to execute kernels that read and/or write memory objects that are also media surfaces. An OpenCL image object may be created from a media surface. OpenCL memory objects may be created from media surfaces if and only if the OpenCL context has been created from a media adapter.

#### 4.2.1.1. Querying OpenCL Devices Corresponding to Media Adapters

Media adapters are an abstraction associated with devices that provide media capabilities. Adapters with associated OpenCL devices can enable media surface sharing between the two.

To query a media adapter for any associated OpenCL devices, call the function

```c
// Provided by cl_khr_dx9_media_sharing
cl_int clGetDeviceIDsFromDX9MediaAdapterKHR(
    cl_platform_id platform,
    cl_uint num_media_adapters,
    cl_dx9_media_adapter_type_khr* media_adapter_type,
    void* media_adapters,
    cl_dx9_media_adapter_set_khr media_adapter_set,
    cl_uint num_entries,
    cl_device_id* devices,
    cl_uint* num_devices);
```

- **clGetDeviceIDsFromDX9MediaAdapterKHR** is provided by the `cl_khr_dx9_media_sharing` extension.

- `platform` refers to the platform ID returned by `clGetPlatformIDs`.

- `num_media_adapters` specifies the number of media adapters.

- `media_adapter_type` is an array of `num_media_adapters` entries. Each entry specifies the type of media adapter and must be one of the values described in the **media adapter type table** below.

- `media_adapters` is an array of `num_media_adapters` entries. Each entry specifies the actual adapter whose type is specified by `media_adapter_type`. The `media_adapters` must be one of the types described in the **cl_dx9_media_adapter_type_khr values** table.

- `media_adapter_set` specifies the set of adapters to return and must be one of the values described in the **cl_dx9_media_adapter_set_khr values** table.
- `num_entries` is the number of `cl_device_id` entries that can be added to `devices`. If `devices` is not `NULL`, the `num_entries` must be greater than zero.

- `devices` returns a list of OpenCL devices found that support the list of media adapters specified. The `cl_device_id` values returned in `devices` can be used to identify a specific OpenCL device. If `devices` argument is `NULL`, this argument is ignored. The number of OpenCL devices returned is the minimum of the value specified by `num_entries` or the number of OpenCL devices whose type matches `device_type`.

- `num_devices` returns the number of OpenCL devices. If `num_devices` is `NULL`, this argument is ignored.

Table 6. DirectX 9 object types that may be used by `clGetDeviceIDsFromDX9MediaAdapterKHR`

<table>
<thead>
<tr>
<th>cl_dx9_media_adapter_type_khr</th>
<th>Type of Media Adapter</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>CL_ADAPTER_D3D9_KHR</code></td>
<td>provided by the cl_khr_dx9_media_sharing extension.</td>
</tr>
<tr>
<td><code>CL_ADAPTER_D3D9EX_KHR</code></td>
<td>provided by the cl_khr_dx9_media_sharing extension.</td>
</tr>
<tr>
<td><code>CL_ADAPTER_DXVA_KHR</code></td>
<td>provided by the cl_khr_dx9_media_sharing extension.</td>
</tr>
</tbody>
</table>

Table 7. Sets of devices queriable using `clGetDeviceIDsFromDX9MediaAdapterKHR`

<table>
<thead>
<tr>
<th>cl_dx9_media_adapter_set_khr</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>CL_PREFERRED_DEVICES_FOR_DX9_MEDIA_ADAPTER_KHR</code></td>
<td>The preferred OpenCL devices associated with the media adapter.</td>
</tr>
<tr>
<td>provided by the cl_khr_dx9_media_sharing extension.</td>
<td></td>
</tr>
<tr>
<td><code>CL_ALL_DEVICES_FOR_DX9.MEDIA_ADAPTER_KHR</code></td>
<td>All OpenCL devices that may interoperate with the media adapter.</td>
</tr>
<tr>
<td>provided by the cl_khr_dx9_media_sharing extension.</td>
<td></td>
</tr>
</tbody>
</table>

`clGetDeviceIDsFromDX9MediaAdapterKHR` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_PLATFORM` if `platform` is not a valid platform.

- `CL_INVALID_VALUE` if `num_media_adapters` is zero or if `media_adapters_type` is `NULL` or if `media_adapters` is `NULL`.

- `CL_INVALID_VALUE` if any of the entries in `media_adapters_type` or `media_adapters` is not a valid value.
• **CL_INVALID_VALUE** if `media_adapter_set` is not a valid value.

• **CL_INVALID_VALUE** if `num_entries` is equal to zero and `devices` is not **NULL** or if both `num_devices` and `devices` are **NULL**.

• **CL_DEVICE_NOT_FOUND** if no OpenCL devices that correspond to adapters specified in `media_adapters` and `media_adapters_type` were found.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 4.2.2. Sharing Direct3D 10 Resources With OpenCL Memory Objects

This section discusses OpenCL functions that allow applications to use Direct3D 10 resources as OpenCL memory objects. This allows efficient sharing of data between OpenCL and Direct3D 10. The OpenCL API may be used to execute kernels that read and/or write memory objects that are also Direct3D 10 resources. An OpenCL image object may be created from a Direct3D 10 texture resource. An OpenCL buffer object may be created from a Direct3D 10 buffer resource. OpenCL memory objects may be created from Direct3D 10 objects if and only if the OpenCL context has been created from a Direct3D 10 device.

#### 4.2.2.1. Querying OpenCL Devices Corresponding to Direct3D 10 Devices

The OpenCL devices corresponding to a Direct3D 10 device may be queried. The OpenCL devices corresponding to a DXGI adapter may also be queried. The OpenCL devices corresponding to a Direct3D 10 device will be a subset of the OpenCL devices corresponding to the DXGI adapter against which the Direct3D 10 device was created.

To query OpenCL devices corresponding to a Direct3D 10 device or a DXGI device, call the function

```c
// Provided by cl_khr_d3d10_sharing
cl_int clGetDeviceIDsFromD3D10KHR(
    cl_platform_id platform,
    cl_d3d10_device_source_khr d3d_device_source,
    void* d3d_object,
    cl_d3d10_device_set_khr d3d_device_set,
    cl_uint num_entries,
    cl_device_id* devices,
    cl_uint* num_devices);
```

- **platform** refers to the platform ID returned by `clGetPlatformIDs`.

- **d3d_device_source** specifies the type of `d3d_object`, and must be one of the values shown in the Direct3D 10 object types that may be used by `clGetDeviceIDsFromD3D10KHR` table.
• d3d_object specifies the object whose corresponding OpenCL devices are being queried. The type of d3d_object must be as specified in the Direct3D 10 object types that may be used by clGetDeviceIDsFromD3D10KHR table.

• d3d_device_set specifies the set of devices to return, and must be one of the values shown in the Sets of devices queriable using clGetDeviceIDsFromD3D10KHR table.

• num_entries is the number of cl_device_id entries that can be added to devices. If devices is not NULL then num_entries must be greater than zero.

• devices returns a list of OpenCL devices found. The cl_device_id values returned in devices can be used to identify a specific OpenCL device. If devices is NULL, this argument is ignored. The number of OpenCL devices returned is the minimum of the value specified by num_entries and the number of OpenCL devices corresponding to d3d_object.

• num_devices returns the number of OpenCL devices available that correspond to d3d_object. If num_devices is NULL, this argument is ignored.

Table 8. Direct3D 10 object types that may be used by clGetDeviceIDsFromD3D10KHR

<table>
<thead>
<tr>
<th>cl_d3d10_device_source_khr</th>
<th>Type of d3d_object</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_D3D10_DEVICE_KHR</td>
<td>ID3D10Device *</td>
</tr>
<tr>
<td>provided by the cl_khr_d3d10_sharing extension.</td>
<td></td>
</tr>
<tr>
<td>CL_D3D10_DXGI_ADAPTER_KHR</td>
<td>IDXGIAPIDevice *</td>
</tr>
<tr>
<td>provided by the cl_khr_d3d10_sharing extension.</td>
<td></td>
</tr>
</tbody>
</table>

Table 9. Sets of devices queriable using clGetDeviceIDsFromD3D10KHR

<table>
<thead>
<tr>
<th>cl_d3d10_device_set_khr</th>
<th>Devices returned in devices</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_PREFERRED_DEVICES_FOR_D3D10_KHR</td>
<td>The preferred OpenCL devices associated with the specified Direct3D object.</td>
</tr>
<tr>
<td>provided by the cl_khr_d3d10_sharing extension.</td>
<td></td>
</tr>
<tr>
<td>CL_ALL_DEVICES_FOR_D3D10_KHR</td>
<td>All OpenCL devices which may interoperate with the specified Direct3D object. Performance of sharing data on these devices may be considerably less than on the preferred devices.</td>
</tr>
<tr>
<td>provided by the cl_khr_d3d10_sharing extension.</td>
<td></td>
</tr>
</tbody>
</table>

clGetDeviceIDsFromD3D10KHR returns CL_SUCCESS if the function is executed successfully. Otherwise it may return

• CL_INVALID_PLATFORM if platform is not a valid platform.

• CL_INVALID_VALUE if d3d_device_source is not a valid value, d3d_device_set is not a valid value, num_entries is equal to zero and devices is not NULL, or if both num_devices and devices are NULL.

• CL_DEVICE_NOT_FOUND if no OpenCL devices that correspond to d3d_object were found.
4.2.3. Sharing Direct3D 11 Resources With OpenCL Memory Objects

This section discusses OpenCL functions that allow applications to use Direct3D 11 resources as OpenCL memory objects. This allows efficient sharing of data between OpenCL and Direct3D 11. The OpenCL API may be used to execute kernels that read and/or write memory objects that are also Direct3D 11 resources. An OpenCL image object may be created from a Direct3D 11 texture resource. An OpenCL buffer object may be created from a Direct3D 11 buffer resource. OpenCL memory objects may be created from Direct3D 11 objects if and only if the OpenCL context has been created from a Direct3D 11 device.

4.2.3.1. Querying OpenCL Devices Corresponding to Direct3D 11 Devices

The OpenCL devices corresponding to a Direct3D 11 device may be queried. The OpenCL devices corresponding to a DXGI adapter may also be queried. The OpenCL devices corresponding to a Direct3D 11 device will be a subset of the OpenCL devices corresponding to the DXGI adapter against which the Direct3D 11 device was created.

To query OpenCL devices corresponding to a Direct3D 11 device or a DXGI device, call the function

```c
// Provided by cl_khr_d3d11_sharing
cl_int clGetDeviceIDsFromD3D11KHR(
    cl_platform_id platform,
    cl_d3d11_device_source_khr d3d_device_source,
    void* d3d_object,
    cl_d3d11_device_set_khr d3d_device_set,
    cl_uint num_entries,
    cl_device_id* devices,
    cl_uint* num_devices);
```

- `platform` refers to the platform ID returned by `clGetPlatformIDs`.
- `d3d_device_source` specifies the type of `d3d_object`, and must be one of the values shown in the Direct3D 11 object types that may be used by `clGetDeviceIDsFromD3D11KHR` table.
- `d3d_object` specifies the object whose corresponding OpenCL devices are being queried. The type of `d3d_object` must be as specified in the Direct3D 11 object types that may be used by `clGetDeviceIDsFromD3D11KHR` table.
- `d3d_device_set` specifies the set of devices to return, and must be one of the values shown in the Sets of devices queriable using `clGetDeviceIDsFromD3D11KHR` table.
- `num_entries` is the number of `cl_device_id` entries that can be added to `devices`. If `devices` is not `NULL` then `num_entries` must be greater than zero.
- `devices` returns a list of OpenCL devices found. The `cl_device_id` values returned in `devices` can be used to identify a specific OpenCL device. If `devices` is `NULL`, this argument is ignored. The number of OpenCL devices returned is the minimum of the value specified by `num_entries` and the number of OpenCL devices corresponding to `d3d_object`. 
• `num_devices` returns the number of OpenCL devices available that correspond to `d3d_object`. If `num_devices` is `NULL`, this argument is ignored.

### Table 10. Direct3D 11 object types that may be used by `clGetDeviceIDsFromD3D11KHR`

<table>
<thead>
<tr>
<th>cl_d3d11_device_source_khr</th>
<th>Type of <code>d3d_object</code></th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_D3D11_DEVICE_KHR</td>
<td>ID3D11Device *</td>
</tr>
<tr>
<td>provided by the <code>cl_khr_d3d11_sharing</code> extension.</td>
<td></td>
</tr>
<tr>
<td>CL_D3D11_DXGI_ADAPTER_KHR</td>
<td>IDXGIAdapter *</td>
</tr>
<tr>
<td>provided by the <code>cl_khr_d3d11_sharing</code> extension.</td>
<td></td>
</tr>
</tbody>
</table>

### Table 11. Sets of devices queriable using `clGetDeviceIDsFromD3D11KHR`

<table>
<thead>
<tr>
<th>cl_d3d11_device_set_khr</th>
<th>Devices returned in <code>devices</code></th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_PREFERRED_DEVICES_FOR_D3D11_KHR</td>
<td>The preferred OpenCL devices associated with the specified Direct3D object.</td>
</tr>
<tr>
<td>provided by the <code>cl_khr_d3d11_sharing</code> extension.</td>
<td></td>
</tr>
<tr>
<td>CL_ALL_DEVICES_FOR_D3D11_KHR</td>
<td>All OpenCL devices which may interoperate with the specified Direct3D object. Performance of sharing data on these devices may be considerably less than on the preferred devices.</td>
</tr>
<tr>
<td>provided by the <code>cl_khr_d3d11_sharing</code> extension.</td>
<td></td>
</tr>
</tbody>
</table>

`clGetDeviceIDsFromD3D11KHR` returns `CL_SUCCESS` if the function is executed successfully. Otherwise it may return

- `CL_INVALID_PLATFORM` if `platform` is not a valid platform.
- `CL_INVALID_VALUE` if `d3d_device_source` is not a valid value, `d3d_device_set` is not a valid value, `num_entries` is equal to zero and `devices` is not `NULL`, or if both `num_devices` and `devices` are `NULL`.
- `CL_DEVICE_NOT_FOUND` if no OpenCL devices that correspond to `d3d_object` were found.

### 4.3. Partitioning a Device

Partitioning devices is missing before version 1.2.

To create sub-devices partitioning an OpenCL device, call the function:

```c
// Provided by CL_VERSION_1_2
cl_int clCreateSubDevices(
    cl_device_id in_device,
    const cl_device_partition_property* properties,
    cl_uint num_devices,
    cl_device_id* out_devices,
    cl_uint* num_devices_ret);
```
clCreateSubDevices is missing before version 1.2.

- **in_device** is the device to be partitioned.

- **properties** specifies how **in_device** is to be partitioned, described by a partition name and its corresponding value. Each partition name is immediately followed by the corresponding desired value. The list is terminated with 0. The list of supported partitioning schemes is described in the **Sub-device Partition** table. Only one of the listed partitioning schemes can be specified in **properties**.

- **num_devices** is the size of memory pointed to by **out_devices** specified as the number of **cl_device_id** entries.

- **out_devices** is the buffer where the OpenCL sub-devices will be returned. If **out_devices** is **NULL**, this argument is ignored. If **out_devices** is not **NULL**, **num_devices** must be greater than or equal to the number of sub-devices that **device** may be partitioned into according to the partitioning scheme specified in **properties**.

- **num_devices_ret** returns the number of sub-devices that **device** may be partitioned into according to the partitioning scheme specified in **properties**. If **num_devices_ret** is **NULL**, it is ignored.

**clCreateSubDevices** creates an array of sub-devices that each reference a non-intersecting set of compute units within **in_device**, according to the partition scheme given by **properties**. The output sub-devices may be used in every way that the root (or parent) device can be used, including creating contexts, building programs, further calls to **clCreateSubDevices** and creating command-queues. When a command-queue is created against a sub-device, the commands enqueued on the queue are executed only on the sub-device.

### Table 12. List of supported partition schemes by clCreateSubDevices

<table>
<thead>
<tr>
<th>Partition Property</th>
<th>Partition Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_DEVICE_PARTITION_EQUIVLY</td>
<td>cl_uint</td>
<td>Split the aggregate device into as many smaller aggregate devices as can be created, each containing ( n ) compute units. The value ( n ) is passed as the value accompanying this property. If ( n ) does not divide evenly into <strong>CL_DEVICE_MAX_COMPUTES_UNITS</strong>, then the remaining compute units are not used.</td>
</tr>
</tbody>
</table>

**missing before** version 1.2.
<table>
<thead>
<tr>
<th>Partition Property</th>
<th>Partition Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>CL_DEVICE_PARTITION_BY_COUNTS</strong></td>
<td>cl_uint</td>
<td>This property is followed by a list of compute unit counts terminated with 0 or <strong>CL_DEVICE_PARTITION_BY_COUNTS_LIST_END</strong>. For each non-zero count ( m ) in the list, a sub-device is created with ( m ) compute units in it.</td>
</tr>
<tr>
<td><strong>missing before</strong> version 1.2.</td>
<td></td>
<td>The number of non-zero count entries in the list may not exceed <strong>CL_DEVICE_PARTITION_MAX_SUB_DEVICES</strong>.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The total number of compute units specified may not exceed <strong>CL_DEVICE_MAX_COMPUTE_UNITS</strong>.</td>
</tr>
<tr>
<td>Partition Property</td>
<td>Partition Value</td>
<td>Description</td>
</tr>
<tr>
<td>--------------------------------------------------</td>
<td>-----------------------------</td>
<td>---------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_DEVICE_PARTITION_BY_AFFINITY_DOMAIN</td>
<td>cl_device_affinity_domain</td>
<td>Split the device into smaller aggregate devices containing one or more compute units that all share part of a cache hierarchy. The value accompanying this property may be drawn from the following list:</td>
</tr>
<tr>
<td>missing before version 1.2.</td>
<td></td>
<td><strong>CL_DEVICE_AFFINITY_DOMAIN_NUMA</strong> - Split the device into sub-devices comprised of compute units that share a NUMA node.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_DEVICE_AFFINITY_DOMAIN_L4_CACHE</strong> - Split the device into sub-devices comprised of compute units that share a level 4 data cache.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_DEVICE_AFFINITY_DOMAIN_L3_CACHE</strong> - Split the device into sub-devices comprised of compute units that share a level 3 data cache.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_DEVICE_AFFINITY_DOMAIN_L2_CACHE</strong> - Split the device into sub-devices comprised of compute units that share a level 2 data cache.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_DEVICE_AFFINITY_DOMAIN_L1_CACHE</strong> - Split the device into sub-devices comprised of compute units that share a level 1 data cache.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_DEVICE_AFFINITY_DOMAIN_NEXT_PARTITIONABLE</strong> - Split the device along the next partitionable affinity domain. The implementation shall find the first level along which the device or sub-device may be further subdivided in the order NUMA, L4, L3, L2, L1, and partition the device into sub-devices comprised of compute units that share memory subsystems at this level.</td>
</tr>
</tbody>
</table>

The user may determine what happened by calling `clGetDeviceInfo(CL DEVICE_PARTITION_TYPE)` on the sub-devices.

`clCreateSubDevices` returns `CL_SUCCESS` if the partition is created successfully. Otherwise, it returns a `NULL` value with the following error values returned in `errcode_ret`:

- **CL_INVALID_DEVICE** if `in_device` is not a valid device.
- **CL_INVALID_VALUE** if values specified in `properties` are not valid or if values specified in `properties` are valid but not supported by the device.
• **CL_INVALID_VALUE** if `out_devices` is not **NULL** and `num_devices` is less than the number of sub-devices created by the partition scheme.

• **CL_DEVICE_PARTITION_FAILED** if the partition name is supported by the implementation but `in_device` could not be further partitioned.

• **CL_INVALID_DEVICE_PARTITION_COUNT** if the partition name specified in `properties` is **CL_DEVICE_PARTITION_BY_COUNTS** and the number of sub-devices requested exceeds **CL_DEVICE_PARTITION_MAX_SUB_DEVICES** or the total number of compute units requested exceeds **CL_DEVICE_MAX_COMPUTE_UNITS** for `in_device`, or the number of compute units requested for one or more sub-devices is less than zero or the number of sub-devices requested exceeds **CL_DEVICE_MAX_COMPUTE_UNITS** for `in_device`.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

A few examples that describe how to specify partition properties in `properties` argument to `clCreateSubDevices` are given below:

To partition a device containing 16 compute units into two sub-devices, each containing 8 compute units, pass the following in `properties`:

```c
{ CL_DEVICE_PARTITION_EQUALLY, 8, 0 } // 0 terminates the property list
```

To partition a device with four compute units into two sub-devices with one sub-device containing 3 compute units and the other sub-device 1 compute unit, pass the following in `properties` argument:

```c
{ CL_DEVICE_PARTITION_BY_COUNTS, 3, 1, CL_DEVICE_PARTITION_BY_COUNTS_LIST_END, 0 } // 0 terminates the property list
```

To split a device along the outermost cache line (if any), pass the following in `properties` argument:

```c
{ CL_DEVICE_PARTITION_BY_AFFINITY_DOMAIN, CL_DEVICE_AFFINITY_DOMAIN_NEXT_PARTITIONABLE, 0 } // 0 terminates the property list
```

To retain a device, call the function:

```c
// Provided by CL_VERSION_1_2
cl_int clRetainDevice(
    cl_device_id device);
```
**clRetainDevice** is missing before version 1.2.

- *device* is the OpenCL device to retain.

**clRetainDevice** increments the *device* reference count if *device* is a valid sub-device created by a call to **clCreateSubDevices**. If *device* is a root level device i.e. a **cl_device_id** returned by **clGetDeviceIDs**, the *device* reference count remains unchanged.

**clRetainDevice** returns **CL_SUCCESS** if the function is executed successfully or the device is a root-level device. Otherwise, it returns one of the following errors:

- **CL_INVALID_DEVICE** if *device* is not a valid device.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To release a device, call the function:

```c
// Provided by CL_VERSION_1_2
cl_int clReleaseDevice(
    cl_device_id device);
```

**clReleaseDevice** is missing before version 1.2.

- *device* is the OpenCL device to release.

**clReleaseDevice** decrements the *device* reference count if device is a valid sub-device created by a call to **clCreateSubDevices**. If *device* is a root level device i.e. a **cl_device_id** returned by **clGetDeviceIDs**, the *device* reference count remains unchanged.

**clReleaseDevice** returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_DEVICE** if *device* is not a valid device.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

After the *device* reference count becomes zero and all the objects attached to *device* (such as command-queues) are released, the *device* object is deleted. Using this function to release a reference that was not obtained by creating the object or by calling **clRetainDevice** causes undefined behavior.
4.4. Contexts

To create an OpenCL context, call the function:

```c
// Provided by CL_VERSION_1_0
cl_context clCreateContext(
    const cl_context_properties* properties,
    cl_uint num_devices,
    const cl_device_id* devices,
    void (CL_CALLBACK* pfn_notify)(const char* errinfo, const void* private_info,
    size_t cb, void* user_data),
    void* user_data,
    cl_int* errcode_ret);
```

- `properties` specifies a list of context property names and their corresponding values. Each property name is immediately followed by the corresponding desired value. The list is terminated with 0. The list of supported properties, and their default values if not present in `properties`, is described in the Context Properties table. `properties` can be NULL, in which case all properties take on their default values.

- `num_devices` is the number of devices specified in the `devices` argument.

- `devices` is a pointer to a list of unique devices returned by `clGetDeviceIDs` or sub-devices created by `clCreateSubDevices` for a platform. [10]

- `pfn_notify` is a callback function that can be registered by the application. This callback function will be used by the OpenCL implementation to report information on errors during context creation as well as errors that occur at runtime in this context. This callback function may be called asynchronously by the OpenCL implementation. It is the application’s responsibility to ensure that the callback function is thread-safe. If `pfn_notify` is NULL, no callback function is registered.

- `user_data` will be passed as the `user_data` argument when `pfn_notify` is called. `user_data` can be NULL.

- `errcode_ret` will return an appropriate error code. If `errcode_ret` is NULL, no error code is returned.

The parameters to the callback function `pfn_notify` are:

- `errinfo` is a pointer to an error string.

- `private_info` and `cb` represent a pointer to binary data that is returned by the OpenCL implementation that can be used to log additional information helpful in debugging the error.

- `user_data` is a pointer to user supplied data.

Contexts are used by the OpenCL runtime for managing objects such as command-queues, memory, program and kernel objects and for executing kernels on one or more devices specified in the context.

Table 13. List of supported context creation properties by `clCreateContext`
<table>
<thead>
<tr>
<th>Context Property</th>
<th>Property Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_CONTEXT_PLATFORM</td>
<td>cl_platform_id</td>
<td>Specifies the platform to use. Defaults to an implementation-defined platform if not specified.</td>
</tr>
<tr>
<td>CL_CONTEXT_INTEROP_USER_SYNC</td>
<td>cl_bool</td>
<td>Specifies whether the user is responsible for synchronization between OpenCL and other APIs. Please refer to the specific sections in the OpenCL Extension Specification that describe sharing with other APIs for restrictions on using this flag. Defaults to CL_FALSE if not specified.</td>
</tr>
<tr>
<td>CL_CONTEXT_ADAPTER_D3D9_KHR</td>
<td>IDirect3DDevice9 *</td>
<td>Specifies an IDirect3DDevice9 to use for D3D9 interop.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_dx9_media_sharing extension.</td>
</tr>
<tr>
<td>CL_CONTEXT_ADAPTER_D3D9EX_KHR</td>
<td>IDirect3DDeviceEx *</td>
<td>Specifies an IDirect3DDevice9Ex to use for D3D9 interop.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_dx9_media_sharing extension.</td>
</tr>
<tr>
<td>CL_CONTEXT_ADAPTER_DXVA_KHR</td>
<td>IDXVAHD_Device *</td>
<td>Specifies an IDXVAHD_Device to use for DXVA interop.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_dx9_media_sharing extension.</td>
</tr>
<tr>
<td>CL_CONTEXT_D3D10_DEVICE_KHR</td>
<td>ID3D10Device *</td>
<td>Specifies the ID3D10Device * to use for Direct3D 10 interoperability. The default value is NULL.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_d3d10_sharing extension.</td>
</tr>
<tr>
<td>CL_CONTEXT_D3D11_DEVICE_KHR</td>
<td>ID3D11Device *</td>
<td>Specifies the ID3D11Device * to use for Direct3D 11 interoperability. The default value is NULL.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_d3d11_sharing extension.</td>
</tr>
<tr>
<td>CL_GL_CONTEXT_KHR</td>
<td>OpenGL context handle</td>
<td>OpenGL context to associate the OpenCL context with. Defaults to 0 if not specified.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_glSharing extension.</td>
</tr>
<tr>
<td>CL_CGL_SHAREGROUP_KHR</td>
<td>CGL share group handle</td>
<td>CGL share group to associate the OpenCL context with. Defaults to 0 if not specified.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_glSharing extension.</td>
</tr>
</tbody>
</table>
Some of the properties specified in the **Context Properties** table control sharing of OpenCL memory objects with OpenGL buffer, texture, and renderbuffer objects.

Depending on the platform-specific API used to bind OpenGL contexts to the window system, the following properties may be set to identify an OpenGL context:

- When the CGL binding API is supported, the property **CL_CGL_SHAREGROUP_KHR** should be set to a CGLShareGroup handle to a CGL share group object.

- When the EGL binding API is supported, the property **CL_GL_CONTEXT_KHR** should be set to an EGLContext handle to an OpenGL ES or OpenGL context, and the property **CL_EGL_DISPLAY_KHR** should be set to the EGLDisplay handle of the display used to create the OpenGL ES or OpenGL context.

- When the GLX binding API is supported, the property **CL_GL_CONTEXT_KHR** should be set to a GLXContext handle to an OpenGL context, and the property **CL_GLX_DISPLAY_KHR** should be set to the Display handle of the X Window System display used to create the OpenGL context.

- When the WGL binding API is supported, the property **CL_GL_CONTEXT_KHR** should be set to an HGLRC handle to an OpenGL context, and the property **CL_WGL_HDC_KHR** should be set to the HDC.
handle of the display used to create the OpenGL context.

Memory objects created in the context so specified may be shared with the specified OpenGL or OpenGL ES context (as well as with any other OpenGL contexts on the share list of that context, according to the description of sharing in the GLX 1.4 and EGL 1.5 specifications, and the WGL documentation for OpenGL implementations on Microsoft Windows), or with the explicitly identified OpenGL share group for CGL. If no OpenGL or OpenGL ES context or share group is specified in the property list, then memory objects may not be shared, and attempts to create such objects will result in a CL_INVALID_GL_SHAREGROUP_REFERENCE_KHR error.

OpenCL / OpenGL sharing does not support the CL_CONTEXT_INTEROP_USER_SYNC property defined in the Context Properties table. Specifying this property when creating a context with OpenCL / OpenGL sharing will return an appropriate error.

There are a number of cases where error notifications need to be delivered due to an error that occurs outside a context. Such notifications may not be delivered through the pfn_notify callback. Where these notifications go is implementation-defined.

clCreateContext returns a valid non-zero context and errcode_ret is set to CL_SUCCESS if the context is created successfully. Otherwise, it returns a NULL value with the following error values returned in errcode_ret:

- CL_INVALID_PLATFORM if no platform is specified in properties and no platform could be selected, or if the platform specified in properties is not a valid platform.
- CL_INVALID_PROPERTY if a context property name in properties is not a supported property name, if the value specified for a supported property name is not valid, or if the same property name is specified more than once. This error code is missing before version 1.1.
- CL_INVALID_VALUE if devices is NULL.
- CL_INVALID_VALUE if num_devices is equal to zero.
- CL_INVALID_VALUE if pfn_notify is NULL but user_data is not NULL.
- CL_INVALID_DEVICE if any device in devices is not a valid device.
- CL_DEVICE_NOT_AVAILABLE if a device in devices is currently not available even though the device was returned by clGetDeviceIDs.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The following errors may be returned if the cl_khr_dx9_media_sharing extension is supported:

- CL_INVALID_DX9_MEDIA_ADAPTER_KHR if any of the values of the properties CL_CONTEXT_ADAPTER_D3D9_KHR, CL_CONTEXT_ADAPTER_D3D9EX_KHR or CL_CONTEXT_ADAPTER_DXVA_KHR is non-NULL and does not specify a valid media adapter with which the cl_device_ids against which this context is to be created may interoperate.
The following errors may be returned if the `cl_khr_d3d10_sharing` extension is supported:

- **CL_INVALID_D3D10_DEVICE_KHR** if the value of the property `CL_CONTEXT_D3D10_DEVICE_KHR` is non-NULL and does not specify a valid Direct3D 10 device with which the `cl_device_ids` against which this context is to be created may interoperate.

- **CL_INVALID_OPERATION** if Direct3D 10 interoperability is specified by setting `CL_INVALID_D3D10_DEVICE_KHR` to a non-NULL value, and interoperability with another graphics API is also specified.

The following errors may be returned if the `cl_khr_d3d11_sharing` extension is supported:

- **CL_INVALID_D3D11_DEVICE_KHR** if the value of the property `CL_CONTEXT_D3D11_DEVICE_KHR` is non-NULL and does not specify a valid Direct3D 11 device with which the `cl_device_ids` against which this context is to be created may interoperate.

- **CL_INVALID_OPERATION** if Direct3D 11 interoperability is specified by setting `CL_INVALID_D3D11_DEVICE_KHR` to a non-NULL value, and interoperability with another graphics API is also specified.

The following errors may be returned if the `cl_khr_gl_sharing` extension is supported:

- **CL_INVALID_GL_SHAREGROUP_REFERENCE_KHR** if a context was specified for an OpenGL or OpenGL ES implementation using the EGL, GLX, or WGL binding APIs, as described above; and any of the following conditions hold:
  - The specified display and context properties do not identify a valid OpenGL or OpenGL ES context.
  - The specified context does not support buffer and renderbuffer objects.
  - The specified context is not compatible with the OpenCL context being created (for example, it exists in a physically distinct address space, such as another hardware device; or it does not support sharing data with OpenCL due to implementation restrictions).

- **CL_INVALID_GL_SHAREGROUP_REFERENCE_KHR** if a share group was specified for a CGL-based OpenGL implementation by setting the property `CL_CGL_SHAREGROUP_KHR`, and the specified share group does not identify a valid CGL share group object.

- **CL_INVALID_OPERATION** if a context was specified as described above and any of the following conditions hold:
  - A context or share group object was specified for one of CGL, EGL, GLX, or WGL and the OpenGL implementation does not support that window-system binding API.
  - More than one of the properties `CL_CGL_SHAREGROUP_KHR`, `CL_EGL_DISPLAY_KHR`, `CL_GLX_DISPLAY_KHR`, and `CL_WGL_HDC_KHR` is set to a non-default value.
  - Both of the properties `CL_CGL_SHAREGROUP_KHR` and `CL_GL_CONTEXT_KHR` are set to non-default values.
  - Any of the devices specified in the `devices` argument cannot support OpenCL objects which share the data store of an OpenGL object.

- **CL_INVALID_PROPERTY** if both `CL_CONTEXT_INTEROP_USER_SYNC`, and any of the properties defined by the `cl_khr_gl_sharing` extension are defined in `properties`.

The following errors may be returned if the `cl_khr_terminate_context` extension is supported:
• CL_INVALID_PROPERTY if the cl_khr_terminate_context extension is supported and CL_CONTEXT_TERMINATE_KHR is set to CL_TRUE in properties, but not all of the devices associated with the context support the ability to support context termination (i.e. CL_DEVICE_TERMINATE_CAPABILITY_CONTEXT_KHR is set for CL_DEVICE_TERMINATE_CAPABILITY_KHR).

It is possible that a device(s) becomes unavailable after a context and command-queues that use this device(s) have been created and commands have been queued to command-queues. In this case the behavior of OpenCL API calls that use this context (and command-queues) are considered to be implementation-defined. The user callback function, if specified, when the context is created can be used to record appropriate information in the errinfo, private_info arguments passed to the callback function when the device becomes unavailable.

To create an OpenCL context from a specific device type\textsuperscript{[11]}, call the function:

```c
// Provided by CL_VERSION_1_0
cl_context clCreateContextFromType(
    const cl_context_properties* properties,
    cl_device_type device_type,
    void (CL_CALLBACK* pfn_notify)(const char* errinfo, const void* private_info,
                                  size_t cb, void* user_data),
    void* user_data,
    cl_int* errcode_ret);
```

- **properties** specifies a list of context property names and their corresponding values. Each property name is immediately followed by the corresponding desired value. The list of supported properties, and their default values if not present in properties, is described in the \textit{Context Properties} table. properties can be NULL, in which case all properties take on their default values.

- **device_type** is a bit-field that identifies the type of device and is described in the \textit{Device Types} table.

- **pfn_notify** and **user_data** are described in \textit{clCreateContext}.

- **errcode_ret** will return an appropriate error code. If errcode_ret is NULL, no error code is returned.

Only devices that are returned by \textit{clGetDeviceIDs} for device_type are used to create the context. The context does not reference any sub-devices that may have been created from these devices.

\textit{clCreateContextFromType} returns a valid non-zero context and errcode_ret is set to CL_SUCCESS if the context is created successfully. Otherwise, it returns a NULL value with the following error values returned in errcode_ret:

- CL_INVALID_PLATFORM if no platform is specified in properties and no platform could be selected, or if the platform specified in properties is not a valid platform.

- CL_INVALID_PROPERTY if a context property name in properties is not a supported property name, if the value specified for a supported property name is not valid, or if the same property name
is specified more than once. This error code is missing before version 1.1.

• **CL_INVALID_VALUE** if `pfn_notify` is **NULL** but `user_data` is not **NULL**.

• **CL_INVALID_DEVICE_TYPE** if `device_type` is not a valid value.

• **CL_DEVICE_NOT_AVAILABLE** if no devices that match `device_type` and property values specified in `properties` are currently available.

• **CL_DEVICE_NOT_FOUND** if no devices that match `device_type` and property values specified in `properties` were found.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

The following errors may be returned if the **cl_khr_dx9_media_sharing** extension is supported:

• **CL_INVALID_DX9_MEDIA_ADAPTER_KHR** if any of the values of the properties `CL_CONTEXT_ADAPTER_D3D9_KHR`, `CL_CONTEXT_ADAPTER_D3D9EX_KHR` or `CL_CONTEXT_ADAPTER_DXVA_KHR` is non-**NULL** and does not specify a valid media adapter with which the `cl_device_ids` against which this context is to be created may interoperate.

The following errors may be returned if the **cl_khr_d3d10_sharing** extension is supported:

• **CL_INVALID_D3D10_DEVICE_KHR** if the value of the property `CL_CONTEXT_D3D10_DEVICE_KHR` is non-**NULL** and does not specify a valid Direct3D 10 device with which the `cl_device_ids` against which this context is to be created may interoperate.

• **CL_INVALID_OPERATION** if Direct3D 10 interoperability is specified by setting `CL_INVALID_D3D10_DEVICE_KHR` to a non-**NULL** value, and interoperability with another graphics API is also specified.

The following errors may be returned if the **cl_khr_d3d11_sharing** extension is supported:

• **CL_INVALID_D3D11_DEVICE_KHR** if the value of the property `CL_CONTEXT_D3D11_DEVICE_KHR` is non-**NULL** and does not specify a valid Direct3D 11 device with which the `cl_device_ids` against which this context is to be created may interoperate.

• **CL_INVALID_OPERATION** if Direct3D 11 interoperability is specified by setting `CL_INVALID_D3D11_DEVICE_KHR` to a non-**NULL** value, and interoperability with another graphics API is also specified.

The following errors may be returned if the **cl_khr_gl_sharing** extension is supported:

• **CL_INVALID_GL_SHAREGROUP_REFERENCE_KHR** if a context was specified for an OpenGL or OpenGL ES implementation using the EGL, GLX, or WGL binding APIs, as described for `clCreateContext`; and any of the following conditions hold:

  ◦ The specified display and context properties do not identify a valid OpenGL or OpenGL ES context.

  ◦ The specified context does not support buffer and renderbuffer objects.

  ◦ The specified context is not compatible with the OpenCL context being created (for example, it exists in a physically distinct address space, such as another hardware device; or it does
not support sharing data with OpenCL due to implementation restrictions).

- **CL_INVALID_GL_SHAREGROUP_REFERENCE_KHR** if a share group was specified for a CGL-based OpenGL implementation by setting the property **CL_CGL_SHAREGROUP_KHR**, and the specified share group does not identify a valid CGL share group object.

- **CL_INVALID_OPERATION** if a context was specified as described above and any of the following conditions hold:
  - A context or share group object was specified for one of CGL, EGL, GLX, or WGL and the OpenGL implementation does not support that window-system binding API.
  - More than one of the properties **CL_CGL_SHAREGROUP_KHR**, **CL_EGL_DISPLAY_KHR**, **CL_GLX_DISPLAY_KHR**, and **CL_WGL_HDC_KHR** is set to a non-default value.
  - Both of the properties **CL_CGL_SHAREGROUP_KHR** and **CL_GL_CONTEXT_KHR** are set to non-default values.
  - Any of the devices specified in the **devices** argument cannot support OpenCL objects which share the data store of an OpenGL object.

- **CL_INVALID_PROPERTY** if both **CL_CONTEXT_INTEROP_USER_SYNC**, and any of the properties defined by the **cl_khr_gl_sharing** extension are defined in **properties**.

To retain a context, call the function:

```c
// Provided by CL_VERSION_1_0
cl_int clRetainContext(
    cl_context context);
```

- **context** specifies the OpenCL context to retain.

**clRetainContext** increments the **context** reference count.

**clCreateContext** and **clCreateContextFromType** perform an implicit retain. This is very helpful for 3rd party libraries, which typically get a context passed to them by the application. However, it is possible that the application may delete the context without informing the library. Allowing functions to attach to (i.e. retain) and release a context solves the problem of a context being used by a library no longer being valid.

**clRetainContext** returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_CONTEXT** if **context** is not a valid OpenCL context.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To release a context, call the function:


```c
// Provided by CL_VERSION_1_0
cl_int clReleaseContext(
    cl_context context);
```

- `context` specifies the OpenCL context to release.

`clReleaseContext` decrements the `context` reference count. After the reference count becomes zero and all the objects attached to `context` (such as memory objects, command-queues) are released, the `context` is deleted. Using this function to release a reference that was not obtained by creating the object or by calling `clRetainContext` causes undefined behavior.

`clReleaseContext` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_CONTEXT` if `context` is not a valid OpenCL context.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

To terminate all pending work associated with a context and render all data owned by the context invalid, call the function

```c
// Provided by cl_khr_terminate_context
cl_int clTerminateContextKHR(
    cl_context context);
```

- `clTerminateContextKHR` is provided by the `cl_khr_terminate_context` extension.

  - `context` must be a valid OpenCL context.

It is the responsibility of the application to release all objects associated with the context being terminated.

When a context is terminated:

- The execution status of enqueued commands will be `CL_CONTEXT_TERMINATED_KHR`. Event objects can be queried using `clGetEventInfo`. Event callbacks can be registered and registered event callbacks will be called with `event_command_status` set to `CL_CONTEXT_TERMINATED_KHR`. `clWaitForEvents` will return as immediately for commands associated with event objects specified in `event_list`. The status of user events can be set. Event objects can be retained and released. `clGetEventProfilingInfo` returns `CL_PROFILING_INFO_NOT_AVAILABLE`.

- The context is considered to be terminated. A callback function registered when the context was created will be called. Only queries, retain and release operations can be performed on the context. All other APIs that use a context as an argument will return `CL_CONTEXT_TERMINATED_KHR`.

- The contents of the memory regions of the memory objects is undefined. Queries, registering a
destructor callback, retain and release operations can be performed on the memory objects.

• Once a context has been terminated, all OpenCL API calls that create objects or enqueue commands will return `CL_CONTEXT_TERMINATED_KHR`. APIs that release OpenCL objects will continue to operate as though `clTerminateContextKHR` was not called.

• The behavior of callbacks will remain unchanged, and will report appropriate error, if executing after termination of context. This behavior is similar to enqueued commands, after the command-queue has become invalid.

`clTerminateContextKHR` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

• `CL_INVALID_CONTEXT` if `context` is not a valid OpenCL context.

• `CL_CONTEXT_TERMINATED_KHR` if `context` has already been terminated.

• `CL_INVALID_OPERATION` if `context` was not created with `CL_CONTEXT_TERMINATE_KHR` set to `CL_TRUE`.

• `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.

• `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

An implementation that supports this extension must be able to terminate commands currently executing on devices or queued across all command-queues associated with the context that is being terminated. The implementation cannot implement this extension by waiting for currently executing (or queued) commands to finish execution on devices associated with this context (i.e. doing a `clFinish`).

To query information about a context, call the function:

```c
// Provided by CL_VERSION_1_0
cl_int clGetContextInfo(
    cl_context context,
    cl_context_info param_name,
    size_t param_value_size,
    void* param_value,
    size_t* param_value_size_ret);
```

• `context` specifies the OpenCL context being queried.

• `param_name` is an enumeration constant that specifies the information to query.

• `param_value` is a pointer to memory where the appropriate result being queried is returned. If `param_value` is NULL, it is ignored.

• `param_value_size` specifies the size in bytes of memory pointed to by `param_value`. This size must be greater than or equal to the size of return type as described in the `Context Attributes` table.

• `param_value_size_ret` returns the actual size in bytes of data being queried by `param_name`. If `param_value_size_ret` is NULL, it is ignored.
The list of supported `param_name` values and the information returned in `param_value` by `clGetContextInfo` is described in the Context Attributes table.

<table>
<thead>
<tr>
<th>Context Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_CONTEXT_NUM_DEVICES missing before version 1.1.</td>
<td>cl_uint</td>
<td>Return the number of devices in context.</td>
</tr>
<tr>
<td>CL_CONTEXT_DEVICES</td>
<td>cl_device_id[]</td>
<td>Return the list of devices and sub-devices in context.</td>
</tr>
<tr>
<td>CL_CONTEXT_PROPERTIES</td>
<td>cl_context_properties[]</td>
<td>Return the properties argument specified in clCreateContext or clCreateContextFromType.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>If the <code>properties</code> argument specified in clCreateContext or clCreateContextFromType used to create context was not NULL, the implementation must return the values specified in the properties argument in the same order and without including additional properties. If the <code>properties</code> argument specified in clCreateContext or clCreateContextFromType used to create context was NULL, the implementation must return <code>param_value_size_ret</code> equal to 0, indicating that there are no properties to be returned.</td>
</tr>
<tr>
<td>CL_CONTEXT_D3D10_PREFER_SHARED_RESOURCES_KHR</td>
<td>cl_bool</td>
<td>Returns CL_TRUE if Direct3D 10 resources created as shared by setting MiscFlags to include D3D10_RESOURCE_MISC_SHARED will perform faster when shared with OpenCL, compared with resources which have not set this flag. Otherwise returns CL_FALSE.</td>
</tr>
<tr>
<td>provided by the cl_khr_d3d10_sharing extension.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_CONTEXT_D3D11_PREFER_SHARED_RESOURCES_KHR</td>
<td>cl_bool</td>
<td>Returns CL_TRUE if Direct3D 11 resources created as shared by setting MiscFlags to include D3D11_RESOURCE_MISC_SHARED will perform faster when shared with OpenCL, compared with resources which have not set this flag. Otherwise returns CL_FALSE.</td>
</tr>
<tr>
<td>provided by the cl_khr_d3d11_sharing extension.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

`clGetContextInfo` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

- CL_INVALID_CONTEXT if context is not a valid context.
• **CL_INVALID_VALUE** if `param_name` is not one of the supported values or if size in bytes specified by `param_value_size` is < size of return type as specified in the Context Attributes table and `param_value` is not a NULL value.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To register a callback function with a context that is called when the context is destroyed, call the function

```c
// Provided by CL_VERSION_3_0
cl_int clSetContextDestructorCallback(
    cl_context context,
    void (CL_CALLBACK* pfn_notify)(cl_context context, void* user_data),
    void* user_data);
```

- `clSetContextDestructorCallback` is **missing before** version 3.0.

- `context` specifies the OpenCL context to register the callback to.

- `pfn_notify` is the callback function to register. This callback function may be called asynchronously by the OpenCL implementation. It is the application’s responsibility to ensure that the callback function is thread-safe. The parameters to this callback function are:
  - `context` is the OpenCL context being deleted. When the callback function is called by the implementation, this context is no longer valid. `context` is only provided for reference purposes.
  - `user_data` is a pointer to user-supplied data.

- `user_data` will be passed as the `user_data` argument when `pfn_notify` is called. `user_data` can be NULL.

Each call to `clSetContextDestructorCallback` registers the specified callback function on a destructor callback stack associated with `context`. The registered callback functions are called in the reverse order in which they were registered. If a context callback function was specified when `context` was created, it will not be called after any context destructor callback is called. Therefore, the context destructor callback provides a mechanism for an application to safely re-use or free any `user_data` specified for the context callback function when `context` was created.

`clSetContextDestructorCallback` returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_CONTEXT** if `context` is not a valid context.

- **CL_INVALID_VALUE** if `pfn_notify` is NULL.

- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

[1] The platform profile returns the profile that is implemented by the OpenCL framework. If the platform profile returned is FULL_PROFILE, the OpenCL framework will support devices that are FULL_PROFILE and may also support devices that are EMBEDDED_PROFILE. The compiler must be available for all devices i.e. **CL_DEVICE_COMPILER_AVAILABLE** is **CL_TRUE**. If the platform profile returned is EMBEDDED_PROFILE, then devices that are only EMBEDDED_PROFILE are supported.

[2] A null terminated string is returned by OpenCL query function calls if the return type of the information being queried is a **char**.

[3] The OpenCL specification does not describe the order of precedence for error codes returned by API calls.

[4] **clGetDeviceIDs** may return all or a subset of the actual physical devices present in the platform and that match **device_type**.

[5] OpenCL adopters must report a valid vendor ID for their implementation. If there is no valid PCI vendor ID defined for the physical device, implementations must obtain a Khronos vendor ID. This is a unique identifier greater than the largest PCI vendor ID (0x10000) and is representable by a **cl_uint**. Khronos vendor IDs are synchronized across APIs by utilizing Vulkan’s vk.xml as the central Khronos vendor ID registry. An ID must be reserved here prior to use in OpenCL, regardless of whether a vendor implements Vulkan. Only once the ID has been allotted may it be exposed to OpenCL by proposing a merge request against cl.xml, in the **main** branch of the OpenCL-Docs project. The merge must define a new enumerant by adding an **<enum>** tag to the **cl_khronos_vendor_id <enums>** tag, with the **<value>** attribute set as the acquired Khronos vendor ID. The **<name>** attribute must identify the vendor/adopter, and be of the form **CL_KHRONOS_VENDOR_ID_<vendor>**.

[6] A kernel that uses an image argument with the write_only or read_write image qualifier may result in additional read_only images resources being created internally by an implementation. The internally created read_only image resources will count against the max supported read image arguments given by **CL_DEVICE_MAX_READ_IMAGE_ARGS**. Enqueuing a kernel that requires more images than the implementation can support will result in a **CL_OUT_OF_RESOURCES** error being returned.

[7] The optional rounding modes should be included as a device capability only if it is supported natively. All explicit conversion functions with specific rounding modes must still operate correctly.

[8] The reference count returned should be considered immediately stale. It is unsuitable for general use in applications. This feature is provided for identifying memory leaks.

[9] Note that this flag does not provide meaning for atomic memory operations, but only for atomic fence operations in certain circumstances, refer to the Memory Scope section of the OpenCL C specification.

[10] Duplicate devices specified in **devices** are ignored.

[11] **clCreateContextFromType** may may create a context for all or a subset of the actual physical devices present in the platform that match **device_type**.

[12] The reference count returned should be considered immediately stale. It is unsuitable for general use in applications. This feature is provided for identifying memory leaks.
Chapter 5. The OpenCL Runtime

In this section we describe the API calls that manage OpenCL objects such as command-queues, memory objects, program objects, kernel objects for kernel functions in a program and calls that allow you to enqueue commands to a command-queue such as executing a kernel, reading, or writing a memory object.

5.1. Command-Queues

OpenCL objects such as memory, program and kernel objects are created using a context. Operations on these objects are performed using a command-queue. The command-queue can be used to queue a set of operations (referred to as commands) in order. Having multiple command-queues allows applications to queue multiple independent commands without requiring synchronization. Note that this should work as long as these objects are not being shared. Sharing of objects across multiple command-queues will require the application to perform appropriate synchronization. This is described in Shared OpenCL Objects

To create a host or device command-queue on a specific device, call the function

```c
// Provided by CL_VERSION_2_0
cl_command_queue clCreateCommandQueueWithProperties(
    cl_context context,
    cl_device_id device,
    const cl_queue_properties* properties,
    cl_int* errcode_ret);
```

- **clCreateCommandQueueWithProperties** is missing before version 2.0.

or the equivalent

```c
// Provided by cl_khr_create_command_queue
cl_command_queue clCreateCommandQueueWithPropertiesKHR(
    cl_context context,
    cl_device_id device,
    const cl_queue_properties_khr* properties,
    cl_int* errcode_ret);
```

- **clCreateCommandQueueWithPropertiesKHR** is provided by the cl_khr_create_command_queue extension.

- **context** must be a valid OpenCL context.
- **device** must be a device or sub-device associated with **context**. It can either be in the list of devices and sub-devices specified when **context** is created using **clCreateContext** or be a root device with the same device type as specified when **context** is created using **clCreateContextFromType**.
• *properties* specifies a list of properties for the command-queue and their corresponding values. Each property name is immediately followed by the corresponding desired value. The list is terminated with 0. The list of supported properties is described in the table below. If a supported property and its value is not specified in *properties*, its default value will be used. *properties* can be NULL in which case the default values for supported command-queue properties will be used.

• *errcode_ret* will return an appropriate error code. If *errcode_ret* is NULL, no error code is returned.

**Table 15. List of supported queue creation properties by clCreateCommandQueueWithProperties**

<table>
<thead>
<tr>
<th>Queue Property</th>
<th>Property Value</th>
<th>Description</th>
</tr>
</thead>
</table>
| CL_QUEUE_PROPERTIES | cl_command_queue_properties | This is a bitfield and can be set to a combination of the following values:

- **CL_QUEUE_OUT_OF_ORDER_EXEC_MODE_ENABLE** - Determines whether the commands queued in the command-queue are executed in-order or out-of-order. If set, the commands in the command-queue are executed out-of-order. Otherwise, commands are executed in-order.

- **CL_QUEUE_PROFILING_ENABLE** - Enable or disable profiling of commands in the command-queue. If set, the profiling of commands is enabled. Otherwise profiling of commands is disabled.

- **CL_QUEUE_ON_DEVICE** - Indicates that this is a device queue. If **CL_QUEUE_ON_DEVICE** is set, **CL_QUEUE_OUT_OF_ORDER_EXEC_MODE_ENABLE** must also be set.

  *missing before version 2.0.*

- **CL_QUEUE_ON_DEVICE_DEFAULT**[^1] - indicates that this is the default device queue. This can only be used with **CL_QUEUE_ON_DEVICE**.

  *missing before version 2.0.*

If **CL_QUEUE_PROPERTIES** is not specified an in-order host command-queue is created for the specified device.
<table>
<thead>
<tr>
<th>Queue Property</th>
<th>Property Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>CL_QUEUE_SIZE</strong></td>
<td>cl_uint</td>
<td>Specifies the size of the device queue in bytes. This can only be specified if CL_QUEUE_ON_DEVICE is set in CL_QUEUE_PROPERTIES. This must be a value ≤ CL_DEVICE_QUEUE_ON_DEVICE_MAX_SIZE. For best performance, this should be ≤ CL_DEVICE_QUEUE_ON_DEVICE_PREFERRED_SIZE. If CL_QUEUE_SIZE is not specified, the device queue is created with CL_DEVICE_QUEUE_ON_DEVICE_PREFERRED_SIZE as the size of the queue.</td>
</tr>
<tr>
<td><strong>CL_QUEUE_PRIORITY_KHR</strong></td>
<td>cl_queue_priority_khr</td>
<td>Specifies a priority hint for command queues belonging to the same OpenCL context. NOTE: Refer to the user guide associated with each implementation supporting this extension for its priority behavior guarantees, if any. CL_QUEUE_PRIORITY_HIGH_KHR - Indicates command queues should have high priority. CL_QUEUE_PRIORITY_MED_KHR - Indicates command queues should have medium priority. CL_QUEUE_PRIORITY_LOW_KHR - Indicates command queues should have low priority. If CL_QUEUE_PRIORITY_KHR is not specified, the default priority CL_QUEUE_PRIORITY_MED_KHR is used.</td>
</tr>
<tr>
<td>Queue Property</td>
<td>Property Value</td>
<td>Description</td>
</tr>
<tr>
<td>--------------------------------</td>
<td>----------------------</td>
<td>------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_QUEUE_THROTTLE_KHR</td>
<td>cl_queue_throttle_khr</td>
<td>Specifies a throttle hint for a command queue.</td>
</tr>
<tr>
<td>provided by the</td>
<td></td>
<td>NOTE: Refer to the user guide associated with each implementation supporting</td>
</tr>
<tr>
<td>cl_khr_throttle_hints</td>
<td></td>
<td>this extension for its throttling behavior guarantees, if any.</td>
</tr>
<tr>
<td>extension.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_QUEUE_THROTTLE_HIGH_KHR</td>
<td></td>
<td>- Indicates the queue should execute at full throttle, which may consume</td>
</tr>
<tr>
<td></td>
<td></td>
<td>more energy.</td>
</tr>
<tr>
<td>CL_QUEUE_THROTTLE_MED_KHR</td>
<td></td>
<td>- Indicates normal throttling behavior.</td>
</tr>
<tr>
<td>CL_QUEUE_THROTTLE_LOW_KHR</td>
<td></td>
<td>- Indicates the queue should execute at low throttle, optimized for lowest</td>
</tr>
<tr>
<td></td>
<td></td>
<td>energy consumption.</td>
</tr>
<tr>
<td>If CL_QUEUE_THROTTLE_KHR is</td>
<td></td>
<td>the default priority CL_QUEUE_THROTTLE_MED_KHR is used.</td>
</tr>
<tr>
<td>not specified, the default</td>
<td></td>
<td>priority CL_QUEUE_THROTTLE_MED_KHR is used.</td>
</tr>
<tr>
<td>priority CL_QUEUE_THROTTLE_MED_KHR is used.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**clCreateCommandQueueWithProperties** returns a valid non-zero command-queue and `errcode_ret` is set to **CL_SUCCESS** if the command-queue is created successfully. Otherwise, it returns a NULL value with one of the following error values returned in `errcode_ret`:

- **CL_INVALID_CONTEXT** if `context` is not a valid context.
- **CL_INVALIDDEVICE** if `device` is not a valid device or is not associated with `context`.
- **CL_INVALID_VALUE** if values specified in `properties` are not valid.
- **CL_INVALID_QUEUE_PROPERTIES** if values specified in `properties` are valid but are not supported by the device.
- **CL INVALID_QUEUE_PROPERTIES** if the `cl_khr_priority_hints` extension is supported, the `CL_QUEUE_PRIORITY_KHR` property is specified, and the queue is a `CL_QUEUE_ON_DEVICE`.
- **CL INVALID_QUEUE_PROPERTIES** if the `cl_khr_throttle_hints` extension is supported, the `CL_QUEUE_THROTTLE_KHR` property is specified, and the queue is a `CL_QUEUE_ON_DEVICE`.
- **CL OUT OF RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL OUT OF HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To create a host command-queue on a specific device, call the function
clCreateCommandQueue is deprecated by version 2.0.

- `context` must be a valid OpenCL context.
- `device` must be a device or sub-device associated with `context`. It can either be in the list of devices and sub-devices specified when `context` is created using `clCreateContext` or be a root device with the same device type as specified when `context` is created using `clCreateContextFromType`.
- `properties` specifies a list of properties for the command-queue. This is a bit-field and the supported properties are described in the table below. Only command-queue properties specified in this table can be used, otherwise the value specified in `properties` is considered to be not valid. `properties` can be 0 in which case the default values for supported command-queue properties will be used.

<table>
<thead>
<tr>
<th>Command-Queue Properties</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_QUEUE_OUT_OF_ORDER_EXEC_MODE_ENABLE</td>
<td>Determines whether the commands queued in the command-queue are executed in-order or out-of-order. If set, the commands in the command-queue are executed out-of-order. Otherwise, commands are executed in-order.</td>
</tr>
<tr>
<td>CL_QUEUE_PROFILING_ENABLE</td>
<td>Enable or disable profiling of commands in the command-queue. If set, the profiling of commands is enabled. Otherwise profiling of commands is disabled.</td>
</tr>
</tbody>
</table>

- `errcode_ret` will return an appropriate error code. If `errcode_ret` is `NULL`, no error code is returned.

`clCreateCommandQueue` returns a valid non-zero command-queue and `errcode_ret` is set to `CL_SUCCESS` if the command-queue is created successfully. Otherwise, it returns a `NULL` value with one of the following error values returned in `errcode_ret`:

- CL_INVALID_CONTEXT if `context` is not a valid context.
- CL_INVALID_DEVICE if `device` is not a valid device or is not associated with `context`.
- CL_INVALID_VALUE if values specified in `properties` are not valid.
- CL_INVALID_QUEUE_PROPERTIES if values specified in `properties` are valid but are not supported by the device.
• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To replace the default command-queue on a device, call the function

```c
// Provided by CL_VERSION_2_1
cl_int clSetDefaultDeviceCommandQueue(
    cl_context context,
    cl_device_id device,
    cl_command_queue command_queue);
```

- `clSetDefaultDeviceCommandQueue` is missing before version 2.1.

- *context* is the OpenCL context used to create `command_queue`.

- *device* is a valid OpenCL device associated with `context`.

- *command_queue* specifies a command-queue object which replaces the default device command-queue

`clSetDefaultDeviceCommandQueue` may be used to replace a default device command-queue created with `clCreateCommandQueueWithProperties` and the `CL_QUEUE_ON_DEVICE_DEFAULT` flag.

`clSetDefaultDeviceCommandQueue` returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_CONTEXT** if `context` is not a valid context.

- **CL_INVALID_DEVICE** if `device` is not a valid device or is not associated with `context`.

- **CL_INVALID_OPERATION** if `device` does not support a replaceable default on-device queue.

- **CL_INVALID_COMMAND_QUEUE** if `command_queue` is not a valid command-queue for `device`.

- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To retain a command-queue, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clRetainCommandQueue(
    cl_command_queue command_queue);
```

- *command_queue* specifies the command-queue to be retained.

The `command_queue` reference count is incremented.
**clCreateCommandQueueWithProperties** and **clCreateCommandQueue** perform an implicit retain. This is very helpful for 3rd party libraries, which typically get a command-queue passed to them by the application. However, it is possible that the application may delete the command-queue without informing the library. Allowing functions to attach to (i.e. retain) and release a command-queue solves the problem of a command-queue being used by a library no longer being valid.

**clRetainCommandQueue** returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_COMMAND_QUEUE** if command_queue is not a valid command-queue.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To release a command-queue, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clReleaseCommandQueue(
    cl_command_queue command_queue);
```

- command_queue specifies the command-queue to be released.

The command_queue reference count is decremented.

After the command_queue reference count becomes zero and all commands queued to command_queue have finished (e.g. kernel-instances, memory object updates etc.), the command-queue is deleted.

**clReleaseCommandQueue** performs an implicit flush to issue any previously queued OpenCL commands in command_queue. Using this function to release a reference that was not obtained by creating the object or by calling **clRetainCommandQueue** causes undefined behavior.

**clReleaseCommandQueue** returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_COMMAND_QUEUE** if command_queue is not a valid command-queue.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To query information about a command-queue, call the function
cl_int clGetCommandQueueInfo(
  cl_command_queue command_queue,
  cl_command_queue_info param_name,
  size_t param_value_size,
  void* param_value,
  size_t* param_value_size_ret);

- `command_queue` specifies the command-queue being queried.
- `param_name` specifies the information to query.
- `param_value` is a pointer to memory where the appropriate result being queried is returned. If `param_value` is NULL, it is ignored.
- `param_value_size` is used to specify the size in bytes of memory pointed to by `param_value`. This size must be ≥ size of return type as described in the Command-Queue Parameter table. If `param_value` is NULL, it is ignored.
- `param_value_size_ret` returns the actual size in bytes of data being queried by `param_name`. If `param_value_size_ret` is NULL, it is ignored.

The list of supported `param_name` values and the information returned in `param_value` by `clGetCommandQueueInfo` is described in the Command-Queue Parameter table.

### Table 17. List of supported `param_names` by `clGetCommandQueueInfo`

<table>
<thead>
<tr>
<th>Queue Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_QUEUE_CONTEXT</td>
<td>cl_context</td>
<td>Return the context specified when the command-queue is created.</td>
</tr>
<tr>
<td>CL_QUEUE_DEVICE</td>
<td>cl_device_id</td>
<td>Return the device specified when the command-queue is created.</td>
</tr>
<tr>
<td>CL_QUEUE_REFERENCE_COUNT</td>
<td>cl_uint</td>
<td>Return the command-queue reference count.</td>
</tr>
<tr>
<td>CL_QUEUE_PROPERTIES</td>
<td>cl_command_queue_properties</td>
<td>Return the currently specified properties for the command-queue. These properties are specified by the value associated with the CL_QUEUE_PROPERTIES passed in <code>properties</code> argument in <code>clCreateCommandQueueWithProperties</code>, or the value of the <code>properties</code> argument in <code>clCreateCommandQueue</code>.</td>
</tr>
<tr>
<td>Queue Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>------------------------------------------</td>
<td>--------------</td>
<td>---------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_QUEUE_PROPERTIES_ARRAY</td>
<td>cl_queue_properties[]</td>
<td>Return the properties argument specified in clCreateCommandQueueWithProperties. If the properties argument specified in clCreateCommandQueueWithProperties used to create command_queue was not NULL, the implementation must return the values specified in the properties argument in the same order and without including additional properties. If command_queue was created using clCreateCommandQueue, or if the properties argument specified in clCreateCommandQueueWithProperties was NULL, the implementation must return param_value_size_ret equal to 0, indicating that there are no properties to be returned.</td>
</tr>
<tr>
<td>CL_QUEUE_SIZE</td>
<td>cl_uint</td>
<td>Return the size of the device command-queue. To be considered valid for this query, command_queue must be a device command-queue.</td>
</tr>
<tr>
<td>CL_QUEUE_DEVICE_DEFAULT</td>
<td>cl_command_queue</td>
<td>Return the current default command-queue for the underlying device.</td>
</tr>
</tbody>
</table>

clGetCommandQueueInfo returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_COMMAND_QUEUE** if command_queue is not a valid command-queue, or if command_queue is not a valid command-queue for param_name.

- **CL_INVALID_VALUE** if param_name is not one of the supported values or if size in bytes specified by param_value_size is < size of return type as specified in the Command-Queue Parameter table, and param_value is not a NULL value.

- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To enable or disable the properties of a command-queue, call the function
// Provided by CL_VERSION_1_0
cl_int clSetCommandQueueProperty(
    cl_command_queue command_queue,
    cl_command_queue_properties properties,
    cl_bool enable,
    cl_command_queue_properties* old_properties);

警示：`clSetCommandQueueProperty` 是被 `version 1.1` 削弱的。

- `command_queue` 指定要修改的命令队列。
- `properties` 指定命令队列的新属性列表。这是位字段，支持的属性在 `clCreateCommandQueue` 的 `Command-Queue Properties` 表中描述。仅可以使用该表中指定的命令队列属性，否则 `properties` 中指定的值将被视为无效。
- `enable` 决定是否启用 `properties` 中指定的属性（如果 `enable` 是 `CL_TRUE`），或者禁用（如果 `enable` 是 `CL_FALSE`）。
- `old_properties` 返回命令队列的原始属性，这些属性在 `clSetCommandQueueProperty` 被更改前。如果 `old_properties` 是 `NULL`，则忽略。

`clSetCommandQueueProperty` 可能无条件返回错误，如果上下文关联的设备不支持修改命令队列的属性。支持修改命令队列的属性仅对于 `OpenCL 1.0` 设备。

`clSetCommandQueueProperty` 返回 `CL_SUCCESS` 如果函数执行成功。否则，返回其中一个错误：

- `CL_INVALID_COMMAND_QUEUE` 如果 `command_queue` 不是有效的命令队列。
- `CL_INVALID_OPERATION` 如果上下文关联的设备不支持修改命令队列的属性。
- `CL_INVALID_VALUE` 如果 `properties` 中指定的值无效。
- `CL_INVALID_QUEUE_PROPERTIES` 如果 `properties` 中指定的值是有效的，但不支持该设备。
- `CL_OUT_OF_RESOURCES` 如果在设备上分配资源失败。
- `CL_OUT_OF_HOST_MEMORY` 如果在主机上分配资源失败。

### 5.2. Buffer Objects

一个 `buffer` 对象存储一维的元素集合。元素可以是标量数据类型（例如 int, float），向量类型，或用户自定义的结构。

5.2. Buffer Objects

一个 `buffer` 对象存储一维的元素集合。元素可以是标量数据类型（例如 int, float），向量类型，或用户自定义的结构。
5.2.1. Creating Buffer Objects

A buffer object may be created using the function

```c
#define CL_VERSION_1_0
cl_mem clCreateBuffer(
    cl_context context,
    cl_mem_flags flags,
    size_t size,
    void* host_ptr,
    cl_int* errcode_ret);
```

A buffer object may also be created with additional properties using the function

```c
#define CL_VERSION_3_0
cl_mem clCreateBufferWithProperties(
    cl_context context,
    const cl_mem_properties* properties,
    cl_mem_flags flags,
    size_t size,
    void* host_ptr,
    cl_int* errcode_ret);
```

**clCreateBufferWithProperties** is missing before version 3.0.

- **context** is a valid OpenCL context used to create the buffer object.
- **properties** is an optional list of properties for the buffer object and their corresponding values. The list is terminated with the special property 0. If no properties are required, **properties** may be **NULL**. OpenCL 3.0 does not define any optional properties for buffers, but extensions may define properties as described in the List of supported buffer creation properties.
- **flags** is a bit-field that is used to specify allocation and usage information about the image memory object being created and is described in the supported memory flag values table.
- **size** is the size in bytes of the buffer memory object to be allocated.
- **host_ptr** is a pointer to the buffer data that may already be allocated by the application. The size of the buffer that **host_ptr** points to must be greater than or equal to **size** bytes.
- **errcode_ret** may return an appropriate error code. If **errcode_ret** is **NULL**, no error code is returned.

The alignment requirements for data stored in buffer objects are described in Alignment of Application Data Types.

If **clCreateBuffer** or **clCreateBufferWithProperties** is called with **CL_MEM_USE_HOST_PTR** set in its **flags** argument, the contents of the memory pointed to by **host_ptr** at the time of the **clCreateBuffer** call define the initial contents of the buffer object.
If `clCreateBuffer` or `clCreateBufferWithProperties` is called with a pointer returned by `clSVMAlloc` as its `host_ptr` argument, and `CL_MEM_USE_HOST_PTR` is set in its `flags` argument, `clCreateBuffer` or `clCreateBufferWithProperties` will succeed and return a valid non-zero buffer object as long as the `size` argument is no larger than the `size` argument passed in the original `clSVMAlloc` call. The new buffer object returned has the shared memory as the underlying storage. Locations in the buffers underlying shared memory can be operated on using atomic operations to the devices level of support as defined in the memory model.

Table 18. List of supported buffer creation properties

<table>
<thead>
<tr>
<th>Property</th>
<th>Property Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>CL_MEM_DEVICE_HANDLE_LIST_KHR</code> provided by the <code>cl_khr_external_memory</code> extension.</td>
<td><code>cl_device_id[]</code></td>
<td>Specifies the list of OpenCL devices (terminated with <code>CL_MEM_DEVICE_HANDLE_LIST_END_KHR</code>) to associate with the external memory handle.</td>
</tr>
</tbody>
</table>

If `CL_MEM_DEVICE_HANDLE_LIST_KHR` is not specified as part of `properties`, the memory object created by `clCreateBufferWithProperties` or `clCreateImageWithProperties` is by default accessible to all devices in the `context`.

The properties used to create a buffer from an external memory handle are described for the corresponding extensions. When a buffer is created from an external memory handle, the `flags` used to specify usage information for the buffer must not include `CL_MEM_USE_HOST_PTR`, `CL_MEM_ALLOC_HOST_PTR`, or `CL_MEM_COPY_HOST_PTR`, and the `host_ptr` argument must be `NULL`.

`clCreateBuffer` and `clCreateBufferWithProperties` returns a valid non-zero buffer object and `errcode_ret` is set to `CL_SUCCESS` if the buffer object is created successfully. Otherwise, they return a `NULL` value with one of the following error values returned in `errcode_ret`:

- `CL_INVALID_CONTEXT` if `context` is not a valid context.
- `CL_INVALID_PROPERTY` if a property name in `properties` is not a supported property name, if the value specified for a supported property name is not valid, or if the same property name is specified more than once.
- `CL_INVALID_VALUE` if values specified in `flags` are not valid as defined in the Memory Flags table.
- `CL_INVALID_BUFFER_SIZE` if `size` is 0, or if `size` is greater than `CL_DEVICE_MAX_MEM_ALLOC_SIZE` for all devices in `context`, or if `CL_MEM_USE_HOST_PTR` is set in `flags` and `host_ptr` is a pointer returned by `clSVMAlloc` and `size` is greater than the size passed to `clSVMAlloc`.
- `CL_INVALID_HOST_PTR` if `host_ptr` is `NULL` and `CL_MEM_USE_HOST_PTR` or `CL_MEM_COPY_HOST_PTR` are set in `flags` or if `host_ptr` is not `NULL` but `CL_MEM_COPY_HOST_PTR` or `CL_MEM_USE_HOST_PTR` are not set in `flags`.
- `CL_MEM_OBJECT_ALLOCATION_FAILURE` if there is a failure to allocate memory for buffer object.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.
• **CL_INVALID_DEVICE**
  ◦ if a device identified by the property `CL_MEM_DEVICE_HANDLE_LIST_KHR` is not a valid device or is not associated with `context`, or
  ◦ if a device identified by property `CL_MEM_DEVICE_HANDLE_LIST_KHR` cannot import the requested external memory object type, or
  ◦ if `CL_MEM_DEVICE_HANDLE_LIST_KHR` is not specified as part of `properties` and one or more devices in `context` cannot import the requested external memory object type.

• **CL_INVALID_VALUE**
  ◦ if `properties` includes a supported external memory handle and `flags` includes `CL_MEM_USE_HOST_PTR`, `CL_MEM_ALLOC_HOST_PTR`, or `CL_MEM_COPY_HOST_PTR`.

• **CL_INVALID_HOST_PTR**
  ◦ if `properties` includes a supported external memory handle and `host_ptr` is not `NULL`.

• **CL_INVALID_PROPERTY**
  ◦ if `properties` does not include a supported external memory handle and `CL_MEM_DEVICE_HANDLE_LIST_KHR` is specified as part of `properties`.

Table 19. List of supported memory flag values

<table>
<thead>
<tr>
<th>Memory Flags</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>CL_MEM_READ_WRITE</strong></td>
<td>This flag specifies that the memory object will be read and written by a kernel. This is the default.</td>
</tr>
<tr>
<td><strong>CL_MEM_WRITE_ONLY</strong></td>
<td>This flag specifies that the memory object will be written but not read by a kernel. Reading from a buffer or image object created with <code>CL_MEM_WRITE_ONLY</code> inside a kernel is undefined.</td>
</tr>
<tr>
<td></td>
<td><code>CL_MEM_READ_WRITE</code> and <code>CL_MEM_WRITE_ONLY</code> are mutually exclusive.</td>
</tr>
<tr>
<td><strong>CL_MEM_READ_ONLY</strong></td>
<td>This flag specifies that the memory object is a readonly memory object when used inside a kernel. Writing to a buffer or image object created with <code>CL_MEM_READ_ONLY</code> inside a kernel is undefined.</td>
</tr>
<tr>
<td></td>
<td><code>CL_MEM_READ_WRITE</code> or <code>CL_MEM_WRITE_ONLY</code> and <code>CL_MEM_READ_ONLY</code> are mutually exclusive.</td>
</tr>
<tr>
<td>Memory Flags</td>
<td>Description</td>
</tr>
<tr>
<td>---------------------------</td>
<td>-----------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td><strong>CL_MEM_USE_HOST_PTR</strong></td>
<td>This flag is valid only if host_ptr is not <strong>NULL</strong>. If specified, it indicates that the application wants the OpenCL implementation to use memory referenced by host_ptr as the storage bits for the memory object.</td>
</tr>
<tr>
<td></td>
<td>The contents of the memory pointed to by host_ptr at the time of the <code>clCreateBuffer</code>, <code>clCreateBufferWithProperties</code>, <code>clCreateImage</code>, <code>clCreateImageWithProperties</code>, <code>clCreateImage2D</code>, or <code>clCreateImage3D</code> call define the initial contents of the memory object.</td>
</tr>
<tr>
<td></td>
<td>OpenCL implementations are allowed to cache the contents pointed to by host_ptr in device memory. This cached copy can be used when kernels are executed on a device.</td>
</tr>
<tr>
<td></td>
<td>The result of OpenCL commands that operate on multiple buffer objects created with the same host_ptr or from overlapping host or SVM regions is considered to be undefined.</td>
</tr>
<tr>
<td><strong>CL_MEM_ALLOC_HOST_PTR</strong></td>
<td>This flag specifies that the application wants the OpenCL implementation to allocate memory from host accessible memory.</td>
</tr>
<tr>
<td></td>
<td><code>CL_MEM_ALLOC_HOST_PTR</code> and <code>CL_MEM_USE_HOST_PTR</code> are mutually exclusive.</td>
</tr>
<tr>
<td>Memory Flags</td>
<td>Description</td>
</tr>
<tr>
<td>---------------------------------</td>
<td>-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td><strong>CL_MEM_COPY_HOST_PTR</strong></td>
<td>This flag is valid only if host_ptr is not <strong>NULL</strong>. If specified, it indicates that the application wants the OpenCL implementation to allocate memory for the memory object and copy the data from memory referenced by host_ptr. The implementation will copy the memory immediately and host_ptr is available for reuse by the application when the <code>clCreateBuffer</code>, <code>clCreateBufferWithProperties</code>, <code>clCreateImage</code>, <code>clCreateImageWithProperties</code>, <code>clCreateImage2D</code>, or <code>clCreateImage3D</code> operation returns. CL_MEM_COPY_HOST_PTR and CL_MEM_USE_HOST_PTR are mutually exclusive. CL_MEM_COPY_HOST_PTR can be used with CL_MEM_ALLOC_HOST_PTR to initialize the contents of the cl_mem object allocated using host-accessible (e.g. PCIe) memory.</td>
</tr>
<tr>
<td><strong>CL_MEM_HOST_WRITE_ONLY</strong></td>
<td>This flag specifies that the host will only write to the memory object (using OpenCL APIs that enqueue a write or a map for write). This can be used to optimize write access from the host (e.g. enable write-combined allocations for memory objects for devices that communicate with the host over a system bus such as PCIe).</td>
</tr>
<tr>
<td><strong>CL_MEM_HOST_READ_ONLY</strong></td>
<td>This flag specifies that the host will only read the memory object (using OpenCL APIs that enqueue a read or a map for read). CL_MEM_HOST_WRITE_ONLY and CL_MEM_HOST_READ_ONLY are mutually exclusive.</td>
</tr>
<tr>
<td><strong>CL_MEM_HOST_NO_ACCESS</strong></td>
<td>This flag specifies that the host will not read or write the memory object. CL_MEM_HOST_WRITE_ONLY or CL_MEM_HOST_READ_ONLY and CL_MEM_HOST_NO_ACCESS are mutually exclusive.</td>
</tr>
</tbody>
</table>

**CL_MEM_HOST_WRITE_ONLY** and **CL_MEM_HOST_READ_ONLY** are mutually exclusive.

**CL_MEM_COPY_HOST_PTR** and **CL_MEM_USE_HOST_PTR** are mutually exclusive.
Memory Flags | Description
--- | ---
CL_MEM_KERNEL_READ_AND_WRITE | This flag is only used by `clGetSupportedImageFormats` to query image formats that may be both read from and written to by the same kernel instance. To create a memory object that may be read from and written to use `CL_MEM_READ_WRITE`.

To create a new buffer object (referred to as a sub-buffer object) from an existing buffer object, call the function

```c
// Provided by CL_VERSION_1_1
cl_mem clCreateSubBuffer(
    cl_mem buffer,
    cl_mem_flags flags,
    cl_buffer_create_type buffer_create_type,
    const void* buffer_create_info,
    cl_int* errcode_ret);
```

- `clCreateSubBuffer` is missing before version 1.1.

- `buffer` must be a valid buffer object and cannot be a sub-buffer object.

- `flags` is a bit-field that is used to specify allocation and usage information about the sub-buffer memory object being created and is described in the Memory Flags table. If the `CL_MEM_READ_WRITE`, `CL_MEM_READ_ONLY`, or `CL_MEM_WRITE_ONLY` values are not specified in `flags`, they are inherited from the corresponding memory access qualifiers associated with `buffer`. The `CL_MEM_USE_HOST_PTR`, `CL_MEM_ALLOC_HOST_PTR`, and `CL_MEM_COPY_HOST_PTR` values cannot be specified in `flags` but are inherited from the corresponding memory access qualifiers associated with `buffer`. If `CL_MEM_COPY_HOST_PTR` is specified in the memory access qualifier values associated with `buffer` it does not imply any additional copies when the sub-buffer is created from `buffer`. If the `CL_MEM_HOST_WRITE_ONLY`, `CL_MEM_HOST_READ_ONLY`, or `CL_MEM_HOST_NO_ACCESS` values are not specified in `flags`, they are inherited from the corresponding memory access qualifiers associated with `buffer`.

- `buffer_create_type` and `buffer_create_info` describe the type of buffer object to be created. The list of supported values for `buffer_create_type` and corresponding descriptor that `buffer_create_info` points to is described in the SubBuffer Attributes table.

Table 20. List of supported buffer creation types by `clCreateSubBuffer`
<table>
<thead>
<tr>
<th>Buffer Creation Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_BUFFER_CREATE_TYPE_REGION</td>
<td>Create a buffer object that represents a specific region in buffer. \n\nbuffer_create_info is a pointer to a cl_buffer_region structure specifying a region of the buffer. \nIf buffer is created with CL_MEM_USE_HOST_PTR, the host_ptr associated with the buffer object returned is host_ptr + origin. \nThe buffer object returned references the data store allocated for buffer and points to the region specified by buffer_create_info in this data store.</td>
</tr>
<tr>
<td>missing before version 1.1.</td>
<td></td>
</tr>
</tbody>
</table>

**clCreateSubBuffer** returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors in **errcode_ret**:

- **CL_INVALID_MEM_OBJECT** if buffer is not a valid buffer object or is a sub-buffer object.
- **CL_INVALID_VALUE** if buffer was created with CL_MEM_WRITE_ONLY and flags specifies CL_MEM_READ_WRITE or CL_MEM_READ_ONLY, or if buffer was created with CL_MEM_READ_ONLY and flags specifies CL_MEM_READ_WRITE or CL_MEM_WRITE_ONLY, or if flags specifies CL_MEM_USE_HOST_PTR or CL_MEM_ALLOC_HOST_PTR or CL_MEM_COPY_HOST_PTR.
- **CL_INVALID_VALUE** if buffer was created with CL_MEM_HOST_WRITE_ONLY and flags specify CL_MEM_HOST_READ_ONLY, or if buffer was created with CL_MEM_HOST_READ_ONLY and flags specify CL_MEM_HOST_WRITE_ONLY, or if buffer was created with CL_MEM_HOST_NO_ACCESS and flags specify CL_MEM_HOST_READ_ONLY or CL_MEM_HOST_WRITE_ONLY.
- **CL_INVALID_VALUE** if the value specified in buffer_create_type is not valid.
- **CL_INVALID_VALUE** if value(s) specified in buffer_create_info (for a given buffer_create_type) is not valid or if buffer_create_info is NULL.
- **CL_MEM_OBJECT_ALLOCATION_FAILURE** if there is a failure to allocate memory for sub-buffer object.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.
- **CL_INVALID_VALUE** if the region specified by the cl_buffer_region structure passed in buffer_create_info is out of bounds in buffer.
- **CL_INVALID_BUFFER_SIZE** if the size field of the cl_buffer_region structure passed in buffer_create_info is 0.
- **CL_MISALIGNED_SUB_BUFFER_OFFSET** if there are no devices in context associated with buffer for which the origin field of the cl_buffer_region structure passed in buffer_create_info is aligned to
Concurrent reading from, writing to and copying between both a buffer object and its sub-buffer object(s) is undefined. Concurrent reading from, writing to and copying between overlapping sub-buffer objects created with the same buffer object is undefined. Only reading from both a buffer object and its sub-buffer objects or reading from multiple overlapping sub-buffer objects is defined.

The `cl_buffer_region` structure specifies a region of a buffer object:

```c
// Provided by CL_VERSION_1_0
typedef struct cl_buffer_region {
  size_t origin;
  size_t size;
} cl_buffer_region;
```

- `origin` is the offset in bytes of the region.
- `size` is the size in bytes of the region.

Constraints on the values of `origin` and `size` are specified for the `clCreateSubBuffer` function to which this structure is passed.

### 5.2.2. Reading, Writing and Copying Buffer Objects

The following functions enqueue commands to read from a buffer object to host memory or write to a buffer object from host memory.

To read from a buffer object to host memory or to write to a buffer object from host memory call one of the functions

```c
// Provided by CL_VERSION_1_0
cl_int clEnqueueReadBuffer(
    cl_command_queue command_queue,
    cl_mem buffer,
    cl_bool blocking_read,
    size_t offset,
    size_t size,
    void* ptr,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```
cl_int clEnqueueWriteBuffer(
    cl_command_queue command_queue,
    cl_mem buffer,
    cl_bool blocking_write,
    size_t offset,
    size_t size,
    const void* ptr,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);

- `command_queue` is a valid host command-queue in which the read / write command will be queued. `command_queue` and `buffer` must be created with the same OpenCL context.

- `buffer` refers to a valid buffer object.

- `blocking_read` and `blocking_write` indicate if the read and write operations are blocking or non-blocking (see below).

- `offset` is the offset in bytes in the buffer object to read from or write to.

- `size` is the size in bytes of data being read or written.

- `ptr` is the pointer to buffer in host memory where data is to be read into or to be written from.

- `event_wait_list` and `num_events_in_wait_list` specify events that need to complete before this particular command can be executed. If `event_wait_list` is NULL, then this particular command does not wait on any event to complete. If `event_wait_list` is NULL, `num_events_in_wait_list` must be 0. If `event_wait_list` is not NULL, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0. The events specified in `event_wait_list` act as synchronization points. The context associated with events in `event_wait_list` and `command_queue` must be the same. The memory associated with `event_wait_list` can be reused or freed after the function returns.

- `event` returns an event object that identifies this read / write command and can be used to query or queue a wait for this command to complete. If `event` is NULL or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If `event_wait_list` and `event` are not NULL, `event` must not refer to an element of the `event_wait_list` array.

If `blocking_read` is `CL_TRUE` i.e. the read command is blocking, `clEnqueueReadBuffer` does not return until the buffer data has been read and copied into memory pointed to by `ptr`.

If `blocking_read` is `CL_FALSE` i.e. the read command is non-blocking, `clEnqueueReadBuffer` queues a non-blocking read command and returns. The contents of the buffer that `ptr` points to cannot be used until the read command has completed. The `event` argument returns an event object which can be used to query the execution status of the read command. When the read command has completed, the contents of the buffer that `ptr` points to can be used by the application.

If `blocking_write` is `CL_TRUE`, the write command is blocking and does not return until the command is complete, including transfer of the data. The memory pointed to by `ptr` can be reused by the
application after the clEnqueueWriteBuffer call returns.

If blocking_write is CL_FALSE, the OpenCL implementation will use ptr to perform a non-blocking write. As the write is non-blocking the implementation can return immediately. The memory pointed to by ptr cannot be reused by the application after the call returns. The event argument returns an event object which can be used to query the execution status of the write command. When the write command has completed, the memory pointed to by ptr can then be reused by the application.

cEnqueueReadBuffer and clEnqueueWriteBuffer return CL_SUCCESS if the function is executed successfully. Otherwise, they return one of the following errors:

- CL_INVALID_COMMAND_QUEUE if command_queue is not a valid host command-queue.
- CL_INVALID_CONTEXT if the context associated with command_queue and buffer are not the same or if the context associated with command_queue and events in event_wait_list are not the same.
- CL_INVALID_MEM_OBJECT if buffer is not a valid buffer object.
- CL_INVALID_VALUE if the region being read or written specified by (offset, size) is out of bounds or if ptr is a NULL value.
- CL_INVALID_EVENT_WAIT_LIST if event_wait_list is NULL and num_events_in_wait_list > 0, or event_wait_list is not NULL and num_events_in_wait_list is 0, or if event objects in event_wait_list are not valid events.
- CL_MISALIGNED_SUB_BUFFER_OFFSET if buffer is a sub-buffer object and offset specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for device associated with queue. This error code is missing before version 1.1.
- CL_EXEC_STATUS_ERROR_FOR_EVENTS_IN_WAIT_LIST if the read and write operations are blocking and the execution status of any of the events in event_wait_list is a negative integer value. This error code is missing before version 1.1.
- CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for data store associated with buffer.
- CL_INVALID_OPERATION if clEnqueueReadBuffer is called on buffer which has been created with CL_MEM_HOST_WRITE_ONLY or CL_MEM_HOST_NO_ACCESS.
- CL_INVALID_OPERATION if clEnqueueWriteBuffer is called on buffer which has been created with CL_MEM_HOST_READ_ONLY or CL_MEM_HOST_NO_ACCESS.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

The following functions enqueue commands to read a 2D or 3D rectangular region from a buffer object to host memory or write a 2D or 3D rectangular region to a buffer object from host memory.
clEnqueueReadBufferRect is missing before version 1.1.

clEnqueueWriteBufferRect is missing before version 1.1.

- `command_queue` refers is a valid host command-queue in which the read / write command will be queued. `command_queue` and `buffer` must be created with the same OpenCL context.

- `buffer` refers to a valid buffer object.

- `blocking_read` and `blocking_write` indicate if the read and write operations are blocking or non-blocking (see below).

- `buffer_origin` defines the \((x, y, z)\) offset in the memory region associated with `buffer`. For a 2D rectangle region, the \(z\) value given by `buffer_origin[2]` should be 0. The offset in bytes is computed as `buffer_origin[2] \times buffer_slice_pitch + buffer_origin[1] \times buffer_row_pitch + ...`
buffer_origin[0].

- **host_origin** defines the \((x, y, z)\) offset in the memory region pointed to by \(ptr\). For a 2D rectangle region, the \(z\) value given by \(host_origin[2]\) should be 0. The offset in bytes is computed as \(host_origin[2] \times host_slice_pitch + host_origin[1] \times host_row_pitch + host_origin[0]\).

- **region** defines the \((width\) in bytes, \(height\) in rows, \(depth\) in slices) of the 2D or 3D rectangle being read or written. For a 2D rectangle copy, the \(depth\) value given by \(region[2]\) should be 1. The values in region cannot be 0.

- **buffer_row_pitch** is the length of each row in bytes to be used for the memory region associated with \(buffer\). If \(buffer_row_pitch\) is 0, \(buffer_row_pitch\) is computed as \(region[0]\).

- **buffer_slice_pitch** is the length of each 2D slice in bytes to be used for the memory region associated with \(buffer\). If \(buffer_slice_pitch\) is 0, \(buffer_slice_pitch\) is computed as \(region[1] \times buffer_row_pitch\).

- **host_row_pitch** is the length of each row in bytes to be used for the memory region pointed to by \(ptr\). If \(host_row_pitch\) is 0, \(host_row_pitch\) is computed as \(region[0]\).

- **host_slice_pitch** is the length of each 2D slice in bytes to be used for the memory region pointed to by \(ptr\). If \(host_slice_pitch\) is 0, \(host_slice_pitch\) is computed as \(region[1] \times host_row_pitch\).

- **ptr** is the pointer to \(buffer\) in host memory where data is to be read into or to be written from.

- **event_wait_list** and **num_events_in_wait_list** specify events that need to complete before this particular command can be executed. If **event_wait_list** is **NULL**, then this particular command does not wait on any event to complete. If **event_wait_list** is **NULL**, **num_events_in_wait_list** must be 0. If **event_wait_list** is not **NULL**, the list of events pointed to by **event_wait_list** must be valid and **num_events_in_wait_list** must be greater than 0. The events specified in **event_wait_list** act as synchronization points. The context associated with events in **event_wait_list** and **command_queue** must be the same. The memory associated with **event_wait_list** can be reused or freed after the function returns.

- **event** returns an event object that identifies this read / write command and can be used to query or queue a wait for this command to complete. If **event** is **NULL** or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If **event_wait_list** and **event** are not **NULL**, **event** must not refer to an element of the **event_wait_list** array.

If **blocking_read** is **CL_TRUE** i.e. the read command is blocking, **clEnqueueReadBufferRect** does not return until the buffer data has been read and copied into memory pointed to by **ptr**.

If **blocking_read** is **CL_FALSE** i.e. the read command is non-blocking, **clEnqueueReadBufferRect** queues a non-blocking read command and returns. The contents of the buffer that **ptr** points to cannot be used until the read command has completed. The **event** argument returns an event object which can be used to query the execution status of the read command. When the read command has completed, the contents of the buffer that **ptr** points to can be used by the application.

If **blocking_write** is **CL_TRUE**, the write command is blocking and does not return until the command is complete, including transfer of the data. The memory pointed to by **ptr** can be reused by the application after the **clEnqueueWriteBufferRect** call returns.

If **blocking_write** is **CL_FALSE**, the OpenCL implementation will use **ptr** to perform a non-blocking
write. As the write is non-blocking the implementation can return immediately. The memory pointed to by ptr cannot be reused by the application after the call returns. The event argument returns an event object which can be used to query the execution status of the write command. When the write command has completed, the memory pointed to by ptr can then be reused by the application.

`clEnqueueReadBufferRect` and `clEnqueueWriteBufferRect` return CL_SUCCESS if the function is executed successfully. Otherwise, they return one of the following errors:

- CL_INVALID_COMMAND_QUEUE if command_queue is not a valid host command-queue.
- CL_INVALID_CONTEXT if the context associated with command_queue and buffer are not the same or if the context associated with command_queue and events in event_wait_list are not the same.
- CL_INVALID_MEM_OBJECT if buffer is not a valid buffer object.
- CL_INVALID_VALUE if buffer_origin, host_origin, or region is NULL.
- CL_INVALID_VALUE if the region being read or written specified by (buffer_origin, region, buffer_row_pitch, buffer_slice_pitch) is out of bounds.
- CL_INVALID_VALUE if any region array element is 0.
- CL_INVALID_VALUE if buffer_row_pitch is not 0 and is less than region[0].
- CL_INVALID_VALUE if host_row_pitch is not 0 and is less than region[0].
- CL_INVALID_VALUE if buffer_slice_pitch is not 0 and is less than region[1] × buffer_row_pitch and not a multiple of buffer_row_pitch.
- CL_INVALID_VALUE if host_slice_pitch is not 0 and is less than region[1] × host_row_pitch and not a multiple of host_row_pitch.
- CL_INVALID_VALUE if ptr is NULL.
- CL_INVALID_EVENT_WAIT_LIST if event_wait_list is NULL and num_events_in_wait_list > 0, or event_wait_list is not NULL and num_events_in_wait_list is 0, or if event objects in event_wait_list are not valid events.
- CL_MISALIGNED_SUB_BUFFER_OFFSET if buffer is a sub-buffer object and offset specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for device associated with queue. This error code is missing before version 1.1.
- CL_EXEC_STATUS_ERROR_FOR_EVENTS_IN_WAIT_LIST if the read and write operations are blocking and the execution status of any of the events in event_wait_list is a negative integer value. This error code is missing before version 1.1.
- CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for data store associated with buffer.
- CL_INVALID_OPERATION if `clEnqueueReadBufferRect` is called on buffer which has been created with CL_MEM_HOST_WRITE_ONLY or CL_MEM_HOST_NO_ACCESS.
- CL_INVALID_OPERATION if `clEnqueueWriteBufferRect` is called on buffer which has been created with CL_MEM_HOST_READ_ONLY or CL_MEM_HOST_NO_ACCESS.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

Calling `clEnqueueReadBuffer` to read a region of the buffer object with the `ptr` argument value set to `host_ptr + offset`, where `host_ptr` is a pointer to the memory region specified when the buffer object being read is created with `CL_MEM_USE_HOST_PTR`, must meet the following requirements in order to avoid undefined behavior:

- All commands that use this buffer object or a memory object (buffer or image) created from this buffer object have finished execution before the read command begins execution.
- The buffer object or memory objects created from this buffer object are not mapped.
- The buffer object or memory objects created from this buffer object are not used by any command-queue until the read command has finished execution.

Calling `clEnqueueReadBufferRect` to read a region of the buffer object with the `ptr` argument value set to `host_ptr` and `host_origin`, `buffer_origin` values are the same, where `host_ptr` is a pointer to the memory region specified when the buffer object being read is created with `CL_MEM_USE_HOST_PTR`, must meet the same requirements given above for `clEnqueueReadBuffer`.

Calling `clEnqueueWriteBuffer` to update the latest bits in a region of the buffer object with the `ptr` argument value set to `host_ptr + offset`, where `host_ptr` is a pointer to the memory region specified when the buffer object being written is created with `CL_MEM_USE_HOST_PTR`, must meet the following requirements in order to avoid undefined behavior:

- The host memory region given by `(host_ptr + offset, cb)` contains the latest bits when the enqueued write command begins execution.
- The buffer object or memory objects created from this buffer object are not mapped.
- The buffer object or memory objects created from this buffer object are not used by any command-queue until the write command has finished execution.

Calling `clEnqueueWriteBufferRect` to update the latest bits in a region of the buffer object with the `ptr` argument value set to `host_ptr` and `host_origin`, `buffer_origin` values are the same, where `host_ptr` is a pointer to the memory region specified when the buffer object being written is created with `CL_MEM_USE_HOST_PTR`, must meet the following requirements in order to avoid undefined behavior:

- The host memory region given by `(buffer_origin region)` contains the latest bits when the enqueued write command begins execution.
- The buffer object or memory objects created from this buffer object are not mapped.
• The buffer object or memory objects created from this buffer object are not used by any command-queue until the write command has finished execution.

To enqueue a command to copy a buffer object identified by src_buffer to another buffer object identified by dst_buffer, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clEnqueueCopyBuffer(
    cl_command_queue command_queue,
    cl_mem src_buffer,
    cl_mem dst_buffer,
    size_t src_offset,
    size_t dst_offset,
    size_t size,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

• `command_queue` refers to a host command-queue in which the copy command will be queued. The OpenCL context associated with `command_queue`, `src_buffer` and `dst_buffer` must be the same.

• `src_offset` refers to the offset where to begin copying data from `src_buffer`.

• `dst_offset` refers to the offset where to begin copying data into `dst_buffer`.

• `size` refers to the size in bytes to copy.

• `event_wait_list` and `num_events_in_wait_list` specify events that need to complete before this particular command can be executed. If `event_wait_list` is `NULL`, then this particular command does not wait on any event to complete. If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0. The events specified in `event_wait_list` act as synchronization points. The context associated with events in `event_wait_list` and `command_queue` must be the same. The memory associated with `event_wait_list` can be reused or freed after the function returns.

• `event` returns an event object that identifies this copy command and can be used to query or queue a wait for this command to complete. If `event` is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If `event_wait_list` and `event` are not `NULL`, `event` must not refer to an element of the `event_wait_list` array.

`clEnqueueCopyBuffer` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

• `CL_INVALID_COMMAND_QUEUE` if `command_queue` is not a valid host command-queue.

• `CL_INVALID_CONTEXT` if the context associated with `command_queue`, `src_buffer` and `dst_buffer` are not the same or if the context associated with `command_queue` and events in `event_wait_list` are not the same.
• **CL_INVALID_MEM_OBJECT** if `src_buffer` and `dst_buffer` are not valid buffer objects.

• **CL_INVALID_VALUE** if `src_offset`, `dst_offset`, `size`, `src_offset + size` or `dst_offset + size` require accessing elements outside the `src_buffer` and `dst_buffer` buffer objects respectively.

• **CL_INVALID_EVENT_WAIT_LIST** if `event_wait_list` is `NULL` and `num_events_in_wait_list > 0`, or `event_wait_list` is not `NULL` and `num_events_in_wait_list` is `0`, or if event objects in `event_wait_list` are not valid events.

• **CL_MISALIGNED_SUB_BUFFER_OFFSET** if `src_buffer` is a sub-buffer object and `offset` specified when the sub-buffer object is created is not aligned to `CL_DEVICE_MEM_BASE_ADDR_ALIGN` value for device associated with `queue`. This error code is missing before version 1.1.

• **CL_MISALIGNED_SUB_BUFFER_OFFSET** if `dst_buffer` is a sub-buffer object and `offset` specified when the sub-buffer object is created is not aligned to `CL_DEVICE_MEM_BASE_ADDR_ALIGN` value for device associated with `queue`. This error code is missing before version 1.1.

• **CL_MEM_COPY_OVERLAP** if `src_buffer` and `dst_buffer` are the same buffer or sub-buffer object and the source and destination regions overlap or if `src_buffer` and `dst_buffer` are different sub-buffers of the same associated buffer object and they overlap. The regions overlap if `src_offset ≤ dst_offset ≤ src_offset + size - 1` or if `dst_offset ≤ src_offset ≤ dst_offset + size - 1`.

• **CL_MEM_OBJECT_ALLOCATION_FAILURE** if there is a failure to allocate memory for data store associated with `src_buffer` or `dst_buffer`.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To enqueue a command to copy a 2D or 3D rectangular region from the buffer object identified by `src_buffer` to a 2D or 3D region in the buffer object identified by `dst_buffer`, call the function

```c
// Provided by CL_VERSION_1_1
cl_int clEnqueueCopyBufferRect(
    cl_command_queue command_queue,
    cl_mem src_buffer,
    cl_mem dst_buffer,
    const size_t* src_origin,
    const size_t* dst_origin,
    const size_t* region,
    size_t src_row_pitch,
    size_t src_slice_pitch,
    size_t dst_row_pitch,
    size_t dst_slice_pitch,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

---

• `clEnqueueCopyBufferRect` is missing before version 1.1.

• `command_queue` refers to the host command-queue in which the copy command will be queued.
The OpenCL context associated with `command_queue`, `src_buffer` and `dst_buffer` must be the same.

- `src_origin` defines the \((x, y, z)\) offset in the memory region associated with `src_buffer`. For a 2D rectangle region, the \(z\) value given by `src_origin[2]` should be 0. The offset in bytes is computed as \(src_origin[2] \times src_slice_pitch + src_origin[1] \times src_row_pitch + src_origin[0]\).

- `dst_origin` defines the \((x, y, z)\) offset in the memory region associated with `dst_buffer`. For a 2D rectangle region, the \(z\) value given by `dst_origin[2]` should be 0. The offset in bytes is computed as \(dst_origin[2] \times dst_slice_pitch + dst_origin[1] \times dst_row_pitch + dst_origin[0]\).

- `region` defines the \((width\) in bytes, \(height\) in rows, \(depth\) in slices) of the 2D or 3D rectangle being copied. For a 2D rectangle, the \(depth\) value given by `region[2]` should be 1. The values in `region` cannot be 0.

- `src_row_pitch` is the length of each row in bytes to be used for the memory region associated with `src_buffer`. If `src_row_pitch` is 0, `src_row_pitch` is computed as `region[0]`.

- `src_slice_pitch` is the length of each 2D slice in bytes to be used for the memory region associated with `src_buffer`. If `src_slice_pitch` is 0, `src_slice_pitch` is computed as `region[1] \times src_row_pitch`.

- `dst_row_pitch` is the length of each row in bytes to be used for the memory region associated with `dst_buffer`. If `dst_row_pitch` is 0, `dst_row_pitch` is computed as `region[0]`.

- `dst_slice_pitch` is the length of each 2D slice in bytes to be used for the memory region associated with `dst_buffer`. If `dst_slice_pitch` is 0, `dst_slice_pitch` is computed as `region[1] \times dst_row_pitch`.

- `event_wait_list` and `num_events_in_wait_list` specify events that need to complete before this particular command can be executed. If `event_wait_list` is `NULL`, then this particular command does not wait on any event to complete. If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0. The events specified in `event_wait_list` act as synchronization points. The context associated with events in `event_wait_list` and `command_queue` must be the same. The memory associated with `event_wait_list` can be reused or freed after the function returns.

- `event` returns an event object that identifies this copy command and can be used to query or queue a wait for this command to complete. If `event` is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If `event_wait_list` and `event` are not `NULL`, `event` must not refer to an element of the `event_wait_list` array.

Copying begins at the source offset and destination offset which are computed as described below in the description for `src_origin` and `dst_origin`. Each byte of the region’s width is copied from the source offset to the destination offset. After copying each width, the source and destination offsets are incremented by their respective source and destination row pitches. After copying each 2D rectangle, the source and destination offsets are incremented by their respective source and destination slice pitches.

If `src_buffer` and `dst_buffer` are the same buffer object, `src_row_pitch` must equal `dst_row_pitch` and `src_slice_pitch` must equal `dst_slice_pitch`.

`clEnqueueCopyBufferRect` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it
returns one of the following errors:

- **CL_INVALID_COMMAND_QUEUE** if `command_queue` is not a valid host command-queue.
- **CL_INVALID_CONTEXT** if the context associated with `command_queue, src_buffer` and `dst_buffer` are not the same or if the context associated with `command_queue` and events in `event_wait_list` are not the same.
- **CL_INVALID_MEM_OBJECT** if `src_buffer` and `dst_buffer` are not valid buffer objects.
- **CL_INVALID_VALUE** if `src_origin, dst_origin, or region` is NULL.
- **CL_INVALID_VALUE** if `(src_origin, region, src_row_pitch, src_slice_pitch)` or `(dst_origin, region, dst_row_pitch, dst_slice_pitch)` require accessing elements outside the `src_buffer` and `dst_buffer` buffer objects respectively.
- **CL_INVALID_VALUE** if any `region` array element is 0.
- **CL_INVALID_VALUE** if `src_row_pitch` is not 0 and is less than `region[0]`.
- **CL_INVALID_VALUE** if `dst_row_pitch` is not 0 and is less than `region[0]`.
- **CL_INVALID_VALUE** if `src_slice_pitch` is not 0 and is less than `region[1]` × `src_row_pitch` or if `src_slice_pitch` is not 0 and is not a multiple of `src_row_pitch`.
- **CL_INVALID_VALUE** if `dst_slice_pitch` is not 0 and is less than `region[1]` × `dst_row_pitch` or if `dst_slice_pitch` is not 0 and is not a multiple of `dst_row_pitch`.
- **CL_INVALID_VALUE** if `src_buffer` and `dst_buffer` are the same buffer object and `src_slice_pitch` is not equal to `dst_slice_pitch` and `src_row_pitch` is not equal to `dst_row_pitch`.
- **CL_INVALID_EVENT_WAIT_LIST** if `event_wait_list` is NULL and `num_events_in_wait_list` > 0, or `event_wait_list` is not NULL and `num_events_in_wait_list` is 0, or if event objects in `event_wait_list` are not valid events.
- **CL_MEM_COPY_OVERLAP** if `src_buffer` and `dst_buffer` are the same buffer or sub-buffer object and the source and destination regions overlap or if `src_buffer` and `dst_buffer` are different sub-buffers of the same associated buffer object and they overlap. Refer to Checking for Memory Copy Overlap for details on how to determine if source and destination regions overlap.
- **CL_MISALIGNED_SUB_BUFFER_OFFSET** if `src_buffer` is a sub-buffer object and `offset` specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for device associated with `queue`. This error code is missing before version 1.1.
- **CL_MISALIGNED_SUB_BUFFER_OFFSET** if `dst_buffer` is a sub-buffer object and `offset` specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for device associated with `queue`. This error code is missing before version 1.1.
- **CL_MEM_OBJECT_ALLOCATION_FAILURE** if there is a failure to allocate memory for data store associated with `src_buffer` or `dst_buffer`.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.
5.2.3. Filling Buffer Objects

Filling buffer objects is missing before version 1.2.

To enqueue a command to fill a buffer object with a pattern of a given pattern size, call the function

```c
// Provided by CL_VERSION_1_2
cl_int clEnqueueFillBuffer(
    cl_command_queue command_queue,
    cl_mem buffer,
    const void* pattern,
    size_t pattern_size,
    size_t offset,
    size_t size,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

- `command_queue` refers to the host command-queue in which the fill command will be queued. The OpenCL context associated with `command_queue` and `buffer` must be the same.
- `buffer` is a valid buffer object.
- `pattern` is a pointer to the data pattern of size `pattern_size` in bytes. `pattern` will be used to fill a region in `buffer` starting at `offset` and is `size` bytes in size. The data pattern must be a scalar or vector integer or floating-point data type supported by OpenCL as described in Supported Application Scalar Data Types and Supported Application Vector Data Types. For example, if `buffer` is to be filled with a pattern of `float4` values, then `pattern` will be a pointer to a `cl_float4` value and `pattern_size` will be `sizeof(cl_float4)`. The maximum value of `pattern_size` is the size of the largest integer or floating-point vector data type supported by the OpenCL device. The memory associated with `pattern` can be reused or freed after the function returns.
- `offset` is the location in bytes of the region being filled in `buffer` and must be a multiple of `pattern_size`.
- `size` is the size in bytes of region being filled in `buffer` and must be a multiple of `pattern_size`.
- `event_wait_list` and `num_events_in_wait_list` specify events that need to complete before this particular command can be executed. If `event_wait_list` is `NULL`, then this particular command does not wait on any event to complete. If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0. The events specified in `event_wait_list` act as synchronization points. The context associated with events in `event_wait_list` and `command_queue` must be the same. The memory associated with `event_wait_list` can be reused or freed after the function returns.
- `event` returns an event object that identifies this command and can be used to query or queue a wait for this command to complete. If `event` is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait
for this command to complete. If event_wait_list and event are not NULL, event must not refer to an element of the event_wait_list array.

The usage information which indicates whether the memory object can be read or written by a kernel and/or the host and is given by the cl_mem_flags argument value specified when buffer is created is ignored by clEnqueueFillBuffer.

clEnqueueFillBuffer returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_COMMAND_QUEUE** if command_queue is not a valid host command-queue.
- **CL_INVALID_CONTEXT** if the context associated with command_queue and buffer are not the same or if the context associated with command_queue and events in event_wait_list are not the same.
- **CL_INVALID_MEM_OBJECT** if buffer is not a valid buffer object.
- **CL_INVALID_VALUE** if offset or offset + size require accessing elements outside the buffer buffer object respectively.
- **CL_INVALID_VALUE** if pattern is NULL or if pattern_size is 0 or if pattern_size is not one of { 1, 2, 4, 8, 16, 32, 64, 128 }.
- **CL_INVALID_VALUE** if offset and size are not a multiple of pattern_size.
- **CL_INVALID_EVENT_WAIT_LIST** if event_wait_list is NULL and num_events_in_wait_list > 0, or event_wait_list is not NULL and num_events_in_wait_list is 0, or if event objects in event_wait_list are not valid events.
- **CL_MISALIGNED_SUB_BUFFER_OFFSET** if buffer is a sub-buffer object and offset specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for device associated with queue. This error code is missing before version 1.1.
- **CL_MEM_OBJECT_ALLOCATION_FAILURE** if there is a failure to allocate memory for data store associated with buffer.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.2.4. Mapping Buffer Objects

To enqueue a command to map a region of the buffer object given by buffer into the host address space and returns a pointer to this mapped region, call the function
// Provided by CL_VERSION_1_0
void* clEnqueueMapBuffer(
    cl_command_queue command_queue,
    cl_mem buffer,
    cl_bool blocking_map,
    cl_map_flags map_flags,
    size_t offset,
    size_t size,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event,
    cl_int* errcode_ret);

• command_queue must be a valid host command-queue.

• blocking_map indicates if the map operation is blocking or non-blocking.

If blocking_map is CL_TRUE, clEnqueueMapBuffer does not return until the specified region in buffer is mapped into the host address space and the application can access the contents of the mapped region using the pointer returned by clEnqueueMapBuffer.

If blocking_map is CL_FALSE i.e. map operation is non-blocking, the pointer to the mapped region returned by clEnqueueMapBuffer cannot be used until the map command has completed. The event argument returns an event object which can be used to query the execution status of the map command. When the map command is completed, the application can access the contents of the mapped region using the pointer returned by clEnqueueMapBuffer.

• map_flags is a bit-field and is described in the Memory Map Flags table.

• buffer is a valid buffer object. The OpenCL context associated with command_queue and buffer must be the same.

• offset and size are the offset in bytes and the size of the region in the buffer object that is being mapped.

• event_wait_list and num_events_in_wait_list specify events that need to complete before this particular command can be executed. If event_wait_list is NULL, then this particular command does not wait on any event to complete. If event_wait_list is NULL, num_events_in_wait_list must be 0. If event_wait_list is not NULL, the list of events pointed to by event_wait_list must be valid and num_events_in_wait_list must be greater than 0. The events specified in event_wait_list act as synchronization points. The context associated with events in event_wait_list and command_queue must be the same. The memory associated with event_wait_list can be reused or freed after the function returns.

• event returns an event object that identifies this command and can be used to query or queue a wait for this command to complete. If event is NULL or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If event_wait_list and event are not NULL, event must not refer to an element of the event_wait_list array.

• errcode_ret will return an appropriate error code. If errcode_ret is NULL, no error code is returned.
clEnqueueMapBuffer will return a pointer to the mapped region. The errcode_ret is set to CL_SUCCESS.

A NULL pointer is returned otherwise with one of the following error values returned in errcode_ret:

- CL_INVALID_COMMAND_QUEUE if command_queue is not a valid host command-queue.
- CL_INVALID_CONTEXT if context associated with command_queue and buffer are not the same or if the context associated with command_queue and events in event_wait_list are not the same.
- CL_INVALID_MEM_OBJECT if buffer is not a valid buffer object.
- CL_INVALID_VALUE if region being mapped given by (offset, size) is out of bounds or if size is 0 or if values specified in map_flags are not valid.
- CL_INVALID_EVENT_WAIT_LIST if event_wait_list is NULL and num_events_in_wait_list > 0, or event_wait_list is not NULL and num_events_in_wait_list is 0, or if event objects in event_wait_list are not valid events.
- CL_MISALIGNED_SUB_BUFFER_OFFSET if buffer is a sub-buffer object and offset specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for the device associated with queue. This error code is missing before version 1.1.
- CL_MAP_FAILURE if there is a failure to map the requested region into the host address space. This error cannot occur for buffer objects created with CL_MEM_USE_HOST_PTR or CL_MEM_ALLOC_HOST_PTR.
- CL_EXEC_STATUS_ERROR_FOR_EVENTS_IN_WAIT_LIST if the map operation is blocking and the execution status of any of the events in event_wait_list is a negative integer value. This error code is missing before version 1.1.
- CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for data store associated with buffer.
- CL_INVALID_OPERATION if buffer has been created with CL_MEM_HOST_WRITE_ONLY or CL_MEM_HOST_NO_ACCESS and CL_MAP_READ is set in map_flags or if buffer has been created with CL_MEM_HOST_READ_ONLY or CL_MEM_HOST_NO_ACCESS and CL_MAP_WRITE or CL_MAP_WRITE_INVALIDATE_REGION is set in map_flags.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.
- CL_INVALID_OPERATION if mapping would lead to overlapping regions being mapped for writing.

The pointer returned maps a region starting at offset and is at least size bytes in size. The result of a memory access outside this region is undefined.

If the buffer object is created with CL_MEM_USE_HOST_PTR set in mem_flags, the following will be true:

- The host_ptr specified in clCreateBuffer or clCreateBufferWithProperties will contain the latest bits in the region being mapped when the clEnqueueMapBuffer command has completed.
- The pointer value returned by clEnqueueMapBuffer will be derived from the host_ptr.
specifying when the buffer object is created.

Mapped buffer objects are unmapped using `clEnqueueUnmapMemObject`. This is described in Unmapping Mapped Memory Objects.

### Table 21. List of supported map flag values

<table>
<thead>
<tr>
<th>Map Flags</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>CL_MAP_READ</strong></td>
<td>This flag specifies that the region being mapped in the memory object is being mapped for reading. The pointer returned by <code>clEnqueueMapBuffer</code> (<code>clEnqueueMapImage</code>) is guaranteed to contain the latest bits in the region being mapped when the <code>clEnqueueMapBuffer</code> (<code>clEnqueueMapImage</code>) command has completed.</td>
</tr>
<tr>
<td><strong>CL_MAP_WRITE</strong></td>
<td>This flag specifies that the region being mapped in the memory object is being mapped for writing. The pointer returned by <code>clEnqueueMapBuffer</code> (<code>clEnqueueMapImage</code>) is guaranteed to contain the latest bits in the region being mapped when the <code>clEnqueueMapBuffer</code> (<code>clEnqueueMapImage</code>) command has completed</td>
</tr>
<tr>
<td><strong>CL_MAP_WRITE_INVALIDATE_REGION</strong></td>
<td>missing before version 1.2. This flag specifies that the region being mapped in the memory object is being mapped for writing. The contents of the region being mapped are to be discarded. This is typically the case when the region being mapped is overwritten by the host. This flag allows the implementation to no longer guarantee that the pointer returned by <code>clEnqueueMapBuffer</code> (<code>clEnqueueMapImage</code>) contains the latest bits in the region being mapped which can be a significant performance enhancement.</td>
</tr>
</tbody>
</table>

*CL_MAP_READ* or *CL_MAP_WRITE* and *CL_MAP_WRITE_INVALIDATE_REGION* are mutually exclusive.
5.2.5. Creating OpenCL Buffer Objects From Direct3D 10 Buffer Resources

To create an OpenCL buffer object from a Direct3D 10 buffer, call the function

```c
// Provided by cl_khr_d3d10_sharing
cl_mem clCreateFromD3D10BufferKHR(
    cl_context context,
    cl_mem_flags flags,
    ID3D10Buffer* resource,
    cl_int* errcode_ret);
```

---

- **context** is a valid OpenCL context created from a Direct3D 10 device.
- **flags** is a bit-field that is used to specify usage information. Refer to the List of supported memory flag values table for a description of flags. Only the CL_MEM_READ_ONLY, CL_MEM_WRITE_ONLY and CL_MEM_READ_WRITE flags specified in that table can be used.
- **resource** is a pointer to the Direct3D 10 buffer to share.
- **errcode_ret** will return an appropriate error code. If errcode_ret is NULL, no error code is returned.

The size of the returned OpenCL buffer object is the same as the size of resource. This call will increment the internal Direct3D 10 reference count on resource. The internal Direct3D 10 reference count on resource will be decremented when the OpenCL reference count on the returned OpenCL memory object drops to zero.

Refer to the Lifetime of Shared Direct3D Memory Objects and Acquiring, Releasing, and Synchronizing Access to Shared OpenCL/OpenGL Memory Objects sections for more information.

clCreateFromD3D10BufferKHR returns a valid non-zero OpenCL buffer object and errcode_ret is set to CL_SUCCESS if the buffer object is created successfully. Otherwise, it returns a NULL value with one of the following error values returned in errcode_ret:

- **CL_INVALID_CONTEXT** if context is not a valid context.
- **CL_INVALID_VALUE** if values specified in flags are not valid.
- **CL_INVALID_D3D10_RESOURCE_KHR** if resource is not a Direct3D 10 buffer resource, if resource was created with the D3D10_USAGE flag D3D10_USAGE_IMMUTABLE, if a cl_mem from resource has already been created using clCreateFromD3D10BufferKHR, or if context was not created against the same Direct3D 10 device from which resource was created.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.
5.2.6. Creating OpenCL Buffer Objects From Direct3D 11 Buffer Resources

To create an OpenCL buffer object from a Direct3D 11 buffer, call the function

```c
// Provided by cl_khr_d3d11_sharing
cl_mem clCreateFromD3D11BufferKHR(
    cl_context context,
    cl_mem_flags flags,
    ID3D11Buffer* resource,
    cl_int* errcode_ret);
```

**clCreateFromD3D11BufferKHR** is provided by the **cl_khr_d3d11_sharing** extension.

- **context** is a valid OpenCL context created from a Direct3D 11 device.
- **flags** is a bit-field that is used to specify usage information. Refer to the List of supported memory flag values table for a description of flags. Only the **CL_MEM_READ_ONLY**, **CL_MEM_WRITE_ONLY** and **CL_MEM_READ_WRITE** flags specified in that table can be used.
- **resource** is a pointer to the Direct3D 11 buffer to share.
- **errcode_ret** will return an appropriate error code. If **errcode_ret** is **NULL**, no error code is returned.

The size of the returned OpenCL buffer object is the same as the size of **resource**. This call will increment the internal Direct3D 11 reference count on **resource**. The internal Direct3D 11 reference count on **resource** will be decremented when the OpenCL reference count on the returned OpenCL memory object drops to zero.

Refer to the Lifetime of Shared Direct3D Memory Objects and Acquiring, Releasing, and Synchronizing Access to Shared OpenCL/OpenGL Memory Objects sections for more information.

**clCreateFromD3D11BufferKHR** returns a valid non-zero OpenCL buffer object and **errcode_ret** is set to **CL_SUCCESS** if the buffer object is created successfully. Otherwise, it returns a **NULL** value with one of the following error values returned in **errcode_ret**:

- **CL_INVALID_CONTEXT** if **context** is not a valid context.
- **CL_INVALID_VALUE** if values specified in **flags** are not valid.
- **CL_INVALID_D3D11RESOURCE_KHR** if **resource** is not a Direct3D 11 buffer resource, if **resource** was created with the D3D11_USAGE flag D3D11_USAGE_IMMUTABLE, if a **cl_mem** from **resource** has already been created using **clCreateFromD3D11BufferKHR**, or if **context** was not created against the same Direct3D 11 device from which **resource** was created.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.
5.2.7. Creating OpenCL Buffer Objects From OpenGL Buffer Objects

To create an OpenCL buffer object from an OpenGL buffer object, call the function

```c
// Provided by cl_khr_gl_sharing
cl_mem clCreateFromGLBuffer(
    cl_context context,
    cl_mem_flags flags,
    cl_Gluint bufobj,
    cl_int* errcode_ret);
```

**clCreateFromGLBuffer** is provided by the *cl_khr_gl_sharing* extension.

- `context` is a valid OpenCL context created from an OpenGL context.
- `flags` is a bit-field that is used to specify usage information. Refer to the Memory Flags table for a description of `flags`. Only the `CL_MEM_READ_ONLY`, `CL_MEM_WRITE_ONLY` and `CL_MEM_READ_WRITE` flags specified in that table can be used.
- `bufobj` is the name of an OpenGL buffer object. The data store of the OpenGL buffer object must have have been previously created by calling *glBufferData*, although its contents need not be initialized. The size of the data store will be used to determine the size of the OpenCL buffer object.
- `errcode_ret` will return an appropriate error code as described below. If `errcode_ret` is `NULL`, no error code is returned.

The size of the OpenGL buffer object data store at the time `clCreateFromGLBuffer` is called will be used as the size of buffer object returned by `clCreateFromGLBuffer`. If the state of an OpenGL buffer object is modified through the OpenGL API (e.g. *glBufferData*) while there exists a corresponding OpenCL buffer object, subsequent use of the OpenCL buffer object will result in undefined behavior.

The `clRetainMemObject` and `clReleaseMemObject` functions can be used to retain and release the buffer object.

The OpenCL buffer object created using `clCreateFromGLBuffer` can also be used to create an OpenCL 1D image buffer object.

Refer to the Lifetime of Shared OpenCL/OpenGL Memory Objects and Acquiring, Releasing, and Synchronizing Access to Shared OpenCL/OpenGL Memory Objects sections for more information.

`clCreateFromGLBuffer` returns a valid non-zero OpenCL buffer object and `errcode_ret` is set to `CL_SUCCESS` if the buffer object is created successfully. Otherwise, it returns a `NULL` value with one of the following error values returned in `errcode_ret`:

- `CL_INVALID_CONTEXT` if `context` is not a valid context or was not created from an OpenGL context.
- `CL_INVALID_VALUE` if values specified in `flags` are not valid.
• **CL_INVALID_GL_OBJECT** if `bufobj` is not an OpenGL buffer object or is a OpenGL buffer object but does not have an existing data store or the size of the buffer is 0.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.3. Image Objects

An *image* object is used to store a one-, two- or three-dimensional texture, frame-buffer or image. The elements of an image object are selected from a list of predefined image formats. The minimum number of elements in a memory object is one.

#### 5.3.1. Creating Image Objects

An *image object* may be created using the function

```c
// Provided by CL_VERSION_1_2
cl_mem clCreateImage(
    cl_context context,
    cl_mem_flags flags,
    const cl_image_format* image_format,
    const cl_image_desc* image_desc,
    void* host_ptr,
    cl_int* errcode_ret);
```

*clCreateImage* is missing before version 1.2.

An *image object* may also be created with additional properties using the function

```c
// Provided by CL_VERSION_3_0
cl_mem clCreateImageWithProperties(
    cl_context context,
    const cl_mem_properties* properties,
    cl_mem_flags flags,
    const cl_image_format* image_format,
    const cl_image_desc* image_desc,
    void* host_ptr,
    cl_int* errcode_ret);
```

*clCreateImageWithProperties* is missing before version 3.0.

- **context** is a valid OpenCL context used to create the image object.

- **properties** is an optional list of properties for the image object and their corresponding values. The list is terminated with the special property 0. If no properties are required, **properties** may
OpenCL 3.0 does not define any optional properties for images, but extensions may define properties as described in the List of supported image creation properties.

- **flags** is a bit-field that is used to specify allocation and usage information about the image memory object being created and is described in the supported memory flag values table.

- **image_format** is a pointer to a structure that describes format properties of the image to be allocated. A 1D image buffer or 2D image can be created from a buffer by specifying a buffer object in the `image_desc→mem_object`. A 2D image can be created from another 2D image object by specifying an image object in the `image_desc→mem_object`. Refer to the Image Format Descriptor section for a detailed description of the image format descriptor.

- **image_desc** is a pointer to a structure that describes type and dimensions of the image to be allocated. Refer to the Image Descriptor section for a detailed description of the image descriptor.

- **host_ptr** is a pointer to the image data that may already be allocated by the application. Refer to the table below for a description of how large the buffer that `host_ptr` points to must be.

- **errcode_ret** will return an appropriate error code. If `errcode_ret` is `NULL`, no error code is returned.

The alignment requirements for data stored in image objects are described in Alignment of Application Data Types.

For all image types except **CL_MEM_OBJECT_IMAGE1D_BUFFER**, if the value specified for `flags` is 0, the default is used which is **CL_MEM_READ_WRITE**.

For **CL_MEM_OBJECT_IMAGE1D_BUFFER** image type, or an image created from another memory object (image or buffer), if the **CL_MEM_READ_WRITE**, **CL_MEM_READ_ONLY**, or **CL_MEM_WRITE_ONLY** values are not specified in `flags`, they are inherited from the corresponding memory access qualifiers associated with `mem_object`. The **CL_MEM_USE_HOST_PTR**, **CL_MEM_ALLOC_HOST_PTR**, and **CL_MEM_COPY_HOST_PTR** values cannot be specified in `flags` but are inherited from the corresponding memory access qualifiers associated with `mem_object`. If **CL_MEM_COPY_HOST_PTR** is specified in the memory access qualifier values associated with `mem_object` it does not imply any additional copies when the image is created from `mem_object`. If the **CL_MEM_HOST_WRITE_ONLY**, **CL_MEM_HOST_READ_ONLY**, or **CL_MEM_HOST_NO_ACCESS** values are not specified in `flags`, they are inherited from the corresponding memory access qualifiers associated with `mem_object`.

**Mipmap Images**

A mipmapped 1D image, 1D image array, 2D image, 2D image array or 3D image is created by specifying **num_mip_levels** to be a value greater than one in `image_desc`. The dimensions of a mipmapped image can be a power of two or a non-power of two. Each successively smaller mipmap level is half the size of the previous level, rounded down to the nearest integer.

The following restrictions apply when mipmapped images are created with **clCreateImage**:

- **CL_MEM_USE_HOST_PTR** or **CL_MEM_COPY_HOST_PTR** cannot be specified if a mipmapped image is created.

- The `host_ptr` argument to **clCreateImage** must be a **NULL** value.

- Mip-mapped images cannot be created for **CL_MEM_OBJECT_IMAGE1D_BUFFER** images, depth images
or multi-sampled (i.e. msaa) images.

**Image Data in Host Memory**

For a 3D image or 2D image array, the image data specified by `host_ptr` is stored as a linear sequence of adjacent 2D image slices or 2D images respectively. Each 2D image is a linear sequence of adjacent scanlines. Each scanline is a linear sequence of image elements.

For a 2D image, the image data specified by `host_ptr` is stored as a linear sequence of adjacent scanlines. Each scanline is a linear sequence of image elements.

For a 1D image array, the image data specified by `host_ptr` is stored as a linear sequence of adjacent 1D images. Each 1D image is stored as a single scanline which is a linear sequence of adjacent elements.

For 1D image or 1D image buffer, the image data specified by `host_ptr` is stored as a single scanline which is a linear sequence of adjacent elements.

Image elements are stored according to their image format as described in the Image Format Descriptor section.

**Table 22. List of supported image creation properties**

<table>
<thead>
<tr>
<th>Property</th>
<th>Property Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_MEMDEVICEHANDLELIST_KHR</td>
<td>cl_device_id[]</td>
<td>Specifies the list of OpenCL devices (terminated with CL_MEMDEVICEHANDLELISTEND_KHR) to associate with the external memory handle.</td>
</tr>
<tr>
<td>provided by the cl_khr_external_memory</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

If **CL_MEMDEVICEHANDLELIST_KHR** is not specified as part of *properties*, the memory object created by `clCreateBufferWithProperties` or `clCreateImageWithProperties` is by default accessible to all devices in the *context*.

The properties used to create an image from an external memory handle are described for the corresponding extensions. When an image is created from an external memory handle, the *flags* used to specify usage information for the image must not include **CL_USE_HOST_PTR**, **CL_ALLOC_HOST_PTR**, or **CL_COPY_HOST_PTR**, and the *host_ptr* argument must be **NULL**. When images are created from an external memory handle, implementations may acquire information about image attributes such as format and layout at the time of creation. When such information is acquired at image creation time, it is used for the lifetime of the image object.

`clCreateImage` and `clCreateImageWithProperties` returns a valid non-zero image object and *errcode_ret* is set to **CL_SUCCESS** if the image object is created successfully. Otherwise, they return a **NULL** value with one of the following error values returned in *errcode_ret*:

- **CL_INVALID_CONTEXT** if *context* is not a valid context.
- **CL_INVALID_PROPERTY** if a property name in *properties* is not a supported property name, if the value specified for a supported property name is not valid, or if the same property name is specified more than once.
• **CL_INVALID_VALUE** if values specified in *flags* are not valid.

• **CL_INVALID_IMAGE_FORMAT_DESCRIPTOR** if values specified in *image_format* are not valid or if *image_format* is NULL.

• **CL_INVALID_IMAGE_FORMAT_DESCRIPTOR** if a 2D image is created from a buffer and the row pitch and base address alignment does not follow the rules described for creating a 2D image from a buffer.

• **CL_INVALID_IMAGE_FORMAT_DESCRIPTOR** if a 2D image is created from a 2D image object and the rules described above are not followed.

• **CL_INVALID_IMAGE_DESCRIPTOR** if values specified in *image_desc* are not valid or if *image_desc* is NULL.

• **CL_INVALID_IMAGE_SIZE** if image dimensions specified in *image_desc* exceed the maximum image dimensions described in the **Device Queries** table for all devices in *context*.

• **CL_INVALID_HOST_PTR** if *host_ptr* is NULL and **CL_MEM_USE_HOST_PTR** or **CL_MEM_COPY_HOST_PTR** are set in *flags* or if *host_ptr* is not NULL but **CL_MEM_COPY_HOST_PTR** or **CL_MEM_USE_HOST_PTR** are not set in *flags*.

• **CL_INVALID_VALUE** if an image is being created from another memory object (buffer or image) under one of the following circumstances: 1) *mem_object* was created with **CL_MEM_WRITE_ONLY** and *flags* specifies **CL_MEM_READ_WRITE** or **CL_MEM_READ_ONLY**, 2) *mem_object* was created with **CL_MEM_READ_ONLY** and *flags* specifies **CL_MEM_READ_WRITE** or **CL_MEM_WRITE_ONLY**, 3) *flags* specifies **CL_MEM_USE_HOST_PTR** or **CL_MEM_ALLOC_HOST_PTR** or **CL_MEM_COPY_HOST_PTR**.

• **CL_INVALID_VALUE** if an image is being created from another memory object (buffer or image) and *mem_object* was created with **CL_MEM_HOST_WRITE_ONLY** and *flags* specifies **CL_MEM_HOST_READ_ONLY**, or if *mem_object* was created with **CL_MEM_HOST_READ_ONLY** and *flags* specifies **CL_MEM_HOST_WRITE_ONLY**, or if *mem_object* was created with **CL_MEM_HOST_NO_ACCESS** and *flags* specifies **CL_MEM_HOST_READ_ONLY** or **CL_MEM_HOST_WRITE_ONLY**.

• **CL_IMAGE_FORMAT_NOT_SUPPORTED** if there are no devices in *context* that support *image_format*.

• **CL_MEM_OBJECT_ALLOCATION_FAILURE** if there is a failure to allocate memory for image object.

• **CL_INVALID_OPERATION** if there are no devices in *context* that support images (i.e. **CL_DEVICE_IMAGE_SUPPORT** specified in the **Device Queries** table is **CL_FALSE**).

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

• **CL_INVALID_DEVICE**
  
  ◦ if a device identified by the property **CL_MEM_DEVICE_HANDLE_LIST_KHR** is not a valid device or is not associated with *context*, or
  
  ◦ if a device identified by property **CL_MEM_DEVICE_HANDLE_LIST_KHR** cannot import the requested external memory object type, or
  
  ◦ if **CL_MEM_DEVICE_HANDLE_LIST_KHR** is not specified as part of *properties* and one or more devices in *context* cannot import the requested external memory object type.

• **CL_INVALID_VALUE**
• If properties includes a supported external memory handle and flags includes CL_MEM_USE_HOST_PTR, CL_MEM_ALLOC_HOST_PTR, or CL_MEM_COPY_HOST_PTR.

• CL_INVALID_HOST_PTR
  • If properties includes a supported external memory handle and host_ptr is not NULL.

• CL_INVALID_PROPERTY
  • If properties does not include a supported external memory handle and CL_MEM_DEVICEHANDLE_LIST_KHR is specified as part of properties.

### Table 23. Required host_ptr buffer sizes for images

<table>
<thead>
<tr>
<th>Image Type</th>
<th>Size of buffer that host_ptr points to</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_MEM_OBJECT_IMAGE1D</td>
<td>≥ image_row_pitch</td>
</tr>
<tr>
<td>missing before version 1.2.</td>
<td></td>
</tr>
<tr>
<td>CL_MEM_OBJECT_IMAGE1D_BUFFER</td>
<td>≥ image_row_pitch</td>
</tr>
<tr>
<td>missing before version 1.2.</td>
<td></td>
</tr>
<tr>
<td>CL_MEM_OBJECT_IMAGE2D</td>
<td>≥ image_row_pitch × image_height</td>
</tr>
<tr>
<td>CL_MEM_OBJECT_IMAGE3D</td>
<td>≥ image_slice_pitch × image_depth</td>
</tr>
<tr>
<td>CL_MEM_OBJECT_IMAGE1D_ARRAY</td>
<td>≥ image_slice_pitch × image_array_size</td>
</tr>
<tr>
<td>missing before version 1.2.</td>
<td></td>
</tr>
<tr>
<td>CL_MEM_OBJECT_IMAGE2D_ARRAY</td>
<td>≥ image_slice_pitch × image_array_size</td>
</tr>
<tr>
<td>missing before version 1.2.</td>
<td></td>
</tr>
</tbody>
</table>

A 2D image object can be created using the following function

```c
// Provided by CL_VERSION_1_0
cl_mem clCreateImage2D(
    cl_context context,
    cl_mem_flags flags,
    const cl_image_format* image_format,
    size_t image_width,
    size_t image_height,
    size_t image_row_pitch,
    void* host_ptr,
    cl_int* errcode_ret);
```

**clCreateImage2D** is deprecated by version 1.2.

• context is a valid OpenCL context on which the image object is to be created.

• flags is a bit-field that is used to specify allocation and usage information about the image memory object being created and is described in the supported memory flag values table. If the
value specified for flags is 0, the default is used which is `CL_MEM_READ_WRITE`.

- **image_format** is a pointer to a structure that describes format properties of the image to be allocated. Refer to the Image Format Descriptor section for a detailed description of the image format descriptor.

- **image_width** and **image_height** are the width and height of the image in pixels. These must be values greater than or equal to 1.

- **image_row_pitch** is the scan-line pitch in bytes. This must be 0 if `host_ptr` is `NULL` and can be either 0 or \( \geq \text{image_width} \times \text{size of element in bytes} \) if `host_ptr` is not `NULL`. If `host_ptr` is not `NULL` and `image_row_pitch` is 0, `image_row_pitch` is calculated as \( \text{image_width} \times \text{size of element in bytes} \). If `image_row_pitch` is not 0, it must be a multiple of the image element size in bytes.

- **host_ptr** is a pointer to the image data that may already be allocated by the application. Refer to the CL_MEM_OBJECT_IMAGE2D entry in the required host_ptr buffer size table for a description of how large the buffer that `host_ptr` points to must be. The image data specified by `host_ptr` is stored as a linear sequence of adjacent scanlines. Each scanline is a linear sequence of image elements. Image elements are stored according to their image format as described in the Image Format Descriptor section.

- **errcode_ret** will return an appropriate error code. If `errcode_ret` is `NULL`, no error code is returned.

`clCreateImage2D` returns a valid non-zero image object created and the `errcode_ret` is set to `CL_SUCCESS` if the image object is created successfully. Otherwise, it returns a `NULL` value with one of the following error values returned in `errcode_ret`:

- **CL_INVALID_CONTEXT** if `context` is not a valid context.

- **CL_INVALID_VALUE** if values specified in flags are not valid.

- **CL_INVALID_IMAGE_FORMAT_DESCRIPTOR** if values specified in `image_format` are not valid or if `image_format` is `NULL`.

- **CL_INVALID_IMAGE_SIZE** if `image_width` or `image_height` are 0 or if they exceed the maximum values specified in `CL_DEVICE_IMAGE2D_MAX_WIDTH` or `CL_DEVICE_IMAGE2D_MAX_HEIGHT` respectively for all devices in `context` or if values specified by `image_row_pitch` do not follow rules described in the argument description above.

- **CL_INVALID_HOST_PTR** if `host_ptr` is `NULL` and `CL_MEM_USE_HOST_PTR` or `CL_MEM_COPY_HOST_PTR` are set in flags or if `host_ptr` is not `NULL` but `CL_MEM_COPY_HOST_PTR` or `CL_MEM_USE_HOST_PTR` are not set in flags.

- **CL_IMAGE_FORMAT_NOT_SUPPORTED** if there are no devices in `context` that support `image_format`.

- **CL_MEM_OBJECT_ALLOCATION_FAILURE** if there is a failure to allocate memory for image object.

- **CL_INVALID_OPERATION** if there are no devices in `context` that support images (i.e. `CL_DEVICE_IMAGE_SUPPORT` specified in the Device Queries table is `CL_FALSE`).

- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.
A 3D image object can be created using the following function

```c
// Provided by CL_VERSION_1_0
cl_mem clCreateImage3D(
    cl_context context,
    cl_mem_flags flags,
    const cl_image_format* image_format,
    size_t image_width,
    size_t image_height,
    size_t image_depth,
    size_t image_row_pitch,
    size_t image_slice_pitch,
    void* host_ptr,
    cl_int* errcode_ret);
```

- `context` is a valid OpenCL context on which the image object is to be created.
- `flags` is a bit-field that is used to specify allocation and usage information about the image memory object being created and is described in the supported memory flag values table. If the value specified for `flags` is 0, the default is used which is CL_MEM_READ_WRITE.
- `image_format` is a pointer to a structure that describes format properties of the image to be allocated. Refer to the Image Format Descriptor section for a detailed description of the image format descriptor.
- `image_width` and `image_height` are the width and height of the image in pixels. These must be values greater than or equal to 1.
- `image_depth` is the depth of the image in pixels. For clCreateImage3D, this must be a value > 1.
- `image_row_pitch` is the scan-line pitch in bytes. This must be 0 if `host_ptr` is NULL and can be either 0 or ≥ image_width × size of element in bytes if `host_ptr` is not NULL. If `host_ptr` is not NULL and `image_row_pitch` is 0, `image_row_pitch` is calculated as image_width × size of element in bytes. If `image_row_pitch` is not 0, it must be a multiple of the image element size in bytes.
- `image_slice_pitch` is the size in bytes of each 2D slice in the 3D image. This must be 0 if `host_ptr` is NULL and can be 0 or ≥ image_row_pitch × image_height if `host_ptr` is not NULL. If `host_ptr` is not NULL and `image_slice_pitch` is 0, `image_slice_pitch` is calculated as image_row_pitch × image_height. If `image_slice_pitch` is not 0, it must be a multiple of the image_row_pitch.
- `host_ptr` is a pointer to the image data that may already be allocated by the application. Refer to the CL_MEM_OBJECT_IMAGE3D entry in the required host_ptr buffer size table for a description of how large the buffer that `host_ptr` points to must be. The image data specified by `host_ptr` is stored as a linear sequence of adjacent 2D slices. Each scanline is a linear sequence of image elements. Image elements are stored according to their image format as described in the Image Format Descriptor section.
- `errcode_ret` will return an appropriate error code. If `errcode_ret` is NULL, no error code is returned.

clCreateImage3D is deprecated by version 1.2.
clCreateImage3D returns a valid non-zero image object created and the errcode_ret is set to CL_SUCCESS if the image object is created successfully. Otherwise, it returns a NULL value with one of the following error values returned in errcode_ret:

- CL_INVALID_CONTEXT if context is not a valid context.
- CL_INVALID_VALUE if values specified in flags are not valid.
- CL_INVALID_IMAGE_FORMAT_DESCRIPTOR if values specified in image_format are not valid or if image_format is NULL.
- CL_INVALID_IMAGE_SIZE if image_width or image_height are 0 or if image_depth ≤ 1, or if they exceed the maximum values specified in CL_DEVICE_IMAGE3D_MAX_WIDTH, CL_DEVICE_IMAGE3D_MAX_HEIGHT or CL_DEVICE_IMAGE3D_MAX_DEPTH respectively for all devices in context, or if values specified by image_row_pitch and image_slice_pitch do not follow rules described in the argument description above.
- CL_INVALID_HOST_PTR if host_ptr is NULL and CL_MEM_USE_HOST_PTR or CL_MEM_COPY_HOST_PTR are set in flags or if host_ptr is not NULL but CL_MEM_COPY_HOST_PTR or CL_MEM_USE_HOST_PTR are not set in flags.
- CL_IMAGE_FORMAT_NOT_SUPPORTED if there are no devices in context that support image_format.
- CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for image object.
- CL_INVALID_OPERATION if there are no devices in context that support images (i.e. CL_DEVICE_IMAGE_SUPPORT specified in the Device Queries table is CL_FALSE).
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

5.3.1.1. Image Format Descriptor

The cl_image_format image format descriptor structure describes an image format, and is defined as:

```c
// Provided by CL_VERSION_1_0
typedef struct cl_image_format {
    cl_channel_order image_channel_order;
    cl_channel_type image_channel_data_type;
} cl_image_format;
```

- **image_channel_order** specifies the number of channels and the channel layout i.e. the memory layout in which channels are stored in the image. Valid values are described in the Image Channel Order table.
- **image_channel_data_type** describes the size of the channel data type. The list of supported values is described in the Image Channel Data Types table. The number of bits per element determined by the image_channel_data_type and image_channel_order must be a power of two.

Table 24. List of supported Image Channel Order Values
<table>
<thead>
<tr>
<th>Image Channel Order</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_R, CL_A,</td>
<td>Single channel image formats where the single channel represents a RED or ALPHA component.</td>
</tr>
<tr>
<td>CL_DEPTH</td>
<td>A single channel image format where the single channel represents a DEPTH component. Also supported if the cl_khr_depth_images extension is supported.</td>
</tr>
<tr>
<td>CL_LUMINANCE</td>
<td>A single channel image format where the single channel represents a LUMINANCE value. The LUMINANCE value is replicated into the RED, GREEN, and BLUE components.</td>
</tr>
<tr>
<td>CL_INTENSITY,</td>
<td>A single channel image format where the single channel represents an INTENSITY value. The INTENSITY value is replicated into the RED, GREEN, BLUE, and ALPHA components.</td>
</tr>
<tr>
<td>CL_RG, CL_RA</td>
<td>Two channel image formats. The first channel always represents a RED component. The second channel represents a GREEN component or an ALPHA component.</td>
</tr>
<tr>
<td>CL_Rx</td>
<td>A two channel image format, where the first channel represents a RED component and the second channel is ignored.</td>
</tr>
<tr>
<td>CL_DEPTH_STENCIL</td>
<td>A two channel image format, where the first channel represents a DEPTH component and the second channel represents a stencil component. This format can only be used if the image channel data type is CL_UNORM_INT24 or CL_FLOAT. See Restrictions on Depth/Stencil Images.</td>
</tr>
<tr>
<td>CL_RGB</td>
<td>A three channel image format, where the three channels represent RED, GREEN, and BLUE components.</td>
</tr>
<tr>
<td>CL_RGBx</td>
<td>A three channel image format, where the first two channels represent RED and GREEN components and the third channel is ignored.</td>
</tr>
<tr>
<td>CL_RGBA, CL_ARGB, CL_BGRA, CL_ABGR</td>
<td>Four channel image formats, where the four channels represent RED, GREEN, BLUE, and ALPHA components. CL_ABGR is missing before version 2.0.</td>
</tr>
<tr>
<td>CL_RGBA</td>
<td>A four channel image format, where the first three channels represent RED, GREEN, and BLUE components and the fourth channel is ignored.</td>
</tr>
<tr>
<td>CL_RGBx</td>
<td>A four channel image format, where the first three channels represent RED, GREEN, and BLUE components and the fourth channel is ignored.</td>
</tr>
<tr>
<td>Image Channel Order</td>
<td>Description</td>
</tr>
<tr>
<td>---------------------</td>
<td>-------------</td>
</tr>
<tr>
<td>CL_sRGB</td>
<td>A three channel image format, where the three channels represent RED, GREEN, and BLUE components in the sRGB color space.</td>
</tr>
<tr>
<td>missing before version 2.0.</td>
<td></td>
</tr>
<tr>
<td>CL_sRGBA, CL_sBGRA</td>
<td>Four channel image formats, where the first three channels represent RED, GREEN, and BLUE components in the sRGB color space. The fourth channel represents an ALPHA component.</td>
</tr>
<tr>
<td>missing before version 2.0.</td>
<td></td>
</tr>
<tr>
<td>CL_sRGBx</td>
<td>A four channel image format, where the three channels represent RED, GREEN, and BLUE components in the sRGB color space. The fourth channel is ignored.</td>
</tr>
<tr>
<td>missing before version 2.0.</td>
<td></td>
</tr>
</tbody>
</table>

Table 25. List of supported Image Channel Data Types

<table>
<thead>
<tr>
<th>Image Channel Data Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_SNORM_INT8</td>
<td>Each channel component is a normalized signed 8-bit integer value</td>
</tr>
<tr>
<td>CL_SNORM_INT16</td>
<td>Each channel component is a normalized signed 16-bit integer value</td>
</tr>
<tr>
<td>CL_UNORM_INT8</td>
<td>Each channel component is a normalized unsigned 8-bit integer value</td>
</tr>
<tr>
<td>CL_UNORM_INT16</td>
<td>Each channel component is a normalized unsigned 16-bit integer value</td>
</tr>
<tr>
<td></td>
<td>Also supported if the cl_khr_depth_images extension is supported.</td>
</tr>
<tr>
<td>CL_UNORM_SHORT_565</td>
<td>Represents a normalized 5-6-5 3-channel RGB image. The channel order must be CL_RGB or CL_RGBx.</td>
</tr>
<tr>
<td>CL_UNORM_SHORT_555</td>
<td>Represents a normalized x-5-5-5 4-channel xRGB image. The channel order must be CL_RGB or CL_RGBx.</td>
</tr>
<tr>
<td>CL_UNORM_INT_101010</td>
<td>Represents a normalized x-10-10-10 4-channel xRGB image. The channel order must be CL_RGB or CL_RGBx.</td>
</tr>
<tr>
<td>CL_UNORM_INT_101010_2</td>
<td>Represents a normalized 10-10-10-2 four-channel RGBA image. The channel order must be CL_RGBA.</td>
</tr>
<tr>
<td>missing before version 2.1.</td>
<td></td>
</tr>
<tr>
<td>CL_SIGNED_INT8</td>
<td>Each channel component is an unnormalized signed 8-bit integer value</td>
</tr>
<tr>
<td>CL_SIGNED_INT16</td>
<td>Each channel component is an unnormalized signed 16-bit integer value</td>
</tr>
<tr>
<td>Image Channel Data Type</td>
<td>Description</td>
</tr>
<tr>
<td>------------------------</td>
<td>-------------</td>
</tr>
<tr>
<td>CL_SIGNED_INT32</td>
<td>Each channel component is an unnormalized signed 32-bit integer value</td>
</tr>
<tr>
<td>CL_UNSIGNED_INT8</td>
<td>Each channel component is an unnormalized unsigned 8-bit integer value</td>
</tr>
<tr>
<td>CL_UNSIGNED_INT16</td>
<td>Each channel component is an unnormalized unsigned 16-bit integer value</td>
</tr>
<tr>
<td>CL_UNORM_INT24</td>
<td>Provided by the <code>cl_khr_gl_depth_images</code> extension. Each channel component is a normalized unsigned 24-bit integer value</td>
</tr>
<tr>
<td>CL_UNSIGNED_INT32</td>
<td>Each channel component is an unnormalized unsigned 32-bit integer value</td>
</tr>
<tr>
<td>CL_HALF_FLOAT</td>
<td>Each channel component is a 16-bit half-float value</td>
</tr>
<tr>
<td>CL_FLOAT</td>
<td>Also supported if the <code>cl_khr_depth_images</code> extension is supported. Each channel component is a single precision floating-point value</td>
</tr>
</tbody>
</table>

For example, to specify a normalized unsigned 8-bit / channel RGBA image, `image_channel_order = CL_RGBA`, and `image_channel_data_type = CL_UNORM_INT8`. The memory layout of this image format is described below:

```
R   G   B   A   ...
```

with the corresponding byte offsets

```
0   1   2   3   ...
```

Similar, if `image_channel_order = CL_RGBA` and `image_channel_data_type = CL_SIGNED_INT16`, the memory layout of this image format is described below:

```
R   G   B   A   ...
```

with the corresponding byte offsets

```
0   2   4   6   ...
```

`image_channel_data_type` values of CL_UNORM_SHORT_565, CL_UNORM_SHORT_555, CL_UNORM_INT_101010, and CL_UNORM_INT_101010_2 are special cases of packed image formats where the channels of each element are packed into a single unsigned short or unsigned int. For these special packed image formats, the channels are normally packed with the first channel in the most significant bits of the bitfield, and successive channels occupying progressively less significant locations. For CL_UNORM_SHORT_565, R is in bits 15:11, G is in bits 10:5 and B is in bits 4:0. For CL_UNORM_SHORT_555, bit 15 is
undefined, R is in bits 14:10, G in bits 9:5 and B in bits 4:0. For \texttt{CL\_UNORM\_INT\_101010}, bits 31:30 are undefined, R is in bits 29:20, G in bits 19:10 and B in bits 9:0. For \texttt{CL\_UNORM\_INT\_101010\_2}, R is in bits 31:22, G in bits 21:12, B in bits 11:2 and A in bits 1:0.

OpenCL implementations must maintain the minimum precision specified by the number of bits in \texttt{image\_channel\_data\_type}. If the image format specified by \texttt{image\_channel\_order}, and \texttt{image\_channel\_data\_type} cannot be supported by the OpenCL implementation, then the call to \texttt{clCreateImage}, \texttt{clCreateImageWithProperties}, \texttt{clCreateImage2D}, or \texttt{clCreateImage3D} will return a \texttt{NULL} memory object.

### 5.3.1.2. Image Descriptor

The \texttt{cl\_image\_desc} image descriptor structure describes the image type and dimensions of an image or image array when creating an image using \texttt{clCreateImage} or \texttt{clCreateImageWithProperties}, and is defined as:

```c
// Provided by CL\_VERSION\_1\_2
typedef struct cl_image_desc {
    cl_mem_object_type image_type;
    size_t image_width;
    size_t image_height;
    size_t image_depth;
    size_t image_array_size;
    size_t image_row_pitch;
    size_t image_slice_pitch;
    cl_uint num_mip_levels;
    cl_uint num_samples;
    union {
        cl_mem buffer;
        cl_mem mem_object;
    }
} cl_image_desc;
```

- \texttt{image\_type} describes the image type and must be either \texttt{CL\_MEM\_OBJECT\_IMAGE1D}, \texttt{CL\_MEM\_OBJECT\_IMAGE1D\_BUFFER}, \texttt{CL\_MEM\_OBJECT\_IMAGE1D\_ARRAY}, \texttt{CL\_MEM\_OBJECT\_IMAGE2D}, \texttt{CL\_MEM\_OBJECT\_IMAGE2D\_ARRAY}, or \texttt{CL\_MEM\_OBJECT\_IMAGE3D}.

- \texttt{image\_width} is the width of the image in pixels. For a 2D image and image array, the image width must be a value ≥ 1 and ≤ \texttt{CL\_DEVICE\_IMAGE2D\_MAX\_WIDTH}. For a 3D image, the image width must be a value ≥ 1 and ≤ \texttt{CL\_DEVICE\_IMAGE3D\_MAX\_WIDTH}. For a 1D image buffer, the image width must be a value ≥ 1 and ≤ \texttt{CL\_DEVICE\_IMAGE\_MAX\_BUFFER\_SIZE}. For a 1D image and 1D image array, the image width must be a value ≥ 1 and ≤ \texttt{CL\_DEVICE\_IMAGE2D\_MAX\_WIDTH}.

- \texttt{image\_height} is the height of the image in pixels. This is only used if the image is a 2D or 3D image, or a 2D image array. For a 2D image or image array, the image height must be a value ≥ 1 and ≤ \texttt{CL\_DEVICE\_IMAGE2D\_MAX\_HEIGHT}. For a 3D image, the image height must be a value ≥ 1 and ≤ \texttt{CL\_DEVICE\_IMAGE3D\_MAX\_HEIGHT}.

- \texttt{image\_depth} is the depth of the image in pixels. This is only used if the image is a 3D image and must be a value ≥ 1 and ≤ \texttt{CL\_DEVICE\_IMAGE3D\_MAX\_DEPTH}.
• **image_array_size**[^4] is the number of images in the image array. This is only used if the image is a 1D or 2D image array. The values for **image_array_size**, if specified, must be a value ≥ 1 and ≤ CL_DEVICE_IMAGE_MAX_ARRAY_SIZE.

• **image_row_pitch** is the scan-line pitch in bytes. The **image_row_pitch** must be zero if **host_ptr** is NULL, the image is not an image created from an external memory handle, and the image is not a 2D image created from a buffer. If **image_row_pitch** is zero and **host_ptr** is not NULL, then the image row pitch is calculated as **image_width** × the size of an image element in bytes. If **image_row_pitch** is zero and the image is created from an external memory handle, then the image row pitch is implementation-defined. The row pitch must be ≥ **image_width** × the size of an image element in bytes, and must be a multiple of the size of an image element in bytes. For a 2D image created from a buffer the image row pitch must also be a multiple of the maximum of the CL_DEVICE_IMAGE_PITCH_ALIGNMENT value for all devices in the context that support images.

• **image_slice_pitch** is the size in bytes of each 2D slice in a 3D image, or the size in bytes of each image in a 1D or 2D image array. The **image_slice_pitch** must be zero if **host_ptr** is NULL and the image is not an image created from an external memory handle. If **image_slice_pitch** is zero and **host_ptr** is not NULL, then the image slice pitch is calculated as the image row pitch × **image_height** for a 2D image array or a 3D image, and as the image row pitch for a 1D image array. If **image_slice_pitch** is zero and the image is created from an external memory handle, then the image slice pitch is implementation-defined. The slice pitch must be ≥ the image row pitch × **image_height** for a 2D image array or a 3D image, must be ≥ the image row pitch for a 1D image array, and must be a multiple of the image row pitch.

• **num_mip_levels** must be 0 unless the cl_khr_mipmap_image extension is supported, in which case it must be a value greater than 1 specifying the number of mipmap levels in the image.

• **num_samples** must be 0.

• **mem_object** may refer to a valid buffer or image memory object. **mem_object** can be a buffer memory object if **image_type** is CL_MEM_OBJECT_IMAGE1D_BUFFER or CL_MEM_OBJECT_IMAGE2D[^5]. **mem_object** can be an image object if **image_type** is CL_MEM_OBJECT_IMAGE2D[^6]. Otherwise it must be NULL. The image pixels are taken from the memory objects data store. When the contents of the specified memory objects data store are modified, those changes are reflected in the contents of the image object and vice-versa at corresponding synchronization points.

For a 1D image buffer created from a buffer object, the **image_width** × size of element in bytes must be ≤ size of the buffer object. The image data in the buffer object is stored as a single scanline which is a linear sequence of adjacent elements.

For a 2D image created from a buffer object, the **image_row_pitch** × **image_height** must be ≤ size of the buffer object specified by **mem_object**. The image data in the buffer object is stored as a linear sequence of adjacent scanlines. Each scanline is a linear sequence of image elements padded to **image_row_pitch** bytes.

For an image object created from another image object, the values specified in the image descriptor except for **mem_object** must match the image descriptor information associated with **mem_object**.

Image elements are stored according to their image format as described in Image Format Descriptor.
If the buffer object specified by `mem_object` was created with `CL_MEM_USE_HOST_PTR`, the `host_ptr` specified to `clCreateBuffer` or `clCreateBufferWithProperties` must be aligned to the maximum of the `CL_DEVICE_IMAGE_BASE_ADDRESS_ALIGNMENT` value for all devices in the context associated with the buffer specified by `mem_object` that support images.

Creating a 2D image object from another 2D image object creates a new 2D image object that shares the image data store with `mem_object` but views the pixels in the image with a different image channel order. Restrictions are:

- All of the values specified in `image_desc` must match the image descriptor information associated with `mem_object`, except for `mem_object`.
- The image channel data type specified in `image_format` must match the image channel data type associated with `mem_object`.
- The image channel order specified in `image_format` must be compatible with the image channel order associated with `mem_object`, as described in the Compatible Image Channel Orders table.

The image channel order compatibility constraint allows creation of a sRGB view of the image from a linear RGB view or vice-versa, i.e. the pixels stored in the image can be accessed as linear RGB or sRGB values.

### Table 26. Compatible Image Channel Orders

<table>
<thead>
<tr>
<th>Image Channel Order in <code>image_format</code>:</th>
<th>Image Channel Order associated with <code>mem_object</code>:</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_sBGRA</td>
<td>CL_BGRA</td>
</tr>
<tr>
<td>CL_BGRA</td>
<td>CL_sBGRA</td>
</tr>
<tr>
<td>CL_sRGBA</td>
<td>CL_RGBA</td>
</tr>
<tr>
<td>CL_RGBA</td>
<td>CL_sRGBA</td>
</tr>
<tr>
<td>CL_sRGB</td>
<td>CL_RGB</td>
</tr>
<tr>
<td>CL_RGB</td>
<td>CL_sRGBx</td>
</tr>
<tr>
<td>CL_sRGBx</td>
<td>CL_RGBx</td>
</tr>
<tr>
<td>CL_RGBAx</td>
<td>CL_DEPTH</td>
</tr>
</tbody>
</table>

Concurrent reading from, writing to and copying between both a buffer object and 1D image buffer or 2D image object associated with the buffer object is undefined. Only reading from both a buffer object and 1D image buffer or 2D image object associated with the buffer object is defined.

Writing to an image created from a buffer and then reading from this buffer in a kernel even if appropriate synchronization operations (such as a barrier) are performed between the writes and reads is undefined. Similarly, writing to the buffer and reading from the image created from this buffer with appropriate synchronization between the writes and reads is undefined.
5.3.2. Querying List of Supported Image Formats

To get the list of image formats supported by an OpenCL implementation for a specified context, image type, and allocation information, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clGetSupportedImageFormats(
    cl_context context,
    cl_mem_flags flags,
    cl_mem_object_type image_type,
    cl_uint num_entries,
    cl_image_format* image_formats,
    cl_uint* num_image_formats);
```

- **context** is a valid OpenCL context on which the image object(s) will be created.

- **flags** is a bit-field that is used to specify usage information about the image formats being queried and is described in the Memory Flags table. **flags** may be **CL_MEM_READ_WRITE** to query image formats that may be read from and written to by different kernel instances when correctly ordered by event dependencies, or **CL_MEM_READ_ONLY** to query image formats that may be read from by a kernel, or **CL_MEM_WRITE_ONLY** to query image formats that may be written to by a kernel, or **CL_MEM_KERNEL_READ_AND_WRITE** to query image formats that may be both read from and written to by the same kernel instance. Please see Image Format Mapping for clarification.

- **image_type** describes the image type and must be either **CL_MEM_OBJECT_IMAGE1D**, **CL_MEM_OBJECT_IMAGE1D_BUFFER**, **CL_MEM_OBJECT_IMAGE2D**, **CL_MEM_OBJECT_IMAGE3D**, **CL_MEM_OBJECT_IMAGE1D_ARRAY**, or **CL_MEM_OBJECT_IMAGE2D_ARRAY**.

- **num_entries** specifies the number of entries that can be returned in the memory location given by **image_formats**.

- **image_formats** is a pointer to a memory location where the list of supported image formats are returned. Each entry describes a **cl_image_format** structure supported by the OpenCL implementation. If **image_formats** is **NULL**, it is ignored.

- **num_image_formats** is the actual number of supported image formats for a specific **context** and values specified by **flags**. If **num_image_formats** is **NULL**, it is ignored.

**clGetSupportedImageFormats** returns a union of image formats supported by all devices in the context.

**clGetSupportedImageFormats** returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_CONTEXT** if **context** is not a valid context.

- **CL_INVALID_VALUE** if **flags** or **image_type** are not valid, or if **num_entries** is 0 and **image_formats** is not **NULL**.

- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL
implementation on the host.

If `CL_DEVICE_IMAGE_SUPPORT` specified in the Device Queries table is `CL_TRUE`, the values assigned to `CL_DEVICE_MAX_READ_IMAGE_ARGS`, `CL_DEVICE_MAX_WRITE_IMAGE_ARGS`, `CL_DEVICE_IMAGE2D_MAX_WIDTH`, `CL_DEVICE_IMAGE2D_MAX_HEIGHT`, `CL_DEVICE_IMAGE3D_MAX_WIDTH`, `CL_DEVICE_IMAGE3D_MAX_HEIGHT`, `CL_DEVICE_IMAGE3D_MAX_DEPTH`, and `CL_DEVICE_MAX_SAMPLERS` by the implementation must be greater than or equal to the minimum values specified in the Device Queries table.

5.3.2.1. Minimum List of Supported Image Formats

The tables below describe the required minimum lists of supported image formats. To query all image formats supported by an implementation, call the function `clGetSupportedImageFormats`.

For full profile devices supporting OpenCL 2.0, 2.1, or 2.2, the minimum list of supported image formats for either reading or writing in a kernel is:

**Table 27. Minimum list of supported image formats for reading or writing (OpenCL 2.0, 2.1, or 2.2)**

<table>
<thead>
<tr>
<th>num_channels</th>
<th>channel_order</th>
<th>channel_data_type</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>CL_R</td>
<td>CL_UNORM_INT8, CL_UNORM_INT16, CL_SNORM_INT8, CL_SNORM_INT16, CL_SIGNED_INT8, CL_SIGNED_INT16, CL_SIGNED_INT32, CL_UNSIGNED_INT8, CL_UNSIGNED_INT16, CL_UNSIGNED_INT32, CL_HALF_FLOAT, CL_FLOAT</td>
</tr>
<tr>
<td>1</td>
<td>CL_DEPTH [7]</td>
<td>CL_UNORM_INT16, CL_FLOAT</td>
</tr>
<tr>
<td></td>
<td>Also supported if the <code>cl_khr_depth_images</code> extension is supported.</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>CL_DEPTH_STENCIL</td>
<td>CL_UNORM_INT24, CL_FLOAT</td>
</tr>
<tr>
<td></td>
<td>See Restrictions on Depth/Stencil Images.</td>
<td></td>
</tr>
<tr>
<td>num_channels</td>
<td>channel_order</td>
<td>channel_data_type</td>
</tr>
<tr>
<td>--------------</td>
<td>---------------</td>
<td>-------------------</td>
</tr>
<tr>
<td>2</td>
<td>CL_RG</td>
<td>CL_UNORM_INT8, CL_UNORM_INT16, CL_SNORM_INT8, CL_SNORM_INT16, CL_SIGNED_INT8, CL_SIGNED_INT16, CL_SIGNED_INT32, CL_UNSIGNED_INT8, CL_UNSIGNED_INT16, CL_UNSIGNED_INT32, CL_HALF_FLOAT, CL_FLOAT</td>
</tr>
<tr>
<td>4</td>
<td>CL_RGBA</td>
<td>CL_UNORM_INT8, CL_UNORM_INT16, CL_SNORM_INT8, CL_SNORM_INT16, CL_SIGNED_INT8, CL_SIGNED_INT16, CL_SIGNED_INT32, CL_UNSIGNED_INT8, CL_UNSIGNED_INT16, CL_UNSIGNED_INT32, CL_HALF_FLOAT, CL_FLOAT</td>
</tr>
<tr>
<td>4</td>
<td>CL_BGRA</td>
<td>CL_UNORM_INT8</td>
</tr>
<tr>
<td>4</td>
<td>CL_sRGBA [1]</td>
<td>CL_UNORM_INT8</td>
</tr>
</tbody>
</table>

For full profile devices supporting other OpenCL versions, such as OpenCL 1.2 or OpenCL 3.0, the minimum list of supported image formats for either reading or writing in a kernel is:

Table 28. Minimum list of required image formats for reading or writing

<table>
<thead>
<tr>
<th>num_channels</th>
<th>channel_order</th>
<th>channel_data_type</th>
</tr>
</thead>
<tbody>
<tr>
<td>4</td>
<td>CL_RGBA</td>
<td>CL_UNORM_INT8, CL_UNORM_INT16, CL_SNORM_INT8, CL_SNORM_INT16, CL_SIGNED_INT8, CL_SIGNED_INT16, CL_SIGNED_INT32, CL_UNSIGNED_INT8, CL_UNSIGNED_INT16, CL_UNSIGNED_INT32, CL_HALF_FLOAT, CL_FLOAT</td>
</tr>
<tr>
<td>4</td>
<td>CL_BGRA</td>
<td>CL_UNORM_INT8</td>
</tr>
</tbody>
</table>

[1] sRGB is not a standard image format in OpenCL, but it is commonly used in graphics applications to represent color values in a way that is perceptually linear with human vision.
For full profile devices that support reading from and writing to the same image object from the same kernel instance (see `CL_DEVICE_MAX_READ_WRITE_IMAGE_ARGS`), the minimum list of supported image formats for reading and writing in the same kernel instance is:

Table 29. Minimum list of required image formats for reading and writing

<table>
<thead>
<tr>
<th>num_channels</th>
<th>channel_order</th>
<th>channel_data_type</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>CL_R</td>
<td>CL_UNORM_INT8, CL_SIGNED_INT8, CL_SIGNED_INT16, CL_SIGNED_INT32, CL_UNSIGNED_INT8, CL_UNSIGNED_INT16, CL_UNSIGNED_INT32, CL_HALF_FLOAT, CL_FLOAT</td>
</tr>
<tr>
<td>4</td>
<td>CL_RGBA</td>
<td>CL_UNORM_INT8, CL_SIGNED_INT8, CL_SIGNED_INT16, CL_SIGNED_INT32, CL_UNSIGNED_INT8, CL_UNSIGNED_INT16, CL_UNSIGNED_INT32, CL_HALF_FLOAT, CL_FLOAT</td>
</tr>
</tbody>
</table>

5.3.2.2. Image Format Mapping to OpenCL Kernel Language Image Access Qualifiers

Image arguments to kernels may have the `read_only`, `write_only` or `read_write` qualifier. Not all image formats supported by the device and platform are valid to be passed to all of these access qualifiers. For each access qualifier, only images whose format is in the list of formats returned by `clGetSupportedImageFormats` with the given flag arguments in the Image Format Mapping table are permitted. It is not valid to pass an image supporting writing as both a `read_only` image and a `write_only` image parameter, or to a `read_write` image parameter and any other image parameter.

Table 30. Mapping from format flags passed to `clGetSupportedImageFormats` to OpenCL kernel language image access qualifiers

<table>
<thead>
<tr>
<th>Access Qualifier</th>
<th>Memory Flags</th>
</tr>
</thead>
<tbody>
<tr>
<td>read_only</td>
<td>CL_MEM_READ_ONLY, CL_MEM_READ_WRITE, CL_MEM_KERNEL_READ_AND_WRITE</td>
</tr>
<tr>
<td>write_only</td>
<td>CL_MEM_WRITE_ONLY, CL_MEM_READ_WRITE, CL_MEM_KERNEL_READ_AND_WRITE</td>
</tr>
<tr>
<td>read_write</td>
<td>CL_MEM_KERNEL_READ_AND_WRITE</td>
</tr>
</tbody>
</table>
5.3.3. Mapping to External Image Formats

OpenCL image objects can be created which share storage with image objects in external APIs such as DirectX and OpenGL when the corresponding OpenCL extensions are supported. When creating such OpenCL images, there are restrictions on the allowed formats. The tables in this section list, for each such external API, the supported image formats in that API and the corresponding OpenCL image format.

5.3.3.1. Image Formats for DirectX 9 Media Surface Sharing

When the `cl_khr_dx9_media_sharing` extension is supported, image objects sharing storage with Direct3D 9 surfaces can be created. This section describes the Direct3D 9 surface formats that are supported when the adapter type is one of the Direct 3D lineage. Using a Direct3D 9 surface format not listed here is an error. To extend the use of this extension to support media adapters beyond DirectX 9 tables similar to the ones in this section will need to be defined for the surface formats supported by the new media adapter. All implementations that support this extension are required to support the NV12 surface format. The other surface formats supported are the same surface formats that the adapter you are sharing with supports as long as they are listed in the YUV FourCC Codes and Corresponding OpenCL Image Formats or Direct3D 9 Formats and Corresponding OpenCL Image Formats tables.

### Table 31. YUV FourCC Codes and Corresponding OpenCL Image Formats

<table>
<thead>
<tr>
<th>FOUR CC Code</th>
<th>CL Image Format (Channel Order, Channel Data Type)</th>
</tr>
</thead>
<tbody>
<tr>
<td>NV12(Y, V U), Plane 0</td>
<td>CL_R, CL_UNORM_INT8</td>
</tr>
<tr>
<td>NV12(Y, V U), Plane 1</td>
<td>CL_RG, CL_UNORM_INT8</td>
</tr>
<tr>
<td>YV12(Y, U V), Plane 0</td>
<td>CL_R, CL_UNORM_INT8</td>
</tr>
<tr>
<td>YV12(Y, U V), Plane 1</td>
<td>CL_R, CL_UNORM_INT8</td>
</tr>
<tr>
<td>YV12(Y, U V), Plane 2</td>
<td>CL_R, CL_UNORM_INT8</td>
</tr>
</tbody>
</table>

In the YUV FourCC Codes and Corresponding OpenCL Image Formats table, NV12 Plane 0 corresponds to the luminance (Y) channel and Plane 1 corresponds to the UV channels. The YV12 Plane 0 corresponds to the Y channel, Plane 1 corresponds to the V channel and Plane 2 corresponds to the U channel. Note that the YUV formats map to CL_R and CL_RG but do not perform any YUV to RGB conversion, and vice-versa.

### Table 32. Direct3D 9 Formats and Corresponding OpenCL Image Formats

<table>
<thead>
<tr>
<th>Direct3D 9 Format</th>
<th>CL Image Format (Channel Order, Channel Data Type)</th>
</tr>
</thead>
<tbody>
<tr>
<td>D3DFMT_R32F</td>
<td>CL_R, CL_FLOAT</td>
</tr>
<tr>
<td>D3DFMT_R16F</td>
<td>CL_R, CL_HALF_FLOAT</td>
</tr>
<tr>
<td>D3DFMT_L16</td>
<td>CL_R, CL_UNORM_INT16</td>
</tr>
<tr>
<td>D3DFMT_A8</td>
<td>CL_A, CL_UNORM_INT8</td>
</tr>
<tr>
<td>D3DFMT_L8</td>
<td>CL_R, CL_UNORM_INT8</td>
</tr>
</tbody>
</table>
The Direct3D 9 format names in the table above seem to imply that the order of the color channels are switched relative to OpenCL, but this is not the case. For example, the layout of channels for each pixel for \texttt{D3DFMT_A32FB32FG32FR32F} is the same as \texttt{CL_RGBA, CL_FLOAT}.

### 5.3.3.2. Image Formats for Direct3D Texture Sharing

When the \texttt{cl_khr_d3d10_sharing} or \texttt{cl_khr_d3d11_sharing} extensions are supported, image objects sharing storage with Direct3D 10 and Direct3D 11 textures, respectively, can be created. The DXGI Formats and Corresponding OpenCL Image Formats table describes the supported DirectX Graphics Infrastructure (DXGI) texture formats.

<table>
<thead>
<tr>
<th>DXGI Format</th>
<th>CL Image Format (Channel Order, Channel Data Type)</th>
</tr>
</thead>
<tbody>
<tr>
<td>DXGI_FORMAT_R32G32B32A32_FLOAT</td>
<td>CL_RGBA, CL_FLOAT</td>
</tr>
<tr>
<td>DXGI_FORMAT_R32G32B32A32_UINT</td>
<td>CL_RGBA, CL_UNSIGNED_INT32</td>
</tr>
<tr>
<td>DXGI_FORMAT_R32G32B32A32_SINT</td>
<td>CL_RGBA, CL_SIGNED_INT32</td>
</tr>
<tr>
<td>DXGI_FORMAT_R16G16B16A16_FLOAT</td>
<td>CL_RGBA, CL_HALF_FLOAT</td>
</tr>
<tr>
<td>DXGI_FORMAT_R16G16B16A16_UNORM</td>
<td>CL_RGBA, CL_UNORM_INT16</td>
</tr>
<tr>
<td>DXGI_FORMAT_R16G16B16A16_UINT</td>
<td>CL_RGBA, CL_UNSIGNED_INT16</td>
</tr>
<tr>
<td>DXGI_FORMAT_R16G16B16A16_SNORM</td>
<td>CL_RGBA, CL_SNORM_INT16</td>
</tr>
<tr>
<td>DXGI_FORMAT_R16G16B16A16_SINT</td>
<td>CL_RGBA, CL_SIGNED_INT16</td>
</tr>
<tr>
<td>DXGI Format</td>
<td>CL Image Format (Channel Order, Channel Data Type)</td>
</tr>
<tr>
<td>-------------------------------------</td>
<td>---------------------------------------------------------------------</td>
</tr>
<tr>
<td>DXGI_FORMAT_B8G8R8A8_UNORM</td>
<td>CL_BGRA, CL_UNORM_INT8</td>
</tr>
<tr>
<td>DXGI_FORMAT_R8G8B8A8_UNORM</td>
<td>CL_RGBA, CL_UNORM_INT8</td>
</tr>
<tr>
<td>DXGI_FORMAT_R8G8B8A8_UINT</td>
<td>CL_RGBA, CL_UNSIGNED_INT8</td>
</tr>
<tr>
<td>DXGI_FORMAT_R8G8B8A8_SNORM</td>
<td>CL_RGBA, CL_SNORM_INT8</td>
</tr>
<tr>
<td>DXGI_FORMAT_R8G8B8A8_SINT</td>
<td>CL_RGBA, CL_SIGNED_INT8</td>
</tr>
<tr>
<td>DXGI_FORMAT_R32G32_FLOAT</td>
<td>CL_RG, CL_FLOAT</td>
</tr>
<tr>
<td>DXGI_FORMAT_R32G32_UINT</td>
<td>CL_RG, CL_UNSIGNED_INT32</td>
</tr>
<tr>
<td>DXGI_FORMAT_R32G32_SINT</td>
<td>CL_RG, CL_SIGNED_INT32</td>
</tr>
<tr>
<td>DXGI_FORMAT_R16G16_FLOAT</td>
<td>CL_RG, CL_HALF_FLOAT</td>
</tr>
<tr>
<td>DXGI_FORMAT_R16G16_UNORM</td>
<td>CL_RG, CL_UNORM_INT16</td>
</tr>
<tr>
<td>DXGI_FORMAT_R16G16_UINT</td>
<td>CL_RG, CL_UNSIGNED_INT16</td>
</tr>
<tr>
<td>DXGI_FORMAT_R16G16_SNORM</td>
<td>CL_RG, CL_SNORM_INT16</td>
</tr>
<tr>
<td>DXGI_FORMAT_R16G16_SINT</td>
<td>CL_RG, CL_SIGNED_INT16</td>
</tr>
<tr>
<td>DXGI_FORMAT_R16_FLOAT</td>
<td>CL_R, CL_FLOAT</td>
</tr>
<tr>
<td>DXGI_FORMAT_R16_UINT</td>
<td>CL_R, CL_UNSIGNED_INT32</td>
</tr>
<tr>
<td>DXGI_FORMAT_R16_SINT</td>
<td>CL_R, CL_SIGNED_INT32</td>
</tr>
<tr>
<td>DXGI_FORMAT_R8G8_UNORM</td>
<td>CL_R, CL_UNORM_INT8</td>
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<td>DXGI_FORMAT_R8G8_UINT</td>
<td>CL_R, CL_UNSIGNED_INT8</td>
</tr>
<tr>
<td>DXGI_FORMAT_R8G8_SNORM</td>
<td>CL_R, CL_SNORM_INT8</td>
</tr>
<tr>
<td>DXGI_FORMAT_R8G8_SINT</td>
<td>CL_R, CL_SIGNED_INT8</td>
</tr>
</tbody>
</table>
5.3.3.3. Image Formats for OpenGL Texture and Renderbuffer Sharing

When the `cl_khr_gl_sharing` extension is supported, image objects sharing storage with OpenGL texture and renderbuffer objects can be created. The **OpenGL Internal Formats and Corresponding OpenCL Internal Formats** table describes the supported OpenGL image formats. If an OpenGL texture or renderbuffer object with an internal format from the table is successfully created by OpenGl, then there is guaranteed to be a mapping to one of the corresponding OpenCL image format(s) in the table. Texture and renderbuffer objects created with other OpenGL internal formats may (but are not guaranteed to) have a mapping to an OpenCL image format. If such mappings exist, they are guaranteed to preserve all color components, data types, and at least the number of bits/component actually allocated by OpenGL for that format.

**Table 34. OpenGL Internal Formats and Corresponding OpenCL Internal Formats**

<table>
<thead>
<tr>
<th>OpenGL internal format</th>
<th>OpenCL Image Format (Channel Order, Channel Data Type)</th>
</tr>
</thead>
<tbody>
<tr>
<td>GL_RGBA8</td>
<td>CL_RGBA, CL_UNORM_INT8 or CL_BGRA, CL_UNORM_INT8</td>
</tr>
<tr>
<td>GL_SRG8_ALPHA8</td>
<td>CL_SRGBA, CL_UNORM_INT8</td>
</tr>
<tr>
<td>GL_RGBA, GL_UNSIGNED_INT_8_8_8_8_REV</td>
<td>CL_RGBA, CL_UNORM_INT8</td>
</tr>
<tr>
<td>GL_BGRA, GL_UNSIGNED_INT_8_8_8_8_REV</td>
<td>CL_BGRA, CL_UNORM_INT8</td>
</tr>
<tr>
<td>GL_RGBA8I, GL_RGBA8I_EXT</td>
<td>CL_RGBA, CL_SIGNED_INT8</td>
</tr>
<tr>
<td>GL_RGBA16I, GL_RGBA16I_EXT</td>
<td>CL_RGBA, CL_SIGNED_INT16</td>
</tr>
<tr>
<td>GL_RGBA32I, GL_RGBA32I_EXT</td>
<td>CL_RGBA, CL_SIGNED_INT32</td>
</tr>
<tr>
<td>GL_RGBA8UI, GL_RGBA8UI_EXT</td>
<td>CL_RGBA, CL_UNSIGNED_INT8</td>
</tr>
<tr>
<td>GL_RGBA16UI, GL_RGBA16UI_EXT</td>
<td>CL_RGBA, CL_UNSIGNED_INT16</td>
</tr>
<tr>
<td>GL_RGBA32UI, GL_RGBA32UI_EXT</td>
<td>CL_RGBA, CL_UNSIGNED_INT32</td>
</tr>
<tr>
<td>GL_RGBA8_SNORM</td>
<td>CL_RGBA, CL_SNORM_INT8</td>
</tr>
<tr>
<td>GL_RGBA16</td>
<td>CL_RGBA, CL_UNORM_INT16</td>
</tr>
<tr>
<td>GL_RGBA16_SNORM</td>
<td>CL_RGBA, CL_SNORM_INT16</td>
</tr>
<tr>
<td>GL_RGBA16F, GL_RGBA16F_ARB</td>
<td>CL_RGBA, CL_HALF_FLOAT</td>
</tr>
<tr>
<td>GL_RGBA32F, GL_RGBA32F_ARB</td>
<td>CL_RGBA, CL_FLOAT</td>
</tr>
<tr>
<td>GL_R8</td>
<td>CL_R, CL_UNORM_INT8</td>
</tr>
<tr>
<td>GL_R8_SNORM</td>
<td>CL_R, CL_SNORM_INT8</td>
</tr>
<tr>
<td>GL_R16</td>
<td>CL_R, CL_UNORM_INT16</td>
</tr>
<tr>
<td>GL_R16_SNORM</td>
<td>CL_R, CL_SNORM_INT16</td>
</tr>
<tr>
<td>GL_R16F</td>
<td>CL_R, CL_HALF_FLOAT</td>
</tr>
<tr>
<td>GL_R32F</td>
<td>CL_R, CL_FLOAT</td>
</tr>
<tr>
<td>OpenGL internal format</td>
<td>OpenCL Image Format (Channel Order, Channel Data Type)</td>
</tr>
<tr>
<td>------------------------</td>
<td>--------------------------------------------------------</td>
</tr>
<tr>
<td>GL_R8I</td>
<td>CL_R, CL_SIGNED_INT8</td>
</tr>
<tr>
<td>GL_R16I</td>
<td>CL_R, CL_SIGNED_INT16</td>
</tr>
<tr>
<td>GL_R32I</td>
<td>CL_R, CL_SIGNED_INT32</td>
</tr>
<tr>
<td>GL_R8UI</td>
<td>CL_R, CL_UNSIGNED_INT8</td>
</tr>
<tr>
<td>GL_R16UI</td>
<td>CL_R, CL_UNSIGNED_INT16</td>
</tr>
<tr>
<td>GL_R32UI</td>
<td>CL_R, CL_UNSIGNED_INT32</td>
</tr>
<tr>
<td>GL_RG8</td>
<td>CL_RG, CL_UNORM_INT8</td>
</tr>
<tr>
<td>GL_RG8_SNORM</td>
<td>CL_RG, CL_SNORM_INT8</td>
</tr>
<tr>
<td>GL_RG16</td>
<td>CL_RG, CL_UNORM_INT16</td>
</tr>
<tr>
<td>GL_RG16_SNORM</td>
<td>CL_RG, CL_SNORM_INT16</td>
</tr>
<tr>
<td>GL_RG16F</td>
<td>CL_RG, CL_HALF_FLOAT</td>
</tr>
<tr>
<td>GL_RG32F</td>
<td>CL_RG, CL_FLOAT</td>
</tr>
<tr>
<td>GL_RG8I</td>
<td>CL_RG, CL_SIGNED_INT8</td>
</tr>
<tr>
<td>GL_RG16I</td>
<td>CL_RG, CL_SIGNED_INT16</td>
</tr>
<tr>
<td>GL_RG32I</td>
<td>CL_RG, CL_SIGNED_INT32</td>
</tr>
<tr>
<td>GL_RG8UI</td>
<td>CL_RG, CL_UNSIGNED_INT8</td>
</tr>
<tr>
<td>GL_RG16UI</td>
<td>CL_RG, CL_UNSIGNED_INT16</td>
</tr>
<tr>
<td>GL_RG32UI</td>
<td>CL_RG, CL_UNSIGNED_INT32</td>
</tr>
<tr>
<td>GL_DEPTH_COMPONENT32F</td>
<td>CL_DEPTH, CL_FLOAT</td>
</tr>
<tr>
<td>GL_DEPTH_COMPONENT16</td>
<td>CL_DEPTH, CL_UNORM_INT16</td>
</tr>
<tr>
<td>GL_DEPTH24_STENCIL8</td>
<td>CL_DEPTH_STENCIL, CL_UNORM_INT24</td>
</tr>
<tr>
<td>GL_DEPTH32F_STENCIL8</td>
<td>CL_DEPTH_STENCIL, CL_FLOAT</td>
</tr>
</tbody>
</table>

5.3.4. Reading, Writing and Copying Image Objects

The following functions enqueue commands to read from an image or image array object to host memory or write to an image or image array object from host memory.
cl_int clEnqueueReadImage(
    cl_command_queue command_queue,
    cl_mem image,
    cl_bool blocking_read,
    const size_t* origin,
    const size_t* region,
    size_t row_pitch,
    size_t slice_pitch,
    void* ptr,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);

cl_int clEnqueueWriteImage(
    cl_command_queue command_queue,
    cl_mem image,
    cl_bool blocking_write,
    const size_t* origin,
    const size_t* region,
    size_t input_row_pitch,
    size_t input_slice_pitch,
    const void* ptr,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);

- **command_queue** refers to the host command-queue in which the read / write command will be queued. **command_queue** and **image** must be created with the same OpenCL context.

- **image** refers to a valid image or image array object.

- **blocking_read** and **blocking_write** indicate if the read and write operations are **blocking** or **non-blocking**.

- **origin** defines the \((x, y, z)\) offset in pixels in the 1D, 2D or 3D image, the \((x, y)\) offset and the image index in the 2D image array or the \(x\) offset and the image index in the 1D image array. If **image** is a 2D image object, **origin[2]** must be 0. If **image** is a 1D image or 1D image buffer object, **origin[1]** and **origin[2]** must be 0. If **image** is a 1D image array object, **origin[2]** describes the image index in the 1D image array. If **image** is a 2D image array object, **origin[2]** describes the image index in the 2D image array.

- **region** defines the \((width, height, depth)\) in pixels of the 1D, 2D or 3D rectangle, the \((width, height)\) in pixels of the 2D rectangle and the number of images of a 2D image array or the \(width\) in pixels of the 1D rectangle and the number of images of a 1D image array. If **image** is a 2D image object, **region[2]** must be 1. If **image** is a 1D image or 1D image buffer object, **region[1]** and **region[2]** must be 1. If **image** is a 1D image array object, **region[2]** must be 1. The values in **region** cannot be 0. If **image** is a mipmapped image, the mip level to read or write is determined.
from origin as described in Specifying Mipmap Levels to Image Operations

• **row_pitch** in `clEnqueueReadImage` and **input_row_pitch** in `clEnqueueWriteImage` is the length of each row in bytes. This value must be greater than or equal to the element size in bytes × **width**. If **row_pitch** (or **input_row_pitch**) is set to 0, the appropriate row pitch is calculated based on the size of each element in bytes multiplied by **width**.

• **slice_pitch** in `clEnqueueReadImage` and **input_slice_pitch** in `clEnqueueWriteImage` is the size in bytes of the 2D slice of the 3D region of a 3D image or each image of a 1D or 2D image array being read or written respectively. This must be 0 if **image** is a 1D or 2D image. Otherwise this value must be greater than or equal to **row_pitch** × **height**. If **slice_pitch** (or **input_slice_pitch**) is set to 0, the appropriate slice pitch is calculated based on the **row_pitch** × **height**.

• **ptr** is the pointer to a buffer in host memory where image data is to be read from or to be written to. The alignment requirements for **ptr** are specified in Alignment of Application Data Types.

• **event_wait_list** and **num_events_in_wait_list** specify events that need to complete before this particular command can be executed. If **event_wait_list** is **NULL**, then this particular command does not wait on any event to complete. If **event_wait_list** is **NULL**, **num_events_in_wait_list** must be 0. If **event_wait_list** is not **NULL**, the list of events pointed to by **event_wait_list** must be valid and **num_events_in_wait_list** must be greater than 0. The events specified in **event_wait_list** act as synchronization points. The context associated with events in **event_wait_list** and **command_queue** must be the same. The memory associated with **event_wait_list** can be reused or freed after the function returns.

• **event** returns an event object that identifies this read / write command and can be used to query or queue a wait for this command to complete. If **event** is **NULL** or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If **event_wait_list** and **event** are not **NULL**, **event** must not refer to an element of the **event_wait_list** array.

If **blocking_read** is **CL_TRUE** i.e. the read command is blocking, `clEnqueueReadImage` does not return until the buffer data has been read and copied into memory pointed to by **ptr**.

If **blocking_read** is **CL_FALSE** i.e. the read command is non-blocking, `clEnqueueReadImage` queues a non-blocking read command and returns. The contents of the buffer that **ptr** points to cannot be used until the read command has completed. The **event** argument returns an event object which can be used to query the execution status of the read command. When the read command has completed, the contents of the buffer that **ptr** points to can be used by the application.

If **blocking_write** is **CL_TRUE**, the write command is blocking and does not return until the command is complete, including transfer of the data. The memory pointed to by **ptr** can be reused by the application after the **clEnqueueWriteImage** call returns.

If **blocking_write** is **CL_FALSE**, the OpenCL implementation will use **ptr** to perform a non-blocking write. As the write is non-blocking the implementation can return immediately. The memory pointed to by **ptr** cannot be reused by the application after the call returns. The **event** argument returns an event object which can be used to query the execution status of the write command. When the write command has completed, the memory pointed to by **ptr** can then be reused by the application.
clEnqueueReadImage and clEnqueueWriteImage return CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_COMMAND_QUEUE** if command_queue is not a valid host command-queue.
- **CL_INVALID_CONTEXT** if the context associated with command_queue and image are not the same or if the context associated with command_queue and events in event_wait_list are not the same.
- **CL_INVALID_MEM_OBJECT** if image is not a valid image object.
- **CL_INVALID_VALUE** if origin or region is NULL.
- **CL_INVALID_VALUE** if the region being read or written specified by origin and region is out of bounds.
- **CL_INVALID_VALUE** if values in origin and region do not follow rules described in the argument description for origin and region.
- **CL_INVALID_VALUE** if image is a 1D or 2D image and slice_pitch or input_slice_pitch is not 0.
- **CL_INVALID_VALUE** if ptr is NULL.
- **CL_INVALID_EVENT_WAIT_LIST** if event_wait_list is NULL and num_events_in_wait_list > 0, or event_wait_list is not NULL and num_events_in_wait_list is 0, or if event objects in event_wait_list are not valid events.
- **CL_INVALID_IMAGE_SIZE** if image dimensions (image width, height, specified or compute row and/or slice pitch) for image are not supported by device associated with queue.
- **CL_IMAGE_FORMAT_NOT_SUPPORTED** if image format (image channel order and data type) for image are not supported by device associated with queue.
- **CL_MEM_OBJECT_ALLOCATION_FAILURE** if there is a failure to allocate memory for data store associated with image.
- **CL_INVALID_OPERATION** if the device associated with command_queue does not support images (i.e. CL_DEVICE_IMAGE_SUPPORT specified in the Device Queries table is CL_FALSE).
- **CL_INVALID_OPERATION** if clEnqueueReadImage is called on image which has been created with CL_MEM_HOST_WRITE_ONLY or CL_MEM_HOST_NO_ACCESS.
- **CL_INVALID_OPERATION** if clEnqueueWriteImage is called on image which has been created with CL_MEM_HOST_READ_ONLY or CL_MEM_HOST_NO_ACCESS.
- **CL_EXEC_STATUS_ERROR_FOR_EVENTS_IN_WAIT_LIST** if the read and write operations are blocking and the execution status of any of the events in event_wait_list is a negative integer value. This error code is missing before version 1.1.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.
- **CL_INVALID_MIP_LEVEL** if the cl_khr_mipmap_image extension is supported, and the mip level specified in origin is not a valid level for image.

Calling clEnqueueReadImage to read a region of the image with the ptr argument value set to host_ptr + (origin[2] × image slice pitch + origin[1] × image row pitch +
origin[0] \times \text{bytes per pixel}, where host_ptr is a pointer to the memory region specified when the image being read is created with \texttt{CL\_MEM\_USE\_HOST\_PTR}, must meet the following requirements in order to avoid undefined behavior:

- All commands that use this image object have finished execution before the read command begins execution.
- The \texttt{row_pitch} and \texttt{slice_pitch} argument values in \texttt{clEnqueueReadImage} must be set to the image row pitch and slice pitch.
- The image object is not mapped.
- The image object is not used by any command-queue until the read command has finished execution.

Calling \texttt{clEnqueueWriteImage} to update the latest bits in a region of the image with the \texttt{ptr} argument value set to host_ptr + (origin[2] \times \text{image slice pitch} + origin[1] \times \text{image row pitch} + origin[0] \times \text{bytes per pixel}), where host_ptr is a pointer to the memory region specified when the image being written is created with \texttt{CL\_MEM\_USE\_HOST\_PTR}, must meet the following requirements in order to avoid undefined behavior:

- The host memory region being written contains the latest bits when the enqueued write command begins execution.
- The \texttt{input_row_pitch} and \texttt{input_slice_pitch} argument values in \texttt{clEnqueueWriteImage} must be set to the image row pitch and slice pitch.
- The image object is not mapped.
- The image object is not used by any command-queue until the write command has finished execution.

To enqueue a command to copy image objects, call the function

```c
// Provided by CL\_VERSION\_1\_0
cl_int clEnqueueCopyImage(
    cl_command_queue command_queue,
    cl_mem src_image,
    cl_mem dst_image,
    const size_t* src_origin,
    const size_t* dst_origin,
    const size_t* region,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

- \texttt{src_image} and \texttt{dst_image} can be 1D, 2D, 3D image or a 1D, 2D image array objects. It is possible to copy subregions between any combinations of source and destination types, provided that the dimensions of the subregions are the same e.g., one can copy a rectangular region from a 2D image to a slice of a 3D image.
• **command_queue** refers to the host command-queue in which the copy command will be queued. The OpenCL context associated with **command_queue**, **src_image** and **dst_image** must be the same.

• **src_origin** defines the \((x, y, z)\) offset in pixels in the 1D, 2D or 3D image, the \((x, y)\) offset and the image index in the 2D image array or the \((x)\) offset and the image index in the 1D image array. If **image** is a 2D image object, **src_origin[2]** must be 0. If **src_image** is a 1D image object, **src_origin[1]** and **src_origin[2]** must be 0. If **src_image** is a 1D image array object, **src_origin[2]** must be 0. If **src_image** is a 1D image array object, **src_origin[1]** describes the image index in the 1D image array. If **src_image** is a 2D image array object, **src_origin[2]** describes the image index in the 2D image array. If **src_image** is a mipmapped image, the mip level to read is determined from **src_origin** as described in Specifying Mipmap Levels to Image Operations.

• **dst_origin** defines the \((x, y, z)\) offset in pixels in the 1D, 2D or 3D image, the \((x, y)\) offset and the image index in the 2D image array or the \((x)\) offset and the image index in the 1D image array. If **dst_image** is a 2D image object, **dst_origin[2]** must be 0. If **dst_image** is a 1D image or 1D image buffer object, **dst_origin[1]** and **dst_origin[2]** must be 0. If **dst_image** is a 1D image array object, **dst_origin[2]** must be 0. If **dst_image** is a 1D image array object, **dst_origin[1]** describes the image index in the 1D image array. If **dst_image** is a 2D image array object, **dst_origin[2]** describes the image index in the 2D image array. If **dst_image** is a mipmapped image, the mip level to write is determined from **dst_origin** as described in Specifying Mipmap Levels to Image Operations.

• **region** defines the \((width, height, depth)\) in pixels of the 1D, 2D or 3D rectangle, the \((width, height)\) in pixels of the 2D rectangle and the number of images of a 2D image array or the \((width)\) in pixels of the 1D rectangle and the number of images of a 1D image array. If **src_image** or **dst_image** is a 2D image object, **region[2]** must be 1. If **src_image** or **dst_image** is a 1D image or 1D image buffer object, **region[1]** and **region[2]** must be 1. If **src_image** or **dst_image** is a 1D image array object, **region[2]** must be 1. The values in **region** cannot be 0.

• **event_wait_list** and **num_events_in_wait_list** specify events that need to complete before this particular command can be executed. If **event_wait_list** is **NULL**, then this particular command does not wait on any event to complete. If **event_wait_list** is **NULL**, **num_events_in_wait_list** must be 0. If **event_wait_list** is not **NULL**, the list of events pointed to by **event_wait_list** must be valid and **num_events_in_wait_list** must be greater than 0. The events specified in **event_wait_list** act as synchronization points. The context associated with events in **event_wait_list** and **command_queue** must be the same. The memory associated with **event_wait_list** can be reused or freed after the function returns.

• **event** returns an event object that identifies this copy command and can be used to query or queue a wait for this command to complete. If **event** is **NULL** or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If **event_wait_list** and **event** are not **NULL**, **event** must not refer to an element of the **event_wait_list** array.

It is currently a requirement that the **src_image** and **dst_image** image memory objects for **clEnqueueCopyImage** must have the exact same image format (i.e. the **cl_image_format** descriptor specified when **src_image** and **dst_image** are created must match).

**clEnqueueCopyImage** returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:
• **CL_INVALID_COMMAND_QUEUE** if `command_queue` is not a valid host command-queue.

• **CL_INVALID_CONTEXT** if the context associated with `command_queue`, `src_image` and `dst_image` are not the same or if the context associated with `command_queue` and events in `event_wait_list` are not the same.

• **CL_INVALID_MEM_OBJECT** if `src_image` and `dst_image` are not valid image objects.

• **CL_IMAGE_FORMAT_MISMATCH** if `src_image` and `dst_image` do not use the same image format.

• **CL_INVALID_VALUE** if `src_origin`, `dst_origin`, or `region` is **null**.

• **CL_INVALID_VALUE** if the 2D or 3D rectangular region specified by `src_origin` and `src_origin + region` refers to a region outside `src_image`, or if the 2D or 3D rectangular region specified by `dst_origin` and `dst_origin + region` refers to a region outside `dst_image`.

• **CL_INVALID_VALUE** if values in `src_origin`, `dst_origin` and `region` do not follow rules described in the argument description for `src_origin`, `dst_origin` and `region`.

• **CL_INVALID_EVENT_WAIT_LIST** if `event_wait_list` is **null** and `num_events_in_wait_list` > 0, or `event_wait_list` is not **null** and `num_events_in_wait_list` is 0, or if event objects in `event_wait_list` are not valid events.

• **CL_INVALID_IMAGE.SIZE** if image dimensions (image width, height, specified or compute row and/or slice pitch) for `src_image` or `dst_image` are not supported by device associated with `queue`.

• **CL_IMAGE_FORMAT_NOT_SUPPORTED** if image format (image channel order and data type) for `src_image` or `dst_image` are not supported by device associated with `queue`.

• **CL_MEM_OBJECT_ALLOCATION_FAILURE** if there is a failure to allocate memory for data store associated with `src_image` or `dst_image`.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

• **CL_INVALID_OPERATION** if the device associated with `command_queue` does not support images (i.e. `CL_DEVICE_IMAGE_SUPPORT` specified in the **Device Queries** table is **CL_FALSE**).

• **CL_MEM_COPY_OVERLAP** if `src_image` and `dst_image` are the same image object and the source and destination regions overlap.

• **CL_INVALID_MIP_LEVEL** if the `cl_khr_mipmap_image` extension is supported, and the mip level specified in `src_origin` or `dst_origin` is not a valid level for the corresponding `src_image` or `dst_image`.

### 5.3.5. Filling Image Objects

Filling image objects is **missing before** version 1.2.

To enqueue a command to fill an image object with a specified color, call the function
# clEnqueueFillImage

The `clEnqueueFillImage` routine fills the specified section of an image with the specified color.

```c
cl_int clEnqueueFillImage(
    cl_command_queue command_queue,
    cl_mem image,
    const void* fill_color,
    const size_t* origin,
    const size_t* region,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

- **Command Queue (`command_queue`)**: Refers to the host command-queue in which the fill command will be queued. The OpenCL context associated with `command_queue` and `image` must be the same.

- **Image (`image`)**: Must be a valid image object.

- **Color (`fill_color`)**: Specifies the color used to fill the image. The fill color is a single floating-point value if the channel order is `CL_DEPTH`. Otherwise, the fill color is a four component RGBA floating-point color value if the `image` channel data type is not an unnormalized signed or unsigned integer type, is a four component signed integer value if the `image` channel data type is an unnormalized signed integer type and is a four component unsigned integer value if the `image` channel data type is an unnormalized unsigned integer type. The fill color will be converted to the appropriate image channel format and order associated with `image`.

- **Origin (`origin`)**: Defines the offset in pixels in the 1D, 2D or 3D image, the offset and the image index in the 2D image array or the (x) offset and the image index in the 1D image array. If `image` is a 2D image object, `origin[2]` must be 0. If `image` is a 1D image or 1D image buffer object, `origin[1]` and `origin[2]` must be 0. If `image` is a 1D image array object, `origin[2]` must be 0. If `image` is a 2D image object, `origin[2]` describes the image index in the 2D image array. If `image` is a 2D image array object, `origin[2]` describes the image index in the 2D image array. If `image` is a mipmapped image, the mip level to fill is determined from `origin` as described in Specifying Mipmap Levels to Image Operations.

- **Region (`region`)**: Defines the rectangle in pixels of the 1D, 2D or 3D image, the rectangle in pixels of the 2D image and the number of images of a 2D image array or the (width) in pixels of the 1D rectangle and the number of images of a 1D image array. If `image` is a 2D image object, `region[2]` must be 1. If `image` is a 1D image or 1D image buffer object, `region[1]` and `region[2]` must be 1. If `image` is a 1D image array object, `region[2]` must be 1. The values in `region` cannot be 0.

- **Event Wait List and Number of Events in Wait List (`event_wait_list` and `num_events_in_wait_list`)**: Specify events that need to complete before this particular command can be executed. If `event_wait_list` is `NULL`, then this particular command does not wait on any event to complete. If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0. The events specified in `event_wait_list` act as synchronization points. The context associated with events in `event_wait_list` and `command_queue` must be the same. The memory associated with `event_wait_list` can be reused or freed after the function returns.
• `event` returns an event object that identifies this command and can be used to query or queue a wait for this command to complete. If `event` is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If `event_wait_list` and `event` are not `NULL`, `event` must not refer to an element of the `event_wait_list` array.

The usage information which indicates whether the memory object can be read or written by a kernel and/or the host and is given by the `cl_mem_flags` argument value specified when `image` is created is ignored by `clEnqueueFillImage`.

`clEnqueueFillImage` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_COMMAND_QUEUE` if `command_queue` is not a valid host command-queue.
- `CL_INVALID_CONTEXT` if the context associated with `command_queue` and `image` are not the same or if the context associated with `command_queue` and events in `event_wait_list` are not the same.
- `CL_INVALID_MEM_OBJECT` if `image` is not a valid image object.
- `CL_INVALID_VALUE` if `fill_color` is `NULL`.
- `CL_INVALID_VALUE` if `origin` or `region` is `NULL`.
- `CL_INVALID_VALUE` if the region being filled as specified by `origin` and `region` is out of bounds.
- `CL_INVALID_VALUE` if values in `origin` and `region` do not follow rules described in the argument description for `origin` and `region`.
- `CL_INVALID_EVENT_WAIT_LIST` if `event_wait_list` is `NULL` and `num_events_in_wait_list` > `0`, or `event_wait_list` is not `NULL` and `num_events_in_wait_list` is `0`, or if event objects in `event_wait_list` are not valid events.
- `CL_INVALID_IMAGE_SIZE` if image dimensions (image width, height, specified or compute row and/or slice pitch) for `image` are not supported by device associated with `queue`.
- `CL_IMAGE_FORMAT_NOT_SUPPORTED` if image format (image channel order and data type) for `image` are not supported by device associated with `queue`.
- `CL_MEM_OBJECT_ALLOCATION_FAILURE` if there is a failure to allocate memory for data store associated with `image`.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.
- `CL_INVALID_MIP_LEVEL` if the `cl_khr_mipmap_image` extension is supported, and the mip level specified in `origin` is not a valid level for `image`.

### 5.3.6. Copying Between Image and Buffer Objects

To enqueue a command to copy an image object to a buffer object, call the function
cl_int clEnqueueCopyImageToBuffer(
    cl_command_queue command_queue,
    cl_mem src_image,
    cl_mem dst_buffer,
    const size_t* src_origin,
    const size_t* region,
    size_t dst_offset,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);

• command_queue must be a valid host command-queue. The OpenCL context associated with command_queue, src_image and dst_buffer must be the same.

• src_image is a valid image object.

• dst_buffer is a valid buffer object.

• src_origin defines the (x, y, z) offset in pixels in the 1D, 2D or 3D image, the (x, y) offset and the image index in the 2D image array or the (x) offset and the image index in the 1D image array. If src_image is a 2D image object, src_origin[2] must be 0. If src_image is a 1D image or 1D image buffer object, src_origin[1] and src_origin[2] must be 0. If src_image is a 1D image array object, src_origin[2] must be 0. If src_image is a 2D image array object, src_origin[1] describes the image index in the 1D image array. If src_image is a 2D image array object, src_origin[2] describes the image index in the 2D image array. If src_image is a mipmapped image, the mip level to read is determined from src_origin as described in Specifying Mipmap Levels to Image Operations

• region defines the (width, height, depth) in pixels of the 1D, 2D or 3D rectangle, the (width, height) in pixels of the 2D rectangle and the number of images of a 2D image array or the (width) in pixels of the 1D rectangle and the number of images of a 1D image array. If src_image is a 2D image object, region[2] must be 1. If src_image is a 1D image or 1D image buffer object, region[1] and region[2] must be 1. If src_image is a 1D image array object, region[2] must be 1. The values in region cannot be 0.

• dst_offset refers to the offset where to begin copying data into dst_buffer. The size in bytes of the region to be copied referred to as dst_cb is computed as width × height × depth × bytes/image element if src_image is a 3D image object, is computed as width × height × bytes/image element if src_image is a 2D image, is computed as width × height × arraysize × bytes/image element if src_image is a 2D image array object, is computed as width × bytes/image element if src_image is a 1D image or 1D image buffer object and is computed as width × arraysize × bytes/image element if src_image is a 1D image array object.

• event_wait_list and num_events_in_wait_list specify events that need to complete before this particular command can be executed. If event_wait_list is NULL, then this particular command does not wait on any event to complete. If event_wait_list is NULL, num_events_in_wait_list must be 0. If event_wait_list is not NULL, the list of events pointed to by event_wait_list must be valid and num_events_in_wait_list must be greater than 0. The events specified in event_wait_list act as synchronization points. The context associated with events in event_wait_list and command_queue must be the same. The memory associated with event_wait_list can be reused or freed after the function returns.
• event returns an event object that identifies this copy command and can be used to query or queue a wait for this command to complete. If event is NULL or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If event_wait_list and event are not NULL, event must not refer to an element of the event_wait_list array.

cEnqueueCopyImageToBuffer returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:

• CL_INVALID_COMMAND_QUEUE if command_queue is not a valid host command-queue.

• CL_INVALID_CONTEXT if the context associated with command_queue, src_image and dst_buffer are not the same or if the context associated with command_queue and events in event_wait_list are not the same.

• CL_INVALID_MEM_OBJECT if src_image is not a valid image object or dst_buffer is not a valid buffer object or if src_image is a 1D image buffer object created from dst_buffer.

• CL_INVALID_VALUE if src_origin or region is NULL.

• CL_INVALID_VALUE if the 1D, 2D or 3D rectangular region specified by src_origin and src_origin + region refers to a region outside src_image, or if the region specified by dst_offset and dst_offset + dst_cb to a region outside dst_buffer.

• CL_INVALID_VALUE if values in src_origin and region do not follow rules described in the argument description for src_origin and region.

• CL_INVALID_EVENT_WAIT_LIST if event_wait_list is NULL and num_events_in_wait_list > 0, or event_wait_list is not NULL and num_events_in_wait_list is 0, or if event objects in event_wait_list are not valid events.

• CL_MISALIGNED_SUB_BUFFER_OFFSET if dst_buffer is a sub-buffer object and offset specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for device associated with queue. This error code is missing before version 1.1.

• CL_INVALID_IMAGE_SIZE if image dimensions (image width, height, specified or compute row and/or slice pitch) for src_image are not supported by device associated with queue.

• CL_IMAGE_FORMAT_NOT_SUPPORTED if image format (image channel order and data type) for src_image are not supported by device associated with queue.

• CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for data store associated with src_image or dst_buffer.

• CL_INVALID_OPERATION if the device associated with command_queue does not support images (i.e. CL_DEVICE_IMAGE_SUPPORT specified in the Device Queries table is CL_FALSE).

• CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.

• CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

• CL_INVALID_MIP_LEVEL if the cl_khr_mipmap_image extension is supported, and the mip level specified in src_origin is not a valid level for src_image.

To enqueue a command to copy a buffer object to an image object, call the function


```c
cl_int clEnqueueCopyBufferToImage(
    cl_command_queue command_queue,
    cl_mem src_buffer,
    cl_mem dst_image,
    size_t src_offset,
    const size_t* dst_origin,
    const size_t* region,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

- `command_queue` must be a valid host command-queue. The OpenCL context associated with `command_queue`, `src_buffer` and `dst_image` must be the same.

- `src_buffer` is a valid buffer object.

- `dst_image` is a valid image object.

- `src_offset` refers to the offset where to begin copying data from `src_buffer`.

- `dst_origin` defines the \((x, y, z)\) offset in pixels in the 1D, 2D or 3D image, the \((x, y)\) offset and the image index in the 2D image array or the \(x\) offset and the image index in the 1D image array. If `dst_image` is a 2D image object, `dst_origin[2]` must be 0. If `dst_image` is a 1D image or 1D image buffer object, `dst_origin[1]` and `dst_origin[2]` must be 0. If `dst_image` is a 1D image array object, `dst_origin[2]` must be 0. If `dst_image` is a mipmapped image, the mip level to write is determined from `dst_origin` as described in [Specifying Mipmap Levels to Image Operations](#).

- `region` defines the \((\text{width}, \text{height}, \text{depth})\) in pixels of the 1D, 2D or 3D rectangle, the \((\text{width}, \text{height})\) in pixels of the 2D rectangle and the number of images of a 2D image array or the \(\text{width}\) in pixels of the 1D rectangle and the number of images of a 1D image array. If `dst_image` is a 2D image object, `region[2]` must be 1. If `dst_image` is a 1D image or 1D image buffer object, `region[1]` and `region[2]` must be 1. If `dst_image` is a 1D image array object, `region[2]` must be 1. The values in `region` cannot be 0.

- `event_wait_list` and `num_events_in_wait_list` specify events that need to complete before this particular command can be executed. If `event_wait_list` is `NULL`, then this particular command does not wait on any event to complete. If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0. The events specified in `event_wait_list` act as synchronization points. The context associated with events in `event_wait_list` and `command_queue` must be the same. The memory associated with `event_wait_list` can be reused or freed after the function returns.

- `event` returns an event object that identifies this copy command and can be used to query or queue a wait for this command to complete. If `event` is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If `event_wait_list` and `event` are not `NULL`, `event` must not refer to an element of the `event_wait_list` array.
The size in bytes of the region to be copied from `src_buffer` referred to as `src_cb` is computed as \( \text{width} \times \text{height} \times \text{depth} \times \text{bytes/image element} \) if `dst_image` is a 3D image object, is computed as \( \text{width} \times \text{height} \times \text{bytes/image element} \) if `dst_image` is a 2D image, is computed as \( \text{width} \times \text{height} \times \text{arraysize} \times \text{bytes/image element} \) if `dst_image` is a 2D image array object, is computed as \( \text{width} \times \text{bytes/image element} \) if `dst_image` is a 1D image or 1D image buffer object and is computed as \( \text{width} \times \text{arraysize} \times \text{bytes/image element} \) if `dst_image` is a 1D image array object.

`clEnqueueCopyBufferToImage` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_COMMAND_QUEUE` if `command_queue` is not a valid host command-queue.
- `CL_INVALID_CONTEXT` if the context associated with `command_queue`, `src_buffer` and `dst_image` are not the same or if the context associated with `command_queue` and events in `event_wait_list` are not the same.
- `CL_INVALID_MEM_OBJECT` if `src_buffer` is not a valid buffer object or `dst_image` is not a valid image object or if `dst_image` is a 1D image buffer object created from `src_buffer`.
- `CL_INVALID_VALUE` if `dst_origin` or `region` is `NULL`.
- `CL_INVALID_VALUE` if the 1D, 2D or 3D rectangular region specified by `dst_origin` and `dst_origin + region` refer to a region outside `dst_image`, or if the region specified by `src_offset` and `src_offset + src_cb` refer to a region outside `src_buffer`.
- `CL_INVALID_VALUE` if values in `dst_origin` and `region` do not follow rules described in the argument description for `dst_origin` and `region`.
- `CL_INVALID_EVENT_WAIT_LIST` if `event_wait_list` is `NULL` and `num_events_in_wait_list > 0`, or `event_wait_list` is not `NULL` and `num_events_in_wait_list` is `0`, or if event objects in `event_wait_list` are not valid events.
- `CL_MISALIGNED_SUB_BUFFER_OFFSET` if `src_buffer` is a sub-buffer object and `offset` specified when the sub-buffer object is created is not aligned to `CL_DEVICE_MEM_BASE_ADDR_ALIGN` value for device associated with `queue`. This error code is missing before version 1.1.
- `CL_INVALID_IMAGE_SIZE` if image dimensions (image width, height, specified or compute row and/or slice pitch) for `dst_image` are not supported by device associated with `queue`.
- `CL_IMAGE_FORMAT_NOT_SUPPORTED` if image format (image channel order and data type) for `dst_image` are not supported by device associated with `queue`.
- `CL_MEM_OBJECT_ALLOCATION_FAILURE` if there is a failure to allocate memory for data store associated with `src_buffer` or `dst_image`.
- `CL_INVALID_OPERATION` if the device associated with `command_queue` does not support images (i.e. `CL_DEVICE_IMAGE_SUPPORT` specified in the Device Queries table is `CL_FALSE`).
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.
- `CL_INVALID_MIP_LEVEL` if the `cl_khr_mipmap_image` extension is supported, and the mip level specified in `dst_origin` is not a valid level for `dst_image`,
5.3.7. Mapping Image Objects

To enqueue a command to map a region in the image object given by image into the host address space and returns a pointer to this mapped region, call the function

```c
// Provided by CL_VERSION_1_0
void* clEnqueueMapImage(
    cl_command_queue command_queue,
    cl_mem image,
    cl_bool blocking_map,
    cl_map_flags map_flags,
    const size_t* origin,
    const size_t* region,
    size_t* image_row_pitch,
    size_t* image_slice_pitch,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event,
    cl_int* errcode_ret);
```

- `command_queue` must be a valid host command-queue.
- `image` is a valid image object. The OpenCL context associated with `command_queue` and `image` must be the same.
- `blocking_map` indicates if the map operation is blocking or non-blocking.
- `map_flags` is a bit-field and is described in the Memory Map Flags table.
- `origin` defines the (x, y, z) offset in pixels in the 1D, 2D or 3D image, the (x, y) offset and the image index in the 2D image array or the (x) offset and the image index in the 1D image array. If `image` is a 2D image object, `origin[2]` must be 0. If `image` is a 1D image or 1D image buffer object, `origin[1]` and `origin[2]` must be 0. If `image` is a 1D image array object, `origin[2]` must be 0. If `image` is a 1D image array object, `origin[1]` describes the image index in the 1D image array. If `image` is a 2D image array object, `origin[2]` describes the image index in the 2D image array.
- `region` defines the (width, height, depth) in pixels of the 1D, 2D or 3D rectangle, the (width, height) in pixels of the 2D rectangle and the number of images of a 2D image array or the (width) in pixels of the 1D rectangle and the number of images of a 1D image array. If `image` is a 2D image object, `region[2]` must be 1. If `image` is a 1D image or 1D image buffer object, `region[1]` and `region[2]` must be 1. If `image` is a 1D image array object, `region[2]` must be 1. The values in `region` cannot be 0.
- `image_row_pitch` returns the scan-line pitch in bytes for the mapped region. This must be a non-NULL value.
- `image_slice_pitch` returns the size in bytes of each 2D slice of a 3D image or the size of each 1D or 2D image in a 1D or 2D image array for the mapped region. For a 1D and 2D image, zero is returned if this argument is not NULL. For a 3D image, 1D and 2D image array, `image_slice_pitch` must be a non-NULL value.
- `event_wait_list` and `num_events_in_wait_list` specify events that need to complete before `clEnqueueMapImage` can be executed. If `event_wait_list` is NULL, then `clEnqueueMapImage`
does not wait on any event to complete. If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0. The events specified in `event_wait_list` act as synchronization points. The context associated with events in `event_wait_list` and `command_queue` must be the same. The memory associated with `event_wait_list` can be reused or freed after the function returns.

- `event` returns an event object that identifies this command and can be used to query or queue a wait for this command to complete. If `event` is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If `event_wait_list` and `event` are not `NULL`, `event` must not refer to an element of the `event_wait_list` array.

- `errcode_ret` will return an appropriate error code. If `errcode_ret` is `NULL`, no error code is returned.

If `blocking_map` is `CL_TRUE`, `clEnqueueMapImage` does not return until the specified region in `image` is mapped into the host address space and the application can access the contents of the mapped region using the pointer returned by `clEnqueueMapImage`.

If `blocking_map` is `CL_FALSE` i.e. map operation is non-blocking, the pointer to the mapped region returned by `clEnqueueMapImage` cannot be used until the map command has completed. The `event` argument returns an event object which can be used to query the execution status of the map command. When the map command is completed, the application can access the contents of the mapped region using the pointer returned by `clEnqueueMapImage`.

`clEnqueueMapImage` will return a pointer to the mapped region. The `errcode_ret` is set to `CL_SUCCESS`.

A `NULL` pointer is returned otherwise with one of the following error values returned in `errcode_ret`:

- `CL_INVALID_COMMAND_QUEUE` if `command_queue` is not a valid host command-queue.
- `CL_INVALID_CONTEXT` if context associated with `command_queue` and `image` are not the same or if context associated with `command_queue` and events in `event_wait_list` are not the same.
- `CL_INVALID_MEM_OBJECT` if `image` is not a valid image object.
- `CL_INVALID_VALUE` if `origin` or `region` is `NULL`.
- `CL_INVALID_VALUE` if region being mapped given by `(origin, origin + region)` is out of bounds or if values specified in `map_flags` are not valid.
- `CL_INVALID_VALUE` if values in `origin` and `region` do not follow rules described in the argument description for `origin` and `region`.
- `CL_INVALID_VALUE` if `image_row_pitch` is `NULL`.
- `CL_INVALID_VALUE` if `image` is a 3D image, 1D or 2D image array object and `image_slice_pitch` is `NULL`.
- `CL_INVALID_EVENT_WAIT_LIST` if `event_wait_list` is `NULL` and `num_events_in_wait_list` > 0, or `event_wait_list` is not `NULL` and `num_events_in_wait_list` is 0, or if event objects in `event_wait_list` are not valid events.
- `CL_INVALID_IMAGE_SIZE` if image dimensions (image width, height, specified or compute row
and/or slice pitch) for image are not supported by device associated with queue.

- **CL_IMAGE_FORMAT_NOT_SUPPORTED** if image format (image channel order and data type) for image are not supported by device associated with queue.

- **CL_MAP_FAILURE** if there is a failure to map the requested region into the host address space. This error cannot occur for image objects created with CL_MEM_USE_HOST_PTR or CL_MEM_ALLOC_HOST_PTR.

- **CL_EXEC_STATUS_ERROR_FOR_EVENTS_IN_WAIT_LIST** if the map operation is blocking and the execution status of any of the events in event_wait_list is a negative integer value. This error code is missing before version 1.1.

- **CL_MEM_OBJECT_ALLOCATION_FAILURE** if there is a failure to allocate memory for data store associated with image.

- **CL_INVALID_OPERATION** if the device associated with command_queue does not support images (i.e. CL_DEVICE_IMAGE_SUPPORT specified in the Device Queries table is CL_FALSE).

- **CL_INVALID_OPERATION** if image has been created with CL_MEM_HOST_WRITE_ONLY or CL_MEM_HOST_NO_ACCESS and CL_MAP_READ is set in map_flags or if image has been created with CL_MEM_HOST_READ_ONLY or CL_MEM_HOST_NO_ACCESS and CL_MAP_WRITE or CL_MAP_WRITE_INVALIDATE_REGION is set in map_flags.

- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

- **CL_INVALID_OPERATION** if mapping would lead to overlapping regions being mapped for writing.

The pointer returned maps a 1D, 2D or 3D region starting at origin and is at least region[0] pixels in size for a 1D image, 1D image buffer or 1D image array, (image_row_pitch × region[1]) pixels in size for a 2D image or 2D image array, and (image_slice_pitch × region[2]) pixels in size for a 3D image. The result of a memory access outside this region is undefined.

If the image object is created with CL_MEM_USE_HOST_PTR set in mem_flags, the following will be true:

- The host_ptr specified in clCreateImage, clCreateImageWithProperties, clCreateImage2D, or clCreateImage3D is guaranteed to contain the latest bits in the region being mapped when the clEnqueueMapImage command has completed.

- The pointer value returned by clEnqueueMapImage will be derived from the host_ptr specified when the image object is created.

Mapped image objects are unmapped using clEnqueueUnmapMemObject. This is described in Unmapping Mapped Memory Objects.

### 5.3.8. Specifying Mipmap Levels to Image Operations

When the cl_khr_mipmap_image extension is supported, the clEnqueueReadImage, clEnqueueWriteImage, clEnqueueMapImage, clEnqueueCopyImage, clEnqueueCopyImageToBuffer, clEnqueueCopyBufferToImage, and clEnqueueFillImage functions described above can operate on mipmapped images.
The mipmap image level(s) to access for each command are determined from the `origin` parameter when accessing a single `image` (non-copy functions), or from the `src_origin` and `dst_origin` parameters when accessing two `src_image` and `dst_image` images (copy functions). The logic below applies to each of these parameters, with `image` and `origin` replaced by `src_image` and `src_origin`, or `dst_image` and `dst_origin` as appropriate:

- If `image` is a 1D image, `origin[1]` specifies the mip level to use.
- If `image` is a 1D image array, `origin[2]` specifies the mip level to use.
- If `image` is a 2D image, `origin[2]` specifies the mip level to use.
- If `image` is a 2D image array or a 3D image, `origin[3]` specifies the mip level to use.

### 5.3.9. Image Object Queries

To get information that is common to all memory objects, use the `clGetMemObjectInfo` function described in Memory Object Queries.

To get information specific to an image object created with `clCreateImage`, `clCreateImageWithProperties`, `clCreateImage2D`, or `clCreateImage3D` call the function

```c
// Provided by CL_VERSION_1_0
cl_int clGetImageInfo(
   cl_mem image,
   cl_image_info param_name,
   size_t param_value_size,
   void* param_value,
   size_t* param_value_size_ret);
```

- `image` specifies the image object being queried.
- `param_name` specifies the information to query. The list of supported `param_name` types and the information returned in `param_value` by `clGetImageInfo` is described in the Image Object Queries table.
- `param_value` is a pointer to memory where the appropriate result being queried is returned. If `param_value` is `NULL`, it is ignored.
- `param_value_size` is used to specify the size in bytes of memory pointed to by `param_value`. This size must be ≥ size of return type as described in the Image Object Queries table.
- `param_value_size_ret` returns the actual size in bytes of data being queried by `param_name`. If `param_value_size_ret` is `NULL`, it is ignored.

<table>
<thead>
<tr>
<th>Image Info</th>
<th>Return type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_IMAGE_FORMAT</td>
<td>cl_image_format</td>
<td>Return the image format descriptor specified when <code>image</code> is created with <code>clCreateImage</code>, <code>clCreateImageWithProperties</code>, <code>clCreateImage2D</code> or <code>clCreateImage3D</code>.</td>
</tr>
<tr>
<td>Image Info</td>
<td>Return type</td>
<td>Description</td>
</tr>
<tr>
<td>-------------------------</td>
<td>-------------</td>
<td>---------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_IMAGE_ELEMENT_SIZE</td>
<td>size_t</td>
<td>Return size of each element of the image memory object given by image in bytes.</td>
</tr>
<tr>
<td>CL_IMAGE_ROW_PITCH</td>
<td>size_t</td>
<td>Returns the row pitch in bytes of a row of elements of the image object given by image. If image was created with a non-zero value for image_row_pitch, then the value provided for image_row_pitch by the application is returned, otherwise the returned value is calculated as CL_IMAGE_WIDTH × CL_IMAGE_ELEMENT_SIZE.</td>
</tr>
<tr>
<td>CL_IMAGE_SLICE_PITCH</td>
<td>size_t</td>
<td>Returns the slice pitch in bytes of a 2D slice for the 3D image object or size of each image in a 1D or 2D image array given by image. If image was created with a non-zero value for image_slice_pitch then the value provided for image_slice_pitch by the application is returned, otherwise the returned value is calculated as: - CL_IMAGE_ROW_PITCH for 1D image arrays. - CL_IMAGE_HEIGHT × CL_IMAGE_ROW_PITCH for 3D images and 2D image arrays. For a 1D image, 1D image buffer and 2D image object return 0.</td>
</tr>
<tr>
<td>CL_IMAGE_WIDTH</td>
<td>size_t</td>
<td>Return width of the image in pixels.</td>
</tr>
<tr>
<td>CL_IMAGE_HEIGHT</td>
<td>size_t</td>
<td>Return height of the image in pixels. For a 1D image, 1D image buffer and 1D image array object, height = 0.</td>
</tr>
<tr>
<td>CL_IMAGE_DEPTH</td>
<td>size_t</td>
<td>Return depth of the image in pixels. For a 1D image, 1D image buffer, 2D image or 1D and 2D image array object, depth = 0.</td>
</tr>
<tr>
<td>CL_IMAGE_ARRAY_SIZE</td>
<td>size_t</td>
<td>Return number of images in the image array. If image is not an image array, 0 is returned.</td>
</tr>
<tr>
<td>CL_IMAGE_BUFFER</td>
<td>cl_mem</td>
<td>Return buffer object associated with image.</td>
</tr>
<tr>
<td>CL_IMAGE_NUM_MIP_LEVELS</td>
<td>cl_uint</td>
<td>Return num_mip_levels associated with image.</td>
</tr>
<tr>
<td>CL_IMAGE_NUM_SAMPLES</td>
<td>cl_uint</td>
<td>Return num_samples associated with image.</td>
</tr>
<tr>
<td>Image Info</td>
<td>Return type</td>
<td>Description</td>
</tr>
<tr>
<td>------------------------------------------------</td>
<td>-------------</td>
<td>-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_IMAGE_DX9_MEDIA_PLANE_KHR</td>
<td>cl_uint</td>
<td>If image was created using clCreateFromDX9MediaSurfaceKHR, returns the plane argument specified when image was created.</td>
</tr>
<tr>
<td>provided by the cl_khr_dx9_media_sharing extension.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_IMAGE_D3D10_SUBRESOURCE_KHR</td>
<td>cl_uint</td>
<td>If image was created using clCreateFromD3D10Texture2DKHR, or clCreateFromD3D10Texture3DKHR, returns the subresource argument specified when image was created.</td>
</tr>
<tr>
<td>provided by the cl_khr_d3d10_sharing extension.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_IMAGE_D3D11_SUBRESOURCE_KHR</td>
<td>cl_uint</td>
<td>If image was created using clCreateFromD3D11Texture2DKHR, or clCreateFromD3D11Texture3DKHR, returns the subresource argument specified when image was created.</td>
</tr>
<tr>
<td>provided by the cl_khr_d3d11_sharing extension.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

clGetImageInfo returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_VALUE** if param_name is not valid, or if size in bytes specified by param_value_size is < size of return type as described in the Image Object Queries table and param_value is not NULL.
- **CL_INVALID_MEM_OBJECT** if image is a not a valid image object.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

The following errors may be returned if the cl_khr_dx9_media_sharing extension is supported:

- **CL_INVALID_DX9_MEDIA_SURFACE_KHR** if param_name is CL_IMAGE_DX9_MEDIA_PLANE_KHR and image was not created by calling clCreateFromDX9MediaSurfaceKHR.

The following errors may be returned if the cl_khr_d3d10_sharing extension is supported:

- **CL_INVALID_D3D10_RESOURCE_KHR** if param_name is CL_IMAGE_D3D10_SUBRESOURCE_KHR and image was not created by the function clCreateFromD3D10Texture2DKHR, or clCreateFromD3D10Texture3DKHR.

The following errors may be returned if the cl_khr_d3d11_sharing extension is supported:

- **CL_INVALID_D3D11_RESOURCE_KHR** if param_name is CL_IMAGE_D3D11_SUBRESOURCE_KHR and image was not created by the function clCreateFromD3D11Texture2DKHR, or clCreateFromD3D11Texture3DKHR.
5.3.10. Creating OpenCL Image Objects From DirectX 9 Media Resources

To create an OpenCL image object from a media surface, call the function

```c
// Provided by cl_khr_dx9_media_sharing
cl_mem clCreateFromDX9MediaSurfaceKHR(
    cl_context context,
    cl_mem_flags flags,
    cl_dx9_media_adapter_type_khr adapter_type,
    void* surface_info,
    cl_uint plane,
    cl_int* errcode_ret);
```

- `context` is a valid OpenCL context created from a media adapter.
- `flags` is a bit-field that is used to specify usage information. Refer to the List of supported memory flag values table for a description of `flags`. Only the `CL_MEM_READ_ONLY`, `CL_MEM_WRITE_ONLY` and `CL_MEM_READ_WRITE` flags specified in that table can be used.
- `adapter_type` is a value from enumeration of supported adapters described in the `cl_dx9_media_adapter_type_khr values` table. The type of `surface_info` is determined by the adapter type. The implementation does not need to support all adapter types. This approach provides flexibility to support additional adapter types in the future. Supported adapter types are `CL_ADAPTER_D3D9_KHR`, `CL_ADAPTER_D3D9EX_KHR` and `CL_ADAPTER_DXVA_KHR`.
- `surface_info` is a pointer to one of the structures defined in the `adapter_type` description above, passed in as a `void *`. If `adapter_type` is `CL_ADAPTER_D3D9_KHR`, `CL_ADAPTER_D3D9EX_KHR` and `CL_ADAPTER_DXVA_KHR`, `surface_info` points to a `[cl_dx9_surface_info_khr]` structure describing the surface.
- `plane` is the plane of resource to share for planar surface formats. For planar formats, we use the plane parameter to obtain a handle to the specific plane (Y, U or V for example). For non-planar formats used by media, `plane` must be 0.
- `errcode_ret` will return an appropriate error code. If `errcode_ret` is `NULL`, no error code is returned.

The width and height of the returned OpenCL 2D image object are determined by the width and height of the `plane` of the resource (`surface_info→_resource`). The channel type and order of the returned image object is determined by the format and plane of the resource, and are described in the YUV FourCC Codes and Corresponding OpenCL Image Formats and Direct3D 9 Formats and Corresponding OpenCL Image Formats tables.

This call will increment the internal media surface count on the resource. The internal media surface reference count on the resource will be decremented when the OpenCL reference count on the returned OpenCL memory object drops to zero.

`clCreateFromDX9MediaSurfaceKHR` returns a valid non-zero 2D image object and `errcode_ret` is
set to CL_SUCCESS if the 2D image object is created successfully. Otherwise it returns a NULL value with one of the following error values returned in errcode_ret:

- **CL_INVALID_CONTEXT** if context is not a valid context.
- **CL_INVALID_VALUE** if values specified in flags are not valid or if plane is not a valid plane of resource specified in surface_info.
- **CL_INVALID_DX9_MEDIA_SURFACE_KHR** if resource specified in surface_info is not a valid resource or is not associated with adapter_type (e.g., adapter_type is set to CL_ADAPTER_D3D9_KHR and resource is not a Direct3D 9 surface created in D3DPOOL_DEFAULT).
- **CL_INVALID_DX9_MEDIA_SURFACE_KHR** if shared_handle specified in surface_info is not NULL or a valid handle value.
- **CL_INVALID_IMAGE_FORMAT_DESCRIPTOR** if the texture format of resource is not listed in the YUV FourCC Codes and Corresponding OpenCL Image Formats or Direct3D 9 Formats and Corresponding OpenCL Image Formats tables.
- **CL_INVALID_OPERATION** if there are no devices in context that support adapter_type.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

The cl_dx9_surface_info_khr structure is passed to clCreateFromDX9MediaSurfaceKHR to describe a DX9 surface, and is defined as:

```c
// Provided by cl_khr_dx9_media_sharing
typedef struct cl_dx9_surface_info_khr {
    IDirect3DSurface9* resource;
    HANDLE shared_handle;
} cl_dx9_surface_info_khr;
```

- **resource** is a pointer to a IDirect3DSurface9 surface interface.
- **shared_handle** is a HANDLE to the resource.

For DX9 surfaces, we need both the handle to the resource and the resource itself to have a sufficient amount of information to eliminate a copy of the surface for sharing in cases where this is possible. Elimination of the copy is driver dependent. shared_handle may be NULL and this may result in sub-optimal performance.

### 5.3.11. Creating OpenCL Image Objects From Direct3D 10 Textures and Resources

To create an OpenCL 2D image object from a subresource of a Direct3D 10 2D texture, call the function
clCreateFromD3D10Texture2DKHR is provided by the cl_khr_d3d10_sharing extension.

- `context` is a valid OpenCL context created from a Direct3D 10 device.
- `flags` is a bit-field that is used to specify usage information. Refer to the List of supported memory flag values table for a description of flags. Only the CL_MEM_READ_ONLY, CL_MEM_WRITE_ONLY and CL_MEM_READ_WRITE flags specified in that table can be used.
- `resource` is a pointer to the Direct3D 10 2D texture to share.
- `subresource` is the subresource of `resource` to share.
- `errcode_ret` will return an appropriate error code. If `errcode_ret` is NULL, no error code is returned.

The width and height of the returned OpenCL 2D image object are determined by the width and height of subresource `subresource` of `resource`. The channel type and order of the returned OpenCL 2D image object is determined by the format of `resource` and the DXGI Formats and Corresponding OpenCL Image Formats table.

This call will increment the internal Direct3D 10 reference count on `resource`. The internal Direct3D 10 reference count on `resource` will be decremented when the OpenCL reference count on the returned OpenCL memory object drops to zero.

Refer to the Lifetime of Shared Direct3D Memory Objects and Acquiring, Releasing, and Synchronizing Access to Shared OpenCL/OpenGL Memory Objects sections for more information.

cCreateFromD3D10Texture2DKHR returns a valid non-zero OpenCL image object and `errcode_ret` is set to CL_SUCCESS if the image object is created successfully. Otherwise, it returns a NULL value with one of the following error values returned in `errcode_ret`:

- CL_INVALID_CONTEXT if `context` is not a valid context.
- CL_INVALID_VALUE if values specified in `flags` are not valid or if `subresource` is not a valid subresource index for `resource`.
- CL_INVALID_D3D10_RESOURCE_KHR if `resource` is not a Direct3D 10 texture resource, if `resource` was created with the D3D10_USAGE flag D3D10_USAGE_IMMUTABLE, if `resource` is a multisampled texture, if a cl_mem from subresource `subresource` of `resource` has already been created using clCreateFromD3D10Texture2DKHR, or if `context` was not created against the same Direct3D 10 device from which `resource` was created.
• **CL_INVALID_IMAGE_FORMAT_DESCRIPTOR** if the Direct3D 10 texture format of resource is not listed in the [DXGI Formats and Corresponding OpenCL Image Formats](table) table or if the Direct3D 10 texture format of resource does not map to a supported OpenCL image format.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To create an OpenCL 3D image object from a subresource of a Direct3D 10 3D texture, call the function

```c
// Provided by cl_khr_d3d10_sharing
cl_mem clCreateFromD3D10Texture3DKHR(
    cl_context context,
    cl_mem_flags flags,
    ID3D10Texture3D* resource,
    UINT subresource,
    cl_int* errcode_ret);
```

**clCreateFromD3D10Texture3DKHR** is provided by the [cl_khr_d3d10_sharing](extension) extension.

- **context** is a valid OpenCL context created from a Direct3D 10 device.

- **flags** is a bit-field that is used to specify usage information. Refer to the [List of supported memory flag values](table) for a description of flags. Only the [CL_MEM_READ_ONLY](flag), [CL_MEM_WRITE_ONLY](flag) and [CL_MEM_READ_WRITE](flag) flags specified in that table can be used.

- **resource** is a pointer to the Direct3D 10 3D texture to share.

- **subresource** is the subresource of resource to share.

- **errcode_ret** will return an appropriate error code. If errcode_ret is NULL, no error code is returned.

The width, height and depth of the returned OpenCL 3D image object are determined by the width, height and depth of subresource subresource of resource. The channel type and order of the returned OpenCL 3D image object is determined by the format of resource and the [DXGI Formats and Corresponding OpenCL Image Formats](table) table.

This call will increment the internal Direct3D 10 reference count on resource. The internal Direct3D 10 reference count on resource will be decremented when the OpenCL reference count on the returned OpenCL memory object drops to zero.

Refer to the [Lifetime of Shared Direct3D Memory Objects](section) and [Acquiring, Releasing, and Synchronizing Access to Shared OpenCL/OpenGL Memory Objects](section) sections for more information.

**clCreateFromD3D10Texture3DKHR** returns a valid non-zero OpenCL image object and **errcode_ret** is set to [CL_SUCCESS](code) if the image object is created successfully. Otherwise, it returns a NULL value with one of the following error values returned in **errcode_ret**:

- **CL_INVALID_IMAGE_FORMAT_DESCRIPTOR**
- **CL_OUT_OF_HOST_MEMORY**
• **CL_INVALID_CONTEXT** if `context` is not a valid context.

• **CL_INVALID_VALUE** if values specified in `flags` are not valid or if `subresource` is not a valid subresource index for `resource`.

• **CL_INVALID_D3D10_Resource_KHR** if `resource` is not a Direct3D 10 texture resource, if `resource` was created with the D3D10_USAGE flag D3D10_USAGE_IMMUTABLE, if `resource` is a multisampled texture, if a `cl_mem` from subresource `subresource` of `resource` has already been created using `clCreateFromD3D10Texture3DKHR`, or if `context` was not created against the same Direct3D 10 device from which `resource` was created.

• **CL_INVALID_IMAGE_FORMAT_DESCRIPTOR** if the Direct3D 10 texture format of `resource` is not listed in the **DXGI Formats and Corresponding OpenCL Image Formats** table or if the Direct3D 10 texture format of `resource` does not map to a supported OpenCL image format.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.3.12. Creating OpenCL Image Objects From Direct3D 11 Textures and Resources

To create an OpenCL 2D image object from a subresource of a Direct3D 11 2D texture, call the function

```c
// Provided by cl_khr_d3d11_sharing
cl_mem clCreateFromD3D11Texture2DKHR(
    cl_context context,
    cl_mem_flags flags,
    ID3D11Texture2D* resource,
    UINT subresource,
    cl_int* errcode_ret);
```

- **context** is a valid OpenCL context created from a Direct3D 11 device.
- **flags** is a bit-field that is used to specify usage information. Refer to the **List of supported memory flag values** table for a description of `flags`. Only the `CL_MEM_READ_ONLY`, `CL_MEM_WRITE_ONLY` and `CL_MEM_READ_WRITE` flags specified in that table can be used.
- **resource** is a pointer to the Direct3D 11 2D texture to share.
- **subresource** is the subresource of `resource` to share.
- **errcode_ret** will return an appropriate error code. If `errcode_ret` is `NULL`, no error code is returned.

The width and height of the returned OpenCL 2D image object are determined by the width and height of subresource `subresource` of `resource`. The channel type and order of the returned OpenCL 2D image object is determined by the format of `resource` and the **DXGI Formats and Corresponding OpenCL Image Formats** table.
This call will increment the internal Direct3D 11 reference count on `resource`. The internal Direct3D 11 reference count on `resource` will be decremented when the OpenCL reference count on the returned OpenCL memory object drops to zero.

Refer to the Lifetime of Shared Direct3D Memory Objects and Acquiring, Releasing, and Synchronizing Access to Shared OpenCL/OpenGL Memory Objects sections for more information.

`clCreateFromD3D11Texture2DKHR` returns a valid non-zero OpenCL image object and `errcode_ret` is set to `CL_SUCCESS` if the image object is created successfully. Otherwise, it returns a NULL value with one of the following error values returned in `errcode_ret`:

- `CL_INVALID_CONTEXT` if `context` is not a valid context.
- `CL_INVALID_VALUE` if values specified in `flags` are not valid or if `subresource` is not a valid subresource index for `resource`.
- `CL_INVALID_D3D11_RESOURCE_KHR` if `resource` is not a Direct3D 11 texture resource, if `resource` was created with the D3D11_USAGE flag `D3D11_USAGE_IMMUTABLE`, if `resource` is a multisampled texture, if a `cl_mem` from subresource `subresource` of `resource` has already been created using `clCreateFromD3D11Texture2DKHR`, or if `context` was not created against the same Direct3D 11 device from which `resource` was created.
- `CL_INVALID_IMAGE_FORMAT_DESCRIPTOR` if the Direct3D 11 texture format of `resource` is not listed in the DXGI Formats and Corresponding OpenCL Image Formats table or if the Direct3D 11 texture format of `resource` does not map to a supported OpenCL image format.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

To create an OpenCL 3D image object from a subresource of a Direct3D 11 3D texture, call the function

```c
// Provided by cl_khr_d3d11_sharing
cl_mem clCreateFromD3D11Texture3DKHR(
    cl_context context,
    cl_mem_flags flags,
    ID3D11Texture3D* resource,
    UINT subresource,
    cl_int* errcode_ret);
```

`clCreateFromD3D11Texture3DKHR` is provided by the `cl_khr_d3d11_sharing` extension.

- `context` is a valid OpenCL context created from a Direct3D 11 device.
- `flags` is a bit-field that is used to specify usage information. Refer to the List of supported memory flag values table for a description of `flags`. Only the `CL_MEM_READ_ONLY`, `CL_MEM_WRITE_ONLY` and `CL_MEM_READ_WRITE` flags specified in that table can be used.
- `resource` is a pointer to the Direct3D 11 3D texture to share.
• subresource is the subresource of resource to share.

• errcode_ret will return an appropriate error code. If errcode_ret is NULL, no error code is returned.

The width, height and depth of the returned OpenCL 3D image object are determined by the width, height and depth of subresource subresource of resource. The channel type and order of the returned OpenCL 3D image object is determined by the format of resource and the DXGI Formats and Corresponding OpenCL Image Formats table.

This call will increment the internal Direct3D 11 reference count on resource. The internal Direct3D 11 reference count on resource will be decremented when the OpenCL reference count on the returned OpenCL memory object drops to zero.

Refer to the Lifetime of Shared Direct3D Memory Objects and Acquiring, Releasing, and Synchronizing Access to Shared OpenCL/OpenGL Memory Objects sections for more information.

clCreateFromD3D11Texture3DKHR returns a valid non-zero OpenCL image object and errcode_ret is set to CL_SUCCESS if the image object is created successfully. Otherwise, it returns a NULL value with one of the following error values returned in errcode_ret:

• CL_INVALID_CONTEXT if context is not a valid context.

• CL_INVALID_VALUE if values specified in flags are not valid or if subresource is not a valid subresource index for resource.

• CL_INVALID_D3D11_RESOURCE_KHR if resource is not a Direct3D 11 texture resource, if resource was created with the D3D11_USAGE flag D3D11_USAGE_IMMUTABLE, if resource is a multisampled texture, if a cl_mem from subresource subresource of resource has already been created using clCreateFromD3D11Texture3DKHR, or if context was not created against the same Direct3D 11 device from which resource was created.

• CL_INVALID_IMAGE_FORMAT_DESCRIPTOR if the Direct3D 11 texture format of resource is not listed in the DXGI Formats and Corresponding OpenCL Image Formats table or if the Direct3D 11 texture format of resource does not map to a supported OpenCL image format.

• CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

5.3.13. Creating OpenCL Image Objects From EGL Images

To create an EGLImage target of type cl_mem from the EGLImage source provided as image, call the function
clCreateFromEGLImageKHR is provided by the cl_khr_egl_image extension.

- **display** should be of type EGLDisplay, cast into the type CLeglDisplayKHR.
- **image** should be of type EGLImageKHR, cast into the type CLeglImageKHR. Assuming no errors are generated in this function, the resulting image object will be an EGLImage target of the specified EGLImage image. The resulting cl_mem is an image object which may be used normally by all OpenCL operations. This maps to an image2d_t type in OpenCL kernel code.
- **flags** is a bit-field that is used to specify usage information about the memory object being created. Refer to the Memory Flags table for a description of flags. Accepted values in flags are described below.
- **properties** specifies a list of property names and their corresponding values. Each property name is immediately followed by the corresponding desired value. The list is terminated with 0. No properties are currently supported with this version of the extension. properties can be NULL.
- **errcode_ret** will return an appropriate error code. If errcode_ret is NULL, no error code is returned.

Accepted for flags are CL_MEM_READ_ONLY, CL_MEM_WRITE_ONLY and CL_MEM_READ_WRITE. If OpenCL 1.2 is supported, flags also accepts CL_MEM_HOST_WRITE_ONLY, CL_MEM_HOST_READ_ONLY, and CL_MEM_HOST_NO_ACCESS.

cl_khr_egl_image only requires support for CL_MEM_READ_ONLY, and for CL_MEM_HOST_NO_ACCESS if OpenCL 1.2 or later is supported. For OpenCL 1.1, a CL_INVALID_OPERATION will be returned for images which do not support host mapping.

If the value passed in flags is not supported by the OpenCL implementation, it will return CL_INVALID_VALUE. The accepted flags may be dependent upon the texture format used.

clCreateFromEGLImageKHR returns a valid non-zero OpenCL image object and errcode_ret is set to CL_SUCCESS if the image object is created successfully. Otherwise, it returns a NULL value with one of the following error values returned in errcode_ret:

- CL_INVALID_CONTEXT if context is not a valid OpenCL context.
- CL_INVALID_VALUE if properties contains invalid values, if display is not a valid display object or if flags are not in the set defined above.
- CL_INVALID_EGL_OBJECT_KHR if image is not a valid EGLImage object.
- CL_IMAGE_FORMAT_NOT_SUPPORTED if the OpenCL implementation is not able to create a cl_mem
compatible with the provided CLeglImageKHR for an implementation-dependent reason (this could be caused by, but not limited to, reasons such as unsupported texture formats, etc).

- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_INVALID_OPERATION** if there are no devices in `context` that support images (i.e. CL_DEVICE_IMAGE_SUPPORT specified in table 4.3 is CL_FALSE) or if the flags passed are not supported for that image type.

### 5.3.14. Creating OpenCL Image Objects From OpenGL Textures and Renderbuffers

To create an OpenCL image object from an OpenGL texture object, call the function

```c
// Provided by cl_khr_gl_sharing
cl_mem clCreateFromGLTexture(
    cl_context context,
    cl_mem_flags flags,
    cl_Glenum target,
    cl_Glint mipmap,
    cl_Gluint texture,
    cl_int* errcode_ret);
```

- **context** is a valid OpenCL context created from an OpenGL context.
- **flags** is a bit-field that is used to specify usage information. Refer to the Memory Flags table for a description of flags. Only the **CL_MEM_READ_ONLY**, **CL_MEM_WRITE_ONLY** and **CL_MEM_READ_WRITE** flags specified in that table can be used.

- **texture_target** must be one of **GL_TEXTURE_1D**, **GL_TEXTURE_1D_ARRAY**, **GL_TEXTURE_BUFFER**, **GL_TEXTURE_2D**, **GL_TEXTURE_2D_ARRAY**, **GL_TEXTURE_3D**, **GL_TEXTURE_CUBE_MAP_POSITIVE_X**, **GL_TEXTURE_CUBE_MAP_POSITIVE_Y**, **GL_TEXTURE_CUBE_MAP_POSITIVE_Z**, **GL_TEXTURE_CUBE_MAP_NEGATIVE_X**, **GL_TEXTURE_CUBE_MAP_NEGATIVE_Y**, **GL_TEXTURE_CUBE_MAP_NEGATIVE_Z**, **GL_TEXTURE_RECTANGLE** or the equivalent **GL_TEXTURE_RECTANGLE_ARB** may be specified if an OpenGL implementation supporting rectangular textures is supported. **GL_TEXTURE_2D_MULTISAMPLE** and **GL_TEXTURE_2D_MULTISAMPLE_ARRAY** may be specified if an OpenGL implementation supporting multi-sample two-dimensional textures is supported, and the cl_khr_gl_msaa_sharing extension is supported. Refer to the Restrictions on Multi-Sample Images section for more information on multi-sample images. **texture_target** is used only to define the image type of texture. No reference to a bound OpenGL texture object is made or implied by this parameter.

- **mipmap** is the mipmap level to be used. If **texture_target** is **GL_TEXTURE_BUFFER**, **mipmap** must be 0. Note: Implementations may return **CL_INVALID_OPERATION** for mipmap values > 0.
texture is the name of an OpenGL 1D, 2D, 3D, 1D array, 2D array, cubemap, rectangle or buffer texture object. The texture object must be a complete texture as per OpenGL rules on texture completeness. The texture format and dimensions defined by OpenGL for the specified miplevel of the texture will be used to create the OpenCL image memory object. Only OpenGL texture objects with an internal format that maps to an appropriate Image Channel Order and Image Channel Data Type may be used to create the OpenCL image memory object.

errcode_ret will return an appropriate error code as described below. If errcode_ret is NULL, no error code is returned.

clCreateFromGLTexture may create any of the following:

- an OpenCL 2D image object from an OpenGL 2D texture object or a single face of an OpenGL cubemap texture object,
- an OpenCL 2D image array object from an OpenGL 2D texture array object,
- an OpenCL 2D multi-sample image object from an OpenGL 2D multi-sample texture.
- an OpenCL 2D multi-sample array image object from an OpenGL 2D multi-sample texture.
- an OpenCL 1D image object from an OpenGL 1D texture object,
- an OpenCL 1D image buffer object from an OpenGL texture buffer object,
- an OpenCL 1D image array object from an OpenGL 1D texture array object,
- an OpenCL 3D image object from an OpenGL 3D texture object.

If both the cl_khr_mipmap_image and cl_khr_gl_sharing extensions are supported by the OpenCL device, clCreateFromGLTexture may also be used to create a mipmapped OpenCL image from a mipmapped OpenGL texture by specify a negative value for miplevel. In this case, then an OpenCL mipmapped image object is created from a mipmapped OpenGL texture object, instead of an OpenCL image object for a specific miplevel of the OpenGL texture.

For a detailed description of how the level of detail is computed, please refer to the “Scale Factor and Level-of-Detail” section of the OpenGL 4.6 Specification.

If the state of an OpenGL texture object is modified through the OpenGL API (e.g. glTexImage2D, glTexImage3D or the values of the texture parameters GL_TEXTURE_BASE_LEVEL or GL_TEXTURE_MAX_LEVEL are modified) while there exists a corresponding OpenCL image object, subsequent use of the OpenCL image object will result in undefined behavior.

The clRetainMemObject and clReleaseMemObject functions can be used to retain and release the image objects.

Refer to the Lifetime of Shared OpenCL/OpenGL Memory Objects and Acquiring, Releasing, and Synchronizing Access to Shared OpenCL/OpenGL Memory Objects sections for more information.

clCreateFromGLTexture returns a valid non-zero OpenCL image object and errcode_ret is set to CL_SUCCESS if the image object is created successfully. Otherwise, it returns a NULL value with one of the following error values returned in errcode_ret:
• **CL_INVALID_CONTEXT** if `context` is not a valid context or was not created from an OpenGL context.

• **CL_INVALID_VALUE** if values specified in `flags` are not valid or if value specified in `texture_target` is not one of the values specified in the description of `texture_target`.

• **CL_INVALID_MIP_LEVEL** if `miplevel` is less than the value of `level_base` (for OpenGL implementations) or zero (for OpenGL ES implementations); or greater than the value of `q` (for both OpenGL and OpenGL ES). `level_base` and `q` are defined for the texture in section 3.8.10 (Texture Completeness) of the OpenGL 2.1 Specification and section 3.7.10 of the OpenGL ES 2.0 Specification.

• **CL_INVALID_MIP_LEVEL** if `miplevel` is greater than zero and the OpenGL implementation does not support creating from non-zero mipmap levels.

• **CL_INVALID_GL_OBJECT** if `texture` is not an OpenGL texture object whose type matches `texture_target`, if the specified `miplevel` of `texture` is not defined, or if the width or height of the specified `miplevel` is zero or if the OpenGL texture object is incomplete.

• **CL_INVALID_IMAGE_FORMAT_DESCRIPTOR** if the internal format of `texture` is not listed in the OpenGL Internal Formats and Corresponding OpenCL Internal Formats table.

• **CL_INVALID_OPERATION** if `texture` is an OpenGL texture object created with a border width value greater than zero.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.3.14.1. Restrictions on Depth/Stencil Images

Depth images with an image channel order of **CL_DEPTH_STENCIL** can only be created using the `clCreateFromGLTexture` API, and only when the `cl_khr_gl_depth_images` extension is supported.

For the image format given by channel order of **CL_DEPTH_STENCIL** and channel data type of **CL_UNORM_INT24**, the depth is stored as an unsigned normalized 24-bit value.

For the image format given by channel order of **CL_DEPTH_STENCIL** and channel data type of **CL_FLOAT**, each pixel is two 32-bit values. The depth is stored as a single precision floating-point value followed by the stencil which is stored as a 8-bit integer value.

Such images appear in the [Minimum List of Supported Image Formats](#), but only require read support, not write support.

The stencil value cannot be read or written using the `read_imagef` and `write_imagef` built-in functions in an OpenCL kernel.

Depth image objects with an image channel order of **CL_DEPTH_STENCIL** cannot be used as arguments to `clEnqueueReadImage`, `clEnqueueWriteImage`, `clEnqueueCopyImage`, `clEnqueueCopyImageToBuffer`, `clEnqueueCopyBufferToImage`, `clEnqueueMapImage`, and `clEnqueueFillImage`. Such use will return a **CL_INVALID_OPERATION** error.
5.3.14.2. Restrictions on Multi-Sample Images

The formats described in the Image Channel Order Values and Image Channel Data Types tables of the OpenCL 3.0 specification, specification and the additional formats described in the Minimum list of supported image formats for reading or writing table also support OpenCL images created from a OpenGL multi-sampled color or depth texture.

Multi-sample OpenCL image objects can only be read from a kernel. Multi-sample OpenCL image objects cannot be used as arguments to clEnqueueReadImage, clEnqueueWriteImage, clEnqueueCopyImage, clEnqueueCopyImageToBuffer, clEnqueueCopyBufferToImage, clEnqueueMapImage, and clEnqueueFillImage. Such use will return a CL_INVALID_OPERATION error.

To create an OpenCL 2D image object from an OpenGL renderbuffer object, call the function

```c
// Provided by cl_khr_gl_sharing
cl_mem clCreateFromGLRenderbuffer(
    cl_context context,
    cl_mem_flags flags,
    cl_Gluint renderbuffer,
    cl_int* errcode_ret);
```

clCreateFromGLRenderbuffer is provided by the cl_khr_gl_sharing extension.

- `context` is a valid OpenCL context created from an OpenGL context.
- `flags` is a bit-field that is used to specify usage information. Refer to the Memory Flags table for a description of flags. Only the CL_MEM_READ_ONLY, CL_MEM_WRITE_ONLY and CL_MEM_READ_WRITE flags specified in that table can be used.
- `renderbuffer` is the name of an OpenGL renderbuffer object. The renderbuffer storage must be specified before the image object can be created. The renderbuffer format and dimensions defined by OpenGL will be used to create the 2D image object. Only OpenGL renderbuffers with an internal format that maps to an appropriate Image Channel Order and Image Channel Data Type may be used to create the 2D image object.
- `errcode_ret` will return an appropriate error code as described below. If `errcode_ret` is NULL, no error code is returned.

If the state of an OpenGL renderbuffer object is modified through the OpenGL API (i.e. changes to the dimensions or format used to represent pixels of the OpenGL renderbuffer using appropriate OpenGL API calls such as glRenderbufferStorage) while there exists a corresponding OpenCL image object, subsequent use of the OpenCL image object will result in undefined behavior.

The clRetainMemObject and clReleaseMemObject functions can be used to retain and release the image objects.

The OpenGL Internal Formats and Corresponding OpenCL Internal Formats table describes the list of OpenGL renderbuffer internal formats and the Corresponding OpenCL Image Formats. If an OpenGL renderbuffer object with an internal format from the table is successfully created by
OpenGL, then there is guaranteed to be a mapping to one of the corresponding OpenCL image format(s) in that table. Renderbuffer objects created with other OpenGL internal formats may (but are not guaranteed to) have a mapping to an OpenCL image format; if such mappings exist, they are guaranteed to preserve all color components, data types, and at least the number of bits/component actually allocated by OpenGL for that format.

Refer to the Lifetime of Shared OpenCL/OpenGL Memory Objects and Acquiring, Releasing, and Synchronizing Access to Shared OpenCL/OpenGL Memory Objects sections for more information.

`clCreateFromGLRenderbuffer` returns a valid non-zero OpenCL image object and `errcode_ret` is set to `CL_SUCCESS` if the image object is created successfully. Otherwise, it returns a `NULL` value with one of the following error values returned in `errcode_ret`:

- `CL_INVALID_CONTEXT` if `context` is not a valid context or was not created from an OpenGL context.
- `CL_INVALID_VALUE` if values specified in `flags` are not valid.
- `CL_INVALID_GL_OBJECT` if `renderbuffer` is not an OpenGL renderbuffer object, or if the width or height of `renderbuffer` is zero.
- `CL_INVALID_IMAGE_FORMAT_DESCRIPTOR` if the internal format of `renderbuffer` is not listed in the OpenGL Internal Formats and Corresponding OpenCL Internal Formats table.
- `CL_INVALID_OPERATION` if `renderbuffer` is a multi-sample OpenGL renderbuffer object.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.4. Pipes

Pipes are missing before version 2.0.

A pipe is a memory object that stores data organized as a FIFO. Pipe objects can only be accessed using built-in functions that read from and write to a pipe. Pipe objects are not accessible from the host. A pipe object encapsulates the following information:

- Packet size in bytes
- Maximum capacity in packets
- Information about the number of packets currently in the pipe
- Data packets

#### 5.4.1. Creating Pipe Objects

To create a pipe object, call the function
clCreatePipe is missing before version 2.0.

- **context** is a valid OpenCL context used to create the pipe object.
- **flags** is a bit-field that is used to specify allocation and usage information such as the memory arena that should be used to allocate the pipe object and how it will be used. The Memory Flags table describes the possible values for `flags`. Only `CL_MEM_READ_WRITE` and `CL_MEM_HOST_NO_ACCESS` can be specified when creating a pipe object. If the value specified for `flags` is 0, the default is used which is `CL_MEM_READ_WRITE | CL_MEM_HOST_NO_ACCESS`.
- **pipe_packet_size** is the size in bytes of a pipe packet.
- **pipe_max_packets** specifies the pipe capacity by specifying the maximum number of packets the pipe can hold.
- **properties** specifies a list of properties for the pipe and their corresponding values. Each property name is immediately followed by the corresponding desired value. The list is terminated with 0. Currently, in all OpenCL versions, `properties` must be `NULL`.
- **errcode_ret** will return an appropriate error code. If `errcode_ret` is `NULL`, no error code is returned.

`clCreatePipe` returns a valid non-zero pipe object and `errcode_ret` is set to `CL_SUCCESS` if the pipe object is created successfully. Otherwise, it returns a `NULL` value with one of the following error values returned in `errcode_ret`:

- `CL_INVALID_CONTEXT` if `context` is not a valid context.
- `CL_INVALID_OPERATION` if no devices in `context` support pipes.
- `CL_INVALID_VALUE` if values specified in `flags` are not as defined above.
- `CL_INVALID_VALUE` if `properties` is not `NULL`.
- `CL_INVALID_PIPE_SIZE` if `pipe_packet_size` is 0 or the `pipe_packet_size` exceeds `CL_DEVICE_PIPE_MAX_PACKET_SIZE` value specified in the Device Queries table for all devices in `context` or if `pipe_max_packets` is 0.
- `CL_MEM_OBJECT_ALLOCATION_FAILURE` if there is a failure to allocate memory for the pipe object.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.
Pipes follow the same memory consistency model as defined for buffer and image objects. The pipe state i.e. contents of the pipe across kernel-instances (on the same or different devices) is enforced at a synchronization point.

5.4.2. Pipe Object Queries

To get information that is common to all memory objects, use the `clGetMemObjectInfo` function described in Memory Object Queries.

To get information specific to a pipe object created with `clCreatePipe`, call the function

```c
// Provided by CL_VERSION_2_0
cl_int clGetPipeInfo(
    cl_mem pipe,
    cl_pipe_info param_name,
    size_t param_value_size,
    void* param_value,
    size_t* param_value_size_ret);
```

- `pipe` specifies the pipe object being queried.
- `param_name` specifies the information to query. The list of supported `param_name` types and the information returned in `param_value` by `clGetPipeInfo` is described in the Pipe Object Queries table.
- `param_value` is a pointer to memory where the appropriate result being queried is returned. If `param_value` is `NULL`, it is ignored.
- `param_value_size` is used to specify the size in bytes of memory pointed to by `param_value`. This size must be ≥ size of return type as described in the Pipe Object Queries table.
- `param_value_size_ret` returns the actual size in bytes of data being queried by `param_name`. If `param_value_size_ret` is `NULL`, it is ignored.

`clGetPipeInfo` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_MEM_OBJECT` if `pipe` is not a valid pipe object.
- `CL_INVALID_VALUE` if `param_name` is not valid, or if size in bytes specified by `param_value_size` is < size of return type as described in the Pipe Object Queries table and `param_value` is not `NULL`.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

Table 36. List of supported `param_names` by `clGetPipeInfo`
<table>
<thead>
<tr>
<th>Pipe Info</th>
<th>Return type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_PIPE_PACKET_SIZE</td>
<td>cl_uint</td>
<td>Return pipe packet size specified when pipe is created with clCreatePipe.</td>
</tr>
<tr>
<td>missing before version 2.0.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_PIPE_MAX_PACKETS</td>
<td>cl_uint</td>
<td>Return max. number of packets specified when pipe is created with clCreatePipe.</td>
</tr>
<tr>
<td>missing before version 2.0.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_PIPE_PROPERTIES</td>
<td>cl_pipe_properties[]</td>
<td>Return the properties argument specified in clCreatePipe.</td>
</tr>
<tr>
<td>missing before version 3.0.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

If the properties argument specified in clCreatePipe used to create pipe was not NULL, the implementation must return the values specified in the properties argument in the same order and without including additional properties.

If the properties argument specified in clCreatePipe used to create pipe was NULL, the implementation must return param_value_size_ret equal to 0, indicating that there are no properties to be returned.

### 5.5. Querying, Unmapping, Migrating, Retaining and Releasing Memory Objects

#### 5.5.1. Retaining and Releasing Memory Objects

To retain a memory object, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clRetainMemObject(
    cl_mem memobj);
```

- `memobj` specifies the memory object to be retained.

The `memobj` reference count is incremented.

`clRetainMemObject` returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:

- CL_INVALID_MEM_OBJECT if `memobj` is not a valid memory object (buffer or image object).
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

`clCreateBuffer`, `clCreateBufferWithProperties`, `clCreateSubBuffer`, `clCreateImage`, `clCreateImageWithProperties`, `clCreateImage2D`, `clCreateImage3D` and `clCreatePipe` perform an implicit retain.

To release a memory object, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clReleaseMemObject(
    cl_mem memobj);
```

• `memobj` specifies the memory object to be released.

The `memobj` reference count is decremented.

`clReleaseMemObject` returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:

• **CL_INVALID_MEM_OBJECT** if `memobj` is not a valid memory object.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

After the `memobj` reference count becomes zero and commands queued for execution on a command-queue(s) that use `memobj` have finished, the memory object is deleted. If `memobj` is a buffer object, `memobj` cannot be deleted until all sub-buffer objects associated with `memobj` are deleted. Using this function to release a reference that was not obtained by creating the object or by calling `clRetainMemObject` causes undefined behavior.

To register a callback function with a memory object that is called when the memory object is destroyed, call the function

```c
// Provided by CL_VERSION_1_1
cl_int clSetMemObjectDestructorCallback(
    cl_mem memobj,
    void (CL_CALLBACK* pfn_notify)(cl_mem memobj, void* user_data),
    void* user_data);
```

• `clSetMemObjectDestructorCallback` is missing before version 1.1.

• `memobj` specifies the memory object to register the callback to.

• `pfn_notify` is the callback function to register. This callback function may be called asynchronously by the OpenCL implementation. It is the application’s responsibility to ensure that the callback function is thread-safe. The parameters to this callback function are:
- `memobj` is the memory object being deleted. When the callback function is called by the implementation, this memory object is not longer valid. `memobj` is only provided for reference purposes.

- `user_data` is a pointer to user-supplied data.
  - `user_data` will be passed as the `user_data` argument when `pfn_notify` is called. `user_data` can be `NULL`.

Each call to `clSetMemObjectDestructorCallback` registers the specified callback function on a destructor callback stack associated with `memobj`. The registered callback functions are called in the reverse order in which they were registered. The registered callback functions are called and then the memory object's resources are freed and the memory object is deleted. Therefore, the memory object destructor callback provides a mechanism for an application to safely re-use or free a `host_ptr` that was specified when `memobj` was created and used as the storage bits for the memory object.

`clSetMemObjectDestructorCallback` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_MEM_OBJECT` if `memobj` is not a valid memory object.
- `CL_INVALID_VALUE` if `pfn_notify` is `NULL`.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

When the user callback function is called by the implementation, the contents of the memory region pointed to by `host_ptr` (if the memory object is created with `CL_MEM_USE_HOST_PTR`) are undefined. The callback function is typically used by the application to either free or reuse the memory region pointed to by `host_ptr`.

The behavior of calling expensive system routines, OpenCL API calls to create contexts or command-queues, or blocking OpenCL operations from the following list below, in a callback is undefined.

- `clFinish`
- `clWaitForEvents`
- blocking calls to `clEnqueueReadBuffer`, `clEnqueueReadBufferRect`, `clEnqueueWriteBuffer`, `clEnqueueWriteBufferRect`
- blocking calls to `clEnqueueReadImage` and `clEnqueueWriteImage`
- blocking calls to `clEnqueueMapBuffer`, `clEnqueueMapImage`
- blocking calls to `clBuildProgram`, `clCompileProgram` or `clLinkProgram`

If an application needs to wait for completion of a routine from the above list in a callback, please use the non-blocking form of the function, and assign a completion callback to it to do the remainder of your work. Note that when a
callback (or other code) enqueues commands to a command-queue, the commands are not required to begin execution until the queue is flushed. In standard usage, blocking enqueue calls serve this role by implicitly flushing the queue. Since blocking calls are not permitted in callbacks, those callbacks that enqueue commands on a command-queue should either call clFlush on the queue before returning or arrange for clFlush to be called later on another thread.

The user callback function may not call OpenCL APIs with the memory object for which the callback function is invoked and for such cases the behavior of OpenCL APIs is considered to be undefined.

5.5.1.1. Acquiring and Releasing External Memory Objects

To enqueue a command to acquire OpenCL memory objects created from external memory handles, call the function

```c
// Provided by cl_khr_external_memory
cl_int clEnqueueAcquireExternalMemObjectsKHR(
    cl_command_queue command_queue,
    cl_uint num_mem_objects,
    const cl_mem* mem_objects,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

• `command_queue` specifies a valid command-queue.
• `num_mem_objects` specifies the number of memory objects to acquire.
• `mem_objects` points to a list of valid memory objects.
• `num_events_in_wait_list` specifies the number of events in `event_wait_list`.
• `event_wait_list` points to the list of events that need to complete before clEnqueueAcquireExternalMemObjectsKHR can be executed. If `event_wait_list` is NULL, then clEnqueueAcquireExternalMemObjectsKHR does not explicitly wait on any event to complete. If `event_wait_list` is NULL, `num_events_in_wait_list` must be 0. If `event_wait_list` is not NULL, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0. The events specified in `event_wait_list` act as synchronization points. The context associated with events in `event_wait_list` and that of `command_queue` must be the same.
• `event` returns an event object that identifies this particular command and can be used to query or queue a wait for this particular command to complete. `event` can be NULL in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete.

Applications must acquire the memory objects that are created using external handles before they
can be used by any OpenCL commands queued to a command-queue. Behavior is undefined if a memory object created from an external memory handle is used by an OpenCL command queued to a command-queue without being acquired. This is to guarantee that the state of the memory objects is up-to-date and they are accessible to OpenCL. See “Example with Acquire / Release” for more details on how to use this API.

If `num_mem_objects` is 0 and `mem_objects` is `NULL`, the command will trivially succeed after its event dependencies are satisfied and will update its completion event.

`clEnqueueAcquireExternalMemObjectsKHR` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_VALUE` if `num_mem_objects` is zero and `mem_objects` is not a `NULL` value, or if `num_mem_objects` is greater than 0 and `mem_objects` is `NULL`.
- `CL_INVALID_MEM_OBJECT` if any of the memory objects in `mem_objects` is not a valid OpenCL memory object created using an external memory handle.
- `CL_INVALID_COMMAND_QUEUE`
  - if `command_queue` is not a valid command-queue, or
  - if device associated with `command_queue` is not one of the devices specified by `CL_MEM_DEVICE_HANDLE_LIST_KHR` at the time of creating one or more of `mem_objects`, or ** if one or more of `mem_objects` belong to a context that does not contain a device associated with `command_queue`.
- `CL_INVALID_EVENT_WAIT_LIST`
  - if `event_wait_list` is `NULL` and `num_events_in_wait_list` is not 0, or
  - if `event_wait_list` is not `NULL` and `num_events_in_wait_list` is 0, or
  - if event objects in `event_wait_list` are not valid events.
- `CL_EXEC_STATUS_ERROR_FOR_EVENTS_IN_WAIT_LIST` if the execution status of any of the events in `event_wait_list` is a negative integer value.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

To enqueue a command to release OpenCL memory objects created from external memory handles, call the function

```
// Provided by cl_khr_external_memory
cl_int clEnqueueReleaseExternalMemObjectsKHR(
    cl_command_queue command_queue,
    cl_uint num_mem_objects,
    const cl_mem* mem_objects,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```
• `command_queue` specifies a valid command-queue.

• `num_mem_objects` specifies the number of memory objects to release.

• `mem_objects` points to a list of valid memory objects.

• `num_events_in_wait_list` specifies the number of events in `event_wait_list`.

• `event_wait_list` points to the list of events that need to complete before `clEnqueueReleaseExternalMemObjectsKHR` can be executed. If `event_wait_list` is `NULL`, then `clEnqueueReleaseExternalMemObjectsKHR` does not wait on any event to complete. If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0. The events specified in `event_wait_list` act as synchronization points. The context associated with events in `event_wait_list` and that of `command_queue` must be the same.

• `event` returns an event object that identifies this particular command and can be used to query or queue a wait for this particular command to complete. `event` can be `NULL` in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete.

Applications must release the memory objects that are acquired using `clEnqueueReleaseExternalMemObjectsKHR` before using them through any commands in the other API. This is to guarantee that the state of memory objects is up-to-date and they are accessible to the other API. See “Example with Acquire / Release” provided in Sample Code for more details on how to use this API.

If `num_mem_objects` is 0 and `mem_objects` is `NULL`, the command will trivially succeed after its event dependencies are satisfied and will update its completion event.

`clEnqueueReleaseExternalMemObjectsKHR` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

• `CL_INVALID_VALUE` if `num_mem_objects` is zero and `mem_objects` is not a `NULL` value, or if `num_mem_objects` is greater than 0 and `mem_objects` is `NULL`.

• `CL_INVALID_MEM_OBJECT` if any of the memory objects in `mem_objects` is not a valid OpenCL memory object created using an external memory handle.

• `CL_INVALID_COMMAND_QUEUE`
  ◦ if `command_queue` is not a valid command-queue, or
  ◦ if device associated with `command_queue` is not one of the devices specified by `CL_MEM_DEVICE_HANDLE_LIST_KHR` at the time of creating one or more of `mem_objects`, or
  ◦ if one or more of `mem_objects` belong to a context that does not contain a device associated with `command_queue`.

• `CL_INVALID_EVENT_WAIT_LIST`
  ◦ if `event_wait_list` is `NULL` and `num_events_in_wait_list` is not 0, or
  ◦ if `event_wait_list` is not `NULL` and `num_events_in_wait_list` is 0, or
  ◦ if event objects in `event_wait_list` are not valid events.

• `CL_EXEC_STATUS_ERROR_FOR_EVENTS_IN_WAIT_LIST` if the execution status of any of the events in
event_wait_list is a negative integer value.

- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.5.2. Descriptions of External Memory Handle Types

This section describes external memory handle types that are added by extensions.

Applications can import the same payload into multiple OpenCL contexts and multiple times into a given OpenCL context. In all cases, each import operation must create a distinct memory object.

#### 5.5.2.1. File Descriptor Handle Types

The `cl_khr_external_memory_opaque_fd` extension extends `cl_external_memory_handle_type_khr` to support the following new types of handles, and adds as a property that may be specified when creating a buffer or an image memory object from an external handle:

- **CL_EXTERNAL_MEMORY_HANDLE_OPAQUE_FD_KHR** specifies a POSIX file descriptor handle that has only limited valid usage outside of OpenCL and other compatible APIs. It must be compatible with the POSIX system calls `dup`, `dup2`, `close`, and the non-standard system call `dup3`. Additionally, it must be transportable over a socket using a `SCM_RIGHTS` control message. It owns a reference to the underlying memory resource represented by its memory object.

The `cl_khr_external_memory_dma_buf` extension extends `cl_external_memory_handle_type_khr` to support the following types of handles, and adds as a property that may be specified when creating a buffer or an image memory object from an external handle:

- **CL_EXTERNAL_MEMORY_HANDLE_DMA_BUF_KHR** is a file descriptor for a Linux dma_buf. It owns a reference to the underlying memory resource represented by its memory object.

For these extensions, importing memory from a file descriptor transfers ownership of the file descriptor from the application to the OpenCL implementation. The application must not perform any operations on the file descriptor after a successful import. The imported memory object holds a reference to its payload.

#### 5.5.2.2. NT Handle Types

The `cl_khr_external_memory_dx` extension extends `cl_external_memory_handle_type_khr` to support the following new types of handles, and adds as a property that may be specified when creating a buffer or an image memory object from an external handle:

- **CL_EXTERNAL_MEMORY_HANDLE_D3D11_TEXTURE_KHR** specifies an NT handle returned by `IDXGIResource1::CreateSharedHandle` referring to a Direct3D 10 or 11 texture resource. It owns a reference to the memory used by the Direct3D resource.

- **CL_EXTERNAL_MEMORY_HANDLE_D3D11_TEXTURE_KMT_KHR** specifies a global share handle returned by `IDXGIResource::GetSharedHandle` referring to a Direct3D 10 or 11 texture resource. It does not own a reference to the underlying Direct3D resource, and will therefore become invalid when...
all memory objects and Direct3D resources associated with it are destroyed.

- **CL_EXTERNAL_MEMORY_HANDLE_D3D12_HEAP_KHR** specifies an NT handle returned by ID3D12Device::CreateSharedHandle referring to a Direct3D 12 heap resource. It owns a reference to the resources used by the Direct3D heap.

- **CL_EXTERNAL_MEMORY_HANDLE_D3D12_RESOURCE_KHR** specifies an NT handle returned by ID3D12Device::CreateSharedHandle referring to a Direct3D 12 committed resource. It owns a reference to the memory used by the Direct3D resource.

The cl_khr_external_memory_win32 extension extends `cl_external_memory_handle_type_khr` to support the following new types of handles, and adds as a property that may be specified when creating a buffer or an image memory object from an external handle:

- **CL_EXTERNAL_MEMORY_HANDLE_OPAQUE_WIN32_KHR** specifies an NT handle that has only limited valid usage outside of OpenCL and other compatible APIs. It must be compatible with the functions DuplicateHandle, CloseHandle, CompareObjectHandles, GetHandleInformation, and SetHandleInformation. It owns a reference to the underlying memory resource represented by its memory object.

- **CL_EXTERNAL_MEMORY_HANDLE_OPAQUE_WIN32_KMT_KHR** specifies a global share handle that has only limited valid usage outside of OpenCL and other compatible APIs. It is not compatible with any native APIs. It does not own a reference to the underlying memory resource represented by its memory object, and will therefore become invalid when all memory objects associated with it are destroyed.

For these extensions, importing memory object payloads from Windows handles does not transfer ownership of the handle to the OpenCL implementation. For handle types defined as NT handles, the application must release handle ownership using the CloseHandle system call when the handle is no longer needed. For handle types defined as NT handles, the imported memory object holds a reference to its payload.

Note: Non-NT handle import operations do not add a reference to their associated payload. If the original object owning the payload is destroyed, all resources and handles sharing that payload will become invalid.

### 5.5.3. Unmapping Mapped Memory Objects

To enqueue a command to unm ap a previously mapped region of a memory object, call the function

```c
// Provided by CL_VERSION_1_0
cl_int cLEnqueueUnmapMemObject(
    cl_command_queue command_queue,
    cl_mem memobj,
    void* mapped_ptr,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```
• *command_queue* must be a valid host command-queue.

• *memobj* is a valid memory (buffer or image) object. The OpenCL context associated with *command_queue* and *memobj* must be the same.

• *mapped_ptr* is the host address returned by a previous call to `clEnqueueMapBuffer`, or `clEnqueueMapImage` for *memobj*.

• *event_wait_list* and *num_events_in_wait_list* specify events that need to complete before `clEnqueueUnmapMemObject` can be executed. If *event_wait_list* is `NULL`, then `clEnqueueUnmapMemObject` does not wait on any event to complete. If *event_wait_list* is `NULL`, *num_events_in_wait_list* must be 0. If *event_wait_list* is not `NULL`, the list of events pointed to by *event_wait_list* must be valid and *num_events_in_wait_list* must be greater than 0. The events specified in *event_wait_list* act as synchronization points. The context associated with events in *event_wait_list* and *command_queue* must be the same. The memory associated with *event_wait_list* can be reused or freed after the function returns.

• *event* returns an event object that identifies this command and can be used to query or queue a wait for this command to complete. If *event* is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If *event_wait_list* and *event* are not `NULL`, *event* must not refer to an element of the *event_wait_list* array.

Reads or writes from the host using the pointer returned by `clEnqueueMapBuffer` or `clEnqueueMapImage` are considered to be complete.

`clEnqueueMapBuffer` and `clEnqueueMapImage` increment the mapped count of the memory object. The initial mapped count value of the memory object is zero. Multiple calls to `clEnqueueMapBuffer`, or `clEnqueueMapImage` on the same memory object will increment this mapped count by appropriate number of calls. `clEnqueueUnmapMemObject` decrements the mapped count of the memory object.

`clEnqueueMapBuffer`, and `clEnqueueMapImage` act as synchronization points for a region of the buffer object being mapped.

`clEnqueueUnmapMemObject` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

• `CL_INVALID_COMMAND_QUEUE` if *command_queue* is not a valid host command-queue.

• `CL_INVALID_MEM_OBJECT` if *memobj* is not a valid memory object or is a pipe object.

• `CL_INVALID_VALUE` if *mapped_ptr* is not a valid pointer returned by `clEnqueueMapBuffer` or `clEnqueueMapImage` for *memobj*.

• `CL_INVALID_EVENT_WAIT_LIST` if *event_wait_list* is `NULL` and *num_events_in_wait_list* > 0, or if *event_wait_list* is not `NULL` and *num_events_in_wait_list* is 0, or if event objects in *event_wait_list* are not valid events.

• `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.

• `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.
• **CL_INVALID_CONTEXT** if context associated with *command_queue* and *memobj* are not the same or if the context associated with *command_queue* and events in *event_wait_list* are not the same.

### 5.5.4. Accessing Mapped Regions of a Memory Object

This section describes the behavior of OpenCL commands that access mapped regions of a memory object.

The contents of the region of a memory object and associated memory objects (sub-buffer objects or 1D image buffer objects that overlap this region) mapped for writing (i.e., **CL_MAP_WRITE** or **CL_MAP_WRITE_INVALIDATE_REGION** is set in *map_flags* argument to *clEnqueueMapBuffer*, or *clEnqueueMapImage*) are considered to be undefined until this region is unmapped.

Multiple commands in command-queues can map a region or overlapping regions of a memory object and associated memory objects (sub-buffer objects or 1D image buffer objects that overlap this region) for reading (i.e., *map_flags* = **CL_MAP_READ**). The contents of the regions of a memory object mapped for reading can also be read by kernels and other OpenCL commands (such as *clEnqueueCopyBuffer*) executing on a device(s).

Mapping (and unmapping) overlapped regions in a memory object and/or associated memory objects (sub-buffer objects or 1D image buffer objects that overlap this region) for writing is an error and will result in **CL_INVALID_OPERATION** error returned by *clEnqueueMapBuffer*, or *clEnqueueMapImage*.

If a memory object is currently mapped for writing, the application must ensure that the memory object is unmapped before any enqueued kernels or commands that read from or write to this memory object or any of its associated memory objects (sub-buffer or 1D image buffer objects) or its parent object (if the memory object is a sub-buffer or 1D image buffer object) begin execution; otherwise the behavior is undefined.

If a memory object is currently mapped for reading, the application must ensure that the memory object is unmapped before any enqueued kernels or commands that write to this memory object or any of its associated memory objects (sub-buffer or 1D image buffer objects) or its parent object (if the memory object is a sub-buffer or 1D image buffer object) begin execution; otherwise the behavior is undefined.

A memory object is considered as mapped if there are one or more active mappings for the memory object irrespective of whether the mapped regions span the entire memory object.

Accessing the contents of the memory region referred to by the mapped pointer that has been unmapped is undefined.

The mapped pointer returned by *clEnqueueMapBuffer* or *clEnqueueMapImage* can be used as the *ptr* argument value to *clEnqueueReadBuffer*, *clEnqueueWriteBuffer*, *clEnqueueReadBufferRect*, *clEnqueueWriteBufferRect*, *clEnqueueReadImage*, or *clEnqueueWriteImage* provided the rules described above are adhered to.

### 5.5.5. Migrating Memory Objects
Migrating memory objects is missing before version 1.2.

This section describes a mechanism for assigning which device an OpenCL memory object resides. A user may wish to have more explicit control over the location of their memory objects on creation. This could be used to:

- Ensure that an object is allocated on a specific device prior to usage.
- Preemptively migrate an object from one device to another.

To enqueue a command to indicate which device a set of memory objects should be associated with, call the function

```c
// Provided by CL_VERSION_1_2
cl_int clEnqueueMigrateMemObjects(
    cl_command_queue command_queue,
    cl_uint num_mem_objects,
    const cl_mem* mem_objects,
    cl_mem_migration_flags flags,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

- `command_queue` is a valid host command-queue. The specified set of memory objects in `mem_objects` will be migrated to the OpenCL device associated with `command_queue` or to the host if the `CL_MIGRATE_MEM_OBJECT_HOST` has been specified.

- `num_mem_objects` is the number of memory objects specified in `mem_objects`.

- `mem_objects` is a pointer to a list of memory objects.

- `flags` is a bit-field that is used to specify migration options. The Memory Migration Flags describes the possible values for flags.

- `event_wait_list` and `num_events_in_wait_list` specify events that need to complete before this particular command can be executed. If `event_wait_list` is `NULL`, then this particular command does not wait on any event to complete. If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0. The events specified in `event_wait_list` act as synchronization points. The context associated with events in `event_wait_list` and `command_queue` must be the same. The memory associated with `event_wait_list` can be reused or freed after the function returns.

- `event` returns an event object that identifies this command and can be used to query or queue a wait for this command to complete. If `event` is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If `event_wait_list` and `event` are not `NULL`, `event` must not refer to an element of the `event_wait_list` array.
Table 37. List of supported migration flags by `clEnqueueMigrateMemObjects`

<table>
<thead>
<tr>
<th>Memory Migration Flags</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>CL_MIGRATE_MEM_OBJECT_HOST</code></td>
<td>This flag indicates that the specified set of memory objects are to be migrated to the host, regardless of the target command-queue.</td>
</tr>
<tr>
<td><code>CL_MIGRATE_MEM_OBJECT_CONTENT_UNDEFINED</code></td>
<td>This flag indicates that the contents of the set of memory objects are undefined after migration. The specified set of memory objects are</td>
</tr>
<tr>
<td></td>
<td>migrated to the device associated with <code>command_queue</code> without incurring the overhead of migrating their contents.</td>
</tr>
</tbody>
</table>

Typically, memory objects are implicitly migrated to a device for which enqueued commands, using the memory object, are targeted. `clEnqueueMigrateMemObjects` allows this migration to be explicitly performed ahead of the dependent commands. This allows a user to preemptively change the association of a memory object, through regular command-queue scheduling, in order to prepare for another upcoming command. This also permits an application to overlap the placement of memory objects with other unrelated operations before these memory objects are needed potentially hiding transfer latencies. Once the event, returned from `clEnqueueMigrateMemObjects`, has been marked CL_COMPLETE the memory objects specified in `mem_objects` have been successfully migrated to the device associated with `command_queue`. The migrated memory object shall remain resident on the device until another command is enqueued that either implicitly or explicitly migrates it away.

`clEnqueueMigrateMemObjects` can also be used to direct the initial placement of a memory object, after creation, possibly avoiding the initial overhead of instantiating the object on the first enqueued command to use it.

The user is responsible for managing the event dependencies, associated with this command, in order to avoid overlapping access to memory objects. Improperly specified event dependencies passed to `clEnqueueMigrateMemObjects` could result in undefined results.

`clEnqueueMigrateMemObjects` return `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_COMMAND_QUEUE` if `command_queue` is not a valid host command-queue.
- `CL_INVALID_CONTEXT` if the context associated with `command_queue` and memory objects in `mem_objects` are not the same or if the context associated with `command_queue` and events in `event_wait_list` are not the same.
- `CL_INVALID_MEM_OBJECT` if any of the memory objects in `mem_objects` is not a valid memory object.
- `CL_INVALID_VALUE` if `num_mem_objects` is zero or if `mem_objects` is `NULL`.
- `CL_INVALID_VALUE` if `flags` is not 0 or is not any of the values described in the table above.
- `CL_INVALID_EVENT_WAIT_LIST` if `event_wait_list` is `NULL` and `num_events_in_wait_list` > 0, or `event_wait_list` is not `NULL` and `num_events_in_wait_list` is 0, or if event objects in `event_wait_list` are not valid events.
• **CL_MEM_OBJECT_ALLOCATION_FAILURE** if there is a failure to allocate memory for the specified set of memory objects in `mem_objects`.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.5.6. Memory Object Queries

To get information that is common to all memory objects (buffer and image objects), call the function

```c
// Provided by CL_VERSION_1_0
cl_int clGetMemObjectInfo(
    cl_mem memobj,
    cl_mem_info param_name,
    size_t param_value_size,
    void* param_value,
    size_t* param_value_size_ret);
```

• `memobj` specifies the memory object being queried.

• `param_name` specifies the information to query. The list of supported `param_name` types and the information returned in `param_value` by `clGetMemObjectInfo` is described in the Memory Object Info table.

• `param_value` is a pointer to memory where the appropriate result being queried is returned. If `param_value` is `NULL`, it is ignored.

• `param_value_size` is used to specify the size in bytes of memory pointed to by `param_value`. This size must be ≥ size of return type as described in the Memory Object Info table.

• `param_value_size_ret` returns the actual size in bytes of data being queried by `param_name`. If `param_value_size_ret` is `NULL`, it is ignored.

*Table 38. List of supported param_names by `clGetMemObjectInfo`*
<table>
<thead>
<tr>
<th>Memory Object Info</th>
<th>Return type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>CL_MEM_TYPE</strong></td>
<td>cl_mem_object_type</td>
<td>Returns one of the following values:</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_MEM_OBJECT_BUFFER</strong> if <code>memobj</code> is created with clCreateBuffer, clCreateBufferWithProperties, or clCreateSubBuffer.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_MEM_OBJECT_IMAGE2D</strong> if <code>memobj</code> is created with clCreateImage2D.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_MEM_OBJECT_IMAGE3D</strong> if <code>memobj</code> is created with clCreateImage3D.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The value of <code>image_desc</code> → <code>image_type</code> if <code>memobj</code> is created with clCreateImage or clCreateImageWithProperties.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_MEM_OBJECT_PIPE</strong> if <code>memobj</code> is created with clCreatePipe.</td>
</tr>
<tr>
<td><strong>CL_MEM_FLAGS</strong></td>
<td>cl_mem_flags</td>
<td>Return the flags argument value specified when <code>memobj</code> is created with clCreateBuffer, clCreateBufferWithProperties, clCreateSubBuffer, clCreateImage, clCreateImageWithProperties, clCreateImage2D, clCreateImage3D, or clCreatePipe.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>If <code>memobj</code> is a sub-buffer the memory access qualifiers inherited from parent buffer is also returned.</td>
</tr>
<tr>
<td><strong>CL_MEM_SIZE</strong></td>
<td>size_t</td>
<td>Return actual size of the data store associated with <code>memobj</code> in bytes.</td>
</tr>
<tr>
<td>Memory Object Info</td>
<td>Return type</td>
<td>Description</td>
</tr>
<tr>
<td>--------------------</td>
<td>-------------</td>
<td>-------------</td>
</tr>
<tr>
<td><strong>CL_MEM_HOST_PTR</strong></td>
<td><code>void*</code></td>
<td>If <code>memobj</code> is created with <code>clCreateBuffer</code>, <code>clCreateBufferWithProperties</code>, <code>clCreateImage</code>, <code>clCreateImageWithProperties</code>, <code>clCreateImage2D</code>, or <code>clCreateImage3D</code>, and <code>CL_MEM_USE_HOST_PTR</code> is specified in <code>mem_flags</code>, return the <code>host_ptr</code> argument value specified when <code>memobj</code> is created. Otherwise, if <code>memobj</code> is created with <code>clCreateSubBuffer</code>, and <code>memobj</code> is created from a buffer that was created with <code>CL_MEM_USE_HOST_PTR</code> specified in <code>mem_flags</code>, return the <code>host_ptr</code> passed to <code>clCreateBuffer</code> or <code>clCreateBufferWithProperties</code>, plus the origin value specified in <code>buffer_create_info</code> when <code>memobj</code> is created. Otherwise, returns <code>NULL</code>.</td>
</tr>
<tr>
<td><strong>CL_MEM_MAP_COUNT</strong>[^9]</td>
<td><code>cl_uint</code></td>
<td>Map count.</td>
</tr>
<tr>
<td><strong>CL_MEM_CONTEXT</strong></td>
<td><code>cl_context</code></td>
<td>Return context specified when memory object is created. If <code>memobj</code> is created using <code>clCreateSubBuffer</code>, the context associated with the memory object specified as the <code>buffer</code> argument to <code>clCreateSubBuffer</code> is returned.</td>
</tr>
<tr>
<td><strong>CL_MEM_ASSOCIATED_MEMOBJECT</strong></td>
<td><code>cl_mem</code></td>
<td>Return memory object from which <code>memobj</code> is created. This returns the memory object specified as buffer argument to <code>clCreateSubBuffer</code> if <code>memobj</code> is a subbuffer object created using <code>clCreateSubBuffer</code>. This returns <code>image_desc-&gt;mem_object</code> if <code>memobj</code> is an image object created using <code>clCreateImage</code> or <code>clCreateImageWithProperties</code>. Otherwise, returns <code>NULL</code>.</td>
</tr>
<tr>
<td><strong>CL_MEM_OFFSET</strong>[^11]</td>
<td><code>size_t</code></td>
<td>Return offset if <code>memobj</code> is a sub-buffer object created using <code>clCreateSubBuffer</code>. This return 0 if <code>memobj</code> is not a subbuffer object.</td>
</tr>
</tbody>
</table>

[^9]: Missing before version 1.1.
[^10]: Missing before version 1.1.
<table>
<thead>
<tr>
<th>Memory Object Info</th>
<th>Return type</th>
<th>Description</th>
</tr>
</thead>
</table>
| **CL_MEM_USES_SVM_POINTER**  
missing before version 2.0. | cl_bool | Return **CL_TRUE** if `memobj` is a buffer object that was created with **CL_MEM_USE_HOST_PTR** or is a sub-buffer object of a buffer object that was created with **CL_MEM_USE_HOST_PTR** and the `host_ptr` specified when the buffer object was created is a SVM pointer; otherwise returns **CL_FALSE**. |
| **CL_MEM_PROPERTIES**  
missing before version 3.0. | cl_mem_properties[] | Return the properties argument specified in `clCreateBufferWithProperties` or `clCreateImageWithProperties`.  
If the `properties` argument specified in `clCreateBufferWithProperties` or `clCreateImageWithProperties` used to create `memobj` was not **NULL**, the implementation must return the values specified in the properties argument in the same order and without including additional properties.  
If `memobj` was created using `clCreateBuffer`, `clCreateSubBuffer`, `clCreateImage`, `clCreateImage2D`, or `clCreateImage3D`, or if the `properties` argument specified in `clCreateBufferWithProperties` or `clCreateImageWithProperties` was **NULL**, the implementation must return `param_value_size_ret` equal to 0, indicating that there are no properties to be returned. |
| **CL_MEM_DX9_MEDIA_ADAPTER_TYPE_KHR**  
provided by the `cl_khr_dx9_media_sharing` extension. | cl_dx9_media_adapter_type_khr | If `memobj` was created using `clCreateFromDX9MediaSurfaceKHR`, returns the `adapter_type` argument specified when `memobj` was created. |
| **CL_MEM_DX9_MEDIA_SURFACE_INFO_KHR**  
provided by the `cl_khr_dx9_media_sharing` extension. | cl_dx9_surface_info_khr | If `memobj` was created using `clCreateFromDX9MediaSurfaceKHR`, returns the `surface_info` argument specified when `memobj` was created. |
<table>
<thead>
<tr>
<th>Memory Object Info</th>
<th>Return type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_MEM_D3D10_RESOURCE_KHR provided by the cl_khr_d3d10_sharing extension.</td>
<td>ID3D10Resource*</td>
<td>If <code>memobj</code> was created using clCreateFromD3D10BufferKHR, clCreateFromD3D10Texture2DKHR, or clCreateFromD3D10Texture3DKHR, returns the resource argument specified when <code>memobj</code> was created.</td>
</tr>
<tr>
<td>CL_MEM_D3D11_RESOURCE_KHR provided by the cl_khr_d3d11_sharing extension.</td>
<td>ID3D11Resource*</td>
<td>If <code>memobj</code> was created using clCreateFromD3D11BufferKHR, clCreateFromD3D11Texture2DKHR, or clCreateFromD3D11Texture3DKHR, returns the resource argument specified when <code>memobj</code> was created.</td>
</tr>
</tbody>
</table>

**clGetMemObjectInfo** returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_MEM_OBJECT** if `memobj` is not a valid memory object.
- **CL_INVALID_VALUE** if `param_name` is not valid, or if size in bytes specified by `param_value_size` is < size of return type as described in the Memory Object Info table and `param_value` is not NULL.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

The following errors may be returned if the cl_khr_dx9_media_sharing extension is supported:

- **CL_INVALID_DX9_MEDIA_SURFACE_KHR** if `param_name` is CL_MEM_DX9_MEDIA_SURFACE_INFO_KHR and `memobj` was not created by calling clCreateFromDX9MediaSurfaceKHR from a Direct3D9 surface.

The following errors may be returned if the cl_khr_d3d10_sharing extension is supported:

- **CL_INVALID_D3D10_RESOURCE_KHR** if `param_name` is CL_MEM_D3D10_RESOURCE_KHR and `memobj` was not created by calling clCreateFromD3D10BufferKHR, clCreateFromD3D10Texture2DKHR, or clCreateFromD3D10Texture3DKHR.

The following errors may be returned if the cl_khr_d3d11_sharing extension is supported:

- **CL_INVALID_D3D11_RESOURCE_KHR** if `param_name` is CL_MEM_D3D11_RESOURCE_KHR and `memobj` was not created by calling clCreateFromD3D11BufferKHR, clCreateFromD3D11Texture2DKHR, or clCreateFromD3D11Texture3DKHR.

**5.5.7. Querying Media Surface Properties of Memory Objects Created From DirectX 9 Media Surfaces**

Properties of media surface objects may be queried using **clGetMemObjectInfo** and
clGetImageInfo with param_name CL_MEM_DX9_MEDIA_ADAPTER_TYPE_KHR, CL_MEM_DX9_MEDIA_SURFACE_INFO_KHR and CL_IMAGE_DX9_MEDIA_PLANE_KHR.

5.5.8. Querying Direct3D Properties of Memory Objects Created From Direct3D 10 Resources

Properties of Direct3D 10 objects may be queried using clGetMemObjectInfo and clGetImageInfo with param_name CL_MEM_D3D10_RESOURCE_KHR and CL_IMAGE_D3D10_SUBRESOURCE_KHR respectively.

5.5.9. Querying Direct3D Properties of Memory Objects Created From Direct3D 11 Resources

Properties of Direct3D 11 objects may be queried using clGetMemObjectInfo and clGetImageInfo with param_name CL_MEM_D3D11_RESOURCE_KHR and CL_IMAGE_D3D11_SUBRESOURCE_KHR respectively.

5.5.10. Querying OpenGL Object Information From an OpenCL Memory Object

To query the OpenGL object and object type used to create an OpenCL memory object, call the function

```c
// Provided by cl_khr_gl_sharing
cl_int clGetGLObjInf.(
    cl_mem memobj,
    cl_gl_object_type* gl_object_type,
    cl_GLuint* gl_object_name);
```

- **clGetGLObjInf.** is provided by the cl_khr_gl_sharing extension.

  - *memobj* is the memory object to query.

  - *gl_object_type* returns the type of OpenGL object attached to *memobj* and can be CL_GL_OBJECT_BUFFER, CL_GL_OBJECT_TEXTURE2D, CL_GL_OBJECT_TEXTURE3D, CL_GL_OBJECT_TEXTURE2D_ARRAY, CL_GL_OBJECT_TEXTURE1D, CL_GL_OBJECT_TEXTURE1D_ARRAY, CL_GL_OBJECT_TEXTURE_BUFFER, or CL_GL_OBJECT_RENDERBUFFER. If *gl_object_type* is NULL, it is ignored.

  - *gl_object_name* returns the OpenGL object name used to create *memobj*. If *gl_object_name* is NULL, it is ignored.

clGetGLObjInf. returns CL_SUCCESS if the call was executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_MEM_OBJECT** if *memobj* is not a valid OpenCL memory object.

- **CL_INVALID_GL_OBJECT** if there is no OpenGL object associated with *memobj*.

- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL
To query additional information about the OpenGL texture object associated with an OpenCL memory object, call the function

```
// Provided by cl_khr_gl_sharing
cl_int clGetGLTextureInfo(
    cl_mem memobj,
    cl_gl_texture_info param_name,
    size_t param_value_size,
    void* param_value,
    size_t* param_value_size_ret);
```

- `memobj` is the memory object to query.
- `param_name` specifies what additional information about the OpenGL texture object associated with `memobj` to query. The list of supported `param_name` types and the information returned in `param_value` by `clGetGLTextureInfo` is described in the table below.
- `param_value` is a pointer to memory where the result being queried is returned. If `param_value` is `NULL`, it is ignored.
- `param_value_size` is used to specify the size in bytes of memory pointed to by `param_value`. This size must be $\geq$ size of return type as described in the table below.
- `param_value_size_ret` returns the actual size in bytes of data copied to `param_value`. If `param_value_size_ret` is `NULL`, it is ignored.

### Table 39. OpenGL texture info that may be queried with `clGetGLTextureInfo`

<table>
<thead>
<tr>
<th><code>cl_gl_texture_info</code></th>
<th>Return Type</th>
<th>Info. Returned in <code>param_value</code></th>
</tr>
</thead>
<tbody>
<tr>
<td><code>CL_GL_TEXTURE_TARGET</code></td>
<td>GLenum</td>
<td>The <code>texture_target</code> argument specified in <code>clCreateFromGLTexture</code>.</td>
</tr>
<tr>
<td>provided by the <code>cl_khr_gl_sharing</code> extension.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><code>CL_GL_MIPMAP_LEVEL</code></td>
<td>GLint</td>
<td>The <code>mipmap</code> argument specified in <code>clCreateFromGLTexture</code>.</td>
</tr>
<tr>
<td>provided by the <code>cl_khr_gl_sharing</code> extension.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><code>CL_GL_NUM_SAMPLES</code></td>
<td>GLsizei</td>
<td>The <code>samples</code> argument passed to <code>glTexImage2DMultisample</code> or <code>glTexImage3DMultisample</code>.</td>
</tr>
<tr>
<td>provided by the <code>cl_khr_gl_msaa_sharing</code> extension.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

`clGetGLTextureInfo` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it
returns one of the following errors:

- **CL_INVALID_MEM_OBJECT** if `memobj` is not a valid OpenCL memory object.
- **CL_INVALID_GL_OBJECT** if there is no OpenGL texture object associated with `memobj`.
- **CL_INVALID_VALUE** if `param_name` is not valid, or if size in bytes specified by `param_value_size` is less than the size of the return type as described in the table above and `param_value` is not `NULL`, or if `param_value` and `param_value_size_ret` are `NULL`.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.5.11. Sharing Memory Objects Created From Media Surfaces Between a Media Adapter and OpenCL

To acquire OpenCL memory objects that have been created from a media surface, call the function

```c
// Provided by cl_khr_dx9_media_sharing
cl_int clEnqueueAcquireDX9MediaSurfacesKHR(
    cl_command_queue command_queue,
    cl_uint num_objects,
    const cl_mem* mem_objects,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

- **command_queue** is a valid command-queue.
- **num_objects** is the number of memory objects to be acquired in `mem_objects`.
- **mem_objects** is a pointer to a list of OpenCL memory objects that were created from media surfaces.
- **event_wait_list** and **num_events_in_wait_list** specify events that need to complete before this particular command can be executed. If `event_wait_list` is `NULL`, then this particular command does not wait on any event to complete. If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be `0`. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than `0`. The events specified in `event_wait_list` act as synchronization points.
- **event** returns an event object that identifies this command and can be used to query or wait for this command to complete. If `event` is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If `event_wait_list` and `event` are not `NULL`, `event` must not refer to an element of the `event_wait_list` array.
The media surfaces are acquired by the OpenCL context associated with `command_queue` and can therefore be used by all command-queues associated with the OpenCL context.

OpenCL memory objects created from media surfaces must be acquired before they can be used by any OpenCL commands queued to a command-queue. If an OpenCL memory object created from a media surface is used while it is not currently acquired by OpenCL, the call attempting to use that OpenCL memory object will return `CL_DX9_MEDIA_SURFACE_NOT_ACQUIRED_KHR`.

If `CL_CONTEXT_INTEROP_USER_SYNC` is not specified as `CL_TRUE` during context creation, `clEnqueueAcquireDX9MediaSurfacesKHR` provides the synchronization guarantee that any media adapter API calls involving the interop device(s) used in the OpenCL context made before `clEnqueueAcquireDX9MediaSurfacesKHR` is called will complete executing before `event` reports completion and before the execution of any subsequent OpenCL work issued in `command_queue` begins. If the context was created with properties specifying `CL_CONTEXT_INTEROP_USER_SYNC` as `CL_TRUE`, the user is responsible for guaranteeing that any media adapter API calls involving the interop device(s) used in the OpenCL context made before `clEnqueueAcquireDX9MediaSurfacesKHR` is called have completed before calling `clEnqueueAcquireDX9MediaSurfacesKHR`.

`clEnqueueAcquireDX9MediaSurfacesKHR` returns `CL_SUCCESS` if the function is executed successfully. If `num_objects` is 0 and `mem_objects` is `NULL` then the function does nothing and returns `CL_SUCCESS`. Otherwise it returns one of the following errors:

- `CL_INVALID_VALUE` if `num_objects` is zero and `mem_objects` is not a `NULL` value or if `num_objects` > 0 and `mem_objects` is `NULL`.
- `CL_INVALID_MEM_OBJECT` if memory objects in `mem_objects` are not valid OpenCL memory objects or if memory objects in `mem_objects` have not been created from media surfaces.
- `CL_INVALID_COMMAND_QUEUE` if `command_queue` is not a valid command-queue.
- `CL_INVALID_CONTEXT` if context associated with `command_queue` was not created from a device that can share the media surface referenced by `mem_objects`.
- `CL_DX9_MEDIA_SURFACE_ALREADY_ACQUIRED_KHR` if memory objects in `mem_objects` have previously been acquired using `clEnqueueAcquireDX9MediaSurfacesKHR` but have not been released using `clEnqueueReleaseDX9MediaSurfacesKHR`.
- `CL_INVALID_EVENT_WAIT_LIST` if `event_wait_list` is `NULL` and `num_events_in_wait_list` > 0, or `event_wait_list` is not `NULL` and `num_events_in_wait_list` is 0, or if event objects in `event_wait_list` are not valid events.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

To release OpenCL memory objects that have been created from media surfaces, call the function
// Provided by cl_khr_dx9_media_sharing
cl_int clEnqueueReleaseDX9MediaSurfacesKHR(
    cl_command_queue command_queue,
    cl_uint num_objects,
    const cl_mem* mem_objects,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);

clEnqueueReleaseDX9MediaSurfacesKHR is provided by the cl_khr_dx9_media_sharing extension.

- `num_objects` is the number of memory objects to be released in `mem_objects`.
- `mem_objects` is a pointer to a list of OpenCL memory objects that were created from media surfaces.
- `event_wait_list` and `num_events_in_wait_list` specify events that need to complete before this particular command can be executed. If `event_wait_list` is `NULL`, then this particular command does not wait on any event to complete. If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0.
- `event` returns an event object that identifies this command and can be used to query or wait for this command to complete. If `event` is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If `event_wait_list` and `event` are not `NULL`, `event` must not refer to an element of the `event_wait_list` array.

The media surfaces are released by the OpenCL context associated with `command_queue`.

OpenCL memory objects created from media surfaces which have been acquired by OpenCL must be released by OpenCL before they may be accessed by the media adapter API. Accessing a media surface while its corresponding OpenCL memory object is acquired is in error and will result in undefined behavior, including but not limited to possible OpenCL errors, data corruption, and program termination.

If `CL_CONTEXT_INTEROP_USER_SYNC` is not specified as `CL_TRUE` during context creation, `clEnqueueReleaseDX9MediaSurfacesKHR` provides the synchronization guarantee that any calls to media adapter APIs involving the interop device(s) used in the OpenCL context made after the call to `clEnqueueReleaseDX9MediaSurfacesKHR` will not start executing until after all events in `event_wait_list` are complete and all work already submitted to `command_queue` completes execution. If the context was created with properties specifying `CL_CONTEXT_INTEROP_USER_SYNC` as `CL_TRUE`, the user is responsible for guaranteeing that any media adapter API calls involving the interop device(s) used in the OpenCL context made after `clEnqueueReleaseDX9MediaSurfacesKHR` will not start executing until after event returned by `clEnqueueReleaseDX9MediaSurfacesKHR` reports completion.

`clEnqueueReleaseDX9MediaSurfacesKHR` returns `CL_SUCCESS` if the function is executed
successfully. If \( \text{num\_objects} \) is 0 and \(<\text{mem\_objects}> \) is NULL the function does nothing and returns CL_SUCCESS. Otherwise it returns one of the following errors:

- **CL_INVALID_VALUE** if \( \text{num\_objects} \) is zero and \( \text{mem\_objects} \) is not a NULL value or if \( \text{num\_objects} > 0 \) and \( \text{mem\_objects} \) is NULL.

- **CL_INVALID_MEM_OBJECT** if memory objects in \( \text{mem\_objects} \) are not valid OpenCL memory objects or if memory objects in \( \text{mem\_objects} \) have not been created from valid media surfaces.

- **CL_INVALID_COMMAND_QUEUE** if \( \text{command\_queue} \) is not a valid command-queue.

- **CL_INVALID_CONTEXT** if context associated with \( \text{command\_queue} \) was not created from a media object.

- **CL_DX9_MEDIA_SURFACE_NOT_ACQUIRED_KHR** if memory objects in \( \text{mem\_objects} \) have not previously been acquired using \text{clEnqueueAcquireDX9MediaSurfacesKHR}, or have been released using \text{clEnqueueReleaseDX9MediaSurfacesKHR} since the last time that they were acquired.

- **CL_INVALID_EVENT_WAIT_LIST** if \( \text{event\_wait\_list} \) is NULL and \( \text{num\_events\_in\_wait\_list} > 0 \), or \( \text{event\_wait\_list} \) is not NULL and \( \text{num\_events\_in\_wait\_list} \) is 0, or if event objects in \( \text{event\_wait\_list} \) are not valid events.

- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.5.12. Sharing Memory Objects Created From Direct3D 10 Resources Between Direct3D 10 and OpenCL Contexts

To acquire OpenCL memory objects that have been created from Direct3D 10 resources, call the function

```c
// Provided by cl_khr_d3d10_sharing
cl_int clEnqueueAcquireD3D10ObjectsKHR(
    cl_command_queue command_queue,
    cl_uint num_objects,
    const cl_mem* mem_objects,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

**clEnqueueAcquireD3D10ObjectsKHR** is provided by the **cl_khr_d3d10_sharing** extension.

- **command\_queue** is a valid command-queue.

- **num\_objects** is the number of memory objects to be acquired in **mem\_objects**.

- **mem\_objects** is a pointer to a list of OpenCL memory objects that were created from Direct3D 10 resources.

- **event\_wait\_list** and **num\_events\_in\_wait\_list** specify events that need to complete before this particular command can be executed. If **event\_wait\_list** is NULL, then this particular command does not wait on any event to complete. If **event\_wait\_list** is NULL, **num\_events\_in\_wait\_list** must
be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0. The events specified in `event_wait_list` act as synchronization points.

- **event** returns an event object that identifies this command and can be used to query or wait for this command to complete. If `event` is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If `event_wait_list` and `event` are not `NULL`, `event` must not refer to an element of the `event_wait_list` array.

The Direct3D 10 objects are acquired by the OpenCL context associated with `command_queue` and can therefore be used by all command-queues associated with the OpenCL context.

OpenCL memory objects created from Direct3D 10 resources must be acquired before they can be used by any OpenCL commands queued to a command-queue. If an OpenCL memory object created from a Direct3D 10 resource is used while it is not currently acquired by OpenCL, the behavior is undefined. Implementations may fail the execution of commands attempting to use that OpenCL memory object and set their associated event’s execution status to `CL_D3D10 RESOURCE NOT ACQUIRED_KHR`.

If `CL_CONTEXT_INTEROP_USER_SYNC` is not specified as `CL_TRUE` during context creation, `clEnqueueAcquireD3D10ObjectsKHR` provides the synchronization guarantee that any Direct3D 10 calls involving the interop device(s) used in the OpenCL context made before `clEnqueueAcquireD3D10ObjectsKHR` is called will complete executing before `event` reports completion and before the execution of any subsequent OpenCL work issued in `command_queue` begins. If the context was created with properties specifying `CL_CONTEXT_INTEROP_USER_SYNC` as `CL_TRUE`, the user is responsible for guaranteeing that any Direct3D 10 calls involving the interop device(s) used in the OpenCL context made before `clEnqueueAcquireD3D10ObjectsKHR` is called have completed before calling `clEnqueueAcquireD3D10ObjectsKHR`.

`clEnqueueAcquireD3D10ObjectsKHR` returns `CL_SUCCESS` if the function is executed successfully. If `num_objects` is 0 and `mem_objects` is `NULL` then the function does nothing and returns `CL_SUCCESS`. Otherwise it returns one of the following errors:

- **CL_INVALID_VALUE** if `num_objects` is zero and `mem_objects` is not a `NULL` value or if `num_objects` > 0 and `mem_objects` is `NULL`.
- **CL_INVALID_MEM_OBJECT** if memory objects in `mem_objects` are not valid OpenCL memory objects or if memory objects in `mem_objects` have not been created from Direct3D 10 resources.
- **CL_INVALID_COMMAND_QUEUE** if `command_queue` is not a valid command-queue.
- **CL_INVALID_CONTEXT** if context associated with `command_queue` was not created from an Direct3D 10 context.
- **CL_D3D10_RESOURCE_ALREADY_ACQUIRED_KHR** if memory objects in `mem_objects` have previously been acquired using `clEnqueueAcquireD3D10ObjectsKHR` but have not been released using `clEnqueueReleaseD3D10ObjectsKHR`.
- **CL_INVALID_EVENT_WAIT_LIST** if `event_wait_list` is `NULL` and `num_events_in_wait_list` > 0, or `event_wait_list` is not `NULL` and `num_events_in_wait_list` is 0, or if event objects in `event_wait_list` are not valid events.
• CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

To release OpenCL memory objects that have been created from Direct3D 10 resources, call the function

// Provided by cl_khr_d3d10_sharing
cl_int clEnqueueReleaseD3D10ObjectsKHR(
    cl_command_queue command_queue,
    cl_uint num_objects,
    const cl_mem* mem_objects,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);

- num_objects is the number of memory objects to be released in mem_objects.
- mem_objects is a pointer to a list of OpenCL memory objects that were created from Direct3D 10 resources.
- event_wait_list and num_events_in_wait_list specify events that need to complete before this particular command can be executed. If event_wait_list is NULL, then this particular command does not wait on any event to complete. If event_wait_list is NULL, num_events_in_wait_list must be 0. If event_wait_list is not NULL, the list of events pointed to by event_wait_list must be valid and num_events_in_wait_list must be greater than 0.
- event returns an event object that identifies this command and can be used to query or wait for this command to complete. If event is NULL or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If event_wait_list and event are not NULL, event must not refer to an element of the event_wait_list array.

The Direct3D 10 objects are released by the OpenCL context associated with command_queue.

OpenCL memory objects created from Direct3D 10 resources which have been acquired by OpenCL must be released by OpenCL before they may be accessed by Direct3D 10. Accessing a Direct3D 10 resource while its corresponding OpenCL memory object is acquired is in error and will result in undefined behavior, including but not limited to possible OpenCL errors, data corruption, and program termination.

If CL_CONTEXT_INTEROP_USER_SYNC is not specified as CL_TRUE during context creation, clEnqueueReleaseD3D10ObjectsKHR provides the synchronization guarantee that any calls to Direct3D 10 calls involving the interop device(s) used in the OpenCL context made after the call to clEnqueueReleaseD3D10ObjectsKHR will not start executing until after all events in event_wait_list are complete and all work already submitted to command_queue completes execution. If the context was created with properties specifying CL_CONTEXT_INTEROP_USER_SYNC as CL_TRUE, the user is responsible for guaranteeing that any Direct3D 10 calls involving the interop
device(s) used in the OpenCL context made after \texttt{clEnqueueReleaseD3D10ObjectsKHR} will not start executing until after event returned by \texttt{clEnqueueReleaseD3D10ObjectsKHR} reports completion.

\texttt{clEnqueueReleaseD3D10ObjectsKHR} returns \texttt{CL_SUCCESS} if the function is executed successfully. If \textit{num\_objects} is 0 and \textit{mem\_objects} is \texttt{NULL} the function does nothing and returns \texttt{CL_SUCCESS}. Otherwise it returns one of the following errors:

- \texttt{CL\_INVALID\_VALUE} if \textit{num\_objects} is zero and \textit{mem\_objects} is not a \texttt{NULL} value or if \textit{num\_objects} > 0 and \textit{mem\_objects} is \texttt{NULL}.
- \texttt{CL\_INVALID\_MEM\_OBJECT} if memory objects in \textit{mem\_objects} are not valid OpenCL memory objects or if memory objects in \textit{mem\_objects} have not been created from Direct3D 10 resources.
- \texttt{CL\_INVALID\_COMMAND\_QUEUE} if \textit{command\_queue} is not a valid command-queue.
- \texttt{CL\_INVALID\_CONTEXT} if context associated with \textit{command\_queue} was not created from a Direct3D 10 device.
- \texttt{CL\_D3D10\_RESOURCE\_NOT\_ACQUIRED\_KHR} if memory objects in \textit{mem\_objects} have not previously been acquired using \texttt{clEnqueueAcquireD3D10ObjectsKHR}, or have been released using \texttt{clEnqueueReleaseD3D10ObjectsKHR} since the last time that they were acquired.
- \texttt{CL\_INVALID\_EVENT\_WAIT\_LIST} if \textit{event\_wait\_list} is \texttt{NULL} and \textit{num\_events\_in\_wait\_list} > 0, or \textit{event\_wait\_list} is not \texttt{NULL} and \textit{num\_events\_in\_wait\_list} > 0, or if event objects in \textit{event\_wait\_list} are not valid events.
- \texttt{CL\_OUT\_OF\_HOST\_MEMORY} if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.5.13. Sharing Memory Objects Created From Direct3D 11 Resources Between Direct3D 11 and OpenCL Contexts

To acquire OpenCL memory objects that have been created from Direct3D 11 resources, call the function

```c
// Provided by cl_khr_d3d11_sharing
cl_int clEnqueueAcquireD3D11ObjectsKHR(
    cl_command_queue command_queue,
    cl_uint num_objects,
    const cl_mem* mem_objects,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

\texttt{clEnqueueAcquireD3D11ObjectsKHR} is provided by the \texttt{cl_khr_d3d11_sharing} extension.

- \textit{command\_queue} is a valid command-queue.
- \textit{num\_objects} is the number of memory objects to be acquired in \textit{mem\_objects}. 

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mem_objects is a pointer to a list of OpenCL memory objects that were created from Direct3D 11 resources.

event_wait_list and num_events_in_wait_list specify events that need to complete before this particular command can be executed. If event_wait_list is NULL, then this particular command does not wait on any event to complete. If event_wait_list is NULL, num_events_in_wait_list must be 0. If event_wait_list is not NULL, the list of events pointed to by event_wait_list must be valid and num_events_in_wait_list must be greater than 0. The events specified in event_wait_list act as synchronization points.

event returns an event object that identifies this command and can be used to query or wait for this command to complete. If event is NULL or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If event_wait_list and event are not NULL, event must not refer to an element of the event_wait_list array.

The Direct3D 11 objects are acquired by the OpenCL context associated with command_queue and can therefore be used by all command-queues associated with the OpenCL context.

OpenCL memory objects created from Direct3D 11 resources must be acquired before they can be used by any OpenCL commands queued to a command-queue. If an OpenCL memory object created from a Direct3D 11 resource is used while it is not currently acquired by OpenCL, the behavior is undefined. Implementations may fail the execution of commands attempting to use that OpenCL memory object and set their associated event's execution status to CL_D3D11_RESOURCE_NOT_ACQUIRED_KHR.

If CL_CONTEXT_INTEROP_USER_SYNC is not specified as CL_TRUE during context creation, clEnqueueAcquireD3D11ObjectsKHR provides the synchronization guarantee that any Direct3D 11 calls involving the interop device(s) used in the OpenCL context made before clEnqueueAcquireD3D11ObjectsKHR is called will complete executing before event reports completion and before the execution of any subsequent OpenCL work issued in command_queue begins. If the context was created with properties specifying CL_CONTEXT_INTEROP_USER_SYNC as CL_TRUE, the user is responsible for guaranteeing that any Direct3D 11 calls involving the interop device(s) used in the OpenCL context made before clEnqueueAcquireD3D11ObjectsKHR is called have completed before calling clEnqueueAcquireD3D11ObjectsKHR.

clEnqueueAcquireD3D11ObjectsKHR returns CL_SUCCESS if the function is executed successfully. If num_objects is 0 and mem_objects is NULL then the function does nothing and returns CL_SUCCESS. Otherwise it returns one of the following errors:

- CL_INVALID_VALUE if num_objects is zero and mem_objects is not a NULL value or if num_objects > 0 and mem_objects is NULL.
- CL_INVALID_MEM_OBJECT if memory objects in mem_objects are not valid OpenCL memory objects or if memory objects in mem_objects have not been created from Direct3D 11 resources.
- CL_INVALID_COMMAND_QUEUE if command_queue is not a valid command-queue.
- CL_INVALID_CONTEXT if context associated with command_queue was not created from a Direct3D 11 context.
- CL_D3D11_RESOURCE_ALREADY_ACQUIRED_KHR if memory objects in mem_objects have previously been
acquired using `clEnqueueAcquireD3D11ObjectsKHR` but have not been released using `clEnqueueReleaseD3D11ObjectsKHR`.

- **CL_INVALID_EVENT_WAIT_LIST** if `event_wait_list` is `NULL` and `num_events_in_wait_list > 0`, or `event_wait_list` is not `NULL` and `num_events_in_wait_list` is 0, or if event objects in `event_wait_list` are not valid events.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To release OpenCL memory objects that have been created from Direct3D 11 resources, call the function

```c
// Provided by cl_khr_d3d11_sharing
c_int clEnqueueReleaseD3D11ObjectsKHR(
   cl_command_queue command_queue,
   cl_uint num_objects,
   const cl_mem* mem_objects,
   cl_uint num_events_in_wait_list,
   const cl_event* event_wait_list,
   cl_event* event);
```

- **num_objects** is the number of memory objects to be released in `mem_objects`.
- **mem_objects** is a pointer to a list of OpenCL memory objects that were created from Direct3D 11 resources.
- **event_wait_list** and **num_events_in_wait_list** specify events that need to complete before this particular command can be executed. If `event_wait_list` is `NULL`, then this particular command does not wait on any event to complete. If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0.
- **event** returns an event object that identifies this command and can be used to query or wait for this command to complete. If `event` is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If `event_wait_list` and `event` are not `NULL`, `event` must not refer to an element of the `event_wait_list` array.

The Direct3D 11 objects are released by the OpenCL context associated with `command_queue`.

OpenCL memory objects created from Direct3D 11 resources which have been acquired by OpenCL must be released by OpenCL before they may be accessed by Direct3D 11. Accessing a Direct3D 11 resource while its corresponding OpenCL memory object is acquired is in error and will result in undefined behavior, including but not limited to possible OpenCL errors, data corruption, and program termination.

If **CL_CONTEXT_INTEROP_USER_SYNC** is not specified as **CL_TRUE** during context creation,
clEnqueueReleaseD3D11ObjectsKHR provides the synchronization guarantee that any calls to Direct3D 11 calls involving the interop device(s) used in the OpenCL context made after the call to clEnqueueReleaseD3D11ObjectsKHR will not start executing until after all events in event_wait_list are complete and all work already submitted to command_queue completes execution. If the context was created with properties specifying CL_CONTEXT_INTEROP_USER_SYNC as CL_TRUE, the user is responsible for guaranteeing that any Direct3D 11 calls involving the interop device(s) used in the OpenCL context made after clEnqueueReleaseD3D11ObjectsKHR will not start executing until after event returned by clEnqueueReleaseD3D11ObjectsKHR reports completion.

clEnqueueReleaseD3D11ObjectsKHR returns CL_SUCCESS if the function is executed successfully. If num_objects is 0 and mem_objects is NULL the function does nothing and returns CL_SUCCESS. Otherwise it returns one of the following errors:

- CL_INVALID_VALUE if num_objects is zero and mem_objects is not a NULL value or if num_objects > 0 and mem_objects is NULL.
- CL_INVALID_MEM_OBJECT if memory objects in mem_objects are not valid OpenCL memory objects or if memory objects in mem_objects have not been created from Direct3D 11 resources.
- CL_INVALID_COMMAND_QUEUE if command_queue is not a valid command-queue.
- CL_INVALID_CONTEXT if context associated with command_queue was not created from a Direct3D 11 device.
- CL_D3D11_RESOURCE_NOT_ACQUIRED_KHR if memory objects in mem_objects have not previously been acquired using clEnqueueAcquireD3D11ObjectsKHR, or have been released using clEnqueueReleaseD3D11ObjectsKHR since the last time that they were acquired.
- CL_INVALID_EVENT_WAIT_LIST if event_wait_list is NULL and num_events_in_wait_list > 0, or event_wait_list is not NULL and num_events_in_wait_list is 0, or if event objects in event_wait_list are not valid events.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

5.5.14. Sharing Memory Objects Created From EGL Resources Between EGL and OpenCL Contexts

To acquire OpenCL memory objects that have been created from EGL resources, call the function

```c
// Provided by cl_khr_egl_image
cl_int clEnqueueAcquireEGLObjectsKHR(
    cl_command_queue command_queue,
    cl_uint num_objects,
    const cl_mem* mem_objects,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

clEnqueueAcquireEGLObjectsKHR is provided by the cl_khr_egl_image
extension.

- `command_queue` is a valid command-queue.
- `num_objects` is the number of memory objects to be acquired in `mem_objects`.
- `mem_objects` is a pointer to a list of OpenCL memory objects that were created from EGL resources, within the context associate with `command_queue`.
- `event_wait_list` and `num_events_in_wait_list` specify events that need to complete before this particular command can be executed. If `event_wait_list` is `NULL`, then this particular command does not wait on any event to complete. If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0. The events specified in `event_wait_list` act as synchronization points.
- `event` returns an event object that identifies this command and can be used to query or wait for this command to complete. If `event` is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If `event_wait_list` and `event` are not `NULL`, `event` must not refer to an element of the `event_wait_list` array.

The EGL objects are acquired by the OpenCL context associated with `command_queue` and can therefore be used by all command-queues associated with the OpenCL context.

OpenCL memory objects created from EGL resources must be acquired before they can be used by any OpenCL commands queued to a command-queue. If an OpenCL memory object created from an EGL resource is used while it is not currently acquired by OpenCL, the behavior is undefined. Implementations may fail the execution of commands attempting to use that OpenCL memory object and set their associated event’s execution status to `CL_EGL_RESOURCE_NOT_ACQUIRED_KHR`.

`clEnqueueAcquireEGLObjectsKHR` returns `CL_SUCCESS` if the function is executed successfully. If `num_objects` is 0 and `mem_objects` is `NULL` then the function does nothing and returns `CL_SUCCESS`. Otherwise it returns one of the following errors:

- `CL_INVALID_VALUE` if `num_objects` is zero and `mem_objects` is not a `NULL` value or if `num_objects > 0` and `mem_objects` is `NULL`.
- `CL_INVALID_MEM_OBJECT` if memory objects in `mem_objects` are not valid OpenCL memory objects in the context associated with `command_queue`.
- `CL_INVALID_EGL_OBJECT_KHR` if memory objects in `mem_objects` have not been created from EGL resources.
- `CL_INVALID_COMMAND_QUEUE` if `command_queue` is not a valid command-queue.
- `CL_INVALID_EVENT_WAIT_LIST` if `event_wait_list` is `NULL` and `num_events_in_wait_list > 0`, or `event_wait_list` is not `NULL` and `num_events_in_wait_list` is 0, or if event objects in `event_wait_list` are not valid events.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.
To release OpenCL memory objects that have been created from EGL resources, call the function

```c
// Provided by cl_khr_egl_image
c_int clEnqueueReleaseEGLObjectsKHR(
    cl_command_queue command_queue,
    cl_uint num_objects,
    const cl_mem* mem_objects,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

- `clEnqueueReleaseEGLObjectsKHR` is provided by the `cl_khr_egl_image` extension.

- `command_queue` is a valid command-queue.

- `num_objects` is the number of memory objects to be acquired in `mem_objects`.

- `mem_objects` is a pointer to a list of OpenCL memory objects that were created from EGL resources, within the context associate with `command_queue`.

- `event_wait_list` and `num_events_in_wait_list` specify events that need to complete before this particular command can be executed. If `event_wait_list` is `NULL`, then this particular command does not wait on any event to complete. If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0. The events specified in `event_wait_list` act as synchronization points.

- `event` returns an event object that identifies this command and can be used to query or wait for this command to complete. If `event` is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If `event_wait_list` and `event` are not `NULL`, `event` must not refer to an element of the `event_wait_list` array.

The EGL objects are released by the OpenCL context associated with `<command_queue>`.

OpenCL memory objects created from EGL resources which have been acquired by OpenCL must be released by OpenCL before they may be accessed by EGL or by EGL client APIs. Accessing a EGL resource while its corresponding OpenCL memory object is acquired is in error and will result in undefined behavior, including but not limited to possible OpenCL errors, data corruption, and program termination.

`clEnqueueReleaseEGLObjectsKHR` returns `CL_SUCCESS` if the function is executed successfully. If `num_objects` is 0 and `mem_objects` is `NULL` then the function does nothing and returns `CL_SUCCESS`. Otherwise it returns one of the following errors:

- `CL_INVALID_VALUE` if `num_objects` is zero and `mem_objects` is not a `NULL` value or if `num_objects` > 0 and `mem_objects` is `NULL`.

- `CL_INVALID_MEM_OBJECT` if memory objects in `mem_objects` are not valid OpenCL memory objects in the context associated with `command_queue`.

- `CL_INVALID_EGL_OBJECT_KHR` if memory objects in `mem_objects` have not been created from EGL
resources.

- **CL_INVALID_COMMAND_QUEUE** if `command_queue` is not a valid command-queue.

- **CL_INVALID_EVENT_WAIT_LIST** if `event_wait_list` is `NULL` and `num_events_in_wait_list > 0`, or `event_wait_list` is not `NULL` and `num_events_in_wait_list` is 0, or if event objects in `event_wait_list` are not valid events.

- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.5.15. Acquiring, Releasing, and Synchronizing Access to Shared OpenCL/OpenGL Memory Objects

To acquire OpenCL memory objects that have been created from OpenGL objects, call the function

```c
// Provided by cl_khr_gl_sharing
cl_int clEnqueueAcquireGLObjets(
    cl_command_queue command_queue,
    cl_uint num_objects,
    const cl_mem* mem_objects,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

**clEnqueueAcquireGLObjects** is provided by the `cl_khr_gl_sharing` extension.

- `command_queue` is a valid command-queue. All devices used to create the OpenCL context associated with `command_queue` must support acquiring shared OpenCL/OpenGL objects. This constraint is enforced at context creation time.

- `num_objects` is the number of memory objects to be acquired in `mem_objects`.

- `mem_objects` is a pointer to a list of OpenCL memory objects that correspond to OpenGL objects.

- `event_wait_list` and `num_events_in_wait_list` specify events that need to complete before this particular command can be executed. If `event_wait_list` is `NULL`, then this particular command does not wait on any event to complete. If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0. The events specified in `event_wait_list` act as synchronization points.

- `event` returns an event object that identifies this command and can be used to query wait for this command to complete. If `event` is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If `event_wait_list` and `event` are not `NULL`, `event` must not refer to an element of the `event_wait_list` array.

If an OpenGL context is bound to the current thread, then any OpenGL commands which
1. affect or access the contents of a memory object listed in the mem_objects list, and
2. were issued on that OpenGL context prior to the call to clEnqueueAcquireGLObjects

will complete before execution of any OpenCL commands following the clEnqueueAcquireGLObjects which affect or access any of those memory objects. If a non-NULL event object is returned, it will report completion only after completion of such OpenGL commands.

These objects need to be acquired before they can be used by any OpenCL commands queued to a command-queue or the behaviour is undefined. The OpenGL objects are acquired by the OpenCL context associated with command_queue and can therefore be used by all command-queues associated with the OpenCL context.

clEnqueueAcquireGLObjects returns CL_SUCCESS if the function is executed successfully. If num_objects is 0 and mem_objects is NULL the function does nothing and returns CL_SUCCESS. Otherwise, it returns one of the following errors:

- CL_INVALID_VALUE if num_objects is zero and mem_objects is not a NULL value or if num_objects > 0 and mem_objects is NULL.
- CL_INVALID_MEM_OBJECT if memory objects in mem_objects are not valid OpenCL memory objects.
- CL_INVALID_COMMAND_QUEUE if command_queue is not a valid command-queue.
- CL_INVALID_CONTEXT if context associated with command_queue was not created from an OpenGL context.
- CL_INVALID_GL_OBJECT if memory objects in mem_objects have not been created from an OpenGL object(s).
- CL_INVALID_EVENT_WAIT_LIST if event_wait_list is NULL and num_events_in_wait_list > 0, or event_wait_list is not NULL and num_events_in_wait_list is 0, or if event objects in event_wait_list are not valid events.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

To release OpenCL memory objects that have been created from OpenGL objects, call the function

```c
// Provided by cl_khr_gl_sharing
c_int clEnqueueReleaseGLObjects(
    cl_command_queue command_queue,
    cl_uint num_objects,
    const cl_mem* mem_objects,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

clEnqueueReleaseGLObjects is provided by the cl_khr_gl_sharing extension.
• \textit{num\_objects} is the number of memory objects to be released in \textit{mem\_objects}.

• \textit{mem\_objects} is a pointer to a list of OpenCL memory objects that correspond to OpenGL objects.

• \textit{event\_wait\_list} and \textit{num\_events\_in\_wait\_list} specify events that need to complete before this command can be executed. If \textit{event\_wait\_list} is \texttt{NULL}, then this particular command does not wait on any event to complete. If \textit{event\_wait\_list} is \texttt{NULL}, \textit{num\_events\_in\_wait\_list} must be 0. If \textit{event\_wait\_list} is not \texttt{NULL}, the list of events pointed to by \textit{event\_wait\_list} must be valid and \textit{num\_events\_in\_wait\_list} must be greater than 0. The events specified in \textit{event\_wait\_list} act as synchronization points.

• \textit{event} returns an event object that identifies this command and can be used to query or wait for this command to complete. If \textit{event} is \texttt{NULL} or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If \textit{event\_wait\_list} and \textit{event} are not \texttt{NULL}, \textit{event} must not refer to an element of the \textit{event\_wait\_list} array.

If an OpenGL context is bound to the current thread, then any OpenGL commands which

1. affect or access the contents of the memory objects listed in the \textit{mem\_objects} list, and
2. are issued on that context after the call to \texttt{clEnqueueReleaseGLObjects}

will not execute until after execution of any OpenCL commands preceding the

\texttt{clEnqueueReleaseGLObjects} which affect or access any of those memory objects. If a non-\texttt{NULL} \textit{event} object is returned, it will report completion before execution of such OpenGL commands.

These objects need to be released before they can be used by OpenGL. The OpenGL objects are released by the OpenCL context associated with \textit{command\_queue}.

\texttt{clEnqueueReleaseGLObjects} returns \texttt{CL\_SUCCESS} if the function is executed successfully. If \textit{num\_objects} is 0 and \textit{mem\_objects} is \texttt{NULL} the function does nothing and returns \texttt{CL\_SUCCESS}. Otherwise, it returns one of the following errors:

• \texttt{CL\_INVALID\_VALUE} if \textit{num\_objects} is zero and \textit{mem\_objects} is not a \texttt{NULL} value or if \textit{num\_objects} > 0 and \textit{mem\_objects} is \texttt{NULL}.

• \texttt{CL\_INVALID\_MEM\_OBJECT} if memory objects in \textit{mem\_objects} are not valid OpenCL memory objects.

• \texttt{CL\_INVALID\_COMMAND\_QUEUE} if \textit{command\_queue} is not a valid command-queue.

• \texttt{CL\_INVALID\_CONTEXT} if context associated with \textit{command\_queue} was not created from an OpenGL context

• \texttt{CL\_INVALID\_GL\_OBJECT} if memory objects in \textit{mem\_objects} have not been created from an OpenGL object(s).

• \texttt{CL\_INVALID\_EVENT\_WAIT\_LIST} if \textit{event\_wait\_list} is \texttt{NULL} and \textit{num\_events\_in\_wait\_list} > 0, or \textit{event\_wait\_list} is not \texttt{NULL} and \textit{num\_events\_in\_wait\_list} is 0, or if event objects in \textit{event\_wait\_list} are not valid events.

• \texttt{CL\_OUT\_OF\_RESOURCES} if there is a failure to allocate resources required by the OpenCL implementation on the device.

• \texttt{CL\_OUT\_OF\_HOST\_MEMORY} if there is a failure to allocate resources required by the OpenCL
5.5.15.1. Synchronizing Access to Memory Objects Shared With EGL or OpenGL

When sharing objects such as EGL images (if the `cl_khr_egl_image` extension is supported) or OpenGL buffers, textures, and renderbuffers (if the `cl_khr_gl_sharing` extension is supported), in order to ensure data integrity, the application is responsible for synchronizing access to shared memory objects through the other API with which such objects are shared.

Failure to provide such synchronization may result in race conditions and other undefined behavior including non-portability between implementations.

Prior to acquiring objects shared with the other API, the application must ensure that any pending operations in that API which accesses the objects specified in `mem_objects` have completed.

Depending on the application and the implementation, there are two extensions which may be used to synchronize with other APIs:

5.5.15.1.1. Synchronization With EGL and EGL Client APIs

When sharing with an EGL context via the `cl_khr_egl_image` extension, if the `cl_khr_egl_event` extension is supported, and the EGL context in question supports fence sync objects, explicit synchronization with EGL or EGL client APIs can be achieved as described in the `Explicit Synchronization Using EGL Fence Sync Objects` section.

If the `cl_khr_egl_event` extension is not supported, completion of EGL client API commands may be determined by issuing and waiting for completion of commands such as `glFinish` or `vgFinish` on all client API contexts with pending references to these objects.

5.5.15.1.2. Synchronization With OpenGL

When sharing with an OpenGL context via the `cl_khr_gl_sharing` extension, the OpenCL implementation will ensure that any such pending OpenGL operations are complete for an OpenGL context bound to the same thread as the OpenCL context. This is referred to as implicit synchronization.

If the `cl_khr_gl_event` extension is supported, and the OpenGL context in question supports fence sync objects, explicit synchronization with OpenGL can be achieved as described in the `Explicit Synchronization Using OpenGL Fence Sync Objects` section.

If the `cl_khr_gl_event` extension is not supported, completion of OpenGL commands may be determined by issuing and waiting for completion of a `glFinish` command on all OpenGL contexts with pending references to these objects.

5.5.15.1.3. General Considerations for Synchronization With Other APIs

Some implementations may offer other efficient synchronization methods. If such methods exist they will be described in platform-specific documentation.

Note that no synchronization method other than `glFinish` is portable between all OpenGL implementations and all OpenCL implementations. While this is the only way to ensure completion
that is portable to all platforms, `glFinish` is an expensive operation and its use should be avoided if
the `cl_khr_egl_event` or `cl_khr_gl_event` extensions are supported on a platform.

5.5.15.1.4. Synchronizing OpenCL Operations With Other APIs

After releasing a shared memory object, the application is responsible for ensuring that any
pending OpenCL operations which access the objects specified in `mem_objects` have completed
prior to executing subsequent commands in the other API which reference these objects.

This may be accomplished portably by calling `clWaitForEvents` with the event object returned by
`clEnqueueReleaseGLObjects`, or by calling `clFinish`. As above, some implementations may offer
more efficient methods.

The application is responsible for maintaining the proper order of operations if the OpenCL context
and the other API context are in separate threads.

If an OpenGL context is bound to a thread other than the one in which
`clEnqueueReleaseGLObjects` is called, changes to any of the objects in `mem_objects` may not be
visible to that context without additional steps being taken by the application. For an OpenGL 3.1
(or later) context, the requirements are described in Appendix D (“Shared Objects and Multiple
Contexts”) of the OpenGL 3.1 Specification. For prior versions of OpenGL, the requirements are
implementation-dependent.

Attempting to access the data store of an OpenGL object after it has been acquired by OpenCL and
before it has been released will result in undefined behavior. Similarly, attempting to access a
shared OpenCL/OpenGL object from OpenCL before it has been acquired by the OpenCL command-
queue, or after it has been released, will result in undefined behavior.

5.6. Shared Virtual Memory

Shared virtual memory is missing before version 2.0.

Shared virtual memory (a.k.a. SVM) allows the host and kernels executing on devices to directly
share complex, pointer-containing data structures such as trees and linked lists. It also eliminates
the need to marshal data between the host and devices. As a result, SVM substantially simplifies
OpenCL programming and may improve performance.

5.6.1. SVM Sharing Granularity: Coarse- and Fine-Grained Sharing

OpenCL maintains memory consistency in a coarse-grained fashion in regions of buffers. We call
this coarse-grained sharing. Many platforms such as those with integrated CPU-GPU processors and
ones using the SVM-related PCI-SIG IOMMU services can do better, and can support sharing at a
granularity smaller than a buffer. We call this fine-grained sharing.

- Coarse-grained sharing: Coarse-grain sharing may be used for memory and virtual pointer
  sharing between multiple devices as well as between the host and one or more devices. The
  shared memory region is a memory buffer allocated using `clSVMAlloc`. Memory consistency is
guaranteed at synchronization points and the host can use calls to `clEnqueueSVMMap` and
`clEnqueueSVMUnmap` or create a `cl_mem` buffer object using the SVM pointer and use OpenCL’s
existing host API functions `clEnqueueMapBuffer` and `clEnqueueUnmapMemObject` to update regions of the buffer. What coarse-grain buffer SVM adds to OpenCL's earlier buffer support are the ability to share virtual memory pointers and a guarantee that concurrent access to the same memory allocation from multiple kernels on a single device is valid. The coarse-grain buffer SVM provides a memory consistency model similar to the global memory consistency model described in sections 3.3.1 and 3.4.3 of the OpenCL 1.2 specification. This memory consistency applies to the regions of buffers being shared in a coarse-grained fashion. It is enforced at the synchronization points between commands enqueued to command-queues in a single context with the additional consideration that multiple kernels concurrently running on the same device may safely share the data.

- Fine-grained sharing: Shared virtual memory where memory consistency is maintained at a granularity smaller than a buffer. How fine-grained SVM is used depends on whether the device supports SVM atomic operations.
  
  ◦ If SVM atomic operations are supported, they provide memory consistency for loads and stores by the host and kernels executing on devices supporting SVM. This means that the host and devices can concurrently read and update the same memory. The consistency provided by SVM atomics is in addition to the consistency provided at synchronization points. There is no need for explicit calls to `clEnqueueSVMMap` and `clEnqueueSVMUnmap` or `clEnqueueMapBuffer` and `clEnqueueUnmapMemObject` on a `cl_mem` buffer object created using the SVM pointer.

  ◦ If SVM atomic operations are not supported, the host and devices can concurrently read the same memory locations and can concurrently update non-overlapping memory regions, but attempts to update the same memory locations are undefined. Memory consistency is guaranteed at synchronization points without the need for explicit calls to `clEnqueueSVMMap` and `clEnqueueSVMUnmap` or `clEnqueueMapBuffer` and `clEnqueueUnmapMemObject` on a `cl_mem` buffer object created using the SVM pointer.

- There are two kinds of fine-grain sharing support. Devices may support either fine-grain buffer sharing or fine-grain system sharing.

  ◦ Fine-grain buffer sharing provides fine-grain SVM only within buffers and is an extension of coarse-grain sharing. To support fine-grain buffer sharing in an OpenCL context, all devices in the context must support `CL_DEVICE_SVM_FINE_GRAIN_BUFFER`.

  ◦ Fine-grain system sharing enables fine-grain sharing of the host's entire virtual memory, including memory regions allocated by the system `malloc` API. OpenCL buffer objects are unnecessary and programmers can pass pointers allocated using `malloc` to OpenCL kernels.

As an illustration of fine-grain SVM using SVM atomic operations to maintain memory consistency, consider the following example. The host and a set of devices can simultaneously access and update a shared work-queue data structure holding work-items to be done. The host can use atomic operations to insert new work-items into the queue at the same time as the devices using similar atomic operations to remove work-items for processing.

It is the programmer's responsibility to ensure that no host code or executing kernels attempt to access a shared memory region after that memory is freed. We require the SVM implementation to work with either 32- or 64-bit host applications subject to the following requirement: the address space size must be the same for the host and all OpenCL devices in the context.
To allocate a shared virtual memory buffer (referred to as a SVM buffer) that can be shared by the host and all devices in an OpenCL context that support shared virtual memory, call the function

```c
// Provided by CL_VERSION_2_0
void* clSVMAlloc(  
    cl_context context,  
    cl_svm_mem_flags flags,  
    size_t size,  
    cl_uint alignment);
```

- `clSVMAlloc` is missing before version 2.0.

- `context` is a valid OpenCL context used to create the SVM buffer.

- `flags` is a bit-field that is used to specify allocation and usage information. The SVM Memory Flags table describes the possible values for `flags`.

- `size` is the size in bytes of the SVM buffer to be allocated.

- `alignment` is the minimum alignment in bytes that is required for the newly created buffers memory region. It must be a power of two up to the largest data type supported by the OpenCL device. For the full profile, the largest data type is long16. For the embedded profile, it is long16 if the device supports 64-bit integers; otherwise it is int16. If alignment is 0, a default alignment will be used that is equal to the size of largest data type supported by the OpenCL implementation.

**Table 40. List of supported SVM memory flag values**

<table>
<thead>
<tr>
<th>SVM Memory Flags</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>CL_MEM_READ_WRITE</code></td>
<td>This flag specifies that the SVM buffer will be read and written by a kernel. This is the default.</td>
</tr>
<tr>
<td><code>CL_MEM_WRITE_ONLY</code></td>
<td>This flag specifies that the SVM buffer will be written but not read by a kernel. Reading from a SVM buffer created with <code>CL_MEM_WRITE_ONLY</code> inside a kernel is undefined.</td>
</tr>
<tr>
<td></td>
<td><code>CL_MEM_READ_WRITE</code> and <code>CL_MEM_WRITE_ONLY</code> are mutually exclusive.</td>
</tr>
<tr>
<td><code>CL_MEM_READ_ONLY</code></td>
<td>This flag specifies that the SVM buffer object is a read-only memory object when used inside a kernel. Writing to a SVM buffer created with <code>CL_MEM_READ_ONLY</code> inside a kernel is undefined.</td>
</tr>
<tr>
<td></td>
<td><code>CL_MEM_READ_WRITE</code> or <code>CL_MEM_WRITE_ONLY</code> and <code>CL_MEM_READ_ONLY</code> are mutually exclusive.</td>
</tr>
</tbody>
</table>
### SVM Memory Flags

<table>
<thead>
<tr>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>This specifies that the application wants the OpenCL implementati</strong></td>
</tr>
<tr>
<td><strong>This flag is valid only if CL_MEM_SVM_FINE_GRAIN_BUFFER is specified in flags. It is used to indicate that SVM atomic operations can control visibility of memory accesses in this SVM buffer.</strong></td>
</tr>
</tbody>
</table>

If `CL_MEM_SVM_FINE_GRAIN_BUFFER` is not specified, the buffer can be created as a coarse grained SVM allocation. Similarly, if `CL_MEM_SVM_ATOMICS` is not specified, the buffer can be created without support for SVM atomic operations (refer to an OpenCL kernel language specifications).

Calling `clSVMAlloc` does not itself provide consistency for the shared memory region. When the host cannot use the SVM atomic operations, it must rely on OpenCL's guaranteed memory consistency at synchronization points.

For SVM to be used efficiently, the host and any devices sharing a buffer containing virtual memory pointers should have the same endianness. If the context passed to `clSVMAlloc` has devices with mixed endianness and the OpenCL implementation is unable to implement SVM because of that mixed endianness, `clSVMAlloc` will fail and return `NULL`.

Although SVM is generally not supported for image objects, `clCreateImage` and `clCreateImageWithProperties` may create an image from a buffer (a 1D image from a buffer or a 2D image from buffer) if the buffer specified in its image description parameter is a SVM buffer. Such images have a linear memory representation so their memory can be shared using SVM. However, fine grained sharing and atomics are not supported for image reads and writes in a kernel.

`clSVMAlloc` returns a valid non-`NULL` shared virtual memory address if the SVM buffer is successfully allocated. Otherwise, like `malloc`, it returns a `NULL` pointer value. `clSVMAlloc` will fail if:

- `context` is not a valid context, or no devices in `context` support SVM.
- `flags` does not contain `CL_MEM_SVM_FINE_GRAIN_BUFFER` but does contain `CL_MEM_SVM_ATOMICS`.
- Values specified in `flags` do not follow rules described for supported values in the SVM Memory Flags table.
- `CL_MEM_SVM_FINE_GRAIN_BUFFER` or `CL_MEM_SVM_ATOMICS` is specified in `flags` and these are not supported by at least one device in `context`.
- The values specified in `flags` are not valid, i.e. do not match those defined in the SVM Memory Flags table.
- `size` is 0 or > `CL_DEVICE_MAX_MEM_ALLOC_SIZE` value for any device in `context`.
- `alignment` is not a power of two or the OpenCL implementation cannot support the specified alignment for at least one device in `context`.
- There was a failure to allocate resources.
To free a shared virtual memory buffer allocated using `clSVMAlloc`, call the function

```c
// Provided by CL_VERSION_2_0
void clSVMFree(
    cl_context context,
    void* svm_pointer);
```

- `context` is a valid OpenCL context used to create the SVM buffer. If no devices in `context` support SVM, no action occurs.
- `svm_pointer` must be the value returned by a call to `clSVMAlloc`. If a `NULL` pointer is passed in `svm_pointer`, no action occurs.

Note that `clSVMFree` does not wait for previously enqueued commands that may be using `svm_pointer` to finish before freeing `svm_pointer`. It is the responsibility of the application to make sure that enqueued commands that use `svm_pointer` have finished before freeing `svm_pointer`. This can be done by enqueuing a blocking operation such as `clFinish`, `clWaitForEvents`, `clEnqueueReadBuffer` or by registering a callback with the events associated with enqueued commands and when the last enqueued command has finished freeing `svm_pointer`.

The behavior of using `svm_pointer` after it has been freed is undefined. In addition, if a buffer object is created using `clCreateBuffer` or `clCreateBufferWithProperties` with `svm_pointer`, the buffer object must first be released before the `svm_pointer` is freed.

The `clEnqueueSVMFree` API can also be used to enqueue a callback to free the shared virtual memory buffer allocated using `clSVMAlloc` or a shared system memory pointer.

To enqueue a command to free the shared virtual memory allocated using `clSVMAlloc` or a shared system memory pointer, call the function

```c
// Provided by CL_VERSION_2_0
cl_int clEnqueueSVMFree(
    cl_command_queue command_queue,
    cl_uint num_svm_pointers,
    void* svm_pointers[],
    void (CL_CALLBACK* pfn_free_func)(cl_command_queue queue, cl_uint num_svm_pointers, void* svm_pointers[], void* user_data),
    void* user_data,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

- `clEnqueueSVMFree` is missing before version 2.0.
- `command_queue` is a valid host command-queue.
• *svm_pointers* and *num_svm_pointers* specify shared virtual memory pointers to be freed. Each pointer in *svm_pointers* that was allocated using `clSVMAlloc` must have been allocated from the same context from which *command_queue* was created. The memory associated with *svm_pointers* can be reused or freed after the function returns.

• *pfn_free_func* specifies the callback function to be called to free the SVM pointers. This callback function may be called asynchronously by the OpenCL implementation. It is the application’s responsibility to ensure that the callback function is thread-safe. *pfn_free_func* takes four arguments: *queue* which is the command-queue in which `clEnqueueSVMFree` was enqueued, the count and list of SVM pointers to free and *user_data* which is a pointer to user specified data. If *pfn_free_func* is `NULL`, all pointers specified in *svm_pointers* must be allocated using `clSVMAlloc` and the OpenCL implementation will free these SVM pointers. *pfn_free_func* must be a valid callback function if any SVM pointer to be freed is a shared system memory pointer i.e. not allocated using `clSVMAlloc`. If *pfn_free_func* is a valid callback function, the OpenCL implementation will call *pfn_free_func* to free all the SVM pointers specified in *svm_pointers*.

• *user_data* will be passed as the *user_data* argument when *pfn_free_func* is called. *user_data* can be `NULL`.

• *event_wait_list* and *num_events_in_wait_list* specify events that need to complete before `clEnqueueSVMFree` can be executed. If *event_wait_list* is `NULL`, then `clEnqueueSVMFree` does not wait on any event to complete. If *event_wait_list* is `NULL`, *num_events_in_wait_list* must be 0. If *event_wait_list* is not `NULL`, the list of events pointed to by *event_wait_list* must be valid and *num_events_in_wait_list* must be greater than 0. The events specified in *event_wait_list* act as synchronization points. The context associated with events in *event_wait_list* and *command_queue* must be the same. The memory associated with *event_wait_list* can be reused or freed after the function returns.

• *event* returns an event object that identifies this command and can be used to query or queue a wait for this command to complete. If *event* is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If *event_wait_list* and *event* are not `NULL`, *event* must not refer to an element of the *event_wait_list* array.

`clEnqueueSVMFree` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

• `CL_INVALID_COMMAND_QUEUE` if *command_queue* is not a valid host command-queue.

• `CL_INVALID_OPERATION` if the device associated with *command_queue* does not support SVM.

• `CL_INVALID_VALUE` if *num_svm_pointers* is 0 and *svm_pointers* is non-`NULL`, or if *svm_pointers* is `NULL` and *num_svm_pointers* is not 0.

• `CL_INVALID_EVENT_WAIT_LIST` if *event_wait_list* is `NULL` and *num_events_in_wait_list* > 0, or *event_wait_list* is not `NULL` and *num_events_in_wait_list* is 0, or if event objects in *event_wait_list* are not valid events.

• `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.

• `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.
To enqueue a command to do a memcpy operation, call the function

```c
// Provided by CL_VERSION_2_0
cl_int clEnqueueSVMMemcpy(
    cl_command_queue command_queue,
    cl_bool blocking_copy,
    void* dst_ptr,
    const void* src_ptr,
    size_t size,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

- **command_queue** refers to the host command-queue in which the read / write command will be queued. If either `dst_ptr` or `src_ptr` is allocated using `clSVMAlloc` then the OpenCL context allocated against must match that of `command_queue`.

- **blocking_copy** indicates if the copy operation is *blocking* or *non-blocking*.

- If `blocking_copy` is `CL_TRUE` i.e. the copy command is blocking, `clEnqueueSVMMemcpy` does not return until the buffer data has been copied into memory pointed to by `dst_ptr`.

- **size** is the size in bytes of data being copied.

- **dst_ptr** is the pointer to a host or SVM memory allocation where data is copied to.

- **src_ptr** is the pointer to a host or SVM memory allocation where data is copied from.

- **event_wait_list** and **num_events_in_wait_list** specify events that need to complete before this particular command can be executed. If `event_wait_list` is `NULL`, then this particular command does not wait on any event to complete. If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0. The events specified in `event_wait_list` act as synchronization points. The context associated with events in `event_wait_list` and `command_queue` must be the same. The memory associated with `event_wait_list` can be reused or freed after the function returns.

- **event** returns an event object that identifies this read / write command and can be used to query or queue a wait for this command to complete. If `event` is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If `event_wait_list` and `event` are not `NULL`, `event` must not refer to an element of the `event_wait_list` array.

If `blocking_copy` is `CL_FALSE` i.e. the copy command is non-blocking, `clEnqueueSVMMemcpy` queues a non-blocking copy command and returns. The contents of the buffer that `dst_ptr` points to cannot be used until the copy command has completed. The `event` argument returns an event object which can be used to query the execution status of the read command. When the copy command has completed, the contents of the buffer that `dst_ptr` points to can be used by the application.

If the memory allocation(s) containing `dst_ptr` and/or `src_ptr` are allocated using `clSVMAlloc` and
either is not allocated from the same context from which `command_queue` was created the behavior is undefined.

`clEnqueueSVMMemcpy` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_COMMAND_QUEUE` if `command_queue` is not a valid host command-queue.
- `CL_INVALID_OPERATION` if the device associated with `command_queue` does not support SVM.
- `CL_INVALID_CONTEXT` if the context associated with `command_queue` and events in `event_wait_list` are not the same.
- `CL_INVALID_EVENT_WAIT_LIST` if `event_wait_list` is `NULL` and `num_events_in_wait_list` > 0, or `event_wait_list` is not `NULL` and `num_events_in_wait_list` is 0, or if event objects in `event_wait_list` are not valid events.
- `CL_EXEC_STATUS_ERROR_FOR_EVENTS_IN_WAIT_LIST` if the copy operation is blocking and the execution status of any of the events in `event_wait_list` is a negative integer value.
- `CL_INVALID_VALUE` if `dst_ptr` or `src_ptr` is `NULL`.
- `CL_MEM_COPY_OVERLAP` if the values specified for `dst_ptr`, `src_ptr` and `size` result in an overlapping copy.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

To enqueue a command to fill a region in memory with a pattern of a given pattern size, call the function

```c
// Provided by CL_VERSION_2_0
cl_int clEnqueueSVMMemFill(
    cl_command_queue command_queue,
    void* svm_ptr,
    const void* pattern,
    size_t pattern_size,
    size_t size,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

- `clEnqueueSVMMemFill` is missing before version 2.0.
- `command_queue` refers to the host command-queue in which the fill command will be queued. The OpenCL context associated with `command_queue` and SVM pointer referred to by `svm_ptr` must be the same.
- `svm_ptr` is a pointer to a memory region that will be filled with `pattern`. It must be aligned to `pattern_size` bytes. If `svm_ptr` is allocated using `clSVMAlloc` then it must be allocated from the
same context from which \texttt{command\_queue} was created. Otherwise the behavior is undefined.

- \textit{pattern} is a pointer to the data pattern of size \textit{pattern\_size} in bytes. \textit{pattern} will be used to fill a region in \textit{buffer} starting at \textit{svm\_ptr} and is \textit{size} bytes in size. The data pattern must be a scalar or vector integer or floating-point data type supported by OpenCL as described in \textit{Shared Application Scalar Data Types} and \textit{Supported Application Vector Data Types}. For example, if region pointed to by \textit{svm\_ptr} is to be filled with a pattern of float4 values, then \textit{pattern} will be a pointer to a cl\_float4 value and \textit{pattern\_size} will be sizeof(cl\_float4). The maximum value of \textit{pattern\_size} is the size of the largest integer or floating-point vector data type supported by the OpenCL device. The memory associated with \textit{pattern} can be reused or freed after the function returns.

- \textit{size} is the size in bytes of region being filled starting with \textit{svm\_ptr} and must be a multiple of \textit{pattern\_size}.

- \textit{event\_wait\_list} and \textit{num\_events\_in\_wait\_list} specify events that need to complete before this particular command can be executed. If \textit{event\_wait\_list} is \texttt{NULL}, then this particular command does not wait on any event to complete. If \textit{event\_wait\_list} is \texttt{NULL}, \textit{num\_events\_in\_wait\_list} must be 0. If \textit{event\_wait\_list} is not \texttt{NULL}, the list of events pointed to by \textit{event\_wait\_list} must be valid and \textit{num\_events\_in\_wait\_list} must be greater than 0. The events specified in \textit{event\_wait\_list} act as synchronization points. The context associated with events in \textit{event\_wait\_list} and \textit{command\_queue} must be the same. The memory associated with \textit{event\_wait\_list} can be reused or freed after the function returns.

- \textit{event} returns an event object that identifies this command and can be used to query or queue a wait for this command to complete. If \textit{event} is \texttt{NULL} or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If \textit{event\_wait\_list} and \textit{event} are not \texttt{NULL}, \textit{event} must not refer to an element of the \textit{event\_wait\_list} array.

\texttt{cl\_EnqueueSVM\_Mem\_Fill} returns \texttt{CL\_SUCCESS} if the function is executed successfully. Otherwise, it returns one of the following errors:

- \texttt{CL\_INVALID\_COMMAND\_QUEUE} if \textit{command\_queue} is not a valid host command-queue.
- \texttt{CL\_INVALID\_OPERATION} if the device associated with \textit{command\_queue} does not support SVM.
- \texttt{CL\_INVALID\_CONTEXT} if the context associated with \textit{command\_queue} and events in \textit{event\_wait\_list} are not the same.
- \texttt{CL\_INVALID\_VALUE} if \textit{svm\_ptr} is \texttt{NULL}.
- \texttt{CL\_INVALID\_VALUE} if \textit{svm\_ptr} is not aligned to \textit{pattern\_size} bytes.
- \texttt{CL\_INVALID\_VALUE} if \textit{pattern} is \texttt{NULL} or if \textit{pattern\_size} is 0 or if \textit{pattern\_size} is not one of \{1, 2, 4, 8, 16, 32, 64, 128\}.
- \texttt{CL\_INVALID\_VALUE} if \textit{size} is not a multiple of \textit{pattern\_size}.
- \texttt{CL\_INVALID\_EVENT\_WAIT\_LIST} if \textit{event\_wait\_list} is \texttt{NULL} and \textit{num\_events\_in\_wait\_list} > 0, or \textit{event\_wait\_list} is not \texttt{NULL} and \textit{num\_events\_in\_wait\_list} is 0, or if event objects in \textit{event\_wait\_list} are not valid events.
- \texttt{CL\_OUT\_OF\_RESOURCES} if there is a failure to allocate resources required by the OpenCL implementation on the device.
• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To enqueue a command that will allow the host to update a region of a SVM buffer, call the function

```c
// Provided by CL_VERSION_2_0
cl_int clEnqueueSVMMap(
    cl_command_queue command_queue,
    cl_bool blocking_map,
    cl_map_flags flags,
    void* svm_ptr,
    size_t size,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

- `command_queue` must be a valid host command-queue.
- `blocking_map` indicates if the map operation is blocking or non-blocking.
- `map_flags` is a bit-field and is described in the Memory Map Flags table.
- `svm_ptr` and `size` are a pointer to a memory region and size in bytes that will be updated by the host. If `svm_ptr` is allocated using `clSVMAlloc` then it must be allocated from the same context from which `command_queue` was created. Otherwise the behavior is undefined.
- `event_wait_list` and `num_events_in_wait_list` specify events that need to complete before this particular command can be executed. If `event_wait_list` is `NULL`, then this particular command does not wait on any event to complete. If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0. The events specified in `event_wait_list` act as synchronization points. The context associated with events in `event_wait_list` and `command_queue` must be the same. The memory associated with `event_wait_list` can be reused or freed after the function returns.
- `event` returns an event object that identifies this command and can be used to query or queue a wait for this command to complete. If `event` is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If `event_wait_list` and `event` are not `NULL`, `event` must not refer to an element of the `event_wait_list` array.

If `blocking_map` is `CL_TRUE`, `clEnqueueSVMMap` does not return until the application can access the contents of the SVM region specified by `svm_ptr` and `size` on the host.

If `blocking_map` is `CL_FALSE` i.e. map operation is non-blocking, the region specified by `svm_ptr` and `size` cannot be used until the map command has completed. The `event` argument returns an event object which can be used to query the execution status of the map command. When the map command is completed, the application can access the contents of the region specified by `svm_ptr` and `size`. 

---

⚠️ **clEnqueueSVMMap** is missing before version 2.0.
Note that since we are enqueuing a command with a SVM buffer, the region is already mapped in the host address space.

`clEnqueueSVMMap` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_COMMAND_QUEUE` if `command_queue` is not a valid host command-queue.
- `CL_INVALID_OPERATION` if the device associated with `command_queue` does not support SVM.
- `CL_INVALID_CONTEXT` if context associated with `command_queue` and events in `event_wait_list` are not the same.
- `CL_INVALID_VALUE` if `svm_ptr` is `NULL`.
- `CL_INVALID_VALUE` if `size` is 0 or if values specified in `map_flags` are not valid.
- `CL_INVALID_EVENT_WAIT_LIST` if `event_wait_list` is `NULL` and `num_events_in_wait_list` is greater than 0, or `event_wait_list` is not `NULL` and `num_events_in_wait_list` is 0, or if event objects in `event_wait_list` are not valid events.
- `CL_EXEC_STATUS_ERROR_FOR_EVENTS_IN_WAIT_LIST` if the map operation is blocking and the execution status of any of the events in `event_wait_list` is a negative integer value.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

To enqueue a command to indicate that the host has completed updating the region given by `svm_ptr` and which was specified in a previous call to `clEnqueueSVMMap`, call the function

```c
// Provided by CL_VERSION_2_0
cl_int clEnqueueSVMUnmap(
    cl_command_queue command_queue,
    void* svm_ptr,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

- `command_queue` must be a valid host command-queue.
- `svm_ptr` is a pointer that was specified in a previous call to `clEnqueueSVMMap`. If `svm_ptr` is allocated using `clSVMAlloc` then it must be allocated from the same context from which `command_queue` was created. Otherwise the behavior is undefined.
- `event_wait_list` and `num_events_in_wait_list` specify events that need to complete before `clEnqueueSVMUnmap` can be executed. If `event_wait_list` is `NULL`, then `clEnqueueSVMUnmap` does not wait on any event to complete. If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0. The events specified in `event_wait_list` act...
as synchronization points. The context associated with events in `event_wait_list` and `command_queue` must be the same. The memory associated with `event_wait_list` can be reused or freed after the function returns.

- `event` returns an event object that identifies this command and can be used to query or queue a wait for this command to complete. If `event` is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If `event_wait_list` and `event` are not `NULL`, `event` must not refer to an element of the `event_wait_list` array.

`clEnqueueSVMMap` and `clEnqueueSVMUnmap` act as synchronization points for the region of the SVM buffer specified in these calls.

`clEnqueueSVMUnmap` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_COMMAND_QUEUE` if `command_queue` is not a valid host command-queue.
- `CL_INVALID_OPERATION` if the device associated with `command_queue` does not support SVM.
- `CL_INVALID_CONTEXT` if context associated with `command_queue` and events in `event_wait_list` are not the same.
- `CL_INVALID_VALUE` if `svm_ptr` is `NULL`.
- `CL_INVALID_EVENT_WAIT_LIST` if `event_wait_list` is `NULL` and `num_events_in_wait_list` > 0, or if `event_wait_list` is not `NULL` and `num_events_in_wait_list` is 0, or if event objects in `event_wait_list` are not valid events.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

If a coarse-grained SVM buffer is currently mapped for writing, the application must ensure that the SVM buffer is unmapped before any enqueued kernels or commands that read from or write to this SVM buffer or any of its associated `cl_mem` buffer objects begin execution; otherwise the behavior is undefined.

If a coarse-grained SVM buffer is currently mapped for reading, the application must ensure that the SVM buffer is unmapped before any enqueued kernels or commands that write to this memory object or any of its associated `cl_mem` buffer objects begin execution; otherwise the behavior is undefined.

A SVM buffer is considered as mapped if there are one or more active mappings for the SVM buffer irrespective of whether the mapped regions span the entire SVM buffer.

The above note does not apply to fine-grained SVM buffers (fine-grained buffers allocated using `clSVMAlloc` or fine-grained system allocations).

To enqueue a command to indicate which device a set of ranges of SVM allocations should be
associated with, call the function

```c
cl_int clEnqueueSVMMigrateMem(
    cl_command_queue command_queue,
    cl_uint num_svm_pointers,
    const void** svm_pointers,
    const size_t* sizes,
    cl_mem_migration_flags flags,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

**clEnqueueSVMMigrateMem** is **missing before** version 2.1.

- **command_queue** is a valid host command-queue. The specified set of allocation ranges will be migrated to the OpenCL device associated with **command_queue**.

- **num_svm_pointers** is the number of pointers in the specified **svm_pointers** array, and the number of sizes in the **sizes** array, if **sizes** is not **NULL**.

- **svm_pointers** is a pointer to an array of pointers. Each pointer in this array must be within an allocation produced by a call to **clSVMAlloc**.

- **sizes** is an array of sizes. The pair **svm_pointers[i]** and **sizes[i]** together define the starting address and number of bytes in a range to be migrated. **sizes** may be **NULL** indicating that every allocation containing any **svm_pointer[i]** is to be migrated. Also, if **sizes[i]** is zero, then the entire allocation containing **svm_pointer[i]** is migrated.

- **flags** is a bit-field that is used to specify migration options. The **Memory Migration Flags** describes the possible values for **flags**.

- **event_wait_list** and **num_events_in_wait_list** specify events that need to complete before this particular command can be executed. If **event_wait_list** is **NULL**, then this particular command does not wait on any event to complete. If **event_wait_list** is **NULL**, **num_events_in_wait_list** must be 0. If **event_wait_list** is not **NULL**, the list of events pointed to by **event_wait_list** must be valid and **num_events_in_wait_list** must be greater than 0. The events specified in **event_wait_list** act as synchronization points. The context associated with events in **event_wait_list** and **command_queue** must be the same. The memory associated with **event_wait_list** can be reused or freed after the function returns.

- **event** returns an event object that identifies this command and can be used to query or queue a wait for this command to complete. If **event** is **NULL** or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If **event_wait_list** and **event** are not **NULL**, **event** must not refer to an element of the **event_wait_list** array.

Once the event returned by **clEnqueueSVMMigrateMem** has become **CL_COMPLETE**, the ranges specified by svm pointers and sizes have been successfully migrated to the device associated with command-queue.
The user is responsible for managing the event dependencies associated with this command in order to avoid overlapping access to SVM allocations. Improperly specified event dependencies passed to `clEnqueueSVMMigrateMem` could result in undefined results.

`clEnqueueSVMMigrateMem` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_COMMAND_QUEUE** if `command_queue` is not a valid host command-queue.
- **CL_INVALID_OPERATION** if the device associated with `command_queue` does not support SVM.
- **CL_INVALID_CONTEXT** if context associated with `command_queue` and events in `event_wait_list` are not the same.
- **CL_INVALID_VALUE** if `num_svm_pointers` is zero or `svm_pointers` is `NULL`.
- **CL_INVALID_VALUE** if `sizes[i]` is non-zero range `[svm_pointers[i], svm_pointers[i]+sizes[i])` is not contained within an existing `clSVMAlloc` allocation.
- **CL_INVALID_EVENT_WAIT_LIST** if `event_wait_list` is `NULL` and `num_events_in_wait_list > 0`, or if `event_wait_list` is not `NULL` and `num_events_in_wait_list` is 0, or if event objects in `event_wait_list` are not valid events.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.6.2. Memory Consistency for SVM Allocations

To ensure memory consistency in SVM allocations, the program can rely on the guaranteed memory consistency at synchronization points. This consistency support already exists in OpenCL 1.x and can be used for coarse-grained SVM allocations or for fine-grained buffer SVM allocations; what SVM adds is the ability to share pointers between the host and all SVM devices.

In addition, sub-buffers can also be used to ensure that each device gets a consistent view of a SVM buffers memory when it is shared by multiple devices. For example, assume that two devices share a SVM pointer. The host can create a `cl_mem` buffer object using `clCreateBuffer` or `clCreateBufferWithProperties` with `CL_MEM_USE_HOST_PTR` and `host_ptr` set to the SVM pointer and then create two disjoint sub-buffers with starting virtual addresses `sb1_ptr` and `sb2_ptr`. These pointers (`sb1_ptr` and `sb2_ptr`) can be passed to kernels executing on the two devices. `clEnqueueMapBuffer` and `clEnqueueUnmapMemObject` and the existing access rules for memory objects ensure consistency for buffer regions (`sb1_ptr` and `sb2_ptr`) read and written by these kernels.

When the host and devices are able to use SVM atomic operations (i.e. `CL_DEVICE_SVM_ATOMICS` is set in `CL_DEVICE_SVM_CAPABILITIES`), these atomic operations can be used to provide memory consistency at a fine grain in a shared memory region. The effect of these operations is visible to the host and all devices with which that memory is shared.
5.7. Sampler Objects

A sampler object describes how to sample an image when the image is read in the kernel. The built-in functions to read from an image in a kernel take a sampler as an argument. The sampler arguments to the image read function can be sampler objects created using OpenCL functions and passed as argument values to the kernel or can be samplers declared inside a kernel. In this section we discuss how sampler objects are created using OpenCL functions.

5.7.1. Creating Sampler Objects

To create a sampler object, call the function

```c
// Provided by CL_VERSION_2_0
cl_sampler clCreateSamplerWithProperties(
    cl_context context,
    const cl_sampler_properties* sampler_properties,
    cl_int* errcode_ret);
```

- `context` must be a valid OpenCL context.
- `sampler_properties` specifies a list of sampler property names and their corresponding values. Each sampler property name is immediately followed by the corresponding desired value. The list is terminated with 0. The list of supported properties is described in the Sampler Properties table. If a supported property and its value is not specified in `sampler_properties`, its default value will be used. `sampler_properties` can be NULL in which case the default values for supported sampler properties will be used.
- `errcode_ret` will return an appropriate error code. If `errcode_ret` is NULL, no error code is returned.

<table>
<thead>
<tr>
<th>Sampler Property</th>
<th>Property Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_SAMPLER_NORMALIZED_COORDS</td>
<td>cl_bool</td>
<td>A boolean value that specifies whether the image coordinates specified are normalized or not. The default value (i.e. the value used if this property is not specified in <code>sampler_properties</code>) is CL_TRUE.</td>
</tr>
<tr>
<td>Sampler Property</td>
<td>Property Value</td>
<td>Description</td>
</tr>
<tr>
<td>----------------------------------</td>
<td>----------------------</td>
<td>--------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_SAMPLER_ADDRESSING_MODE</td>
<td>cl_addressing_mode</td>
<td>Specifies how out-of-range image coordinates are handled when reading from an image. Valid values are:</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_ADDRESS_NONE</strong> - Behavior is undefined for out-of-range image coordinates.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_ADDRESS_CLAMP_TO_EDGE</strong> - Out-of-range image coordinates are clamped to the edge of the image.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_ADDRESS_CLAMP</strong> - Out-of-range image coordinates are assigned a border color value.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_ADDRESS_REPEAT</strong> - Out-of-range image coordinates read from the image as if the image data were replicated in all dimensions.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_ADDRESS_MIRRORED_REPEAT</strong> - Out-of-range image coordinates read from the image as if the image data were replicated in all dimensions,</td>
</tr>
<tr>
<td></td>
<td></td>
<td>mirroring the image contents at the edge of each replication.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The default is <strong>CL_ADDRESS_CLAMP</strong>.</td>
</tr>
<tr>
<td>CL_SAMPLER_FILTER_MODE</td>
<td>cl_filter_mode</td>
<td>Specifies the type of filter that is applied when reading an image. Valid values are:</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_FILTER_NEAREST</strong> - Returns the image element nearest to the image coordinate.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_FILTER_LINEAR</strong> - Returns a weighted average of the four image elements nearest to the image coordinate.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The default value is <strong>CL_FILTER_NEAREST</strong>.</td>
</tr>
<tr>
<td>Sampler Property</td>
<td>Property Value</td>
<td>Description</td>
</tr>
<tr>
<td>----------------------------------------------</td>
<td>----------------</td>
<td>---------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_SAMPLER_MIP_FILTER_MODE_KHR</td>
<td>cl_filter_mode</td>
<td>Specifies the mipmap filter used when sampling from a mipmapped image. The available filter are:</td>
</tr>
<tr>
<td>provided by the cl_khr_mipmap_image extension.</td>
<td></td>
<td><strong>CL_FILTER_NEAREST</strong> - Use the nearest mipmap level to the image coordinate.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_FILTER_LINEAR</strong> - Use a weighted average of the two mipmap levels nearest to the image coordinate.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The default is <strong>CL_FILTER_NEAREST</strong>.</td>
</tr>
<tr>
<td>CL_SAMPLER_LOD_MIN_KHR</td>
<td>cl_float</td>
<td>Specifies the minimum value to which the computed level of detail lambda is clamped when sampling from a mipmapped image.</td>
</tr>
<tr>
<td>provided by the cl_khr_mipmap_image extension.</td>
<td></td>
<td>The default is <strong>0.0f</strong>.</td>
</tr>
<tr>
<td>CL_SAMPLER_LOD_MAX_KHR</td>
<td>cl_float</td>
<td>Specifies the maximum value to which the computed level of detail lambda is clamped when sampling from a mipmapped image.</td>
</tr>
<tr>
<td>provided by the cl_khr_mipmap_image extension.</td>
<td></td>
<td>The default is <strong>MAXFLOAT</strong>.</td>
</tr>
</tbody>
</table>

When the cl_khr_mipmap_image extension is supported, the sampler properties CL_SAMPLER_MIP_FILTER_MODE_KHR, CL_SAMPLER_LOD_MIN_KHR and CL_SAMPLER_LOD_MAX_KHR cannot be specified with any samplers initialized in the OpenCL program source. Only the default values for these properties will be used. To create a sampler with specific values for these properties, a sampler object must be created with clCreateSamplerWithProperties and passed as an argument to a kernel.

clCreateSamplerWithProperties returns a valid non-zero sampler object and errcode_ret is set to CL_SUCCESS if the sampler object is created successfully. Otherwise, it returns a NULL value with one of the following error values returned in errcode_ret:

- **CL_INVALID_CONTEXT** if context is not a valid context.
- **CL_INVALID_VALUE** if the property name in sampler_properties is not a supported property name, if the value specified for a supported property name is not valid, or if the same property name is specified more than once.
- **CL_INVALID_OPERATION** if images are not supported by any device associated with context (i.e. CL_DEVICE_IMAGE_SUPPORT specified in the Device Queries table is CL_FALSE).
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.
To create a sampler object, call the function

```c
// Provided by CL_VERSION_1_0
cl_sampler clCreateSampler(
    cl_context context,
    cl_bool normalized_coords,
    cl_addressing_mode addressing_mode,
    cl_filter_mode filter_mode,
    cl_int* errcode_ret);
```

- `clCreateSampler` is deprecated by version 2.0.

- `context` must be a valid OpenCL context.
- `normalized_coords` has the same interpretation as `CL_SAMPLER_NORMALIZED_COORDS` in the sampler creation properties table.
- `addressing_mode` has the same interpretation as `CL_SAMPLER_ADDRESSING_MODE` in the sampler creation properties table.
- `filter_mode` has the same interpretation as `CL_SAMPLER_FILTER_MODE` in the sampler creation properties table.
- `errcode_ret` will return an appropriate error code. If `errcode_ret` is `NULL`, no error code is returned.

`clCreateSampler` returns a valid non-zero sampler object and `errcode_ret` is set to `CL_SUCCESS` if the sampler object is created successfully. Otherwise, it returns a `NULL` value with one of the following error values returned in `errcode_ret`:

- `CL_INVALID_CONTEXT` if `context` is not a valid context.
- `CL_INVALID_VALUE` if `addressing_mode`, `filter_mode`, `normalized_coords` or a combination of these arguments are not valid.
- `CL_INVALID_OPERATION` if images are not supported by any device associated with `context` (i.e. `CL_DEVICE_IMAGE_SUPPORT` specified in the Device Queries table is `CL_FALSE`).
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

To retain a sampler object, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clRetainSampler(
    cl_sampler sampler);
```

- `sampler` specifies the sampler to be released.
The \textit{sampler} reference count is incremented. \texttt{clCreateSamplerWithProperties} and \texttt{clCreateSampler} perform an implicit retain.

\texttt{clRetainSampler} returns \texttt{CL\_SUCCESS} if the function is executed successfully. Otherwise, it returns one of the following errors:

- \texttt{CL\_INVALID\_SAMPLER} if \textit{sampler} is not a valid sampler object.
- \texttt{CL\_OUT\_OF\_RESOURCES} if there is a failure to allocate resources required by the OpenCL implementation on the device.
- \texttt{CL\_OUT\_OF\_HOST\_MEMORY} if there is a failure to allocate resources required by the OpenCL implementation on the host.

To release a sampler object, call the function

\begin{verbatim}
// Provided by CL\_VERSION\_1\_0
cl_int clReleaseSampler(
    cl_sampler sampler);
\end{verbatim}

- \textit{sampler} specifies the sampler to be released.

The \textit{sampler} reference count is decremented. The sampler object is deleted after the reference count becomes zero and commands queued for execution on a command-queue(s) that use \textit{sampler} have finished.

\texttt{clReleaseSampler} returns \texttt{CL\_SUCCESS} if the function is executed successfully. Otherwise, it returns one of the following errors:

- \texttt{CL\_INVALID\_SAMPLER} if \textit{sampler} is not a valid sampler object.
- \texttt{CL\_OUT\_OF\_RESOURCES} if there is a failure to allocate resources required by the OpenCL implementation on the device.
- \texttt{CL\_OUT\_OF\_HOST\_MEMORY} if there is a failure to allocate resources required by the OpenCL implementation on the host.

Using this function to release a reference that was not obtained by creating the object or by calling \texttt{clRetainSampler} causes undefined behavior.

### 5.7.2. Sampler Object Queries

To return information about a sampler object, call the function
cl_int clGetSamplerInfo(
    cl_sampler sampler,
    cl_sampler_info param_name,
    size_t param_value_size,
    void* param_value,
    size_t* param_value_size_ret);

- **sampler** specifies the sampler being queried.
- **param_name** specifies the information to query. The list of supported **param_name** types and the information returned in **param_value** by **clGetSamplerInfo** is described in the Sampler Object Queries table.
- **param_value** is a pointer to memory where the appropriate result being queried is returned. If **param_value** is **NULL**, it is ignored.
- **param_value_size** is used to specify the size in bytes of memory pointed to by **param_value**. This size must be ≥ size of return type as described in the Sampler Object Queries table.
- **param_value_size_ret** returns the actual size in bytes of data being queried by **param_name**. If **param_value_size_ret** is **NULL**, it is ignored.

Table 42. List of supported **param_names** by **clGetSamplerInfo**

<table>
<thead>
<tr>
<th>Sampler Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_SAMPLER_REFERENCE_COUNT</td>
<td>cl_uint</td>
<td>Return the sampler reference count.</td>
</tr>
<tr>
<td>CL_SAMPLER_CONTEXT</td>
<td>cl_context</td>
<td>Return the context specified when the sampler is created.</td>
</tr>
<tr>
<td>CL_SAMPLER_NORMALIZED_COORDS</td>
<td>cl_bool</td>
<td>Return the normalized coords value associated with sampler.</td>
</tr>
<tr>
<td>CL_SAMPLER_ADDRESSING_MODE</td>
<td>cl_addressing_mode</td>
<td>Return the addressing mode value associated with sampler.</td>
</tr>
<tr>
<td>CL_SAMPLER_FILTER_MODE</td>
<td>cl_filter_mode</td>
<td>Return the filter mode value associated with sampler.</td>
</tr>
<tr>
<td>Sampler Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>----------------------------------</td>
<td>-------------------------------</td>
<td>---------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_SAMPLER_PROPERTIES</td>
<td>cl_sampler_properties[]</td>
<td>Return the properties argument specified in clCreateSamplerWithProperties. If the properties argument specified in clCreateSamplerWithProperties used to create sampler was not NULL, the implementation must return the values specified in the properties argument in the same order and without including additional properties. If sampler was created using clCreateSampler, or if the properties argument specified in clCreateSamplerWithProperties was NULL, the implementation must return param_value_size_ret equal to 0, indicating that there are no properties to be returned.</td>
</tr>
</tbody>
</table>

clGetSamplerInfo returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_VALUE** if param_name is not valid, or if size in bytes specified by param_value_size is < size of return type as described in the Sampler Object Queries table and param_value is not NULL.
- **CL_INVALID_SAMPLER** if sampler is a not a valid sampler object.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.8. Program Objects

An OpenCL program consists of a set of kernels that are identified as functions declared with the __kernel qualifier in the program source. OpenCL programs may also contain auxiliary functions and constant data that can be used by kernel functions. The program executable can be generated online or offline by the OpenCL compiler for the appropriate target device(s).

A program object encapsulates the following information:

- An associated context.
- A program source or binary.
- The latest successfully built program executable, library or compiled binary, the list of devices for which the program executable, library or compiled binary is built, the build options used and a build log.
- The number of kernel objects currently attached.
5.8.1. Creating Program Objects

To create a program object for a context and load source code into that object, call the function

```c
// Provided by CL_VERSION_1_0
cl_program clCreateProgramWithSource(
    cl_context context,
    cl_uint count,
    const char** strings,
    const size_t* lengths,
    cl_int* errcode_ret);
```

- `context` must be a valid OpenCL context.
- `strings` is an array of `count` pointers to optionally null-terminated character strings that make up the source code.
- `lengths` argument is an array with the number of chars in each string (the string length). If an element in `lengths` is zero, its accompanying string is null-terminated. If `lengths` is `NULL`, all strings in the `strings` argument are considered null-terminated. Any length value passed in that is greater than zero excludes the null terminator in its count.
- `errcode_ret` will return an appropriate error code. If `errcode_ret` is `NULL`, no error code is returned.

The source code specified by `strings` will be loaded into the program object.

The devices associated with the program object are the devices associated with `context`. The source code specified by `strings` is either an OpenCL C program source, header or implementation-defined source for custom devices that support an online compiler. OpenCL C++ is not supported as an online-compiled kernel language through this interface.

`clCreateProgramWithSource` returns a valid non-zero program object and `errcode_ret` is set to `CL_SUCCESS` if the program object is created successfully. Otherwise, it returns a `NULL` value with one of the following error values returned in `errcode_ret`:

- `CL_INVALID_CONTEXT` if `context` is not a valid context.
- `CL_INVALID_VALUE` if `count` is zero or if `strings` or any entry in `strings` is `NULL`.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

To create a program object for a context and load code in an intermediate language into that object, call the function
clCreateProgramWithIL is missing before version 2.1.

or the equivalent

clCreateProgramWithILKHR is provided by the cl_khr_il_program extension.

- **context** must be a valid OpenCL context.
- **il** is a pointer to a block of memory containing SPIR-V or an implementation-defined intermediate language.
- **length** is the length of the block pointed to by il.
- **errcode_ret** will return an appropriate error code. If errcode_ret is NULL, no error code is returned.

The intermediate language pointed to by il and with length in bytes length will be loaded into the program object. The devices associated with the program object are the devices associated with context.

clCreateProgramWithIL returns a valid non-zero program object and errcode_ret is set to CL_SUCCESS if the program object is created successfully. Otherwise, it returns a NULL value with one of the following error values returned in errcode_ret:

- CL_INVALID_CONTEXT if context is not a valid context.
- CL_INVALID_OPERATION if no devices in context support intermediate language programs.
- CL_INVALID_VALUE if il is NULL or if length is zero.
- CL_INVALID_VALUE if the length-byte block of memory pointed to by il does not contain well-formed intermediate language input that can be consumed by the OpenCL runtime.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL
To create a program object for a context and load binary bits into that object, call the function

```c
// Provided by CL_VERSION_1_0
cl_program clCreateProgramWithBinary(
    cl_context context,
    cl_uint num_devices,
    const cl_device_id* device_list,
    const size_t* lengths,
    const unsigned char** binaries,
    cl_int* binary_status,
    cl_int* errcode_ret);
```

- `context` must be a valid OpenCL context.
- `device_list` is a pointer to a list of devices that are in `context`. `device_list` must be a non-NULL value. The binaries are loaded for devices specified in this list.
- `num_devices` is the number of devices listed in `device_list`.
- `lengths` is an array of the size in bytes of the program binaries to be loaded for devices specified by `device_list`.
- `binaries` is an array of pointers to program binaries to be loaded for devices specified by `device_list`. For each device given by `device_list[i]`, the pointer to the program binary for that device is given by `binaries[i]` and the length of this corresponding binary is given by `lengths[i]`. `lengths[i]` cannot be zero and `binaries[i]` cannot be a NULL pointer.
- `binary_status` returns whether the program binary for each device specified in `device_list` was loaded successfully or not. It is an array of `num_devices` entries and returns `CL_SUCCESS` in `binary_status[i]` if binary was successfully loaded for device specified by `device_list[i]`; otherwise returns `CL_INVALID_VALUE` if `lengths[i]` is zero or if `binaries[i]` is a NULL value or `CL_INVALID_BINARY` in `binary_status[i]` if program binary is not a valid binary for the specified device. If `binary_status` is NULL, it is ignored.
- `errcode_ret` will return an appropriate error code. If `errcode_ret` is NULL, no error code is returned.

The devices associated with the program object will be the list of devices specified by `device_list`. The list of devices specified by `device_list` must be devices associated with `context`.

The program binaries specified by `binaries` will be loaded into the program object. They contain bits that describe one of the following:

- a program executable to be run on the device(s) associated with `context`,
- a compiled program for device(s) associated with `context`, or
- a library of compiled programs for device(s) associated with `context`.

The program binary can consist of either or both:

- Device-specific code and/or,
• Implementation-specific intermediate representation (IR) which will be converted to the device-specific code.

OpenCL allows applications to create a program object using the program source or binary and build appropriate program executables. This can be very useful as it allows applications to load program source and then compile and link to generate a program executable online on its first instance for appropriate OpenCL devices in the system. These executables can now be queried and cached by the application. The cached executables can be read and loaded by the application, which can help significantly reduce the application initialization time.

If the cl_khr_spir extension is supported, clCreateProgramWithBinary can be used to load a SPIR binary. Once a program object has been created from a SPIR binary, clBuildProgram can be called to build a program executable or clCompileProgram can be called to compile the SPIR binary.

clCreateProgramWithBinary returns a valid non-zero program object and errcode_ret is set to CL_SUCCESS if the program object is created successfully. Otherwise, it returns a NULL value with one of the following error values returned in errcode_ret:

• CL_INVALID_CONTEXT if context is not a valid context.
• CL_INVALID_VALUE if device_list is NULL or num_devices is zero.
• CL_INVALID_DEVICE if any device in device_list is not in the list of devices associated with context.
• CL_INVALID_VALUE if lengths or binaries is NULL or if any entry in lengths[i] is zero or binaries[i] is NULL.
• CL_INVALID_BINARY if an invalid program binary was encountered for any device. binary_status will return specific status for each device.
• CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
• CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

To create a program object for a context and loads the information related to the built-in kernels into that object, call the function

```c
// Provided by CL_VERSION_1_2
cl_program clCreateProgramWithBuiltInKernels(
    cl_context context,
    cl_uint num_devices,
    const cl_device_id* device_list,
    const char* kernel_names,
    cl_int* errcode_ret);
```

clCreateProgramWithBuiltInKernels is missing before version 1.2.

• context must be a valid OpenCL context.
• num_devices is the number of devices listed in device_list.
**device_list** is a pointer to a list of devices that are in **context**. **device_list** must be a non-**NULL** value. The built-in kernels are loaded for devices specified in this list.

**kernel_names** is a semi-colon separated list of built-in kernel names.

The devices associated with the program object will be the list of devices specified by **device_list**. The list of devices specified by **device_list** must be devices associated with **context**.

**clCreateProgramWithBuiltInKernels** returns a valid non-zero program object and **errcode_ret** is set to **CL_SUCCESS** if the program object is created successfully. Otherwise, it returns a **NULL** value with one of the following error values returned in **errcode_ret**:

- **CL_INVALID_CONTEXT** if **context** is not a valid context.
- **CL_INVALID_VALUE** if **device_list** is **NULL** or **num_devices** is zero.
- **CL_INVALID_VALUE** if **kernel_names** is **NULL** or **kernel_names** contains a kernel name that is not supported by any of the devices in **device_list**.
- **CL_INVALID_DEVICE** if any device in **device_list** is not in the list of devices associated with **context**.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.8.2. Retaining and Releasing Program Objects

To retain a program object, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clRetainProgram(
    cl_program program);
```

- **program** is the program object to be retained.

The **program** reference count is incremented. All APIs that create a program do an implicit retain.

**clRetainProgram** returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_PROGRAM** if **program** is not a valid program object.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To release a program object, call the function
• *program* is the program object to be released.

The *program* reference count is decremented. The program object is deleted after all kernel objects associated with *program* have been deleted and the *program* reference count becomes zero.

`clReleaseProgram` returns *CL_SUCCESS* if the function is executed successfully. Otherwise, it returns one of the following errors:

• *CL_INVALID_PROGRAM* if *program* is not a valid program object.
• *CL_OUT_OF_RESOURCES* if there is a failure to allocate resources required by the OpenCL implementation on the device.
• *CL_OUT_OF_HOST_MEMORY* if there is a failure to allocate resources required by the OpenCL implementation on the host.

Using this function to release a reference that was not obtained by creating the object or by calling `clRetainProgram` causes undefined behavior.

To register a callback function with a program object that is called when the program object is destroyed, call the function

```
// Provided by CL_VERSION_2_2
cl_int clSetProgramReleaseCallback(
  cl_program program,
  void (CL_CALLBACK* pfn_notify)(cl_program program, void* user_data),
  void* user_data);
```

`clSetProgramReleaseCallback` is missing before version 2.2 and deprecated by version 3.0.

• *program* specifies the memory object to register the callback to.

• *pfn_notify* is the callback function to register. This callback function may be called asynchronously by the OpenCL implementation. It is the application’s responsibility to ensure that the callback function is thread-safe. The parameters to this callback function are:

  ◦ *program* is the program being deleted. When the callback function is called by the implementation, this program object is not longer valid. *program* is only provided for reference purposes.

  ◦ *user_data* is a pointer to user supplied data.

• *user_data* will be passed as the *user_data* argument when *pfn_notify* is called. *user_data* can be NULL.

Each call to `clSetProgramReleaseCallback` registers the specified callback function on a callback
stack associated with program. The registered callback functions are called in the reverse order in which they were registered. The registered callback functions are called after destructors (if any) for program scope global variables (if any) are called and before the program object is deleted. This provides a mechanism for an application to be notified when destructors for program scope global variables are complete.

**clSetProgramReleaseCallback** may unconditionally return an error if no devices in the context associated with program support destructors for program scope global variables. Support for constructors and destructors for program scope global variables is required only for OpenCL 2.2 devices.

**clSetProgramReleaseCallback** returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_PROGRAM** if program is not a valid program object.
- **CL_INVALID_OPERATION** if no devices in the context associated with program support destructors for program scope global variables.
- **CL_INVALID_VALUE** if pfn_notify is **NULL**.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.8.3. Setting SPIR-V Specialization Constants

Specialization constants are **missing before** version 2.2.

To set the value of a specialization constant, call the function

```c
// Provided by CL_VERSION_2_2
cl_int clSetProgramSpecializationConstant(
    cl_program program,
    cl_uint spec_id,
    size_t spec_size,
    const void* spec_value);
```

- **program** must be a valid OpenCL program created from an intermediate language (e.g. SPIR-V).
- **spec_id** identifies the specialization constant whose value will be set.
- **spec_size** specifies the size in bytes of the data pointed to by **spec_value**. This should be 1 for boolean constants. For all other constant types this should match the size of the specialization constant in the module.
- **spec_value** is a pointer to the memory location that contains the value of the specialization constant. The data pointed to by **spec_value** are copied and can be safely reused by the
application after clSetProgramSpecializationConstant returns. This specialization value will be used by subsequent calls to clBuildProgram until another call to clSetProgramSpecializationConstant changes it. If a specialization constant is a boolean constant, spec_value should be a pointer to a cl_uchar value. A value of zero will set the specialization constant to false; any other value will set it to true.

Calling this function multiple times for the same specialization constant shall cause the last provided value to override any previously specified value. The values are used by a subsequent clBuildProgram call for the program.

Application is not required to provide values for every specialization constant contained in the module. If the value is not set by this API call, default values will be used during the build.

clSetProgramSpecializationConstant returns CL_SUCCESS if the function is executed successfully.

Otherwise, it returns one of the following errors:

- CL_INVALID_PROGRAM if program is not a valid program object created from an intermediate language (e.g. SPIR-V), or if the intermediate language does not support specialization constants.
- CL_INVALID_OPERATION if no devices associated with program support intermediate language programs.
- CL_COMPILER_NOT_AVAILABLE if program is created with clCreateProgramWithIL and a compiler is not available, i.e. CL_DEVICE_COMPILER_AVAILABLE specified in the Device Queries table is set to CL_FALSE.
- CL_INVALID_SPEC_ID if spec_id is not a valid specialization constant identifier.
- CL_INVALID_VALUE if spec_size does not match the size of the specialization constant in the module, or if spec_value is NULL.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

5.8.4. Building Program Executables

To build (compile & link) a program executable, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clBuildProgram(
    cl_program program,
    cl_uint num_devices,
    const cl_device_id* device_list,
    const char* options,
    void (CL_CALLBACK* pfn_notify)(cl_program program, void* user_data),
    void* user_data);
```

- program is the program object.
• *device_list* is a pointer to a list of devices associated with *program*. If *device_list* is a `NULL` value, the program executable is built for all devices associated with *program* for which a source or binary has been loaded. If *device_list* is a non-`NULL` value, the program executable is built for devices specified in this list for which a source or binary has been loaded.

• *num_devices* is the number of devices listed in *device_list*.

• *options* is a pointer to a null-terminated string of characters that describes the build options to be used for building the program executable. The list of supported options is described in Compiler Options. If the program was created using `clCreateProgramWithBinary` and *options* is a `NULL` pointer, the program will be built as if *options* were the same as when the program binary was originally built. If the program was created using `clCreateProgramWithBinary` and *options* string contains anything other than the same options in the same order (whitespace ignored) as when the program binary was originally built, then the behavior is implementation-defined. Otherwise, if *options* is a `NULL` pointer then it will have the same result as the empty string.

• *pfn_notify* is a function pointer to a notification routine. The notification routine is a callback function that an application can register and which will be called when the program executable has been built (successfully or unsuccessfully). If *pfn_notify* is not `NULL`, `clBuildProgram` does not need to wait for the build to complete and can return immediately once the build operation can begin. Any state changes of the program object that result from calling `clBuildProgram` (e.g. build status or log) will be observable from this callback function. The build operation can begin if the context, program whose sources are being compiled and linked, list of devices and build options specified are all valid and appropriate host and device resources needed to perform the build are available. If *pfn_notify* is `NULL`, `clBuildProgram` does not return until the build has completed. This callback function may be called asynchronously by the OpenCL implementation. It is the application's responsibility to ensure that the callback function is thread-safe.

• *user_data* will be passed as an argument when *pfn_notify* is called. *user_data* can be `NULL`.

The program executable is built from the program source or binary for all the devices, or a specific device(s) in the OpenCL context associated with *program*. OpenCL allows program executables to be built using the source or the binary. `clBuildProgram` must be called for *program* created using `clCreateProgramWithSource`, `clCreateProgramWithIL`, or `clCreateProgramWithBinary` to build the program executable for one or more devices associated with *program*. If *program* is created with `clCreateProgramWithBinary`, then the program binary must be an executable binary (not a compiled binary or library).

The executable binary can be queried using `clGetProgramInfo(*program*, CL_PROGRAM_BINARIES, ...) and can be specified to `clCreateProgramWithBinary` to create a new program object.

`clBuildProgram` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

• `CL_INVALID_PROGRAM` if *program* is not a valid program object.

• `CL_INVALID_VALUE` if *device_list* is `NULL` and *num_devices* is greater than zero, or if *device_list* is not `NULL` and *num_devices* is zero.

• `CL_INVALID_VALUE` if *pfn_notify* is `NULL` but *user_data* is not `NULL`. 


• **CL_INVALID_DEVICE** if any device in `device_list` is not in the list of devices associated with `program`.

• **CL_INVALID_BINARY** if `program` is created with `clCreateProgramWithBinary` and devices listed in `device_list` do not have a valid program binary loaded.

• **CL_INVALID_BUILD_OPTIONS** if the build options specified by `options` are invalid.

• **CL_COMPILER_NOT_AVAILABLE** if `program` is created with `clCreateProgramWithILKHR`, `clCreateProgramWithSource` or `clCreateProgramWithIL` and a compiler is not available, i.e. `CL_DEVICE_COMPILER_AVAILABLE` specified in the Device Queries table is set to `CL_FALSE`.

• **CL_BUILD_PROGRAM_FAILURE** if there is a failure to build the program executable. This error will be returned if `clBuildProgram` does not return until the build has completed.

• **CL_INVALID_OPERATION** if the build of a program executable for any of the devices listed in `device_list` by a previous call to `clBuildProgram` for `program` has not completed.

• **CL_INVALID_OPERATION** if there are kernel objects attached to `program`.

• **CL_INVALID_OPERATION** if `program` was not created with `clCreateProgramWithSource`, `clCreateProgramWithIL` or `clCreateProgramWithBinary`.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.8.5. Separate Compilation and Linking of Programs

Separate compilation and linking are **missing before** version 1.2.

OpenCL programs are compiled and linked to support the following:

• Separate compilation and link stages. Program sources can be compiled to generate a compiled binary object and linked in a separate stage with other compiled program objects to the program executable.

• Embedded headers. In OpenCL 1.0 and 1.1, the I build option could be used to specify the list of directories to be searched for headers files that are included by a program source(s). OpenCL 1.2 extends this by allowing the header sources to come from program objects instead of just header files.

• Libraries. The linker can be used to link compiled objects and libraries into a program executable or to create a library of compiled binaries.

To compile a program’s source for all the devices or a specific device(s) in the OpenCL context associated with the program, call the function
// Provided by CL_VERSION_1_2

```c
cl_int clCompileProgram(
    cl_program program,
    cl_uint num_devices,
    const cl_device_id* device_list,
    const char* options,
    cl_uint num_input_headers,
    const cl_program* input_headers,
    const char** header_include_names,
    void (CL_CALLBACK* pfn_notify)(cl_program program, void* user_data),
    void* user_data);
```

---

⚠️ **clCompileProgram** is missing before version 1.2.

- **program** is the program object that is the compilation target.
- **device_list** is a pointer to a list of devices associated with **program**. If **device_list** is a **NULL** value, the compile is performed for all devices associated with **program**. If **device_list** is a non-**NULL** value, the compile is performed for devices specified in this list.
- **num_devices** is the number of devices listed in **device_list**.
- **options** is a pointer to a null-terminated string of characters that describes the compilation options to be used for building the program executable. If **options** is a **NULL** pointer then it will have the same result as the empty string. Certain options are ignored when **program** is created with IL. The list of supported options is as described in Compiler Options.
- **num_input_headers** specifies the number of programs that describe headers in the array referenced by **input_headers**.
- **input_headers** is an array of program embedded headers created with **clCreateProgramWithSource**.
- **header_include_names** is an array that has a one to one correspondence with **input_headers**. Each entry in **header_include_names** specifies the include name used by source in **program** that comes from an embedded header. The corresponding entry in **input_headers** identifies the program object which contains the header source to be used. The embedded headers are first searched before the headers in the list of directories specified by the -I compile option (as described in Preprocessor options). If multiple entries in **header_include_names** refer to the same header name, the first one encountered will be used.
- **pfn_notify** is a function pointer to a notification routine. The notification routine is a callback function that an application can register and which will be called when the program executable has been built (successfully or unsuccessfully). If **pfn_notify** is not **NULL**, **clCompileProgram** does not need to wait for the compiler to complete and can return immediately once the compilation can begin. Any state changes of the program object that result from calling **clCompileProgram** (e.g. compile status or log) will be observable from this callback function. The compilation can begin if the context, program whose sources are being compiled, list of devices, input headers, programs that describe input headers and compiler options specified are all valid and appropriate host and device resources needed to perform the compile are available. If **pfn_notify** is **NULL**, **clCompileProgram** does not return until the compiler has completed. This
callback function may be called asynchronously by the OpenCL implementation. It is the application's responsibility to ensure that the callback function is thread-safe.

- **user_data** will be passed as an argument when **pfn_notify** is called. **user_data** can be **NULL**.

The pre-processor runs before the program sources are compiled. The compiled binary is built for all devices associated with **program** or the list of devices specified. The compiled binary can be queried using **clGetProgramInfo**( **program**, **CL_PROGRAM_BINARIES**, ...) and can be passed to **clCreateProgramWithBinary** to create a new program object.

If **program** was created using **clCreateProgramWithIL**, then **num_input_headers**, **input_headers**, and **header_include_names** are ignored.

For example, consider the following program source:

```c
#include <foo.h>
#include <mydir/myinc.h>
__kernel void
image_filter (int n, int m,
    __constant float *filter_weights,
    __read_only image2d_t src_image,
    __write_only image2d_t dst_image)
{
    ...
}
```

This kernel includes two headers foo.h and mydir/myinc.h. The following describes how these headers can be passed as embedded headers in program objects:

```c
cl_program foo_pg = clCreateProgramWithSource(context,
    1, &foo_header_src, NULL, &err);  
cl_program myinc_pg = clCreateProgramWithSource(context,
    1, &myinc_header_src, NULL, &err);  

// lets assume the program source described above is given
// by program_A and is loaded via clCreateProgramWithSource
cl_program input_headers[2] = { foo_pg, myinc_pg };  
char * input_header_names[2] = { foo.h, mydir/myinc.h };  
clCompileProgram(program_A,
    0, NULL, // num_devices & device_list
    NULL,   // compile_options
    2,      // num_input_headers
    input_headers,
    input_header_names,
    NULL, NULL); // pfn_notify & user_data
```

**clCompileProgram** returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:
• **CL_INVALID_PROGRAM** if *program* is not a valid program object.

• **CL_INVALID_VALUE** if *device_list* is **NULL** and *num_devices* is greater than zero, or if *device_list* is not **NULL** and *num_devices* is zero.

• **CL_INVALID_VALUE** if *num_input_headers* is zero and *header_include_names* or *input_headers* are **NULL** or if *num_input_headers* is not zero and *header_include_names* or *input_headers* are **NULL**.

• **CL_INVALID_VALUE** if *pfn_notify* is **NULL** but *user_data* is not **NULL**.

• **CL_INVALID_DEVICE** if device in *device_list* is not in the list of devices associated with *program*.

• **CL_INVALID_COMPILER_OPTIONS** if the compiler options specified by *options* are invalid.

• **CL_INVALID_OPERATION** if the compilation or build of a program executable for any of the devices listed in *device_list* by a previous call to **clCompileProgram** or **clBuildProgram** for *program* has not completed.

• **CL_COMPILER_NOT_AVAILABLE** if a compiler is not available, i.e. **CL_DEVICE_COMPILER_AVAILABLE** specified in the Device Queries table is set to **CL_FALSE**.

• **CL_COMPILE_PROGRAM_FAILURE** if there is a failure to compile the program source. This error will be returned if **clCompileProgram** does not return until the compile has completed.

• **CL_INVALID_OPERATION** if there are kernel objects attached to *program*.

• **CL_INVALID_OPERATION** if *program* has no source or IL available, i.e. it has not been created with one of
  - **clCreateProgramWithIL** or **clCreateProgramWithILKHR**
  - **clCreateProgramWithBinary** where `-x spir` is present in *options*, if the **cl_khr_spir** extension is supported.
  - **clCreateProgramWithSource**

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To link a set of compiled program objects and libraries for all the devices or a specific device(s) in the OpenCL context and create a library or executable, call the function

```c
// Provided by CL_VERSION_1_2
cl_program cllinkProgram(
    cl_context context,
    cl_uint num_devices,
    const cl_device_id* device_list,
    const char* options,
    cl_uint num_input_programs,
    const cl_program* input_programs,
    void (CL_CALLBACK* pfn_notify)(cl_program program, void* user_data),
    void* user_data,
    cl_int* errcode_ret);
```
clLinkProgram is missing before version 1.2.

- `context` must be a valid OpenCL context.

- `device_list` is a pointer to a list of devices that are in `context`. If `device_list` is a `NULL` value, the link is performed for all devices associated with `context` for which a compiled object is available. If `device_list` is a non-`NULL` value, the link is performed for devices specified in this list for which a compiled object is available.

- `num_devices` is the number of devices listed in `device_list`.

- `options` is a pointer to a null-terminated string of characters that describes the link options to be used for building the program executable. The list of supported options is as described in Linker Options. If the program was created using `clCreateProgramWithBinary` and `options` is a `NULL` pointer, the program will be linked as if `options` were the same as when the program binary was originally built. If the program was created using `clCreateProgramWithBinary` and `options` string contains anything other than the same options in the same order (whitespace ignored) as when the program binary was originally built, then the behavior is implementation-defined. Otherwise, if `options` is a `NULL` pointer then it will have the same result as the empty string.

- `num_input_programs` specifies the number of programs in array referenced by `input_programs`.

- `input_programs` is an array of program objects that are compiled binaries or libraries that are to be linked to create the program executable. For each device in `device_list` or if `device_list` is `NULL` the list of devices associated with context, the following cases occur:
  - All programs specified by `input_programs` contain a compiled binary or library for the device. In this case, a link is performed to generate a program executable for this device.
  - None of the programs contain a compiled binary or library for that device. In this case, no link is performed and there will be no program executable generated for this device.
  - All other cases will return a `CL_INVALID_OPERATION` error.

- `pfn_notify` is a function pointer to a notification routine. The notification routine is a callback function that an application can register and which will be called when the program executable has been built (successfully or unsuccessfully).

- `user_data` will be passed as an argument when `pfn_notify` is called. `user_data` can be `NULL`.

If `pfn_notify` is not `NULL`, `clLinkProgram` does not need to wait for the linker to complete, and can return immediately once the linking operation can begin. Once the linker has completed, the `pfn_notify` callback function is called which returns the program object returned by `clLinkProgram`. Any state changes of the program object that result from calling `clLinkProgram` (e.g. link status or log) will be observable from this callback function. This callback function may be called asynchronously by the OpenCL implementation. It is the application’s responsibility to ensure that the callback function is thread-safe.

If `pfn_notify` is `NULL`, `clLinkProgram` does not return until the linker has completed.

clLinkProgram creates a new program object which contains the library or executable. The library or executable binary can be queried using `clGetProgramInfo(program, CL_PROGRAM_BINARIES, ....)` and can be specified to `clCreateProgramWithBinary` to create a new program object.
The devices associated with the returned program object will be the list of devices specified by
\textit{device\_list} or if \textit{device\_list} is \texttt{NULL} it will be the list of devices associated with \textit{context}.

The linking operation can begin if the context, list of devices, input programs and linker options
specified are all valid and appropriate host and device resources needed to perform the link are
available. If the linking operation can begin, \texttt{clLinkProgram} returns a valid non-zero program
object.

If \textit{pfn\_notify} is \texttt{NULL}, \texttt{errcode\_ret} will be set to \texttt{CL\_SUCCESS} if the link operation was successful and
\texttt{CL\_LINK\_PROGRAM\_FAILURE} if there is a failure to link the compiled binaries and/or libraries.

If \textit{pfn\_notify} is not \texttt{NULL}, \texttt{clLinkProgram} does not have to wait until the linker to complete and can
return \texttt{CL\_SUCCESS} in \texttt{errcode\_ret} if the linking operation can begin. The \textit{pfn\_notify} callback function
will return a \texttt{CL\_SUCCESS} or \texttt{CL\_LINK\_PROGRAM\_FAILURE} if the linking operation was successful or not.

Otherwise \texttt{clLinkProgram} returns a \texttt{NULL} program object with an appropriate error in \texttt{errcode\_ret}.
The application should query the linker status of this program object to check if the link was
successful or not. The list of errors that can be returned are:

- \texttt{CL\_INVALID\_CONTEXT} if \textit{context} is not a valid context.
- \texttt{CL\_INVALID\_VALUE} if \textit{device\_list} is \texttt{NULL} and \texttt{num\_devices} is greater than zero, or if \textit{device\_list} is not
  \texttt{NULL} and \texttt{num\_devices} is zero.
- \texttt{CL\_INVALID\_VALUE} if \texttt{num\_input\_programs} is zero and \textit{input\_programs} is \texttt{NULL} or if
  \texttt{num\_input\_programs} is zero and \textit{input\_programs} is not \texttt{NULL} or if \texttt{num\_input\_programs} is not
  zero and \textit{input\_programs} is \texttt{NULL}.
- \texttt{CL\_INVALID\_PROGRAM} if programs specified in \textit{input\_programs} are not valid program objects.
- \texttt{CL\_INVALID\_VALUE} if \textit{pfn\_notify} is \texttt{NULL} but \textit{user\_data} is not \texttt{NULL}.
- \texttt{CL\_INVALID\_DEVICE} if any device in \textit{device\_list} is not in the list of devices associated with \textit{context}.
- \texttt{CL\_INVALID\_LINKER\_OPTIONS} if the linker options specified by \textit{options} are invalid.
- \texttt{CL\_INVALID\_OPERATION} if the compilation or build of a program executable for any of the devices
  listed in \textit{device\_list} by a previous call to \texttt{clCompileProgram} or \texttt{clBuildProgram} for \textit{program}
  has not completed.
- \texttt{CL\_INVALID\_OPERATION} if the rules for devices containing compiled binaries or libraries as
  described in \textit{input\_programs} argument above are not followed.
- \texttt{CL\_LINKER\_NOT\_AVAILABLE} if a linker is not available, i.e. \texttt{CL\_DEVICE\_LINKER\_AVAILABLE} specified in
  the \texttt{Device Queries} table is set to \texttt{CL\_FALSE}.
- \texttt{CL\_LINK\_PROGRAM\_FAILURE} if there is a failure to link the compiled binaries and/or libraries.
- \texttt{CL\_OUT\_OF\_RESOURCES} if there is a failure to allocate resources required by the OpenCL
  implementation on the device.
- \texttt{CL\_OUT\_OF\_HOST\_MEMORY} if there is a failure to allocate resources required by the OpenCL
  implementation on the host.
5.8.6. Compiler Options

The compiler options are categorized as pre-processor options, options for math intrinsics, options that control optimization and miscellaneous options. This specification defines a standard set of options that must be supported by the compiler when building program executables online or offline from OpenCL C/C++ or, where relevant, from an IL. These may be extended by a set of vendor- or platform-specific options.

5.8.6.1. Preprocessor Options

These options control the OpenCL C/C++ preprocessor which is run on each program source before actual compilation. These options are ignored for programs created with IL.

-D name

Predefine name as a macro, with definition 1.

-D name=definition

The contents of definition are tokenized and processed as if they appeared during translation phase three in a #define directive. In particular, the definition will be truncated by embedded newline characters.

-D options are processed in the order they are given in the options argument to clBuildProgram or clCompileProgram. Note that a space is required between the -D option and the symbol it defines, otherwise behavior is implementation-defined.

-I dir

Add the directory dir to the list of directories to be searched for header files. dir can optionally be enclosed in double quotes.

This option is not portable due to its dependency on host file system and host operating system. It is supported for backwards compatibility with previous OpenCL versions. Developers are encouraged to create and use explicit header objects by means of clCompileProgram followed by clLinkProgram.

5.8.6.2. Math Intrinsics Options

These options control compiler behavior regarding floating-point arithmetic. These options trade off between speed and correctness.

-cl-single-precision-constant

This option forces implicit conversions of double-precision floating-point literals to single precision. This option is ignored for programs created with IL.

-cl-denoms-are-zero

This option controls how single precision and double precision denormalized numbers are handled. If specified as a build option, the single precision denormalized numbers may be flushed to zero; double precision denormalized numbers may also be flushed to zero if the optional extension for double precision is supported. This is intended to be a performance hint and the OpenCL compiler can choose not to flush denorms to zero if the device supports single
precision (or double precision) denormalized numbers.

This option is ignored for single precision numbers if the device does not support single precision denormalized numbers i.e. `CL_FP_DENORM` bit is not set in `CL_DEVICE_SINGLE_FP_CONFIG`.

This option is ignored for double precision numbers if the device does not support double precision or if it does support double precision but not double precision denormalized numbers i.e. `CL_FP_DENORM` bit is not set in `CL_DEVICE_DOUBLE_FP_CONFIG`.

This flag only applies for scalar and vector single precision floating-point variables and computations on these floating-point variables inside a program. It does not apply to reading from or writing to image objects.

`-cl-fp32-correctly-rounded-divide-sqrt`

The `-cl-fp32-correctly-rounded-divide-sqrt` build option to `clBuildProgram` or `clCompileProgram` allows an application to specify that single precision floating-point divide (x/y and 1/x) and sqrt used in the program source are correctly rounded. If this build option is not specified, the minimum numerical accuracy of single precision floating-point divide and sqrt are as defined in the OpenCL C or OpenCL SPIR-V Environment specifications.

This build option can only be specified if the `CL_FP_CORRECTLY_ROUNDED_DIVIDE_SQRT` is set in `CL_DEVICE_SINGLE_FP_CONFIG` (as defined in the Device Queries table) for devices that the program is being build. `clBuildProgram` or `clCompileProgram` will fail to compile the program for a device if the `-cl-fp32-correctly-rounded-divide-sqrt` option is specified and `CL_FP_CORRECTLY_ROUNDED_DIVIDE_SQRT` is not set for the device.

Note: This option is missing before version 1.2.

5.8.6.3. Optimization Options

These options control various sorts of optimizations. Turning on optimization flags makes the compiler attempt to improve the performance and/or code size at the expense of compilation time and possibly the ability to debug the program.

`-cl-opt-disable`

This option disables all optimizations. The default is optimizations are enabled.

`-cl-strict-aliasing`

This option allows the compiler to assume the strictest aliasing rules.

Note: This option is deprecated by version 1.1.

`-cl-uniform-work-group-size`

This requires that the global work-size be a multiple of the work-group size specified to `clEnqueueNDRangeKernel`. Allow optimizations that are made possible by this restriction.

Note: This option is missing before version 2.0.

`-cl-no-subgroup-ifp`

This indicates that kernels in this program do not require sub-groups to make independent
forward progress. Allows optimizations that are made possible by this restriction. This option has no effect for devices that do not support independent forward progress for sub-groups.

Note: This option is missing before version 2.1.

The following options control compiler behavior regarding floating-point arithmetic. These options trade off between performance and correctness and must be specifically enabled. These options are not turned on by default since it can result in incorrect output for programs which depend on an exact implementation of IEEE 754 rules/specifications for math functions.

-cl-mad-enable

Allow a * b + c to be replaced by a mad instruction. The mad instruction may compute a * b + c with reduced accuracy in the embedded profile. See the OpenCL C or OpenCL SPIR-V Environment specification for accuracy details. On some hardware the mad instruction may provide better performance than the expanded computation.

-cl-no-signed-zeros

Allow optimizations for floating-point arithmetic that ignore the signedness of zero. IEEE 754 arithmetic specifies the distinct behavior of +0.0 and -0.0 values, which then prohibits simplification of expressions such as x + 0.0 or 0.0 * x (even with -cl-finite-math-only). This option implies that the sign of a zero result is not significant.

-cl-unsafe-math-optimizations

Allow optimizations for floating-point arithmetic that (a) assume that arguments and results are valid, (b) may violate the IEEE 754 standard, (c) assume relaxed OpenCL numerical compliance requirements as defined in the unsafe math optimization section of the OpenCL C or OpenCL SPIR-V Environment specifications, and (d) may violate edge case behavior in the OpenCL C or OpenCL SPIR-V Environment specifications. This option includes the -cl-no-signed-zeros, -cl-mad-enable, and -cl-denorms-are-zero options.

-cl-finite-math-only

Allow optimizations for floating-point arithmetic that assume that arguments and results are not NaNs, +Inf, -Inf. This option may violate the OpenCL numerical compliance requirements for single precision and double precision floating-point, as well as edge case behavior.

-cl-fast-relaxed-math

Sets the optimization options -cl-finite-math-only and -cl-unsafe-math-optimizations. This option causes the preprocessor macro __FAST_RELAXED_MATH__ to be defined in the OpenCL program.

5.8.6.4. Options to Request or Suppress Warnings

Warnings are diagnostic messages that report constructions which are not inherently erroneous but which are risky or suggest there may have been an error. The following language-independent options do not enable specific warnings but control the kinds of diagnostics produced by the OpenCL compiler. These options are ignored for programs created with IL.

-w

Inhibit all warning messages.
5.8.6.5. Options Controlling the OpenCL C Version

The following option controls the version of OpenCL C that the compiler accepts. These options are ignored for programs created with IL.

-cl-std=

Determine the OpenCL C language version to use. A value for this option must be provided. Valid values are:

- **CL1.1**: Support OpenCL C 1.1 language features defined in section 6 of the OpenCL 1.1 specification or in the unified OpenCL C specification.
- **CL1.2**: Support OpenCL C 1.2 language features defined in section 6 of the OpenCL 1.2 specification or in the unified OpenCL C specification.
- **CL2.0**: Support OpenCL C 2.0 language features defined in the OpenCL C 2.0 specification or in the unified OpenCL C specification.
- **CL3.0**: Support OpenCL C 3.0 language features defined in the unified OpenCL C specification.

Calls to `clBuildProgram` or `clCompileProgram` with the `-cl-std=CL1.1` option will fail to compile the program for any devices with `CL_DEVICE_OPENCL_C_VERSION` equal to OpenCL C 1.0 and when `CL_DEVICE_OPENCL_C_ALL_VERSIONS` does not include OpenCL C 1.1.

Calls to `clBuildProgram` or `clCompileProgram` with the `-cl-std=CL1.2` option will fail to compile the program for any devices with `CL_DEVICE_OPENCL_C_VERSION` equal to OpenCL C 1.1 or earlier and when `CL_DEVICE_OPENCL_C_ALL_VERSIONS` does not include OpenCL C 1.2.

Calls to `clBuildProgram` or `clCompileProgram` with the `-cl-std=CL2.0` option will fail to compile the program for any devices with `CL_DEVICE_OPENCL_C_VERSION` equal to OpenCL C 1.2 or earlier and when `CL_DEVICE_OPENCL_C_ALL_VERSIONS` does not include OpenCL C 2.0.

Calls to `clBuildProgram` or `clCompileProgram` with the `-cl-std=CL3.0` option will fail to compile the program for any devices with `CL_DEVICE_OPENCL_C_VERSION` equal to OpenCL C 2.0 or earlier and when `CL_DEVICE_OPENCL_C_ALL_VERSIONS` does not include OpenCL C 3.0.

If the `-cl-std` build option is not specified, the highest OpenCL C 1.x language version supported by each device is used when compiling the program for each device. Applications are required to specify the `-cl-std=CL2.0` build option to compile or build programs with OpenCL C 2.0 and the `-cl-std=CL3.0` build option to compile or build programs with OpenCL C 3.0.

5.8.6.6. Options for Querying Kernel Argument Information

- **cl-kernel-arg-info**

This option allows the compiler to store information about the arguments of a kernel(s) in the program executable. The argument information stored includes the argument name, its type, the
address space and access qualifiers used. Refer to description of \texttt{clGetKernelArgInfo} on how to query this information.

5.8.6.7. Options for Debugging Your Program

- **Warning**
  - Debugging options are \textit{missing before} version 2.0.

- **-g**
  - This option can currently be used to generate additional errors for the built-in functions that allow you to enqueue commands on a device (refer to OpenCL kernel languages specifications).

5.8.7. Linker Options

- **Information**
  - Linker options are \textit{missing before} version 1.2.

This specification defines a standard set of linker options that must be supported by the OpenCL C compiler when linking compiled programs online or offline. These linker options are categorized as library linking options and program linking options. These may be extended by a set of vendor- or platform-specific options.

5.8.7.1. Library Linking Options

- **Warning**
  - Library linking options are \textit{missing before} version 1.2.

The following options can be specified when creating a library of compiled binaries.

- **\texttt{-create-library}**
  - Create a library of compiled binaries specified in \textit{input\_programs} argument to \texttt{clLinkProgram}.

- **\texttt{-enable-link-options}**
  - Allows the linker to modify the library behavior based on one or more link options (described in Program Linking Options) when this library is linked with a program executable. This option must be specified with the create-library option.

5.8.7.2. Program Linking Options

The following options can be specified when linking a program executable.

- **\texttt{-cl-denorms-are-zero}**
- **\texttt{-cl-no-signed-zeros}**
- **\texttt{-cl-unsafe-math-optimizations}**
- **\texttt{-cl-finite-math-only}**
- **\texttt{-cl-fast-relaxed-math}**
- **\texttt{-cl-no-subgroup-ifp} (missing before version 2.1)**

The options are described in Math Intrinsics Options and Optimization Options. The linker may apply these options to all compiled program objects specified to \texttt{clLinkProgram}. The linker may apply these options only to libraries which were created with the option \texttt{-enable-link-options}.
5.8.7.3. SPIR Compilation Options

If the cl_khr_spir extension is supported, the compile option

-x spir

must be specified to indicate that the binary is in SPIR format, and the compile option

-spir-std

must be used to specify the version of the SPIR specification that describes the format and meaning of the binary.

For example, if the binary is as described in SPIR version 1.2, then

-spir-std=1.2

must be specified. Failing to specify these compile options may result in implementation-defined behavior.

5.8.8. Unloading the OpenCL Compiler

To unload an OpenCL compiler for a platform, call the function

```c
// Provided by CL_VERSION_1_2
cl_int clUnloadPlatformCompiler(
    cl_platform_id platform);
```

- **platform** is the platform to unload.

This function allows the implementation to release the resources allocated by the OpenCL compiler for platform. This is a hint from the application and does not guarantee that the compiler will not be used in the future or that the compiler will actually be unloaded by the implementation. Calls to clBuildProgram, clCompileProgram or clLinkProgram after clUnloadPlatformCompiler will reload the compiler, if necessary, to build the appropriate program executable.

clUnloadPlatformCompiler returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:

- CL_INVALID_PLATFORM if platform is not a valid platform.

Alternatively, if you are not using OpenCL via the ICD loader, you may unload the OpenCL compiler with the function

```c
// Provided by CL_VERSION_1_0
cl_int clUnloadCompiler(void);
```
This function allows the implementation to release the resources allocated by the OpenCL compiler. This is a hint from the application and does not guarantee that the compiler will not be used in the future or that the compiler will actually be unloaded by the implementation. Calls to `clBuildProgram`, `clCompileProgram` or `clLinkProgram` after `clUnloadCompiler` will reload the compiler, if necessary, to build the appropriate program executable.

`clUnloadCompiler` will always return `CL_SUCCESS`.

### 5.8.9. Program Object Queries

To return information about a program object, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clGetProgramInfo(
    cl_program program,
    cl_program_info param_name,
    size_t param_value_size,
    void* param_value,
    size_t* param_value_size_ret);
```

- `program` specifies the program object being queried.
- `param_name` specifies the information to query. The list of supported `param_name` types and the information returned in `param_value` by `clGetProgramInfo` is described in the Program Object Queries table.
- `param_value` is a pointer to memory where the appropriate result being queried is returned. If `param_value` is `NULL`, it is ignored.
- `param_value_size` is used to specify the size in bytes of memory pointed to by `param_value`. This size must be ≥ size of return type as described in the Program Object Queries table.
- `param_value_size_ret` returns the actual size in bytes of data being queried by `param_name`. If `param_value_size_ret` is `NULL`, it is ignored.

#### Table 43. List of supported `param_names` by `clGetProgramInfo`

<table>
<thead>
<tr>
<th>Program Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>CL_PROGRAM_REFERENCE_COUNT</code></td>
<td><code>cl_uint</code></td>
<td>Return the <code>program</code> reference count.</td>
</tr>
<tr>
<td><code>CL_PROGRAM_CONTEXT</code></td>
<td><code>cl_context</code></td>
<td>Return the context specified when the program object is created</td>
</tr>
<tr>
<td><code>CL_PROGRAM_NUM_DEVICES</code></td>
<td><code>cl_uint</code></td>
<td>Return the number of devices associated with <code>program</code>.</td>
</tr>
<tr>
<td>Program Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>-----------------------------</td>
<td>------------------------</td>
<td>-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_PROGRAM_DEVICES</td>
<td>cl_device_id[]</td>
<td>Return the list of devices associated with the program object. This can be the devices associated with context on which the program object has been created or can be a subset of devices that are specified when a program object is created using <code>clCreateProgramWithBinary</code>.</td>
</tr>
<tr>
<td>CL_PROGRAM_SOURCE</td>
<td>char[]</td>
<td>Return the program source code specified by <code>clCreateProgramWithSource</code>. The source string returned is a concatenation of all source strings specified to <code>clCreateProgramWithSource</code> with a null terminator. The concatenation strips any nulls in the original source strings. If <strong>program</strong> is created using <code>clCreateProgramWithBinary, clCreateProgramWithIL, clCreateProgramWithIL_KHR, or clCreateProgramWithBuiltInKernels</code>, a null string or the appropriate program source code is returned depending on whether or not the program source code is stored in the binary. The actual number of characters that represents the program source code including the null terminator is returned in <code>param_value_size_ret</code>.</td>
</tr>
<tr>
<td>CL_PROGRAM_IL</td>
<td>char[]</td>
<td>Returns the program IL for programs created with <code>clCreateProgramWithIL_KHR</code> or <code>clCreateProgramWithIL</code>.</td>
</tr>
<tr>
<td>missing before version 2.1.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_PROGRAM_IL_KHR</td>
<td></td>
<td>Provided by the <code>cl_khr_il_program</code> extension.</td>
</tr>
<tr>
<td>If <strong>program</strong> is created with <code>clCreateProgramWithSource, clCreateProgramWithBinary</code> or <code>clCreateProgramWithBuiltInKernels</code> the memory pointed to by <strong>param_value</strong> will be unchanged and <code>param_value_size_ret</code> will be set to 0.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Program Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>----------------------------</td>
<td>-------------</td>
<td>---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_PROGRAM_BINARY_SIZES</td>
<td>size_t[]</td>
<td>Returns an array that contains the size in bytes of the program binary (could be an executable binary, compiled binary or library binary) for each device associated with program. The size of the array is the number of devices associated with program. If a binary is not available for a device(s), a size of zero is returned. If <em>program</em> is created using <code>clCreateProgramWithBuiltInKernels</code>, the implementation may return zero in any entries of the returned array.</td>
</tr>
<tr>
<td>Program Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>---------------------------</td>
<td>-----------------</td>
<td>-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_PROGRAM_BINARIES</td>
<td>unsigned char*[]</td>
<td>Return the program binaries (could be an executable binary, compiled binary or library binary) for all devices associated with program. For each device in program, the binary returned can be the binary specified for the device when program is created with <code>clCreateProgramWithBinary</code> or it can be the executable binary generated by <code>clBuildProgram</code> or <code>clLinkProgram</code>. If <code>program</code> is created with <code>clCreateProgramWithSource</code> or <code>clCreateProgramWithIL</code>, the binary returned is the binary generated by <code>clBuildProgram</code>, <code>clCompileProgram</code> or <code>clLinkProgram</code>. The bits returned can be an implementation-specific intermediate representation (a.k.a. IR) or device specific executable bits or both. The decision on which information is returned in the binary is up to the OpenCL implementation. <code>param_value</code> points to an array of <code>n</code> pointers allocated by the caller, where <code>n</code> is the number of devices associated with program. The buffer sizes needed to allocate the memory that these <code>n</code> pointers refer to can be queried using the <code>CL_PROGRAM_BINARY_SIZES</code> query as described in this table. Each entry in this array is used by the implementation as the location in memory where to copy the program binary for a specific device, if there is a binary available. To find out which device the program binary in the array refers to, use the <code>CL_PROGRAM_DEVICES</code> query to get the list of devices. There is a one-to-one correspondence between the array of <code>n</code> pointers returned by <code>CL_PROGRAM_BINARIES</code> and array of devices returned by <code>CL_PROGRAM_DEVICES</code>.</td>
</tr>
<tr>
<td>CL_PROGRAM_NUM_KERNELS</td>
<td>size_t</td>
<td>Returns the number of kernels declared in <code>program</code> that can be created with <code>clCreateKernel</code>. This information is only available after a successful program executable has been built for at least one device in the list of devices associated with <code>program</code>.</td>
</tr>
</tbody>
</table>

*missing before version 1.2.*
<table>
<thead>
<tr>
<th>Program Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>CL_PROGRAM_KERNEL_NAMES</strong></td>
<td>char[]</td>
<td>Returns a semi-colon separated list of kernel names in <em>program</em> that can be created with <code>clCreateKernel</code>. This information is only available after a successful program executable has been built for at least one device in the list of devices associated with <em>program</em>.</td>
</tr>
<tr>
<td>Missing before version 1.2.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>CL_PROGRAM_SCOPE_GLOBAL_CTORS_PRESENT</strong></td>
<td>cl_bool</td>
<td>This indicates that the <em>program</em> object contains non-trivial constructor(s) that will be executed by runtime before any kernel from the program is executed. This information is only available after a successful program executable has been built for at least one device in the list of devices associated with <em>program</em>.</td>
</tr>
<tr>
<td>Missing before version 2.2 and deprecated by version 3.0.</td>
<td></td>
<td>Querying <strong>CL_PROGRAM_SCOPE_GLOBAL_CTORS_PRESENT</strong> may unconditionally return <strong>CL_FALSE</strong> if no devices associated with <em>program</em> support constructors for program scope global variables. Support for constructors and destructors for program scope global variables is required only for OpenCL 2.2 devices.</td>
</tr>
<tr>
<td><strong>CL_PROGRAM_SCOPE_GLOBAL_DTORS_PRESENT</strong></td>
<td>cl_bool</td>
<td>This indicates that the program object contains non-trivial destructor(s) that will be executed by runtime when <em>program</em> is destroyed. This information is only available after a successful program executable has been built for at least one device in the list of devices associated with <em>program</em>.</td>
</tr>
<tr>
<td>Missing before version 2.2 and deprecated by version 3.0.</td>
<td></td>
<td>Querying <strong>CL_PROGRAM_SCOPE_GLOBAL_DTORS_PRESENT</strong> may unconditionally return <strong>CL_FALSE</strong> if no devices associated with <em>program</em> support destructors for program scope global variables. Support for constructors and destructors for program scope global variables is required only for OpenCL 2.2 devices.</td>
</tr>
</tbody>
</table>

**clGetProgramInfo** returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_VALUE** if *param_name* is not valid, or if size in bytes specified by *param_value_size* is < size of return type as described in the *Program Object Queries* table and *param_value* is not NULL.
- **CL_INVALID_PROGRAM** if *program* is a not a valid program object.
- **CL_INVALID_PROGRAM_EXECUTABLE** if *param_name* is **CL_PROGRAM_NUM_KERNELS**, **CL_PROGRAM_KERNEL_**
NAMES, CL_PROGRAM_SCOPE_GLOBAL_CTORs_PRESENT, or CL_PROGRAM_SCOPE_GLOBAL_DTORs_PRESENT and a successful program executable has not been built for at least one device in the list of devices associated with program.

- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To return build information for each device in the program object, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clGetProgramBuildInfo(
    cl_program program,
    cl_device_id device,
    cl_program_build_info param_name,
    size_t param_value_size,
    void* param_value,
    size_t* param_value_size_ret);
```

- **program** specifies the program object being queried.
- **device** specifies the device for which build information is being queried. **device** must be a valid device associated with **program**.
- **param_name** specifies the information to query. The list of supported **param_name** types and the information returned in **param_value** by **clGetProgramBuildInfo** is described in the **Program Build Queries** table.
- **param_value** is a pointer to memory where the appropriate result being queried is returned. If **param_value** is NULL, it is ignored.
- **param_value_size** is used to specify the size in bytes of memory pointed to by **param_value**. This size must be \( \geq \) size of return type as described in the **Program Build Queries** table.
- **param_value_size_ret** returns the actual size in bytes of data being queried by **param_name**. If **param_value_size_ret** is NULL, it is ignored.

*Table 44. List of supported param_names by clGetProgramBuildInfo*
<table>
<thead>
<tr>
<th>Program Build Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_PROGRAM_BUILD_STATUS</td>
<td>cl_build_status</td>
<td>Returns the build, compile or link status, whichever was performed last on the specified program object for device.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>This can be one of the following:</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_BUILD_NONE</strong> - The build status returned if no clBuildProgram, clCompileProgram or clLinkProgram has been performed on the specified program object for device).</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_BUILD_ERROR</strong> - The build status returned if clBuildProgram, clCompileProgram or clLinkProgram - whichever was performed last on the specified program object for device - generated an error.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_BUILD_SUCCESS</strong> - The build status returned if clBuildProgram, clCompileProgram or clLinkProgram - whichever was performed last on the specified program object for device - was successful.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_BUILD_IN_PROGRESS</strong> - The build status returned if clBuildProgram, clCompileProgram or clLinkProgram - whichever was performed last on the specified program object for device - has not finished.</td>
</tr>
<tr>
<td>CL_PROGRAM_BUILD_OPTIONS</td>
<td>char[]</td>
<td>Return the build, compile or link options specified by the options argument in clBuildProgram, clCompileProgram or clLinkProgram, whichever was performed last on the specified program object for device.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>If build status of the specified program for device is <strong>CL_BUILD_NONE</strong>, an empty string is returned.</td>
</tr>
<tr>
<td>CL_PROGRAM_BUILD_LOG</td>
<td>char[]</td>
<td>Return the build, compile or link log for clBuildProgram, clCompileProgram or clLinkProgram, whichever was performed last on program for device.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>If build status of the specified program for device is <strong>CL_BUILD_NONE</strong>, an empty string is returned.</td>
</tr>
<tr>
<td>Program Build Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>----------------------------------------</td>
<td>-----------------------------</td>
<td>-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_PROGRAM_BINARY_TYPE</td>
<td>cl_program_binary_type</td>
<td>Return the program binary type for device. This can be one of the following values:</td>
</tr>
<tr>
<td>missing before version 1.2.</td>
<td></td>
<td><strong>CL_PROGRAM_BINARY_TYPE_NONE</strong> - There is no binary associated with the specified <em>program</em> object for <em>device</em>.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_PROGRAM_BINARY_TYPE_COMPILED_OBJECT</strong> - A compiled binary is associated with <em>device</em>. This is the case when the specified <em>program</em> object was created using <em>clCreateProgramWithSource</em> and compiled using <em>clCompileProgram</em>, or when a compiled binary was loaded using <em>clCreateProgramWithBinary</em>.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_PROGRAM_BINARY_TYPE_LIBRARY</strong> - A library binary is associated with <em>device</em>. This is the case when the specified <em>program</em> object was linked by <em>clLinkProgram</em> using the -create-library link option, or when a compiled library binary was loaded using <em>clCreateProgramWithBinary</em>.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_PROGRAM_BINARY_TYPE_EXECUTABLE</strong> - An executable binary is associated with <em>device</em>. This is the case when the specified <em>program</em> object was linked by <em>clLinkProgram</em> without the -create-library link option, or when an executable binary was built using <em>clBuildProgram</em>.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_PROGRAM_BINARY_TYPE_INTERMEDIATE</strong> — An intermediate (non-source) representation for the program is loaded as a binary. The program must be further processed with <em>clCompileProgram</em> or <em>clBuildProgram</em>.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>If processed with <em>clCompileProgram</em>, the result will be a binary of type <strong>CL_PROGRAM_BINARY_TYPE_COMPILED_OBJECT</strong> or <strong>CL_PROGRAM_BINARY_TYPE_LIBRARY</strong>. If processed with <em>clBuildProgram</em>, the result will be a binary of type <strong>CL_PROGRAM_BINARY_TYPE_EXECUTABLE</strong>.</td>
</tr>
<tr>
<td>Program Build Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>--------------------------------------------------------</td>
<td>-------------</td>
<td>-----------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_PROGRAM_BUILD_GLOBAL_VARIABLE_TOTAL_SIZE</td>
<td>size_t</td>
<td>The total amount of storage, in bytes, used by program variables in the global address space.</td>
</tr>
</tbody>
</table>

clGetProgramBuildInfo returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_DEVICE** if device is not in the list of devices associated with program.
- **CL_INVALID_VALUE** if param_name is not valid, or if size in bytes specified by param_value_size is < size of return type as described in the Program Build Queries table and param_value is not NULL.
- **CL_INVALID_PROGRAM** if program is a not a valid program object.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

A program binary (compiled binary, library binary or executable binary) built for a parent device can be used by all its sub-devices. If a program binary has not been built for a sub-device, the program binary associated with the parent device will be used.

A program binary for a device specified with clCreateProgramWithBinary or queried using clGetProgramInfo can be used as the binary for the associated root device, and all sub-devices created from the root-level device or sub-devices thereof.

### 5.9. Kernel Objects

A kernel is a function declared in a program. A kernel is identified by the __kernel qualifier applied to any function in a program. A kernel object encapsulates the specific __kernel function declared in a program and the argument values to be used when executing this __kernel function.

#### 5.9.1. Creating Kernel Objects

To create a kernel object, use the function

```c
// Provided by CL_VERSION_1_0
cl_kernel clCreateKernel(
    cl_program program,
    const char* kernel_name,
    cl_int* errcode_ret);
```

- **program** is a program object with a successfully built executable.
• *kernel_name* is a function name in the program declared with the *__kernel* qualifier.

• *errcode_ret* will return an appropriate error code. If *errcode_ret* is *NULL*, no error code is returned.

**clCreateKernel** returns a valid non-zero kernel object and *errcode_ret* is set to *CL_SUCCESS* if the kernel object is created successfully. Otherwise, it returns a *NULL* value with one of the following error values returned in *errcode_ret*:

• *CL_INVALID_PROGRAM* if *program* is not a valid program object.

• *CL_INVALID_PROGRAM_EXECUTABLE* if there is no successfully built executable for *program*.

• *CL_INVALID_KERNEL_NAME* if *kernel_name* is not found in *program*.

• *CL_INVALID_KERNEL_DEFINITION* if the function definition for *__kernel* function given by *kernel_name* such as the number of arguments, the argument types are not the same for all devices for which the *program* executable has been built.

• *CL_INVALID_VALUE* if *kernel_name* is *NULL*.

• *CL_OUT_OF_RESOURCES* if there is a failure to allocate resources required by the OpenCL implementation on the device.

• *CL_OUT_OF_HOST_MEMORY* if there is a failure to allocate resources required by the OpenCL implementation on the host.

To create kernel objects for all kernel functions in a program, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clCreateKernelsInProgram(
    cl_program program,
    cl_uint num_kernels,
    cl_kernel* kernels,
    cl_uint* num_kernels_ret);
```

• *program* is a program object with a successfully built executable.

• *num_kernels* is the size of memory pointed to by *kernels* specified as the number of *cl_kernel* entries.

• *kernels* is the buffer where the kernel objects for kernels in *program* will be returned. If *kernels* is *NULL*, it is ignored. If *kernels* is not *NULL*, *num_kernels* must be greater than or equal to the number of kernels in *program*.

• *num_kernels_ret* is the number of kernels in *program*. If *num_kernels_ret* is *NULL*, it is ignored.

Kernel objects are not created for any *__kernel* functions in *program* that do not have the same function definition across all devices for which a program executable has been successfully built.

Kernel objects can only be created once you have a program object with a valid program source or binary loaded into the program object and the program executable has been successfully built for one or more devices associated with program. No changes to the program executable are allowed while there are kernel objects associated with a program object. This means that calls to
clBuildProgram and clCompileProgram return CL_INVALID_OPERATION if there are kernel objects attached to a program object. The OpenCL context associated with program will be the context associated with kernel. The list of devices associated with program are the devices associated with kernel. Devices associated with a program object for which a valid program executable has been built can be used to execute kernels declared in the program object.

clCreateKernelsInProgram will return CL_SUCCESS if the kernel objects were successfully allocated. Otherwise, it returns one of the following errors:

- **CL_INVALID_PROGRAM** if program is not a valid program object.
- **CL_INVALID_PROGRAM_EXECUTABLE** if there is no successfully built executable for any device in program.
- **CL_INVALID_VALUE** if kernels is not NULL and num_kernels is less than the number of kernels in program.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To retain a kernel object, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clRetainKernel(
    cl_kernel kernel);
```

- **kernel** is the kernel object to be retained.

The kernel reference count is incremented.

clRetainKernel returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_KERNEL** if kernel is not a valid kernel object.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

clCreateKernel or clCreateKernelsInProgram do an implicit retain.

To release a kernel object, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clReleaseKernel(
    cl_kernel kernel);
```
• *kernel* is the kernel object to be released.

The *kernel* reference count is decremented.

The kernel object is deleted once the number of instances that are retained to *kernel* become zero and the kernel object is no longer needed by any enqueued commands that use *kernel*. Using this function to release a reference that was not obtained by creating the object or by calling *clRetainKernel* causes undefined behavior.

`clReleaseKernel` returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:

• CL_INVALID_KERNEL if *kernel* is not a valid kernel object.
• CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
• CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

5.9.2. Setting Kernel Arguments

To execute a kernel, the kernel arguments must be set.

To set the argument value for a specific argument of a kernel, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clSetKernelArg(
    cl_kernel kernel,
    cl_uint arg_index,
    size_t arg_size,
    const void* arg_value);
```

• *kernel* is a valid kernel object.
• *arg_index* is the argument index. Arguments to the kernel are referred by indices that go from 0 for the leftmost argument to \( n - 1 \), where \( n \) is the total number of arguments declared by a kernel (see below).
• *arg_size* specifies the size of the argument value. If the argument is a memory object, the *arg_size* value must be equal to `sizeof(cl_mem)`. For arguments declared with the `local` qualifier, the size specified will be the size in bytes of the buffer that must be allocated for the `local` argument. If the argument is of type `sampler_t`, the *arg_size* value must be equal to `sizeof(cl_sampler)`. If the argument is of type `queue_t`, the *arg_size* value must be equal to `sizeof(cl_command_queue)`. For all other arguments, the size will be the size of argument type.
• *arg_value* is a pointer to data that should be used as the argument value for argument specified by *arg_index*. The argument data pointed to by *arg_value* is copied and the *arg_value* pointer can therefore be reused by the application after `clSetKernelArg` returns. The argument value specified is the value used by all API calls that enqueue *kernel* (`clEnqueueNDRangeKernel` and `clEnqueueTask`) until the argument value is changed by a call to `clSetKernelArg` for *kernel*. 


For example, consider the following kernel:

```c
kernel void image_filter (int n,
    int m,
    constant float *filter_weights,
    read_only image2d_t src_image,
    write_only image2d_t dst_image)
{
    ...
}
```

Argument index values for `image_filter` will be 0 for `n`, 1 for `m`, 2 for `filter_weights`, 3 for `src_image` and 4 for `dst_image`.

If the argument is a memory object (buffer, pipe, image or image array), the `arg_value` entry will be a pointer to the appropriate buffer, pipe, image or image array object. The memory object must be created with the context associated with the kernel object. If the argument is a buffer object, the `arg_value` pointer can be `NULL` or point to a `NULL` value in which case a `NULL` value will be used as the value for the argument declared as a pointer to `global` or `constant` memory in the kernel. If the argument is declared with the `local` qualifier, the `arg_value` entry must be `NULL`. If the argument is of type `sampler_t`, the `arg_value` entry must be a pointer to the sampler object. If the argument is of type `queue_t`, the `arg_value` entry must be a pointer to the device queue object.

If the `cl_khr_gl_msaa_sharing` extension is supported, then: If the argument is a multi-sample 2D image, the `arg_value` entry must be a pointer to a multi-sample image object. If the argument is a multi-sample 2D depth image, the `arg_value` entry must be a pointer to a multisample depth image object. If the argument is a multi-sample 2D image array, the `arg_value` entry must be a pointer to a multi-sample image array object. If the argument is a multi-sample 2D depth image array, the `arg_value` entry must be a pointer to a multi-sample depth image array object.

If the argument is declared to be a pointer of a built-in scalar or vector type, or a user defined structure type in the global or constant address space, the memory object specified as argument value must be a buffer object (or `NULL`). If the argument is declared with the `constant` qualifier, the size in bytes of the memory object cannot exceed `CL_DEVICE_MAX_CONSTANT_BUFFER_SIZE` and the number of arguments declared as pointers to `constant` memory cannot exceed `CL_DEVICE_MAX_CONSTANT_ARGS`.

The memory object specified as argument value must be a pipe object if the argument is declared with the `pipe` qualifier.

The memory object specified as argument value must be a 2D image object if the argument is declared to be of type `image2d_t`. The memory object specified as argument value must be a 2D image object with image channel order = `CL_DEPTH` if the argument is declared to be of type `image2d_depth_t`. The memory object specified as argument value must be a 3D image object if argument is declared to be of type `image3d_t`. The memory object specified as argument value must be a 1D image object if the argument is declared to be of type `image1d_t`. The memory object specified as argument value must be a 1D image buffer object if the argument is declared to be of type `image1d_buffer_t`. The memory object specified as argument value must be a 1D image array
object if argument is declared to be of type `image1d_array_t`. The memory object specified as argument value must be a 2D image array object if argument is declared to be of type `image2d_array_t`. The memory object specified as argument value must be a 2D image array object with image channel order = `CL_DEPTH` if argument is declared to be of type `image2d_array_depth_t`.

For all other kernel arguments, the `arg_value` entry must be a pointer to the actual data to be used as argument value.

A kernel object does not update the reference count for objects such as memory or sampler objects specified as argument values by `clSetKernelArg`. Users may not rely on a kernel object to retain objects specified as argument values to the kernel.

Implementations shall not allow `cl_kernel` objects to hold reference counts to `cl_kernel` arguments, because no mechanism is provided for the user to tell the kernel to release that ownership right. If the kernel holds ownership rights on kernel args, that would make it impossible for users to tell with certainty when they may safely release user allocated resources associated with OpenCL objects such as the `cl_mem` backing store used with `CL_MEM_USE_HOST_PTR`.

cSetKernelArg returns `CL_SUCCESS` if the function was executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_KERNEL** if `kernel` is not a valid kernel object.
- **CL_INVALID_ARG_INDEX** if `arg_index` is not a valid argument index.
- **CL_INVALID_ARG_VALUE** if `arg_value` specified is not a valid value.
- **CL_INVALID_MEM_OBJECT** for an argument declared to be a memory object when the specified `arg_value` is not a valid memory object.
- **CL_INVALID_MEM_OBJECT** for an argument declared to be a depth image, depth image array, multi-sample image, multi-sample image array, multi-sample depth image, or a multi-sample depth image array when the specified `arg_value` does not follow the rules described above for a depth memory object or memory array object argument.
- **CL_INVALID_SAMPLER** for an argument declared to be of type `sampler_t` when the specified `arg_value` is not a valid sampler object.
- **CL_INVALID_DEVICE_QUEUE** for an argument declared to be of type `queue_t` when the specified `arg_value` is not a valid device queue object. This error code is missing before version 2.0.
- **CL_INVALID_ARG_SIZE** if `arg_size` does not match the size of the data type for an argument that is not a memory object or if the argument is a memory object and `arg_size` != `sizeof(cl_mem)` or if `arg_size` is zero and the argument is declared with the local qualifier or if the argument is a sampler and `arg_size` != `sizeof(cl_sampler)`.
- **CL_MAX_SIZE_RESTRICTION_EXCEEDED** if the size in bytes of the memory object (if the argument is a memory object) or `arg_size` (if the argument is declared with `local` qualifier) exceeds a language- specified maximum size restriction for this argument, such as the `MaxByteOffset` SPIR-V decoration. This error code is missing before version 2.2.
- **CL_INVALID_ARG_VALUE** if the argument is an image declared with the `read_only` qualifier and `arg_value` refers to an image object created with `cl_mem_flags` of `CL_MEM_WRITE_ONLY` or if the
image argument is declared with the `write_only` qualifier and `arg_value` refers to an image object created with `cl_mem_flags` of `CL_MEM_READ_ONLY`.

- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

When `clSetKernelArg` returns an error code different from `CL_SUCCESS`, the internal state of `kernel` may only be modified when that error code is `CL_OUT_OF_RESOURCES` or `CL_OUT_OF_HOST_MEMORY`. When the internal state of `kernel` is modified, it is implementation-defined whether:

- The argument value that was previously set is kept so that it can be used in further kernel enqueues.
- The argument value is unset such that a subsequent kernel enqueue fails with `CL_INVALID_KERNEL_ARGS`.\[14\]

To set a SVM pointer as the argument value for a specific argument of a kernel, call the function

```c
// Provided by CL_VERSION_2_0
cl_int clSetKernelArgSVMPointer(
    cl_kernel kernel,
    cl_uint arg_index,
    const void* arg_value);
```

- `clSetKernelArgSVMPointer` is missing before version 2.0.
- `kernel` is a valid kernel object.
- `arg_index` is the argument index. Arguments to the kernel are referred by indices that go from 0 for the leftmost argument to \(n - 1\), where \(n\) is the total number of arguments declared by a kernel.
- `arg_value` is the SVM pointer that should be used as the argument value for argument specified by `arg_index`. The SVM pointer specified is the value used by all API calls that enqueue `kernel` (clEnqueueNDRangeKernel and clEnqueueTask) until the argument value is changed by a call to `clSetKernelArgSVMPointer` for `kernel`. The SVM pointer can only be used for arguments that are declared to be a pointer to `global` or `constant` memory. The SVM pointer value must be aligned according to the arguments type. For example, if the argument is declared to be `global float4 *p`, the SVM pointer value passed for `p` must be at a minimum aligned to a `float4`. The SVM pointer value specified as the argument value can be the pointer returned by `clSVMAlloc` or can be a pointer offset into the SVM region.

`clSetKernelArgSVMPointer` returns `CL_SUCCESS` if the function was executed successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_KERNEL` if `kernel` is not a valid kernel object.
- `CL_INVALID_OPERATION` if no devices in the context associated with `kernel` support SVM.
• **CL_INVALID_ARG_INDEX** if *arg_index* is not a valid argument index.

• **CL_INVALID_ARG_VALUE** if *arg_value* specified is not a valid value.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To pass additional information other than argument values to a kernel, call the function

```c
// Provided by CL_VERSION_2_0
cl_int clSetKernelExecInfo(
    cl_kernel kernel,
    cl_kernel_exec_info param_name,
    size_t param_value_size,
    const void* param_value);
```

**clSetKernelExecInfo** is missing before version 2.0.

- *kernel* specifies the kernel object being queried.

- *param_name* specifies the information to be passed to kernel. The list of supported *param_name* types and the corresponding values passed in *param_value* is described in the *Kernel Execution Properties* table.

- *param_value_size* specifies the size in bytes of the memory pointed to by *param_value*.

- *param_value* is a pointer to memory where the appropriate values determined by *param_name* are specified.

**Table 45. List of supported param_names by clSetKernelExecInfo**

<table>
<thead>
<tr>
<th>Kernel Exec Info</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>cl_kernel_exec_info_svm_ptr</td>
<td>void*[]</td>
<td>SVM pointers must reference locations contained entirely within buffers that are passed to kernel as arguments, or that are passed through the execution information.</td>
</tr>
<tr>
<td>missing before version 2.0.</td>
<td></td>
<td>Non-argument SVM buffers must be specified by passing pointers to those buffers via clSetKernelExecInfo for coarse-grain and fine-grain buffer SVM allocations but not for finegrain system SVM allocations.</td>
</tr>
<tr>
<td>cl_kernel_exec_info_svm_fine_grain_system</td>
<td>cl_bool</td>
<td>This flag indicates whether the kernel uses pointers that are fine grain system SVM allocations. These fine grain system SVM pointers may be passed as arguments or defined in SVM buffers that are passed as arguments to kernel.</td>
</tr>
<tr>
<td>missing before version 2.0.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
clSetKernelExecInfo returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_KERNEL** if *kernel* is a not a valid kernel object.
- **CL_INVALID_OPERATION** if no devices in the context associated with *kernel* support SVM.
- **CL_INVALID_VALUE** if *param_name* is not valid, if *param_value* is **NULL** or if the size specified by *param_value_size* is not valid.
- **CL_INVALID_OPERATION** if *param_name* is **CL_KERNEL_EXEC_INFO_SVM_FINE_GRAIN_SYSTEM** and *param_value* is **CL_TRUE** but no devices in context associated with *kernel* support fine-grain system SVM allocations.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

Coarse-grain or fine-grain buffer SVM pointers used by a kernel which are not passed as a kernel arguments must be specified using **clSetKernelExecInfo** with **CL_KERNEL_EXEC_INFO_SVM_PTRS**. For example, if SVM buffer A contains a pointer to another SVM buffer B, and the kernel dereferences that pointer, then a pointer to B must either be passed as an argument in the call to that kernel or it must be made available to the kernel using **clSetKernelExecInfo**. For example, we might pass extra SVM pointers as follows:

```cpp
clSetKernelExecInfo(kernel,
        CL_KERNEL_EXEC_INFO_SVM_PTRS,
        num_ptrs * sizeof(void *),
        extra_svm_ptr_list);
```

Here *num_ptrs* specifies the number of additional SVM pointers while *extra_svm_ptr_list* specifies a pointer to memory containing those SVM pointers.

When calling **clSetKernelExecInfo** with **CL_KERNEL_EXEC_INFO_SVM_PTRS** to specify pointers to non-argument SVM buffers as extra arguments to a kernel, each of these pointers can be the SVM pointer returned by **clSVMAlloc** or can be a pointer + offset into the SVM region. It is sufficient to provide one pointer for each SVM buffer used.

**CL_KERNEL_EXEC_INFO_SVM_FINE_GRAIN_SYSTEM** is used to indicate whether SVM pointers used by a kernel will refer to system allocations or not.

**CL_KERNEL_EXEC_INFO_SVM_FINE_GRAIN_SYSTEM = CL_FALSE** indicates that the OpenCL implementation may assume that system pointers are not passed as kernel arguments and are not stored inside SVM allocations passed as kernel arguments.

**CL_KERNEL_EXEC_INFO_SVM_FINE_GRAIN_SYSTEM = CL_TRUE** indicates that the OpenCL implementation must assume that system pointers might be passed as kernel
arguments and/or stored inside SVM allocations passed as kernel arguments. In this case, if the device to which the kernel is enqueued does not support system SVM pointers, **clEnqueueNDRangeKernel** and **clEnqueueTask** will return a **CL_INVALID_OPERATION** error. If none of the devices in the context associated with kernel support fine-grain system SVM allocations, **clSetKernelExecInfo** will return a **CL_INVALID_OPERATION** error.

If **clSetKernelExecInfo** has not been called with a value for **CL_KERNEL_EXEC_INFO_SVM_FINE_GRAIN_SYSTEM**, the default value is used for this kernel attribute. The default value depends on whether the device on which the kernel is enqueued supports fine-grain system SVM allocations. If so, the default value used is **CL_TRUE** (system pointers might be passed); otherwise, the default is **CL_FALSE**.

A call to **clSetKernelExecInfo** for a given value of *param_name* replaces any prior value passed for that value of *param_name*. Only one *param_value* will be stored for each value of *param_name*.

### 5.9.3. Copying Kernel Objects

Copying kernel objects is **missing before** version 2.1.

To clone a kernel object, call the function

```c
// Provided by CL_VERSION_2_1
cl_kernel clCloneKernel(
    cl_kernel source_kernel,
    cl_int* errcode_ret);
```

**clCloneKernel** is **missing before** version 2.1.

- *source_kernel* is a valid **cl_kernel** object that will be copied. *source_kernel* will not be modified in any way by this function.
- *errcode_ret* will be assigned an appropriate error code. If *errcode_ret* is **NULL**, no error code is returned.

Cloning is used to make a shallow copy of the kernel object, its arguments and any information passed to the kernel object using **clSetKernelExecInfo**. If the kernel object was ready to be enqueued before copying it, the clone of the kernel object is ready to enqueue.

The returned kernel object is an exact copy of *source_kernel*, with one caveat: the reference count on the returned kernel object is set as if it had been returned by **clCreateKernel**. The reference count of *source_kernel* will not be changed.

The resulting kernel will be in the same state as if **clCreateKernel** is called to create the resultant kernel with the same arguments as those used to create *source_kernel*, the latest call to **clSetKernelArg** or **clSetKernelArgSVMPointer** for each argument index applied to kernel and the last call to **clSetKernelExecInfo** for each value of the param name parameter are applied to the
new kernel object.

All arguments of the new kernel object must be intact and it may be correctly used in the same situations as kernel except those that assume a pre-existing reference count. Setting arguments on the new kernel object will not affect source_kernel except insofar as the argument points to a shared underlying entity and in that situation behavior is as if two kernel objects had been created and the same argument applied to each. Only the data stored in the kernel object is copied; data referenced by the kernels arguments are not copied. For example, if a buffer or pointer argument is set on a kernel object, the pointer is copied but the underlying memory allocation is not.

clCloneKernel returns a valid non-zero kernel object and errcode_ret is set to CL_SUCCESS if the kernel is successfully copied. Otherwise it returns a NULL value with one of the following error values returned in errcode_ret:

- CL_INVALID_KERNEL if kernel is not a valid kernel object.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

5.9.4. Kernel Object Queries

To return information about a kernel object, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clGetKernelInfo(
    cl_kernel kernel,
    cl_kernel_info param_name,
    size_t param_value_size,
    void* param_value,
    size_t* param_value_size_ret);
```

- `kernel` specifies the kernel object being queried.
- `param_name` specifies the information to query. The list of supported `param_name` types and the information returned in `param_value` by `clGetKernelInfo` is described in the Kernel Object Queries table.
- `param_value` is a pointer to memory where the appropriate result being queried is returned. If `param_value` is NULL, it is ignored.
- `param_value_size` is used to specify the size in bytes of memory pointed to by `param_value`. This size must be ≥ size of return type as described in the Kernel Object Queries table.
- `param_value_size_ret` returns the actual size in bytes of data being queried by `param_name`. If `param_value_size_ret` is NULL, it is ignored.

Table 46. List of supported `param_names` by `clGetKernelInfo`
<table>
<thead>
<tr>
<th>Kernel Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_KERNEL_FUNCTION_NAME</td>
<td>char[]</td>
<td>Return the kernel function name.</td>
</tr>
<tr>
<td>CL_KERNEL_NUM_ARGS</td>
<td>cl_uint</td>
<td>Return the number of arguments to kernel.</td>
</tr>
<tr>
<td>CL_KERNEL_REFERENCE_COUNT</td>
<td>cl_uint</td>
<td>Return the kernel reference count.</td>
</tr>
<tr>
<td>CL_KERNEL_CONTEXT</td>
<td>cl_context</td>
<td>Return the context associated with kernel.</td>
</tr>
<tr>
<td>CL_KERNEL_PROGRAM</td>
<td>cl_program</td>
<td>Return the program object associated with kernel.</td>
</tr>
<tr>
<td>CL_KERNEL_ATTRIBUTES</td>
<td>char[]</td>
<td>Returns any attributes specified using the <strong>attribute</strong> OpenCL C qualifier (or using an OpenCL C++ qualifier syntax [[]] ) with the kernel function declaration in the program source. These attributes include attributes described in the earlier OpenCL C kernel language specifications and other attributes supported by an implementation. Attributes are returned as they were declared inside <strong>attribute</strong>((...)), with any surrounding whitespace and embedded newlines removed. When multiple attributes are present, they are returned as a single, space delimited string. For kernels not created from OpenCL C source and the clCreateProgramWithSource API call the string returned from this query will be empty.</td>
</tr>
</tbody>
</table>

clGetKernelInfo returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_VALUE** if param_name is not valid, or if size in bytes specified by param_value_size is < size of return type as described in the Kernel Object Queries table and param_value is not NULL.
- **CL_INVALID_KERNEL** if kernel is a not a valid kernel object.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To return information about the kernel object that may be specific to a device, call the function
• **kernel** specifies the kernel object being queried.

• **device** identifies a specific device in the list of devices associated with **kernel**. The list of devices is the list of devices in the OpenCL context that is associated with **kernel**. If the list of devices associated with **kernel** is a single device, **device** can be a **NULL** value.

• **param_name** specifies the information to query. The list of supported **param_name** types and the information returned in **param_value** by **clGetKernelWorkGroupInfo** is described in the **Kernel Object Device Queries** table.

• **param_value** is a pointer to memory where the appropriate result being queried is returned. If **param_value** is **NULL**, it is ignored.

• **param_value_size** is used to specify the size in bytes of memory pointed to by **param_value**. This size must be ≥ size of return type as described in the **Kernel Object Device Queries** table.

• **param_value_size_ret** returns the actual size in bytes of data being queried by **param_name**. If **param_value_size_ret** is **NULL**, it is ignored.

Table 47. List of supported **param_name**s by **clGetKernelWorkGroupInfo**

<table>
<thead>
<tr>
<th>Kernel Work-group Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_KERNEL_GLOBAL_WORK_SIZE</td>
<td>size_t[3]</td>
<td>This provides a mechanism for the application to query the maximum global size that can be used to execute a kernel (i.e. <strong>global_work_size</strong> argument to <strong>clEnqueueNDRangeKernel</strong>) on a custom device given by device or a built-in kernel on an OpenCL device given by device. If device is not a custom device and kernel is not a built-in kernel, <strong>clGetKernelWorkGroupInfo</strong> returns the error <strong>CL_INVALID_VALUE</strong>.</td>
</tr>
<tr>
<td>Kernel Work-group Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>----------------------------------------</td>
<td>-------------</td>
<td>---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_KERNEL_WORK_GROUP_SIZE</td>
<td>size_t</td>
<td>This provides a mechanism for the application to query the maximum work-group size that can be used to execute the kernel on a specific device given by device. The OpenCL implementation uses the resource requirements of the kernel (register usage etc.) to determine what this work-group size should be. As a result and unlike CL_DEVICE_MAX_WORK_GROUP_SIZE this value may vary from one kernel to another as well as one device to another. CL_KERNEL_WORK_GROUP_SIZE will be less than or equal to CL_DEVICE_MAX_WORK_GROUP_SIZE for a given kernel object.</td>
</tr>
<tr>
<td>CL_KERNEL_COMPILE_WORK_GROUP_SIZE</td>
<td>size_t[3]</td>
<td>Returns the work-group size specified in the kernel source or IL.</td>
</tr>
<tr>
<td>CL_KERNEL_LOCAL_MEM_SIZE</td>
<td>cl_ulong</td>
<td>Returns the amount of local memory in bytes being used by a kernel. This includes local memory that may be needed by an implementation to execute the kernel, variables declared inside the kernel with the __local address qualifier and local memory to be allocated for arguments to the kernel declared as pointers with the __local address qualifier and whose size is specified with clSetKernelArg. If the local memory size, for any pointer argument to the kernel declared with the __local address qualifier, is not specified, its size is assumed to be 0.</td>
</tr>
<tr>
<td>CL_KERNEL.PREFERRED_WORK_GROUP_SIZE_MULTIPLE</td>
<td>size_t</td>
<td>Returns the preferred multiple of work-group size for launch. This is a performance hint. Specifying a work-group size that is not a multiple of the value returned by this query as the value of the local work size argument to clEnqueueNDRangeKernel will not fail to enqueue the kernel for execution unless the work-group size specified is larger than the device maximum.</td>
</tr>
<tr>
<td>Kernel Work-group Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>--------------------------------</td>
<td>-------------</td>
<td>------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_KERNEL_PRIVATE_MEM_SIZE</td>
<td>cl_ulong</td>
<td>Returns the minimum amount of private memory, in bytes, used by each work-item in the kernel. This value may include any private memory needed by an implementation to execute the kernel, including that used by the language built-ins and variable declared inside the kernel with the __private qualifier.</td>
</tr>
</tbody>
</table>

`clGetKernelWorkGroupInfo` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_DEVICE** if `device` is not in the list of devices associated with `kernel` or if `device` is `NULL` but there is more than one device associated with `kernel`.
- **CL_INVALID_VALUE** if `param_name` is not valid, or if size in bytes specified by `param_value_size` is < size of return type as described in the Kernel Object Device Queries table and `param_value` is not `NULL`.
- **CL_INVALID_VALUE** if `param_name` is `CL_KERNEL_GLOBAL_WORK_SIZE` and `device` is not a custom device and `kernel` is not a built-in kernel.
- **CL_INVALID_KERNEL** if `kernel` is a not a valid kernel object.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To return information about a kernel object, call the function

```c
// Provided by CL_VERSION_2_1
cl_int clGetKernelSubGroupInfo(
    cl_kernel kernel,
    cl_device_id device,
    cl_kernel_sub_group_info param_name,
    size_t input_value_size,
    const void* input_value,
    size_t param_value_size,
    void* param_value,
    size_t* param_value_size_ret);
```

`clGetKernelSubGroupInfo` is missing before version 2.1.

Also see `cl_khr_subgroups`.

- `kernel` specifies the kernel object being queried.
- `device` identifies a specific device in the list of devices associated with `kernel`. The list of devices is the list of devices in the OpenCL context that is associated with `kernel`. If the list of devices
associated with kernel is a single device, device can be a NULL value.

- **param_name** specifies the information to query. The list of supported **param_name** types and the information returned in **param_value** by `clGetKernelSubGroupInfo` is described in the Kernel Object Sub-group Queries table.

- **input_value_size** is used to specify the size in bytes of memory pointed to by **input_value**. This size must be == size of input type as described in the table below.

- **input_value** is a pointer to memory where the appropriate parameterization of the query is passed from. If **input_value** is NULL, it is ignored.

- **param_value** is a pointer to memory where the appropriate result being queried is returned. If **param_value** is NULL, it is ignored.

- **param_value_size** is used to specify the size in bytes of memory pointed to by **param_value**. This size must be ≥ size of return type as described in the table below.

- **param_value_size_ret** returns the actual size in bytes of data being queried by **param_name**. If **param_value_size_ret** is NULL, it is ignored.

### Table 48. List of supported param_names by `clGetKernelSubGroupInfo`

<table>
<thead>
<tr>
<th>Kernel Sub-group Info</th>
<th>Input Type</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_KERNEL_MAX_SUB_</td>
<td>size_t*</td>
<td>size_t</td>
<td>Returns the maximum sub-group size for this kernel. All sub-groups must be the same size, while the last sub-group in any work-group (i.e. the sub-group with the maximum index) could be the same or smaller size.</td>
</tr>
<tr>
<td>GROUP_SIZE_FOR_NDRANGE</td>
<td></td>
<td></td>
<td>The equivalent CL_KERNEL_MAX_SUB_ GROUP_SIZE_FOR_NDRANGE_KHR may be used if the cl_khr_subgroups extension is supported.</td>
</tr>
</tbody>
</table>

The **input_value** must be an array of **size_t** values corresponding to the local work size parameter of the intended dispatch. The number of dimensions in the ND-range will be inferred from the value specified for **input_value_size**.
<table>
<thead>
<tr>
<th>Kernel Sub-group Info</th>
<th>Input Type</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>CL_KERNEL_SUB_GROUP_COUNT_FOR_NDRANGE</strong>&lt;br&gt;missing before version 2.1.</td>
<td><code>size_t*</code></td>
<td><code>size_t</code></td>
<td>Returns the number of sub-groups that will be present in each work-group for a given local work size. All workgroups, apart from the last work-group in each dimension in the presence of non-uniform work-group sizes, will have the same number of sub-groups. The <code>input_value</code> must be an array of <code>size_t</code> values corresponding to the local work size parameter of the intended dispatch. The number of dimensions in the ND-range will be inferred from the value specified for <code>input_value_size</code>.</td>
</tr>
</tbody>
</table>

The equivalent **CL_KERNEL_SUB_GROUP_COUNT_FOR_NDRANGE_KHR** may be used if the cl_khr_subgroups extension is supported.
<table>
<thead>
<tr>
<th>Kernel Sub-group Info</th>
<th>Input Type</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_KERNEL_LOCAL_SIZE_</td>
<td>size_t</td>
<td>size_t[]</td>
<td>Returns the local size that will generate the requested number of sub-groups for the kernel. The output array must be an array of size_t values corresponding to the local size parameter. Any returned work-group will have one dimension. Other dimensions inferred from the value specified for param_value_size will be filled with the value 1. The returned value will produce an exact number of sub-groups and result in no partial groups for an executing kernel except in the case where the last work-group in a dimension has a size different from that of the other groups. If no work-group size can accommodate the requested number of sub-groups, 0 will be returned in each element of the return array.</td>
</tr>
<tr>
<td>FOR_SUB_GROUP_COUNT</td>
<td></td>
<td></td>
<td>missing before version 2.1. Also see cl_khr_subgroups.</td>
</tr>
</tbody>
</table>
## Kernel Sub-group Info

<table>
<thead>
<tr>
<th>Input Type</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_KERNEL_MAX_NUM_SUB_GROUPS</td>
<td>ignored</td>
<td>size_t</td>
</tr>
<tr>
<td>missing before version 2.1.</td>
<td></td>
<td>This provides a mechanism for the application to query the maximum number of sub-groups that may make up each work-group to execute a kernel on a specific device given by device. The OpenCL implementation uses the resource requirements of the kernel (register usage etc.) to determine what this work-group size should be. The returned value may be used to compute a work-group size to enqueue the kernel with to give a round number of sub-groups for an enqueue.</td>
</tr>
<tr>
<td>CL_KERNEL_COMPILE_NUM_SUB_GROUPS</td>
<td>ignored</td>
<td>size_t</td>
</tr>
<tr>
<td>missing before version 2.1.</td>
<td></td>
<td>Returns the number of sub-groups per work-group specified in the kernel source or IL. If the sub-group count is not specified then 0 is returned.</td>
</tr>
<tr>
<td>clGetKernelSubGroupInfo returns</td>
<td>CL_SUCCESS</td>
<td></td>
</tr>
<tr>
<td>CL_INVALID_DEVICE if device is</td>
<td></td>
<td></td>
</tr>
<tr>
<td>not in the list of devices</td>
<td></td>
<td></td>
</tr>
<tr>
<td>associated with kernel or if</td>
<td></td>
<td></td>
</tr>
<tr>
<td>device is NULL but there is</td>
<td></td>
<td></td>
</tr>
<tr>
<td>more than one device associated</td>
<td></td>
<td></td>
</tr>
<tr>
<td>with kernel.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_INVALID_OPERATION if device</td>
<td></td>
<td></td>
</tr>
<tr>
<td>does not support sub-groups.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_INVALID_VALUE if param_name</td>
<td></td>
<td></td>
</tr>
<tr>
<td>is not valid, or if size in bytes specified by param_value_size is &lt; size of return type as described in the Kernel Object Sub-group Queries table and param_value is not NULL.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_INVALID_VALUE if param_name</td>
<td></td>
<td></td>
</tr>
<tr>
<td>is CL_KERNEL_MAX_SUB_GROUP_SIZE_FOR_NDRANGE, CL_KERNEL_SUB_GROUP_COUNT_FOR_NDRANGE or CL_KERNEL_LOCAL_SIZE_FOR_SUB_GROUP_COUNT and the size in bytes specified by input_value_size is not valid or if input_value is NULL.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

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• **CL_INVALID_KERNEL** if *kernel* is a not a valid kernel object.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To return information about the arguments of a kernel, call the function

```c
// Provided by CL_VERSION_1_2
cl_int clGetKernelArgInfo(
    cl_kernel kernel,
    cl_uint arg_index,
    cl_kernel_arg_info param_name,
    size_t param_value_size,
    void* param_value,
    size_t* param_value_size_ret);
```

- **clGetKernelArgInfo** is missing before version 1.2.

- *kernel* specifies the kernel object being queried.

- *arg_index* is the argument index. Arguments to the kernel are referred by indices that go from 0 for the leftmost argument to *n* - 1, where *n* is the total number of arguments declared by a kernel.

- **param_name** specifies the argument information to query. The list of supported **param_name** types and the information returned in **param_value** by **clGetKernelArgInfo** is described in the Kernel Argument Queries table.

- **param_value** is a pointer to memory where the appropriate result being queried is returned. If **param_value** is NULL, it is ignored.

- **param_value_size** is used to specify the size in bytes of memory pointed to by **param_value**. This size must be > size of return type as described in the Kernel Argument Queries table.

- **param_value_size_ret** returns the actual size in bytes of data being queried by **param_name**. If **param_value_size_ret** is NULL, it is ignored.

Kernel argument information is only available if the program object associated with *kernel*:

- is created with **clCreateProgramWithBinary** and the program executable is built with the **-cl -kernel-arg-info** and **-x spir** options specified in the **options** argument to **clBuildProgram** or **clCompileProgram**, if the **cl_khr_spir** extension is supported; or,

- is created with **clCreateProgramWithSource** and the program executable is built with the **-cl -kernel-arg-info** option specified in the **options** argument to **clBuildProgram** or **clCompileProgram**.

*Table 49. List of supported **param_names** by **clGetKernelArgInfo***
<table>
<thead>
<tr>
<th>Kernel Arg Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
</table>
| CL_KERNEL_ARG_ADDRESS_QUALIFIER | cl_kernel_arg_address_qualifier | Returns the address qualifier specified for the argument given by `arg_index`. This can be one of the following values:  
  - CL_KERNEL_ARG_ADDRESS_GLOBAL  
  - CL_KERNEL_ARG_ADDRESS_LOCAL  
  - CL_KERNEL_ARG_ADDRESS_CONSTANT  
  - CL_KERNEL_ARG_ADDRESS_PRIVATE  
  
  If no address qualifier is specified, the default address qualifier which is `CL_KERNEL_ARG_ADDRESS_PRIVATE` is returned. |
| CL_KERNEL_ARG_ACCESS_QUALIFIER | cl_kernel_arg_access_qualifier | Returns the access qualifier specified for the argument given by `arg_index`. This can be one of the following values:  
  - CL_KERNEL_ARG_ACCESS_READ_ONLY  
  - CL_KERNEL_ARG_ACCESS_WRITE_ONLY  
  - CL_KERNEL_ARG_ACCESS_READ_WRITE  
  - CL_KERNEL_ARG_ACCESS_NONE  
  
  If argument is not an image type and is not declared with the pipe qualifier, `CL_KERNEL_ARG_ACCESS_NONE` is returned. If argument is an image type, the access qualifier specified or the default access qualifier is returned. |
<p>| CL_KERNEL_ARG_TYPE_NAME | char[] | Returns the type name specified for the argument given by <code>arg_index</code>. The type name returned will be the argument type name as it was declared with any whitespace removed. If argument type name is an unsigned scalar type (i.e. unsigned char, unsigned short, unsigned int, unsigned long), uchar, ushort, uint and ulong will be returned. The argument type name returned does not include any type qualifiers. |</p>
<table>
<thead>
<tr>
<th>Kernel Arg Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_KERNEL_ARG_TYPE_QUALIFIER</td>
<td>cl_kernel_arg_type_qualifier</td>
<td>Returns a bitfield describing one or more type qualifiers specified for the argument given by arg_index. The returned values can be:</td>
</tr>
</tbody>
</table>
| missing before version 1.2.      |                                          | CL_KERNEL_ARG_TYPE_CONST
CL_KERNEL_ARG_TYPE_RESTRICT
CL_KERNEL_ARG_TYPE_VOLATILE
CL_KERNEL_ARG_TYPE_PIPE, or
CL_KERNEL_ARG_TYPE_NONE

CL_KERNEL_ARG_TYPE_CONST is returned if the kernel argument is a pointer and the referenced type is declared with the const qualifier. For example, a kernel argument declared as global int const* returns CL_KERNEL_ARG_TYPE_CONST but a kernel argument declared as global int* const does not. Additionally, CL_KERNEL_ARG_TYPE_CONST is returned if the kernel argument is declared with the constant address space qualifier.

CL_KERNEL_ARG_TYPE_RESTRICT is returned if the pointer type is marked restrict. For example, global int* restrict returns CL_KERNEL_ARG_TYPE_RESTRICT.

CL_KERNEL_ARG_TYPE_VOLATILE is returned for CL_KERNEL_ARG_TYPE_QUALIFIER if the kernel argument is a pointer and the referenced type is declared with the volatile qualifier. For example, a kernel argument declared as global int volatile* returns CL_KERNEL_ARG_TYPE_VOLATILE but a kernel argument declared as global int* volatile does not.

CL_KERNEL_ARG_TYPE_NONE is returned for all kernel arguments passed by value.

<table>
<thead>
<tr>
<th>CL_KERNEL_ARG_NAME</th>
<th>char[]</th>
<th>Returns the name specified for the argument given by arg_index.</th>
</tr>
</thead>
<tbody>
<tr>
<td>missing before version 1.2.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**clGetKernelArgInfo** returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_ARG_INDEX** if arg_index is not a valid argument index.
- **CL_INVALID_VALUE** if param_name is not valid, or if size in bytes specified by param_value size is < size of return type as described in the Kernel Argument Queries table and param_value is not
• **CL_KERNEL_ARG_INFO_NOT_AVAILABLE** if the argument information is not available for kernel.
• **CL_INVALID_KERNEL** if *kernel* is not a valid kernel object.

To query a suggested local work size for a kernel object, call the function

```c
// Provided by cl_khr_suggested_local_work_size
cl_int clGetKernelSuggestedLocalWorkSizeKHR(
    cl_command_queue command_queue,
    cl_kernel kernel,
    cl_uint work_dim,
    const size_t* global_work_offset,
    const size_t* global_work_size,
    size_t* suggested_local_work_size);
```

- *command_queue* specifies the command-queue and device for the query.
- *kernel* specifies the kernel object and kernel arguments for the query. The OpenCL context associated with *kernel* and *command_queue* must be the same.
- *work_dim* specifies the number of work dimensions in the input global work offset and global work size, and the output suggested local work size.
- *global_work_offset* can be used to specify an array of at least *work_dim* global ID offset values for the query. This is optional and may be **NULL** to indicate there is no global ID offset.
- *global_work_size* is an array of at least *work_dim* values describing the global work size for the query.
- *suggested_local_work_size* is an output array of at least *work_dim* values that will contain the result of the query.

The returned suggested local work size is expected to match the local work size that would be chosen if the specified kernel object, with the same kernel arguments, were enqueued into the specified command-queue with the specified global work size, specified global work offset, and with a **NULL** local work size.

**clGetKernelSuggestedLocalWorkSizeKHR** returns **CL_SUCCESS** if the query executed successfully. Otherwise, it returns one of the following errors:

• **CL_INVALID_COMMAND_QUEUE** if *command_queue* is not a valid host command-queue.
• **CL_INVALID_KERNEL** if *kernel* is not a valid kernel object.
• **CL_INVALID_CONTEXT** if the context associated with *kernel* is not the same as the context associated with *command_queue*.
• **CL_INVALID_PROGRAM_EXECUTABLE** if there is no successfully built program executable available for *kernel* for the device associated with *command_queue*.
• **CL_INVALID_KERNEL_ARGS** if all argument values for *kernel* have not been set.

• **CL_MISALIGNED_SUB_BUFFER_OFFSET** if a sub-buffer object is set as an argument to *kernel* and the offset specified when the sub-buffer object was created is not aligned to **CL_DEVICE_MEM_BASE_ADDR_ALIGN** for the device associated with *command_queue*.

• **CL_INVALID_IMAGE_SIZE** if an image object is set as an argument to *kernel* and the image dimensions are not supported by device associated with *command_queue*.

• **CL_IMAGE_FORMAT_NOT_SUPPORTED** if an image object is set as an argument to *kernel* and the image format is not supported by the device associated with *command_queue*.

• **CL_INVALID_OPERATION** if an SVM pointer is set as an argument to *kernel* and the device associated with *command_queue* does not support SVM or the required SVM capabilities for the SVM pointer.

• **CL_INVALID_WORK_DIMENSION** if *work_dim* is not a valid value (i.e. a value between 1 and **CL_DEVICE_MAX_WORK_ITEM_DIMENSIONS**).

• **CL_INVALID_GLOBAL_WORK_SIZE** if *global_work_size* is NULL or if any of the values specified in *global_work_size* are 0.

• **CL_INVALID_GLOBAL_WORK_SIZE** if any of the values specified in *global_work_size* exceed the maximum value representable by **size_t** on the device associated with *command_queue*.

• **CL_INVALID_GLOBAL_OFFSET** if the value specified in *global_work_size* plus the corresponding value in *global_work_offset* for dimension exceeds the maximum value representable by **size_t** on the device associated with *command_queue*.

• **CL_INVALID_VALUE** if *suggested_local_work_size* is NULL.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

These error conditions are consistent with error conditions for **clEnqueueNDRangeKernel**.

### 5.10. Executing Kernels

To enqueue a command to execute a kernel on a device, call the function
cl_int clEnqueueNDRangeKernel(
    cl_command_queue command_queue,
    cl_kernel kernel,
    cl_uint work_dim,
    const size_t* global_work_offset,
    const size_t* global_work_size,
    const size_t* local_work_size,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);

- `command_queue` is a valid host command-queue. The kernel will be queued for execution on the device associated with `command_queue`.

- `kernel` is a valid kernel object. The OpenCL context associated with `kernel` and `command_queue` must be the same.

- `work_dim` is the number of dimensions used to specify the global work-items and work-items in the work-group. `work_dim` must be greater than zero and less than or equal to `CL_DEVICE_MAX_WORK_ITEM_DIMENSIONS`. If `global_work_size` is `NULL`, or the value in any passed dimension is 0 then the kernel command will trivially succeed after its event dependencies are satisfied and subsequently update its completion event. The behavior in this situation is similar to that of an enqueued marker, except that unlike a marker, an enqueued kernel with no events passed to `event_wait_list` may run at any time.

- `global_work_offset` can be used to specify an array of `work_dim` unsigned values that describe the offset used to calculate the global ID of a work-item. If `global_work_offset` is `NULL`, the global IDs start at offset (0, 0, 0). `global_work_offset` must be `NULL` before version 1.1.

- `global_work_size` points to an array of `work_dim` unsigned values that describe the number of global work-items in `work_dim` dimensions that will execute the kernel function. The total number of global work-items is computed as `global_work_size[0] × ... × global_work_size[work_dim - 1].`

- `local_work_size` points to an array of `work_dim` unsigned values that describe the number of work-items that make up a work-group (also referred to as the size of the work-group) that will execute the kernel specified by `kernel`. The total number of work-items in a work-group is computed as `local_work_size[0] × ... × local_work_size[work_dim - 1].` The total number of work-items in the work-group must be less than or equal to the `CL_KERNEL_WORK_GROUP_SIZE` value specified in the `Kernel Object Device Queries` table, and the number of work-items specified in `local_work_size[0], ..., local_work_size[work_dim - 1]` must be less than or equal to the corresponding values specified by `CL_DEVICE_MAX_WORK_ITEM_SIZES[0], ..., CL_DEVICE_MAX_WORK_ITEM_SIZES[work_dim - 1].` The explicitly specified `local_work_size` will be used to determine how to break the global work-items specified by `global_work_size` into appropriate work-group instances.

- `event_wait_list` and `num_events_in_wait_list` specify events that need to complete before this particular command can be executed. If `event_wait_list` is `NULL`, then this particular command does not wait on any event to complete. If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid.
and num_events_in_wait_list must be greater than 0. The events specified in event_wait_list act as synchronization points. The context associated with events in event_wait_list and command_queue must be the same. The memory associated with event_wait_list can be reused or freed after the function returns.

- event returns an event object that identifies this command and can be used to query or wait for this command to complete. If event is NULL or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If event_wait_list and event are not NULL, event must not refer to an element of the event_wait_list array.

An ND-range kernel command may require uniform work-groups or may support non-uniform work-groups. To support non-uniform work-groups:

1. The device associated with command_queue must support non-uniform work-groups.
2. The program object associated with kernel must support non-uniform work-groups. Specifically, this means:
   a. If the program was created with clCreateProgramWithSource, the program must be compiled or built using the -cl-std=CL2.0 or -cl-std=CL3.0 build option and without the -cl-uniform-work-group-size build option.
   b. If the program was created with clCreateProgramWithIL or clCreateProgramWithBinary, the program must be compiled or built without the -cl-uniform-work-group-size build options.
   c. If the program was created using clLinkProgram, all input programs must support non-uniform work-groups.

If non-uniform work-groups are supported, any single dimension for which the global size is not divisible by the local size will be partitioned into two regions. One region will have work-groups that have the same number of work-items as was specified by the local size parameter in that dimension. The other region will have work-groups with less than the number of work items specified by the local size parameter in that dimension. The global IDs and group IDs of the work-items in the first region will be numerically lower than those in the second, and the second region will be at most one work-group wide in that dimension. Work-group sizes could be non-uniform in multiple dimensions, potentially producing work-groups of up to 4 different sizes in a 2D range and 8 different sizes in a 3D range.

If non-uniform work-groups are supported and local_work_size is NULL, the OpenCL runtime may choose a uniform or non-uniform work-group size.

Otherwise, when non-uniform work-groups are not supported, the size of each work-group must be uniform. If local_work_size is specified, the values specified in global_work_size[0], ..., global_work_size[work_dim - 1] must be evenly divisible by the corresponding values specified in local_work_size[0], ..., local_work_size[work_dim - 1]. If local_work_size is NULL, the OpenCL runtime must choose a uniform work-group size.

The work-group size to be used for kernel can also be specified in the program source or intermediate language. In this case the size of work-group specified by local_work_size must match the value specified in the program source.
These work-group instances are executed in parallel across multiple compute units or concurrently on the same compute unit.

Each work-item is uniquely identified by a global identifier. The global ID, which can be read inside the kernel, is computed using the value given by `global_work_size` and `global_work_offset`. In addition, a work-item is also identified within a work-group by a unique local ID. The local ID, which can also be read by the kernel, is computed using the value given by `local_work_size`. The starting local ID is always (0, 0, ..., 0).

`clEnqueueNDRangeKernel` returns `CL_SUCCESS` if the kernel-instance was successfully queued. Otherwise, it returns one of the following errors:

- `CL_INVALID_PROGRAM_EXECUTABLE` if there is no successfully built program executable available for device associated with `command_queue`.
- `CL_INVALID_COMMAND_QUEUE` if `command_queue` is not a valid host command-queue.
- `CL_INVALID_KERNEL` if `kernel` is not a valid kernel object.
- `CL_INVALID_CONTEXT` if context associated with `command_queue` and `kernel` are not the same or if the context associated with `command_queue` and events in `event_wait_list` are not the same.
- `CL_INVALID_KERNEL_ARGS` if the kernel argument values have not been specified.
- `CL_INVALID_WORK_DIMENSION` if `work_dim` is not a valid value (i.e. a value between 1 and `CL_DEVICE_MAX_WORK_ITEM_DIMENSIONS`).
- `CL_INVALID_GLOBAL_WORK_SIZE` if `global_work_size` is NULL or if any of the values specified in `global_work_size[0]`, ..., `global_work_size[work_dim - 1]` are 0. Returning this error code under these circumstances is deprecated by version 2.1.
- `CL_INVALID_GLOBAL_WORK_SIZE` if any of the values specified in `global_work_size[0]`, ..., `global_work_size[work_dim - 1]` exceed the maximum value representable by `size_t` on the device on which the kernel-instance will be enqueued.
- `CL_INVALID_GLOBAL_OFFSET` if the value specified in `global_work_size +` the corresponding values in `global_work_offset` for any dimensions is greater than the maximum value representable by `size_t` on the device on which the kernel-instance will be enqueued, or if `global_work_offset` is non-NULL before version 1.1.
- `CL_INVALID_WORK_GROUP_SIZE` if `local_work_size` is specified and does not match the required work-group size for `kernel` in the program source.
- `CL_INVALID_WORK_GROUP_SIZE` if `local_work_size` is specified and is not consistent with the required number of sub-groups for `kernel` in the program source.
- `CL_INVALID_WORK_GROUP_SIZE` if `local_work_size` is specified and the total number of work-items in the work-group computed as `local_work_size[0] × ... local_work_size[work_dim - 1]` is greater than the value specified by `CL_KERNEL_WORK_GROUP_SIZE` in the Kernel Object Device Queries table.
- `CL_INVALID_WORK_GROUP_SIZE` if the work-group size must be uniform and the `local_work_size` is not NULL, is not equal to the required work-group size specified in the kernel source, or the `global_work_size` is not evenly divisible by the `local_work_size`.
- `CL_INVALID_WORK_ITEM_SIZE` if the number of work-items specified in any of `local_work_size[0]`, ..., `local_work_size[work_dim - 1]` is greater than the corresponding values specified by `CL_DEVICE_`
MAX_WORK_ITEM_SIZES[0], ..., CL_DEVICE_MAX_WORK_ITEM_SIZES[work_dim - 1].

- **CL_MISALIGNED_SUB_BUFFER_OFFSET** if a sub-buffer object is specified as the value for an argument that is a buffer object and the offset specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for device associated with *queue*. This error code is missing before version 1.1.

- **CL_INVALID_IMAGE_SIZE** if an image object is specified as an argument value and the image dimensions (image width, height, specified or compute row and/or slice pitch) are not supported by device associated with *queue*.

- **CL_IMAGE_FORMAT_NOT_SUPPORTED** if an image object is specified as an argument value and the image format (image channel order and data type) is not supported by device associated with *queue*.

- **CL_OUT_OF_RESOURCES** if there is a failure to queue the execution instance of *kernel* on the command-queue because of insufficient resources needed to execute the kernel. For example, the explicitly specified *local_work_size* causes a failure to execute the kernel because of insufficient resources such as registers or local memory. Another example would be the number of read-only image args used in *kernel* exceed the CL_DEVICE_MAX_READ_IMAGE_ARGS value for device or the number of write-only and read-write image args used in *kernel* exceed the CL_DEVICE_MAX_READ_WRITE_IMAGE_ARGS value for device or the number of samplers used in *kernel* exceed CL_DEVICE_MAX_SAMPLERS for device.

- **CL_MEM_OBJECT_ALLOCATION_FAILURE** if there is a failure to allocate memory for data store associated with image or buffer objects specified as arguments to *kernel*.

- **CL_INVALID_EVENT_WAIT_LIST** if *event_wait_list* is **NULL** and *num_events_in_wait_list* > 0, or *event_wait_list* is not **NULL** and *num_events_in_wait_list* is 0, or if event objects in *event_wait_list* are not valid events.

- **CL_INVALID_OPERATION** if SVM pointers are passed as arguments to a kernel and the device does not support SVM or if system pointers are passed as arguments to a kernel and/or stored inside SVM allocations passed as kernel arguments and the device does not support fine grain system SVM allocations.

- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To enqueue a command to execute a kernel on a device, using a single work-item, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clEnqueueTask(
    cl_command_queue command_queue,
    cl_kernel kernel,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```
clEnqueueTask is deprecated by version 2.0.

- **command_queue** is a valid host command-queue. The kernel will be queued for execution on the device associated with command_queue.

- **kernel** is a valid kernel object. The OpenCL context associated with kernel and command_queue must be the same.

- **event_wait_list** and num_events_in_wait_list specify events that need to complete before this particular command can be executed. If event_wait_list is NULL, then this particular command does not wait on any event to complete. If event_wait_list is NULL, num_events_in_wait_list must be 0. If event_wait_list is not NULL, the list of events pointed to by event_wait_list must be valid and num_events_in_wait_list must be greater than 0. The events specified in event_wait_list act as synchronization points. The context associated with events in event_wait_list and command_queue must be the same. The memory associated with event_wait_list can be reused or freed after the function returns.

- **event** returns an event object that identifies this command and can be used to query or wait for this command to complete. If event is NULL or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If event_wait_list and event are not NULL, event must not refer to an element of the event_wait_list array.

clEnqueueTask is equivalent to calling clEnqueueNDRangeKernel with work_dim set to 1, global_work_offset set to NULL, global_work_size[0] set to 1, and local_work_size[0] set to 1.

clEnqueueTask returns **CL_SUCCESS** if the kernel-instance was successfully queued. Otherwise, it returns one of the following errors:

- **CL_INVALID_PROGRAM_EXECUTABLE** if there is no successfully built program executable available for device associated with command_queue.

- **CL_INVALID_COMMAND_QUEUE** if command_queue is not a valid host command-queue.

- **CL_INVALID_KERNEL** if kernel is not a valid kernel object.

- **CL_INVALID_CONTEXT** if context associated with command_queue and kernel are not the same or if the context associated with command_queue and events in event_wait_list are not the same.

- **CL_INVALID_KERNEL_ARGS** if the kernel argument values have not been specified.

- **CL_INVALID_WORK_GROUP_SIZE** if a work-group size is specified for kernel in the program source and it is not (1, 1, 1).

- **CL_INVALID_WORK_GROUP_SIZE** if the required number of sub-groups is specified for kernel in the program source and is not consistent with a work-group size of (1, 1, 1).

- **CL_MISALIGNED_SUB_BUFFER_OFFSET** if a sub-buffer object is specified as the value for an argument that is a buffer object and the offset specified when the sub-buffer object is created is not aligned to CL_DEVICE_MEM_BASE_ADDR_ALIGN value for device associated with queue. This error code is missing before version 1.1.

- **CL_INVALID_IMAGE_SIZE** if an image object is specified as an argument value and the image dimensions (image width, height, specified or compute row and/or slice pitch) are not supported by device associated with queue.
• **CL_IMAGE_FORMAT_NOT_SUPPORTED** if an image object is specified as an argument value and the image format (image channel order and data type) is not supported by device associated with queue.

• **CL_OUT_OF_RESOURCES** if there is a failure to queue the execution instance of *kernel* on the command-queue because of insufficient resources needed to execute the kernel. See how this error code is used with `clEnqueueNDRangeKernel` for examples.

• **CL_MEM_OBJECT_ALLOCATION_FAILURE** if there is a failure to allocate memory for data store associated with image or buffer objects specified as arguments to *kernel*.

• **CL_INVALID_EVENT_WAIT_LIST** if `event_wait_list` is `NULL` and `num_events_in_wait_list > 0`, or `event_wait_list` is not `NULL` and `num_events_in_wait_list` is `0`, or if event objects in `event_wait_list` are not valid events.

• **CL_INVALID_OPERATION** if SVM pointers are passed as arguments to a kernel and the device does not support SVM or if system pointers are passed as arguments to a kernel and/or stored inside SVM allocations passed as kernel arguments and the device does not support fine grain system SVM allocations.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To enqueue a command to execute a native C/C++ function not compiled using the OpenCL compiler, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clEnqueueNativeKernel(
    cl_command_queue command_queue,
    void (CL_CALLBACK* user_func)(void*),
    void* args,
    size_t cb_args,
    cl_uint num_mem_objects,
    const cl_mem* mem_list,
    const void** args_mem_loc,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

• **command_queue** is a valid host command-queue. A native user function can only be executed on a command-queue created on a device that has `CL_EXEC_NATIVE_KERNEL` capability set in `CL_DEVICE_EXECUTION_CAPABILITIES` as specified in the Device Queries table.

• **user_func** is a pointer to a host-callable user function. It is the application’s responsibility to ensure that the host-callable user function is thread-safe.

• **args** is a pointer to the args list that `user_func` should be called with.

• **cb_args** is the size in bytes of the args list that `args` points to.

• **num_mem_objects** is the number of buffer objects that are passed in `args`. 
mem_list is a list of valid buffer objects, if num_mem_objects > 0. The buffer object values specified in mem_list are memory object handles (cl_mem values) returned by clCreateBuffer or clCreateBufferWithProperties, or NULL.

args_mem_loc is a pointer to appropriate locations that args points to where memory object handles (cl_mem values) are stored. Before the user function is executed, the memory object handles are replaced by pointers to global memory.

event_wait_list, num_events_in_wait_list and event are as described in clEnqueueNDRangeKernel.

The data pointed to by args and cb_args bytes in size will be copied and a pointer to this copied region will be passed to user_func. The copy needs to be done because the memory objects (cl_mem values) that args may contain need to be modified and replaced by appropriate pointers to global memory. When clEnqueueNativeKernel returns, the memory region pointed to by args can be reused by the application.

clEnqueueNativeKernel returns CL_SUCCESS if the user function execution instance was successfully queued. Otherwise, it returns one of the following errors:

- CL_INVALID_COMMAND_QUEUE if command_queue is not a valid host command-queue.
- CL_INVALID_CONTEXT if context associated with command_queue and events in event_wait_list are not the same.
- CL_INVALID_VALUE if user_func is NULL.
- CL_INVALID_VALUE if args is a NULL value and cb_args > 0, or if args is a NULL value and num_mem_objects > 0.
- CL_INVALID_VALUE if args is not NULL and cb_args is 0.
- CL_INVALID_VALUE if num_mem_objects > 0 and mem_list or args_mem_loc are NULL.
- CL_INVALID_VALUE if num_mem_objects = 0 and mem_list or args_mem_loc are not NULL.
- CL_INVALID_OPERATION if the device associated with command_queue cannot execute the native kernel.
- CL_INVALID_MEM_OBJECT if one or more memory objects specified in mem_list are not valid or are not buffer objects.
- CL_OUT_OF_RESOURCES if there is a failure to queue the execution instance of kernel on the command-queue because of insufficient resources needed to execute the kernel.
- CL_MEM_OBJECT_ALLOCATION_FAILURE if there is a failure to allocate memory for data store associated with buffer objects specified as arguments to kernel.
- CL_INVALID_EVENT_WAIT_LIST if event_wait_list is NULL and num_events_in_wait_list > 0, or event_wait_list is not NULL and num_events_in_wait_list is 0, or if event objects in event_wait_list are not valid events.
- CL_INVALID_OPERATION if SVM pointers are passed as arguments to a kernel and the device does not support SVM or if system pointers are passed as arguments to a kernel and/or stored inside SVM allocations passed as kernel arguments and the device does not support fine grain system SVM allocations.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL
• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

The total number of read-only images specified as arguments to a kernel cannot exceed **CL_DEVICE_MAX_READ_IMAGE_ARGS**. Each image array argument to a kernel declared with the `read_only` qualifier counts as one image. The total number of write-only images specified as arguments to a kernel cannot exceed **CL_DEVICE_MAX_WRITE_IMAGE_ARGS**. Each image array argument to a kernel declared with the `write_only` qualifier counts as one image.

The total number of read-write images specified as arguments to a kernel cannot exceed **CL_DEVICE_MAX_READ_WRITE_IMAGE_ARGS**. Each image array argument to a kernel declared with the `read_write` qualifier counts as one image.

### 5.11. Event Objects

An event object can be used to track the execution status of a command. The API calls that enqueue commands to a command-queue create a new event object that is returned in the `event` argument. In case of an error enqueuing the command in the command-queue the event argument does not return an event object.

The execution status of an enqueued command at any given point in time can be one of the following:

- **CL_QUEUED**: Indicates that the command has been enqueued in a command-queue. This is the initial state of all events except user events.
- **CL_SUBMITTED**: The initial state for all user events. For all other events, indicates that the command has been submitted by the host to the device.
- **CL_RUNNING**: Indicates that the device has started executing this command. In order for the execution status of an enqueued command to change from **CL_SUBMITTED** to **CL_RUNNING**, all events that this command is waiting on must have completed successfully i.e. their execution status must be **CL_COMPLETE**.
- **CL_COMPLETE**: Indicates that the command has successfully completed.
- An Error Code: A negative integer value indicating that the command was abnormally terminated. Abnormal termination may occur for a number of reasons, such as a bad memory access.

A command is considered to be complete if its execution status is **CL_COMPLETE** or is a negative integer value.

If the execution of a command is terminated, the command-queue associated with this terminated command, and the associated context (and all other command-queues in this context) may no longer be available. The behavior of OpenCL API calls that use this context (and command-queues associated with this context) are now considered to be implementation-defined. The user registered callback
function specified when context is created can be used to report appropriate error information.

### 5.11.1. Creating, Waiting for, and Releasing Event Objects

To create a user event object, call the function

```c
// Provided by CL_VERSION_1_1
cl_event clCreateUserEvent(
    cl_context context,
    cl_int* errcode_ret);
```

- `context` must be a valid OpenCL context.
- `errcode_ret` will return an appropriate error code. If `errcode_ret` is `NULL`, no error code is returned.

User events allow applications to enqueue commands that wait on a user event to finish before the command is executed by the device.

`clCreateUserEvent` returns a valid non-zero event object and `errcode_ret` is set to `CL_SUCCESS` if the user event object is created successfully. Otherwise, it returns a `NULL` value with one of the following error values returned in `errcode_ret`:

- `CL_INVALID_CONTEXT` if `context` is not a valid context.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

The initial execution status for the user event object is `CL_SUBMITTED`.

To set the execution status of a user event object, call the function

```c
// Provided by CL_VERSION_1_1
cl_int clSetUserEventStatus(
    cl_event event,
    cl_int execution_status);
```

- `event` is a user event object created using `clCreateUserEvent`.
- `execution_status` specifies the new execution status to be set and can be `CL_COMPLETE` or a negative integer value to indicate an error. A negative integer value causes all enqueued
commands that wait on this user event to be terminated. `clSetUserEventStatus` can only be called once to change the execution status of `event`.

If there are enqueued commands with user events in the `event_wait_list` argument of `clEnqueue*` commands, the user must ensure that the status of these user events being waited on are set using `clSetUserEventStatus` before any OpenCL APIs that release OpenCL objects except for event objects are called; otherwise the behavior is undefined.

For example, the following code sequence will result in undefined behavior of `clReleaseMemObject`.

```plaintext
ev1 = clCreateUserEvent(ctx, NULL);
clEnqueueWriteBuffer(cq, buf1, CL_FALSE, ..., 1, &ev1, NULL);
clEnqueueWriteBuffer(cq, buf2, CL_FALSE, ...);
clReleaseMemObject(buf2);
clSetUserEventStatus(ev1, CL_COMPLETE);
```

The following code sequence, however, works correctly.

```plaintext
ev1 = clCreateUserEvent(ctx, NULL);
clEnqueueWriteBuffer(cq, buf1, CL_FALSE, ..., 1, &ev1, NULL);
clEnqueueWriteBuffer(cq, buf2, CL_FALSE, ...);
clSetUserEventStatus(ev1, CL_COMPLETE);
clReleaseMemObject(buf2);
```

`clSetUserEventStatus` returns `CL_SUCCESS` if the function was executed successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_EVENT` if `event` is not a valid user event object.
- `CL_INVALID_VALUE` if the `execution_status` is not `CL_COMPLETE` or a negative integer value.
- `CL_INVALID_OPERATION` if the `execution_status` for `event` has already been changed by a previous call to `clSetUserEventStatus`.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

To wait for events to complete, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clWaitForEvents(
    cl_uint num_events,
    const cl_event* event_list);
```
• **num_events** is the number of events in **event_list**.

• **event_list** is a pointer to a list of event object handles.

This function waits on the host thread for commands identified by event objects in **event_list** to complete. A command is considered complete if its execution status is **CL_COMPLETE** or a negative value. The events specified in **event_list** act as synchronization points.

**clWaitForEvents** returns **CL_SUCCESS** if the execution status of all events in **event_list** is **CL_COMPLETE**. Otherwise, it returns one of the following errors:

- **CL_INVALID_VALUE** if **num_events** is zero or **event_list** is **NULL**.
- **CL_INVALID_CONTEXT** if events specified in **event_list** do not belong to the same context.
- **CL_INVALID_EVENT** if event objects specified in **event_list** are not valid event objects.
- **CL_EXEC_STATUS_ERROR_FOR_EVENTS_IN_WAIT_LIST** if the execution status of any of the events in **event_list** is a negative integer value. This error code is missing before version 1.1.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To return information about an event object, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clGetEventInfo(
    cl_event event,
    cl_event_info param_name,
    size_t param_value_size,
    void* param_value,
    size_t* param_value_size_ret);
```

- **event** specifies the event object being queried.
- **param_name** specifies the information to query. The list of supported **param_name** types and the information returned in **param_value** by **clGetEventInfo** is described in the **Event Object Queries** table.
- **param_value** is a pointer to memory where the appropriate result being queried is returned. If **param_value** is **NULL**, it is ignored.
- **param_value_size** is used to specify the size in bytes of memory pointed to by **param_value**. This size must be ≥ size of return type as described in the **Event Object Queries** table.
- **param_value_size_ret** returns the actual size in bytes of data being queried by **param_name**. If **param_value_size_ret** is **NULL**, it is ignored.

*Table 50. List of supported param_names by **clGetEventInfo***
<table>
<thead>
<tr>
<th>Event Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
</table>
| CL_EVENT_COMMAND_QUEUE         | cl_command_queue  | Return the command-queue associated with event. For user event objects, a NULL value is returned.  
If the cl_khr_command_buffer_multi_device extension is supported, for events returned by a command-buffer enqueue operation to multiple command-queues, NULL is returned. |
<p>| CL_EVENT_CONTEXT               | cl_context        | Return the context associated with event.                                                                                                                                                             |
| <strong>missing before</strong> version 1.1 |                   |                                                                                                                                                                                                      |
| CL_EVENT_COMMAND_TYPE          | cl_command_type   | Return the command type associated with event as described in the Event Command Types table.                                                                                                             |</p>
<table>
<thead>
<tr>
<th>Event Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
</table>
| CL_EVENT_COMMAND_EXECUTION_STATUS | cl_int | Return the execution status of the command identified by event. Valid values are:  
|               |             | CL_QUEUED - Command has been enqueued in the command-queue.  
|               |             | CL_SUBMITTED - Enqueued command has been submitted by the host to the device associated with the command-queue.  
|               |             | CL_RUNNING - Device is currently executing this command.  
|               |             | CL_COMPLETE - The command has completed.  
|               |             | Or an error code given by a negative integer value (command was abnormally terminated - this may be caused by a bad memory access etc.). These error codes come from the same set of error codes that are returned from the platform or runtime API calls as return values or errcode_ret values.  
|               |             | If the cl_khr_command_buffer_multi_device extension is supported, for events returned by a command-buffer enqueue operation to multiple command-queues the semantics of execution status is as follows:  
|               |             | CL_QUEUED - Command-buffer has been enqueued across the command-queues.  
|               |             | CL_SUBMITTED - Commands from the command-buffer have been submitted by the host to any device associated with one of the command-queues.  
|               |             | CL_RUNNING - Any command from the command-buffer has started execution on a device.  
|               |             | CL_COMPLETE - All commands have completed on all devices. |
| CL_EVENT_REFERENCE_COUNT | cl_uint | Return the event reference count. |

Table 51. List of supported event command types
<table>
<thead>
<tr>
<th>Events Created By</th>
<th>Event Command Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>clEnqueueNDRangeKernel</td>
<td>CL_COMMAND_NDRANGE_KERNEL</td>
</tr>
<tr>
<td>clEnqueueTask</td>
<td>CL_COMMAND_TASK</td>
</tr>
<tr>
<td>clEnqueueNativeKernel</td>
<td>CL_COMMAND_NATIVE_KERNEL</td>
</tr>
<tr>
<td>clEnqueueReadBuffer</td>
<td>CL_COMMAND_READ_BUFFER</td>
</tr>
<tr>
<td>clEnqueueWriteBuffer</td>
<td>CL_COMMAND_WRITE_BUFFER</td>
</tr>
<tr>
<td>clEnqueueCopyBuffer</td>
<td>CL_COMMAND_COPY_BUFFER</td>
</tr>
<tr>
<td>clEnqueueReadImage</td>
<td>CL_COMMAND_READ_IMAGE</td>
</tr>
<tr>
<td>clEnqueueWriteImage</td>
<td>CL_COMMAND_WRITE_IMAGE</td>
</tr>
<tr>
<td>clEnqueueCopyImage</td>
<td>CL_COMMAND_COPY_IMAGE</td>
</tr>
<tr>
<td>clEnqueueCopyBufferToImage</td>
<td>CL_COMMAND_COPY_BUFFER_TO_IMAGE</td>
</tr>
<tr>
<td>clEnqueueCopyImageToBuffer</td>
<td>CL_COMMAND_COPY_IMAGE_TO_BUFFER</td>
</tr>
<tr>
<td>clEnqueueMapBuffer</td>
<td>CL_COMMAND_MAP_BUFFER</td>
</tr>
<tr>
<td>clEnqueueMapImage</td>
<td>CL_COMMAND_MAP_IMAGE</td>
</tr>
<tr>
<td>clEnqueueUnmapMemObject</td>
<td>CL_COMMAND_UNMAP_MEM_OBJECT</td>
</tr>
<tr>
<td>clEnqueueMarker, clEnqueueMarkerWithWaitList</td>
<td>CL_COMMAND_MARKER</td>
</tr>
<tr>
<td>clEnqueueReadBufferRect</td>
<td>CL_COMMAND_READ_BUFFER_RECT</td>
</tr>
<tr>
<td></td>
<td>missing before version 1.1.</td>
</tr>
<tr>
<td>clEnqueueWriteBufferRect</td>
<td>CL_COMMAND_WRITE_BUFFER_RECT</td>
</tr>
<tr>
<td></td>
<td>missing before version 1.1.</td>
</tr>
<tr>
<td>clEnqueueCopyBufferRect</td>
<td>CL_COMMAND_COPY_BUFFER_RECT</td>
</tr>
<tr>
<td></td>
<td>missing before version 1.1.</td>
</tr>
<tr>
<td>clCreateUserEvent</td>
<td>CL_COMMAND_USER</td>
</tr>
<tr>
<td></td>
<td>missing before version 1.1.</td>
</tr>
<tr>
<td>clEnqueueBarrier, clEnqueueBarrierWithWaitList</td>
<td>CL_COMMAND_BARRIER</td>
</tr>
<tr>
<td></td>
<td>missing before version 1.2.</td>
</tr>
<tr>
<td>clEnqueueMigrateMemObjects</td>
<td>CL_COMMAND_MIGRATE_MEM_OBJECTS</td>
</tr>
<tr>
<td></td>
<td>missing before version 1.2.</td>
</tr>
<tr>
<td>clEnqueueFillBuffer</td>
<td>CL_COMMAND_FILL_BUFFER</td>
</tr>
<tr>
<td></td>
<td>missing before version 1.2.</td>
</tr>
<tr>
<td>Events Created By</td>
<td>Event Command Type</td>
</tr>
<tr>
<td>------------------------</td>
<td>--------------------------------------------------------</td>
</tr>
<tr>
<td>clEnqueueFillImage</td>
<td>CL_COMMAND_FILL_IMAGE</td>
</tr>
<tr>
<td></td>
<td>missing before version 1.2.</td>
</tr>
<tr>
<td>clEnqueueSVMFree</td>
<td>CL_COMMAND_SVM_FREE</td>
</tr>
<tr>
<td></td>
<td>missing before version 2.0.</td>
</tr>
<tr>
<td>clEnqueueSVMMemcpy</td>
<td>CL_COMMAND_SVM_MEMCPY</td>
</tr>
<tr>
<td></td>
<td>missing before version 2.0.</td>
</tr>
<tr>
<td>clEnqueueSVMMemFill</td>
<td>CL_COMMAND_SVM_MEMFILL</td>
</tr>
<tr>
<td></td>
<td>missing before version 2.0.</td>
</tr>
<tr>
<td>clEnqueueSVMMMap</td>
<td>CL_COMMAND_SVM_MAP</td>
</tr>
<tr>
<td></td>
<td>missing before version 2.0.</td>
</tr>
<tr>
<td>clEnqueueSV Munmap</td>
<td>CL_COMMAND_SVM_UNMAP</td>
</tr>
<tr>
<td></td>
<td>missing before version 2.0.</td>
</tr>
<tr>
<td>clEnqueueSVMMigrateMem</td>
<td>CL_COMMAND_SVM_MIGRATE_MEM</td>
</tr>
<tr>
<td></td>
<td>missing before version 3.0.</td>
</tr>
<tr>
<td></td>
<td>Prior to OpenCL 3.0, implementations should return</td>
</tr>
<tr>
<td></td>
<td>CL_COMMAND_MIGRATE_MEM_OBJECTS, but may return an</td>
</tr>
<tr>
<td></td>
<td>implementation-defined event command type for</td>
</tr>
<tr>
<td></td>
<td>clEnqueueSVMMigrateMem</td>
</tr>
<tr>
<td>clEnqueueCommandBufferKHR</td>
<td>CL_COMMAND_COMMAND_BUFFER_KHR</td>
</tr>
<tr>
<td></td>
<td>provided by the cl_khr_command_buffer extension.</td>
</tr>
<tr>
<td>clEnqueueAcquireDX9MediaSurfaceKHR</td>
<td>CL_COMMAND_ACQUIRE_DX9_MEDIA_SURFACES_KHR</td>
</tr>
<tr>
<td></td>
<td>provided by the cl_khr_dx9_media_sharing extension.</td>
</tr>
<tr>
<td>clEnqueueReleaseDX9MediaSurfaceKHR</td>
<td>CL_COMMAND_RELEASE_DX9_MEDIA_SURFACES_KHR</td>
</tr>
<tr>
<td></td>
<td>provided by the cl_khr_dx9_media_sharing extension.</td>
</tr>
<tr>
<td>clEnqueueAcquireD3D10ObjectsKHR</td>
<td>CL_COMMAND_ACQUIRE_D3D10_OBJECTS_KHR</td>
</tr>
<tr>
<td></td>
<td>provided by the cl_khr_d3d10_sharing extension.</td>
</tr>
<tr>
<td>clEnqueueReleaseD3D10ObjectsKHR</td>
<td>CL_COMMAND_RELEASE_D3D10_OBJECTS_KHR</td>
</tr>
<tr>
<td></td>
<td>provided by the cl_khr_d3d10_sharing extension.</td>
</tr>
<tr>
<td>Events Created By</td>
<td>Event Command Type</td>
</tr>
<tr>
<td>------------------</td>
<td>---------------------</td>
</tr>
<tr>
<td>clEnqueueAcquireD3D11ObjectsKHR</td>
<td>CL_COMMAND_ACQUIRE_D3D11_OBJECTS_KHR provided by the cl_khr_d3d11_sharing extension.</td>
</tr>
<tr>
<td>clEnqueueReleaseD3D11ObjectsKHR</td>
<td>CL_COMMAND_RELEASE_D3D11_OBJECTS_KHR provided by the cl_khr_d3d11_sharing extension.</td>
</tr>
<tr>
<td>clEnqueueAcquireEGLObjectsKHR</td>
<td>CL_COMMAND_ACQUIRE_EGL_OBJECTS_KHR provided by the cl_khr_egl_image extension.</td>
</tr>
<tr>
<td>clEnqueueReleaseEGLObjectsKHR</td>
<td>CL_COMMAND_RELEASE_EGL_OBJECTS_KHR provided by the cl_khr_egl_image extension.</td>
</tr>
<tr>
<td>clCreateEventFromEGLSyncKHR</td>
<td>CL_COMMAND_EGL_FENCE_SYNC_OBJECT_KHR provided by the cl_khr_egl_image extension.</td>
</tr>
<tr>
<td>clEnqueueAcquireExternalMemObjectsKHR</td>
<td>CL_COMMAND_ACQUIRE_EXTERNAL_MEM_OBJECTS_KHR provided by the cl_khr_external_memory extension.</td>
</tr>
<tr>
<td>clEnqueueReleaseExternalMemObjectsKHR</td>
<td>CL_COMMAND_RELEASE_EXTERNAL_MEM_OBJECTS_KHR provided by the cl_khr_external_memory extension.</td>
</tr>
<tr>
<td>clEnqueueAcquireGLObjects</td>
<td>CL_COMMAND_ACQUIRE_GL_OBJECTS</td>
</tr>
<tr>
<td>clEnqueueReleaseGLObjects</td>
<td>CL_COMMAND_RELEASE_GL_OBJECTS</td>
</tr>
<tr>
<td>clCreateEventFromGLSyncKHR</td>
<td>CL_COMMAND_GL_FENCE_SYNC_OBJECT_KHR provided by the cl_khr_gl_event extension.</td>
</tr>
<tr>
<td>clEnqueueSignalSemaphoresKHR</td>
<td>CL_COMMAND_SEMAPHORE_SIGNAL_KHR provided by the cl_khr_semaphore extension.</td>
</tr>
<tr>
<td>clEnqueueWaitSemaphoresKHR</td>
<td>CL_COMMAND_SEMAPHORE_WAIT_KHR provided by the cl_khr_semaphore extension.</td>
</tr>
</tbody>
</table>

Using `clGetEventInfo` to determine if a command identified by `event` has finished execution (i.e. `CL_EVENT_COMMAND_EXECUTION_STATUS` returns `CL_COMPLETE`) is not a synchronization point. There are no guarantees that the memory objects being modified by command associated with `event` will be visible to other enqueued commands.

`clGetEventInfo` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_VALUE` if `param_name` is not valid, or if size in bytes specified by `param_value_size` is <
size of return type as described in the Kernel Argument Queries table and param_value is not NULL.

- **CL_INVALID_VALUE** if information to query given in param_name cannot be queried for event.
- **CL_INVALID_EVENT** if event is a not a valid event object.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To register a user callback function for a specific command execution status, call the function

```c
// Provided by CL_VERSION_1_1
cl_int clSetEventCallback(
    cl_event event,
    cl_int command_exec_callback_type,
    void (CL_CALLBACK* pfn_notify)(cl_event event, cl_int event_command_status, void* user_data),
    void* user_data);
```

- **event** is a valid event object.
- **command_exec_callback_type** specifies the command execution status for which the callback is registered. The command execution status types for which a callback can be registered are **CL_SUBMITTED**, **CL_RUNNING**, or **CL_COMPLETE**. The callback function registered for a **command_exec_callback_type** value of **CL_COMPLETE** will be called when the command has completed successfully or is abnormally terminated.
- **pfn_event_notify** is the event callback function that can be registered by the application. This callback function may be called asynchronously by the OpenCL implementation. It is the application’s responsibility to ensure that the callback function is thread-safe. The parameters to this callback function are:
  - **event** is the event object for which the callback function is invoked.
  - **event_command_status** is equal to the **command_exec_callback_type** used while registering the callback. Refer to the Event Object Queries table for the command execution status values. If the callback is called as the result of the command associated with event being abnormally terminated, an appropriate error code for the error that caused the termination will be passed to **event_command_status** instead.
  - **user_data** is a pointer to user supplied data.
- **user_data** will be passed as the **user_data** argument when **pfn_notify** is called. **user_data** can be **NULL**.

Each call to **clSetEventCallback** registers the specified user callback function on a callback stack associated with **event**. The order in which the registered user callback functions are called is undefined.
The registered callback function will be called when the execution status of the command associated with event changes to an execution status equal to or past the status specified by command_exec_status, or for the execution status CL_COMPLETE, if the command is abnormally terminated. There is no guarantee that the callback functions registered for various command execution status values for an event will be called in the exact order that the execution status of a command changes. Furthermore, it should be noted that calling a callback for an event execution status other than CL_COMPLETE in no way implies that the memory model or execution model as defined by the OpenCL specification has changed. For example, it is not valid to assume that a corresponding memory transfer has completed unless the event is in the state CL_COMPLETE.

All callbacks registered for an event object must be called before the event object is destroyed.

Callbacks should return promptly. Behavior is undefined when calling expensive system routines, OpenCL APIs to create contexts or command-queues, or blocking OpenCL APIs in an event callback. Rather than calling a blocking OpenCL API in an event callback, applications may call a non-blocking OpenCL API, then register a completion callback for the non-blocking OpenCL API with the remainder of the work.

Because commands in a command-queue are not required to begin execution until the command-queue is flushed, callbacks that enqueue commands on a command-queue should either call clFlush on the queue before returning, or arrange for the command-queue to be flushed later.

clSetEventCallback returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:

• CL_INVALID_EVENT if event is not a valid event object.

• CL_INVALID_VALUE if pfn_event_notify is NULL or if command_exec_callback_type is not CL_SUBMITTED, CL_RUNNING, or CL_COMPLETE.

• CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.

• CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

To retain an event object, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clRetainEvent(
    cl_event event);
```

• event is the event object to be retained.

The event reference count is incremented. The OpenCL commands that return an event perform an implicit retain.

clRetainEvent returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:

• CL_INVALID_EVENT if event is not a valid event object.
• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To release an event object, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clReleaseEvent(
    cl_event event);
```

• *event* is the event object to be released.

The *event* reference count is decremented.

The event object is deleted once the reference count becomes zero, the specific command identified by this event has completed (or terminated) and there are no commands in the command-queues of a context that require a wait for this event to complete. Using this function to release a reference that was not obtained by creating the object or by calling `clRetainEvent` causes undefined behavior.

Developers should be careful when releasing their last reference count on events created by `clCreateUserEvent` that have not yet been set to status of **CL_COMPLETE** or an error. If the user event was used in the event_wait_list argument passed to a `clEnqueue*` API or another application host thread is waiting for it in `clWaitForEvents`, those commands and host threads will continue to wait for the event status to reach **CL_COMPLETE** or error, even after the application has released the object. Since in this scenario the application has released its last reference count to the user event, it would be in principle no longer valid for the application to change the status of the event to unblock all the other machinery. As a result the waiting tasks will wait forever, and associated events, `cl_mem` objects, command-queues and contexts are likely to leak. In-order command-queues caught up in this deadlock may cease to do any work.

`clReleaseEvent` returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:

• **CL_INVALID_EVENT** if *event* is not a valid event object.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.11.1.1. Linking Event Objects to EGL Fence Sync Objects

An event object may be created by linking to an EGL **fence sync object**.
To create an OpenCL event object linked to an EGL fence sync object, call the function

```c
// Provided by cl_khr_egl_event
cl_event clCreateEventFromEGLSyncKHR(
    cl_context context, 
    CLegISyncKHR sync, 
    CLegIDisplayKHR display, 
    cl_int* errcode_ret);
```

**clCreateEventFromEGLSyncKHR** is provided by the **cl_khr_egl_event** extension.

- **context** is a valid OpenCL context created from an OpenGL context or share group, using the **cl_khr_gl_sharing** extension.
- **sync** is the name of a sync object of type **EGL_SYNC_FENCE_KHR** created with respect to **EGLDisplay display**.
- **display** is the **EGLDisplay** handle.
- **errcode_ret** will return an appropriate error code. If **errcode_ret** is **NULL**, no error code is returned.

Completion of such an event object is equivalent to waiting for completion of the fence command associated with the linked EGL sync object.

The parameters of an event object linked to an EGL sync object will return the following values when queried with **clGetEventInfo**:

- The **CL_EVENT_COMMAND_QUEUE** of a linked event is **NULL**, because the event is not associated with any OpenCL command-queue.
- The **CL_EVENT_COMMAND_TYPE** of a linked event is **CL_COMMAND_EGL_FENCE_SYNC_OBJECT_KHR**, indicating that the event is associated with a EGL sync object, rather than an OpenCL command.
- The **CL_EVENT_COMMAND_EXECUTION_STATUS** of a linked event is either **CL_SUBMITTED**, indicating that the fence command associated with the sync object has not yet completed, or **CL_COMPLETE**, indicating that the fence command has completed.

**clCreateEventFromEGLSyncKHR** performs an implicit **clRetainEvent** on the returned event object. Creating a linked event object also places a reference on the linked EGL sync object. When the event object is deleted, the reference will be removed from the EGL sync object.

Events returned from **clCreateEventFromEGLSyncKHR** may only be consumed by commands to acquire and release memory objects. Passing such events to any other CL API that enqueues commands will generate a **CL_INVALID_EVENT** error.

**clCreateEventFromEGLSyncKHR** returns a valid OpenCL event object and **errcode_ret** is set to **CL_SUCCESS** if the event object is created successfully. Otherwise, it returns a **NULL** value with one of the following error values returned in **errcode_ret**:

- **CL_INVALID_CONTEXT** if **context** is not a valid context, or was not created from a GL context.
• CL_INVALID_EGL_OBJECT_KHR if sync is not a valid EGLSyncKHR object of type EGL_SYNC_FENCE_KHR created with respect to EGLDisplay display.

5.11.1.1. Explicit Synchronization Using EGL Fence Sync Objects

If the cl_khr_egl_event extension is supported, event objects created with clCreateEventFromEGLSyncKHR provide another method of coordinating sharing between EGL / EGL client API objects, and OpenCL.

Completion of EGL and EGL client API commands may be determined by

• placing an EGL fence command after commands using eglCreateSyncKHR;
• creating an event from the resulting EGL sync object using clCreateEventFromEGLSyncKHR; and
• determining completion of that event object via clEnqueueAcquireGLObjects.

This method may be considerably more efficient than calling operations like glFinish, and is referred to as explicit synchronization. The application is responsible for ensuring the command stream associated with the EGL fence is flushed to ensure the CL queue is submitted to the device. Explicit synchronization is most useful when an EGL client API context bound to another thread is accessing the memory objects.

5.11.1.2. Linking Event Objects to OpenGL Fence Sync Objects

An event object may be created by linking to an OpenGL fence sync object.

To create an OpenCL event object linked to an OpenGL fence sync object, call the function

```c
// Provided by cl_khr_gl_event
cl_event clCreateEventFromGLsyncKHR(
    cl_context context,
    cl_GLsync sync,
    cl_int* errcode_ret);
```

clCreateEventFromGLsyncKHR is provided by the cl_khr_gl_event extension.

• context is a valid OpenCL context created from an OpenGL context or share group, using the cl_khr_gl_sharing extension.
• sync is the name of a sync object in the GL share group associated with context.
• errcode_ret will return an appropriate error code. If errcode_ret is NULL, no error code is returned.

Completion of such an event object is equivalent to waiting for completion of the fence command associated with the linked GL sync object.

clCreateEventFromGLsyncKHR returns a valid OpenCL event object and errcode_ret is set to CL_SUCCESS if the event object is created successfully. Otherwise, it returns a NULL value with one of
the following error values returned in *errcode_ret*:

- **CL_INVALID_CONTEXT** if *context* is not a valid context, or was not created from a GL context.
- **CL_INVALID_GL_OBJECT** if *sync* is not the name of a sync object in the GL share group associated with *context*.

The parameters of an event object linked to a GL sync object will return the following values when queried with **clGetEventInfo**:

- The **CL_EVENT_COMMAND_QUEUE** of a linked event is **NULL**, because the event is not associated with any OpenCL command-queue.
- The **CL_EVENT_COMMAND_TYPE** of a linked event is **CL_COMMAND_GL_FENCE_SYNC_OBJECT_KHR**, indicating that the event is associated with a GL sync object, rather than an OpenCL command.
- The **CL_EVENT_COMMAND_EXECUTION_STATUS** of a linked event is either **CL_SUBMITTED**, indicating that the fence command associated with the sync object has not yet completed, or **CL_COMPLETE**, indicating that the fence command has completed.

**clCreateEventFromGLsyncKHR** performs an implicit **clRetainEvent** on the returned event object. Creating a linked event object also places a reference on the linked GL sync object. When the event object is deleted, the reference will be removed from the GL sync object.

Events returned from **clCreateEventFromGLsyncKHR** can be used in the *event_wait_list* argument to **clEnqueueAcquireGLObjects** and CL APIs that take a **cl_event** as an argument but do not enqueue commands. Passing such events to any other CL API that enqueues commands will generate a **CL_INVALID_EVENT** error.

### 5.11.1.2.1. Explicit Synchronization Using OpenGL Fence Sync Objects

If the **cl_khr_gl_event** extension is supported, event objects created with **clCreateEventFromGLsyncKHR** provide another method of coordinating sharing of buffers and images between OpenGL and OpenCL.

Completion of OpenGL commands may be determined by

- placing an OpenGL fence command after commands using **glFenceSync**;
- creating an event from the resulting OpenGL sync object using **clCreateEventFromGLsyncKHR**; and
- determining completion of that event object via **clEnqueueAcquireGLObjects**.

This method may be considerably more efficient than calling **glFinish**, and is referred to as *explicit synchronization*. Explicit synchronization is most useful when an OpenGL context bound to another thread is accessing the memory objects.

Explicit synchronization is most useful when an OpenGL context bound to another thread is accessing the memory objects.
5.12. Markers, Barriers and Waiting for Events

To enqueue a marker command which waits for events or commands to complete, call the function

```c
// Provided by CL_VERSION_1_2
cl_int clEnqueueMarkerWithWaitList(
    cl_command_queue command_queue,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

- `command_queue` is a valid host command-queue.
- `event_wait_list` and `num_events_in_wait_list` specify events that need to complete before this particular command can be executed.
- `event` returns an event object that identifies this command and can be used to query or wait for this command to complete. If `event` is `NULL` or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If `event_wait_list` and `event` are not `NULL`, `event` must not refer to an element of the `event_wait_list` array.

If `event_wait_list` is `NULL`, `num_events_in_wait_list` must be 0. If `event_wait_list` is not `NULL`, the list of events pointed to by `event_wait_list` must be valid and `num_events_in_wait_list` must be greater than 0. The events specified in `event_wait_list` act as synchronization points. The context associated with events in `event_wait_list` and `command_queue` must be the same. The memory associated with `event_wait_list` can be reused or freed after the function returns.

If `event_wait_list` is `NULL`, then this particular command waits until all previous enqueued commands to `command_queue` have completed.

The marker command either waits for a list of events to complete, or if the list is empty it waits for all commands previously enqueued in `command_queue` to complete before it completes. This command returns an `event` which can be waited on, i.e. this event can be waited on to insure that all events either in the `event_wait_list` or all previously enqueued commands, queued before this command to `command_queue`, have completed.

`clEnqueueMarkerWithWaitList` returns `CL_SUCCESS` if the function is successfully executed. Otherwise, it returns one of the following errors:

- `CL_INVALID_COMMAND_QUEUE` if `command_queue` is not a valid host command-queue.
- `CL_INVALID_CONTEXT` if context associated with `command_queue` and events in `event_wait_list` are not the same.
- `CL_INVALID_EVENT_WAIT_LIST` if `event_wait_list` is `NULL` and `num_events_in_wait_list` > 0, or `event_wait_list` is not `NULL` and `num_events_in_wait_list` is 0, or if event objects in `event_wait_list` are not valid events.
• CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.

• CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

To enqueue a marker command which waits for previous commands to complete, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clEnqueueMarker(
    cl_command_queue command_queue,
    cl_event* event);
```

**clEnqueueMarker** is deprecated by version 1.2.

- command_queue is a valid host command-queue.
- event returns an event object that identifies this command and can be used to query or wait for this command to complete. If **event** is NULL or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for this command to complete. If **event_wait_list** and **event** are not NULL, **event** must not refer to an element of the **event_wait_list** array.

The marker command waits for all commands previously enqueued in **command_queue** to complete before it completes. This command returns an **event** which can be waited on, i.e. this event can be waited on to insure that all previously enqueued commands, queued before this command to **command_queue**, have completed.

**clEnqueueMarker** returns CL_SUCCESS if the function is successfully executed. Otherwise, it returns one of the following errors:

• CL_INVALID_COMMAND_QUEUE if **command_queue** is not a valid host command-queue.

• CL_INVALID_VALUE if **event** is NULL.

• CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.

• CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

To enqueue a wait for a specific event or a list of events to complete before any future commands queued in a command-queue are executed, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clEnqueueWaitForEvents(
    cl_command_queue command_queue,
    cl_uint num_events,
    const cl_event* event_list);
```
**clEnqueueWaitForEvents** is deprecated by version 1.2.

- **command_queue** is a valid host command-queue.
- **event_list** and **num_events** specify events that need to complete before this particular command can be executed.

The events specified in **event_list** act as synchronization points. The context associated with events in **event_list** and **command_queue** must be the same. The memory associated with **event_list** can be reused or freed after the function returns.

**clEnqueueWaitForEvents** returns **CL_SUCCESS** if the function is successfully executed. Otherwise, it returns one of the following errors:

- **CL_INVALID_COMMAND_QUEUE** if **command_queue** is not a valid host command-queue.
- **CL_INVALID_CONTEXT** if context associated with **command_queue** and events in **event_list** are not the same.
- **CL_INVALID_VALUE** if **num_events** is 0 or **event_list** is **NULL**.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To enqueue a barrier command which waits for events or commands to complete, call the function

```c
// Provided by CL_VERSION_1_2
cl_int clEnqueueBarrierWithWaitList(
    cl_command_queue command_queue,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

**clEnqueueBarrierWithWaitList** is missing before version 1.2.

- **command_queue** is a valid host command-queue.
- **event_wait_list** and **num_events_in_wait_list** specify events that need to complete before this particular command can be executed.

If **event_wait_list** is **NULL**, **num_events_in_wait_list** must be 0. If **event_wait_list** is not **NULL**, the list of events pointed to by **event_wait_list** must be valid and **num_events_in_wait_list** must be greater than 0. The events specified in **event_wait_list** act as synchronization points. The context associated with events in **event_wait_list** and **command_queue** must be the same. The memory associated with **event_wait_list** can be reused or freed after the function returns.

- **event** returns an event object that identifies this command and can be used to query or wait for this command to complete. If **event** is **NULL** or the enqueue is unsuccessful, no event will be created and therefore it will not be possible to query the status of this command or to wait for
this command to complete. If `event_wait_list` and `event` are not NULL, `event` must not refer to an element of the `event_wait_list` array.

If `event_wait_list` is NULL, then this particular command waits until all previous enqueued commands to `command_queue` have completed.

The barrier command either waits for a list of events to complete, or if the list is empty it waits for all commands previously enqueued in `command_queue` to complete before it completes. This command blocks command execution, that is, any following commands enqueued after it do not execute until it completes. This command returns an `event` which can be waited on, i.e. this event can be waited on to insure that all events either in the `event_wait_list` or all previously enqueued commands, queued before this command to `command_queue`, have completed.

`clEnqueueBarrierWithWaitList` returns `CL_SUCCESS` if the function is successfully executed. Otherwise, it returns one of the following errors:

- `CL_INVALID_COMMAND_QUEUE` if `command_queue` is not a valid host command-queue.
- `CL_INVALID_CONTEXT` if context associated with `command_queue` and events in `event_wait_list` are not the same.
- `CL_INVALID_EVENT_WAIT_LIST` if `event_wait_list` is NULL and `num_events_in_wait_list` > 0, or `event_wait_list` is not NULL and `num_events_in_wait_list` is 0, or if event objects in `event_wait_list` are not valid events.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

To enqueue a barrier command which waits for commands to complete, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clEnqueueBarrier(
    cl_command_queue command_queue);
```

- `clEnqueueBarrier` is deprecated by version 1.2.

- `command_queue` is a valid host command-queue.

The barrier command waits for all commands previously enqueued in `command_queue` to complete before it completes. This command blocks command execution, that is, any following commands enqueued after it do not execute until it completes. The barrier command is a synchronization point.

`clEnqueueBarrier` returns `CL_SUCCESS` if the function is successfully executed. Otherwise, it returns one of the following errors:

- `CL_INVALID_COMMAND_QUEUE` if `command_queue` is not a valid host command-queue.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL
implementation on the device.

- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

5.13. Semaphores

This section describes the semaphore types and functions defined by the cl_khr_semaphore extension.

5.13.1. Semaphore Types

- cl_semaphore_type_khr represent the different types of semaphores.
  - It is mandatory to support CL_SEMAPHORE_TYPE_BINARY_KHR.
- cl_semaphore_properties_khr represents properties associated with semaphores.
  - CL_SEMAPHORE_TYPE_KHR must be supported.
- cl_semaphore_info_khr represents queries for additional information about semaphores.
  - All enums described in the “New API Enums” section of the cl_khr_semaphore extension for cl_semaphore_info_khr must be supported.
- cl_semaphore_payload_khr represents payload values of semaphores.
- cl_semaphore_khr represent semaphore objects.

5.13.2. Creating Semaphores

To create a semaphore object, call the function

```c
// Provided by cl_khr_semaphore
cl_semaphore_khr clCreateSemaphoreWithPropertiesKHR(
    cl_context context,
    const cl_semaphore_properties_khr* sema_props,
    cl_int* errcode_ret);
```

clCreateSemaphoreWithPropertiesKHR is provided by the cl_khr_semaphore extension.

- context identifies a valid OpenCL context that the created cl_semaphore_khr will belong to.
- sema_props specifies additional semaphore properties in the form list of <property_name, property_value> pairs terminated with 0. CL_SEMAPHORE_TYPE_KHR must be part of the list of properties specified by sema_props.

Following new properties are added to the list of possible supported properties by cl_semaphore_properties_khr that can be passed to clCreateSemaphoreWithPropertiesKHR:

Table 52. List of supported semaphore creation properties by clCreateSemaphoreWithPropertiesKHR
<table>
<thead>
<tr>
<th>Semaphore Property</th>
<th>Property Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_SEMAPHORE_TYPE_KHR</td>
<td>cl_semaphore_type_khr</td>
<td>Specifies the type of semaphore to create. This property is always required.</td>
</tr>
<tr>
<td>CL_SEMAPHORE_DEVICE_HANDLE_LIST_KHR</td>
<td>cl_device_id[]</td>
<td>Specifies the list of OpenCL devices (terminated with CL_SEMAPHORE_DEVICE_HANDLE_LIST_END_KHR) to associate with the semaphore. Only a single device is permitted in the list.</td>
</tr>
<tr>
<td>CL_SEMAPHORE_EXPORTHANDLETYPES_KHR</td>
<td>cl_external_semaphore_handle_type_khr[]</td>
<td>Specifies the list of semaphore handle type properties (terminated with CL_SEMAPHORE_EXPORTHANDLETYPESLIST_END_KHR) that can be used to export the semaphore being created.</td>
</tr>
</tbody>
</table>

If CL_SEMAPHORE_DEVICE_HANDLE_LIST_KHR is not specified as part of sema_props, the semaphore object created by clCreateSemaphoreWithPropertiesKHR is by default accessible to all devices in the context. For a multi-device context CL_SEMAPHORE_DEVICE_HANDLE_LIST_KHR must be specified in sema_props.

errcode_ret returns an appropriate error code. If errcode_ret is NULL, no error code is returned.

clCreateSemaphoreWithPropertiesKHR returns a valid semaphore object in an un-signaled state and and errcode_ret is set to CL_SUCCESS if the function is executed successfully. Otherwise, it returns a NULL value with one of the following error values returned in errcode_ret:

- CL_INVALID_CONTEXT if context is not a valid context.
- CL_INVALID_PROPERTY if a property name in sema_props is not a supported property name, if the value specified for a supported property name is not valid, or if the same property name is specified more than once. Additionally, if context is a multiple device context and sema_props does not specify CL_SEMAPHORE_DEVICE_HANDLE_LIST_KHR.
- CL_INVALID_DEVICE if CL_SEMAPHORE_DEVICE_HANDLE_LIST_KHR is specified as part of sema_props, but it does not identify exactly one valid device; or if a device identified by CL_SEMAPHORE_DEVICE_HANDLE_LIST_KHR is not one of the devices within context.
- CL_INVALID_VALUE
  - if sema_props is NULL, or
  - if sema_props do not specify <property, value> pairs for minimum set of properties (i.e. CL_SEMAPHORE_TYPE_KHR) required for successful creation of a cl_semaphore_khr, or
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.
- CL_INVALID_DEVICE if one or more devices identified by properties CL_SEMAPHORE_DEVICE_HANDLE_LIST_KHR cannot import the requested external semaphore handle type.
- CL_INVALID_VALUE if more than one semaphore handle type is specified in the CL_SEMAPHORE_
• `CL_INVALID_OPERATION` If `props_list` specifies a `cl_external_semaphore_handle_type_khr` followed by a handle as well as `CL_SEMAPHORE_EXPORT_HANDLE_TYPES_KHR`. Exporting a semaphore handle from a semaphore that was created by importing an external semaphore handle is not permitted.

### 5.13.3. Exporting Semaphore External Handles

To export an external handle from a semaphore, call the function

```
// Provided by cl_khr_external_semaphore
cl_int clGetSemaphoreHandleForTypeKHR(
    cl_semaphore_khr sema_object,
    cl_device_id device,
    cl_external_semaphore_handle_type_khr handle_type,
    size_t handle_size,
    void* handle_ptr,
    size_t* handle_size_ret);
```

- `sema_object` specifies a valid semaphore object with exportable properties.
- `device` specifies a valid device for which a semaphore handle is being requested.
- `handle_type` specifies the type of semaphore handle that should be returned for this exportable `sema_object`, and must be one of the values specified when `sema_object` was created.
- `handle_size` specifies the size of memory pointed by `handle_ptr`.
- `handle_ptr` is a pointer to memory where the exported external handle is returned. If `param_value` is `NULL`, it is ignored.
- `handle_size_ret` returns the actual size in bytes for the external handle. If `handle_size_ret` is `NULL`, it is ignored.

`clGetSemaphoreHandleForTypeKHR` returns `CL_SUCCESS` if the semaphore handle is queried successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_SEMAPHORE_KHR`
  - if `sema_object` is not a valid semaphore
  - if `sema_object` is not exportable
- `CL_INVALID_DEVICE`
  - if `device` is not a valid device, or
  - if `sema_object` belongs to a context that is not associated with `device`, or
  - if `sema_object` can not be shared with `device`.
- `CL_INVALID_VALUE` if the requested external semaphore handle type was not specified when `sema_object` was created.
- `CL_INVALID_VALUE` if `handle_size` is less than the size needed to store the returned handle.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL
implementation on the device.

- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.13.4. Importing Semaphore External Handles

Applications can import a semaphore payload into an existing semaphore using an external semaphore handle. The effects of the import operation will be either temporary or permanent, as specified by the application. If the import is temporary, the implementation must restore the semaphore to its prior permanent state after submitting the next semaphore wait operation. Performing a subsequent temporary import on a semaphore before performing a semaphore wait has no effect on this requirement; the next wait submitted on the semaphore must still restore its last permanent state. A permanent payload import behaves as if the target semaphore was destroyed, and a new semaphore was created with the same handle but the imported payload. Because importing a semaphore payload temporarily or permanently detaches the existing payload from a semaphore, similar usage restrictions to those applied to `clReleaseSemaphoreKHR` are applied to any command that imports a semaphore payload. Which of these import types is used is referred to as the import operation’s permanence. Each handle type supports either one or both types of permanence.

The implementation must perform the import operation by either referencing or copying the payload referred to by the specified external semaphore handle, depending on the handle’s type. The import method used is referred to as the handle type’s transference. When using handle types with reference transference, importing a payload to a semaphore adds the semaphore to the set of all semaphores sharing that payload. This set includes the semaphore from which the payload was exported. Semaphore signaling and waiting operations performed on any semaphore in the set must behave as if the set were a single semaphore. Importing a payload using handle types with copy transference creates a duplicate copy of the payload at the time of import, but makes no further reference to it. Semaphore signaling and waiting operations performed on the target of copy imports must not affect any other semaphore or payload.

Export operations have the same transference as the specified handle type’s import operations. Additionally, exporting a semaphore payload to a handle with copy transference has the same side effects on the source semaphore’s payload as executing a semaphore wait operation. If the semaphore was using a temporarily imported payload, the semaphore’s prior permanent payload will be restored.

Please refer to handle specific specifications for more details on transference and permanence requirements specific to handle type.

### 5.13.5. Descriptions of External Semaphore Handle Types

This section describes the external semaphore handle types that are added by related extensions.

Applications can import the same semaphore payload into multiple OpenCL contexts, into the same context from which it was exported, and multiple times into a given OpenCL context. In all cases, each import operation must create a distinct semaphore object.
5.13.5.1. File Descriptor Handle Types

The cl_khr_external_semaphore_opaque_fd extension extends cl_external_semaphore_handle_type_khr to support the following new types of handles, and adds as a property that may be specified when creating a semaphore from an external handle:

- **CL_SEMAPHORE_HANDLE_OPAQUE_FD_KHR** specifies a POSIX file descriptor handle that has only limited valid usage outside of OpenCL and other compatible APIs. It must be compatible with the POSIX system calls `dup`, `dup2`, `close`, and the non-standard system call `dup3`. Additionally, it must be transportable over a socket using an `SCM_RIGHTS` control message. It owns a reference to the underlying synchronization primitive represented by its semaphore object.

The cl_khr_external_semaphore_sync_fd extension extends cl_external_semaphore_handle_type_khr to support the following new types of handles, and adds as a property that may be specified when creating a semaphore from an external handle:

- **CL_SEMAPHORE_HANDLE_SYNC_FD_KHR** specifies a POSIX file descriptor handle to a Linux Sync File or Android Fence object. It can be used with any native API accepting a valid sync file or fence as input. It owns a reference to the underlying synchronization primitive associated with the file descriptor. Implementations which support importing this handle type must accept any type of sync or fence FD supported by the native system they are running on.

The special value -1 for fd is treated like a valid sync file descriptor referring to an object that has already signaled. The import operation will succeed and the semaphore will have a temporarily imported payload as if a valid file descriptor had been provided.

Note: This special behavior for importing an invalid sync file descriptor allows easier interoperability with other system APIs which use the convention that an invalid sync file descriptor represents work that has already completed and does not need to be waited for. It is consistent with the option for implementations to return a -1 file descriptor when exporting a **CL_SEMAPHORE_HANDLE_SYNC_FD_KHR** from a **cl_semaphore_khr** which is signaled.

Table 53. Transference and Permanence Properties for File Descriptor Handles

<table>
<thead>
<tr>
<th>Handle Type</th>
<th>Transference</th>
<th>Permanence</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_SEMAPHORE_HANDLE_OPAQUE_FD_KHR</td>
<td>Reference</td>
<td>Temporary, Permanent</td>
</tr>
<tr>
<td>provided by the cl_khr_external_semaphore_opaque_fd extension.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_SEMAPHORE_HANDLE_SYNC_FD_KHR</td>
<td>Copy</td>
<td>Temporary</td>
</tr>
<tr>
<td>provided by the cl_khr_external_semaphore_sync_fd extension.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Importing a semaphore payload from a file descriptor transfers ownership of the file descriptor from the application to the OpenCL implementation. The application must not perform any operations on the file descriptor after a successful import.

To re-imported a handle of type **CL_SEMAPHORE_HANDLE_SYNC_FD_KHR** into an existing semaphore, call the function:
cl_int clReImportSemaphoreSyncFdKHR(
    cl_semaphore_khr sema_object,
    cl_semaphore_reimport_properties_khr* reimport_props,
    int fd);

- **sema_object** specifies a valid semaphore object with importable properties.
- **reimport_props** must be NULL, and is reserved for future use.
- **fd** specifies an external file descriptor handle to import

Calling `clReImportSemaphoreSyncFdKHR` is equivalent to destroying `sema_object` and re-creating it with the original `sema_props` from `clCreateSemaphoreWithPropertiesKHR`, except a handle specified by `fd` will be imported. The semaphore `sema_object` must have originally imported an external handle of type `CL_SEMAPHORE_HANDLE_SYNC_FD_KHR`.

`clGetSemaphoreHandleForTypeKHR` returns `CL_SUCCESS` if the semaphore handle is re-imported successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_SEMAPHORE_KHR**
  - if `sema_object` is not a valid semaphore
- **CL_INVALID_SEMAPHORE_KHR** if a `CL_SEMAPHORE_HANDLE_SYNC_FD_KHR` handle was not imported when `sema_object` was created.
- **CL_INVALID_VALUE** if `fd` is invalid.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

### 5.13.5.2. NT Handle Types

The `cl_khr_external_semaphore_dx_fence` extension extends `cl_external_semaphore_handle_type_khr` to support the following new types of handles, and adds as a property that may be specified when creating a semaphore from an external handle:

- **CL_SEMAPHORE_HANDLE_D3D12_FENCE_KHR** specifies an NT handle returned by `ID3D12Device::CreateSharedHandle` referring to a Direct3D 12 fence, or `ID3D11Device5::CreateFence` referring to a Direct3D 11 fence. It owns a reference to the underlying synchronization primitive associated with the Direct3D fence.

When waiting on semaphores using `clEnqueueWaitSemaphoresKHR` or signaling semaphores using `clEnqueueSignalSemaphoresKHR`, the semaphore payload must be provided for semaphores created from `CL_SEMAPHORE_HANDLE_D3D12_FENCE_KHR`.

- If `sema_objects` list has a mix of semaphores obtained from `CL_SEMAPHORE_HANDLE_D3D12_FENCE_KHR` and other handle types, then the `sema_payload_list` should point to a list of `num_sema_objects` payload values for each semaphore in `sema_objects`. However, the payload values
corresponding to semaphores with type `CL_SEMAPHORE_TYPE_BINARY_KHR` can be set to 0 or will be ignored.

`clEnqueueWaitSemaphoresKHR` and `clEnqueueSignalSemaphoresKHR` may return `CL_INVALID_VALUE` if `sema_objects` list has one or more semaphores obtained from `CL_SEMAPHORE_HANDLE_D3D12_FENCE_KHR` and `sema_payload_list` is NULL.

The `cl_khr_external_semaphore_win32` extension extends `cl_external_semaphore_handle_type_khr` to support the following new types of handles, and adds as a property that may be specified when creating a semaphore from an external handle:

- `CL_SEMAPHORE_HANDLE_OPAQUE_WIN32_KHR` specifies an NT handle that has only limited valid usage outside of OpenCL and other compatible APIs. It must be compatible with the functions `DuplicateHandle`, `CloseHandle`, `CompareObjectHandles`, `GetHandleInformation`, and `SetHandleInformation`. It owns a reference to the underlying synchronization primitive represented by its semaphore object.

- `CL_SEMAPHORE_HANDLE_OPAQUE_WIN32_KMT_KHR` specifies a global share handle that has only limited valid usage outside of OpenCL and other compatible APIs. It is not compatible with any native APIs. It does not own a reference to the underlying synchronization primitive represented by its semaphore object, and will therefore become invalid when all semaphore objects associated with it are destroyed.

<table>
<thead>
<tr>
<th>Handle Type</th>
<th>Transference</th>
<th>Permanence</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>CL_SEMAPHORE_HANDLE_D3D12_FENCE_KHR</code> provided by the <code>cl_khr_external_semaphore_dx_fence</code> extension.</td>
<td>Reference</td>
<td>Temporary, Permanent</td>
</tr>
<tr>
<td><code>CL_SEMAPHORE_HANDLE_OPAQUE_WIN32_KHR</code> provided by the <code>cl_khr_external_semaphore_win32</code> extension.</td>
<td>Reference</td>
<td>Temporary, Permanent</td>
</tr>
<tr>
<td><code>CL_SEMAPHORE_HANDLE_OPAQUE_WIN32_KMT_KHR</code> provided by the <code>cl_khr_external_semaphore_win32</code> extension.</td>
<td>Reference</td>
<td>Temporary, Permanent</td>
</tr>
</tbody>
</table>

Importing a semaphore payload from Windows handles does not transfer ownership of the handle to the OpenCL implementation. For handle types defined as NT handles, the application must release ownership using the `CloseHandle` system call when the handle is no longer needed.

### 5.13.6. Waiting On and Signaling Semaphores

To enqueue a command to wait on a set of semaphores, call the function
clEnqueueWaitSemaphoresKHR is provided by the cl_khr_semaphore extension.

- **command_queue** specifies a valid command-queue.
- **num_sema_objects** specifies the number of semaphore objects to wait on.
- **sema_objects** points to the list of semaphore objects to wait on. The length of the list must be at least **num_sema_objects**.
- **sema_payload_list** points to the list of values of type cl_semaphore_payload_khr containing valid semaphore payload values to wait on. This can be set to NULL or will be ignored when all semaphores in the list of **sema_objects** are of type CL_SEMAPHORE_TYPE_BINARY_KHR.
- **num_events_in_wait_list** specifies the number of events in **event_wait_list**.
- **event_wait_list** specifies list of events that need to complete before clEnqueueWaitSemaphoresKHR can be executed. If **event_wait_list** is NULL, then clEnqueueWaitSemaphoresKHR does not wait on any event to complete. If **event_wait_list** is NULL, **num_events_in_wait_list** must be 0. If **event_wait_list** is not NULL, the list of events pointed to by **event_wait_list** must be valid and **num_events_in_wait_list** must be greater than 0. The events specified in **event_wait_list** act as synchronization points. The context associated with events in **event_wait_list** and that associated with **command_queue** must be the same.
- **event** returns an event object that identifies this particular command and can be used to query or queue a wait for this particular command to complete. **event** can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete.

The semaphore wait command waits for a list of events to complete and a list of semaphore objects to become signaled. The semaphore wait command returns an **event** which can be waited on to ensure that all events in the **event_wait_list** have completed and all semaphores in **sema_objects** have been signaled. clEnqueueWaitSemaphoresKHR will not return until the binary semaphores in **sema_objects** are in a state that makes them safe to re-signal. If necessary, implementations may block in clEnqueueWaitSemaphoresKHR to ensure the correct state of semaphores when returning. There are no implications from this behavior for the state of **event** or the events in **event_wait_list** when clEnqueueWaitSemaphoresKHR returns. Waiting on the same binary semaphore twice without an interleaving signal may lead to undefined behavior.

clEnqueueWaitSemaphoresKHR returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:
• **CL_INVALID_COMMAND_QUEUE**
  ◦ if *command_queue* is not a valid command-queue, or
  ◦ if the device associated with *command_queue* is not same as one of the devices specified by **CL_SEMAPHORE_DEVICE_HANDLE_LIST_KHR** at the time of creating one or more of *sema_objects*.

• **CL_INVALID_VALUE** if *num_sema_objects* is 0.

• **CL_INVALID_SEMAPHORE_KHR** if any of the semaphore objects specified by *sema_objects* is not valid.

• **CL_INVALID_CONTEXT** if the context associated with *command_queue* and any of the semaphore objects in *sema_objects* are not the same, or if the context associated with *command_queue* and that associated with events in *event_wait_list* are not the same.

• **CL_INVALID_VALUE** if any of the semaphore objects specified by *sema_objects* requires a semaphore payload and *sema_payload_list* is **NULL**.

• **CL_INVALID_EVENT_WAIT_LIST**
  ◦ if *event_wait_list* is **NULL** and *num_events_in_wait_list* is not 0, or
  ◦ if *event_wait_list* is not **NULL** and *num_events_in_wait_list* is 0, or
  ◦ if event objects in *event_wait_list* are not valid events.

• **CL_EXEC_STATUS_ERROR_FOR_EVENTS_IN_WAIT_LIST** if the execution status of any of the events in *event_wait_list* is a negative integer value.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To enqueue a command to signal a set of semaphores, call the function

```c
// Provided by cl_khr_semaphore
cl_int clEnqueueSignalSemaphoresKHR(
    cl_command_queue command_queue,
    cl_uint num_sema_objects,
    const cl_semaphore_khr* sema_objects,
    const cl_semaphore_payload_khr* sema_payload_list,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

**clEnqueueSignalSemaphoresKHR** is provided by the **cl_khr_semaphore** extension.

• *command_queue* specifies a valid command-queue.

• *num_sema_objects* specifies the number of semaphore objects to signal.

• *sema_objects* points to the list of semaphore objects to signal. The length of the list must be at least *num_sema_objects*.

• *sema_payload_list* points to the list of values of type **cl_semaphore_payload_khr** containing
semaphore payload values to signal. This can be set to NULL or will be ignored when all semaphores in the list of sema_objects are of type CL_SEMAPHORE_TYPE_BINARY_KHR.

- **num_events_in_wait_list** specifies the number of events in
- **event_wait_list** points to the list of events that need to complete before clEnqueueSignalSemaphoresKHR can be executed. If event_wait_list is NULL, then clEnqueueSignalSemaphoresKHR does not wait on any event to complete. If event_wait_list is NULL, num_events_in_wait_list must be 0. If event_wait_list is not NULL, the list of events pointed to by event_wait_list must be valid and num_events_in_wait_list must be greater than 0. The events specified in event_wait_list act as synchronization points. The context associated with events in event_wait_list and that associated with command_queue must be the same.

**event** returns an event object that identifies this particular command and can be used to query or queue a wait for this particular command to complete. event can be NULL, in which case it will not be possible for the application to query the status of this command or queue a wait for this command to complete.

The semaphore signal command waits for a list of events to complete and then signals a list of semaphore objects. The semaphore signal command returns an event which can be waited on to ensure that all events in the event_wait_list have completed and all semaphores in sema_objects have been signaled. The successful completion of the event generated by clEnqueueSignalSemaphoresKHR called on one or more semaphore objects of type CL_SEMAPHORE_TYPE_BINARY_KHR changes the state of the corresponding semaphore objects to signaled. clEnqueueSignalSemaphoresKHR will not return until the binary semaphores in sema_objects are in a state that makes them safe to wait on again. If necessary, implementations may block in clEnqueueSignalSemaphoresKHR to ensure the correct state of semaphores when returning. There are no implications from this behavior for the state of event or the events in event_wait_list when clEnqueueSignalSemaphoresKHR returns. Signaling the same binary semaphore twice without an interleaving wait may lead to undefined behavior.

clEnqueueSignalSemaphoresKHR returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_COMMAND_QUEUE**
  - if command_queue is not a valid command-queue, or
  - if the device associated with command_queue is not same as one of the devices specified by CL_SEMAPHORE_DEVICE_HANDLE_LIST_KHR at the time of creating one or more of sema_objects, or
  - if one or more of sema_objects belong to a context that does not contain a device associated with command_queue.

- **CL_INVALID_VALUE** if num_sema_objects is 0.

- **CL_INVALID_SEMAPHORE_KHR** if any of the semaphore objects specified by sema_objects is not valid.

- **CL_INVALID_CONTEXT** if the context associated with command_queue and any of the semaphore objects in sema_objects are not the same, or if the context associated with command_queue and that associated with events in event_wait_list are not the same.

- **CL_INVALID_VALUE** if any of the semaphore objects specified by sema_objects requires a semaphore payload and sema_payload_list is NULL.
• CL_INVALID_EVENT_WAIT_LIST
  ◦ if `event_wait_list` is NULL and `num_events_in_wait_list` is not 0, or
  ◦ if `event_wait_list` is not NULL and `num_events_in_wait_list` is 0, or
  ◦ if event objects in `event_wait_list` are not valid events.

• CL_EXEC_STATUS_ERROR_FOR_EVENTS_IN_WAIT_LIST if the execution status of any of the events in `event_wait_list` is a negative integer value.

• CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.

• CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

5.13.7. Retaining and Releasing Semaphores

To release a semaphore object, call the function

```c
// Provided by cl_khr_semaphore
cl_int clReleaseSemaphoreKHR(
  cl_semaphore_khr sema_object);
```

- `clReleaseSemaphoreKHR` is provided by the cl_khr_semaphore extension.

- `sema_object` specifies the semaphore object to be released.

The `sema_object` reference count is decremented.

`clReleaseSemaphoreKHR` returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:

• CL_INVALID_SEMAPHORE_KHR if `sema_object` is not a valid semaphore object.

• CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.

• CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

After the reference count becomes zero and commands queued for execution on a command-queue(s) that use `sema_object` have finished, the semaphore object is deleted. Using this function to release a reference that was not obtained by creating the object via `clCreateSemaphoreWithPropertiesKHR` or by calling `clRetainSemaphoreKHR` causes undefined behavior.

To retain a semaphore object, call the function
```c
// Provided by cl_khr_semaphore
cl_int clRetainSemaphoreKHR(cl_semaphore_khr sema_object);
```

- `clRetainSemaphoreKHR` is provided by the `cl_khr_semaphore` extension.

- `sema_object` specifies the semaphore object to be retained.

`clRetainSemaphoreKHR` increments the reference count of `sema_object`.

`clRetainSemaphoreKHR` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_SEMAPHORE_KHR` if `sema_object` is not a valid semaphore object.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

5.13.8. Semaphore Queries

To query information about a semaphore object, call the function

```c
// Provided by cl_khr_semaphore
cl_int clGetSemaphoreInfoKHR(
    cl_semaphore_khr sema_object,
    cl_semaphore_info_khr param_name,
    size_t param_value_size,
    void* param_value,
    size_t* param_value_size_ret);
```

- `clGetSemaphoreInfoKHR` is provided by the `cl_khr_semaphore` extension.

- `sema_object` specifies the semaphore object being queried.

- `param_name` is a constant that specifies the semaphore information to query, and must be one of the values shown in the Semaphore Queries table.

- `param_value` is a pointer to memory where the result of the query is returned as described in the Semaphore Queries table. If `param_value` is `NULL`, it is ignored.

- `param_value_size` specifies the size in bytes of memory pointed to `param_value`. This size must be greater than or equal to the size of the return type described in the Semaphore Queries table.

- `param_value_size_ret` returns the actual size in bytes of data being queried by `param_value`. If `param_value_size_ret` is `NULL`, it is ignored.

`Table 55. List of parameter names supported by clGetSemaphoreInfoKHR`
<table>
<thead>
<tr>
<th>Semaphore Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_SEMAPHORE_CONTEXT_KHR</td>
<td>cl_context</td>
<td>Returns the context specified when the semaphore is created.</td>
</tr>
<tr>
<td>CL_SEMAPHORE_REFERENCE_COUNT_KHR</td>
<td>cl_uint</td>
<td>Returns the semaphore reference count.</td>
</tr>
<tr>
<td>CL_SEMAPHORE_PROPERTIES_KHR</td>
<td>cl_semaphore_properties_khr[]</td>
<td>Return the properties argument specified in clCreateSemaphoreWithPropertiesKHR. The implementation must return the values specified in the properties argument in the same order and without including additional properties.</td>
</tr>
<tr>
<td>CL_SEMAPHORE_TYPE_KHR</td>
<td>cl_semaphore_type_khr</td>
<td>Returns the semaphore type.</td>
</tr>
<tr>
<td>CL_SEMAPHORE_PAYLOAD_KHR</td>
<td>cl_semaphore_payload_khr</td>
<td>Returns the semaphore payload value. For semaphores of type CL_SEMAPHORE_TYPE_BINARY_KHR the payload value returned will be 0 if the semaphore is in an un-signaled state, and 1 if it is in a signaled state.</td>
</tr>
<tr>
<td>CL_SEMAPHORE_DEVICE_HANDLE_LIST_KHR</td>
<td>cl_device_id[]</td>
<td>Returns the list of OpenCL devices the semaphore is associated with.</td>
</tr>
<tr>
<td>CL_SEMAPHORE_EXPORT_HANDLE_TYPES_KHR</td>
<td>cl_external_semaphore_handle_type_khr[]</td>
<td>Returns the list of external semaphore handle types that may be used for exporting. The size of this query may be 0 indicating that this semaphore does not support any handle types for exporting.</td>
</tr>
<tr>
<td>CL_SEMAPHORE_EXPORTABLE_KHR</td>
<td>cl_bool[]</td>
<td>Returns CL_TRUE if the semaphore is exportable and CL_FALSE otherwise.</td>
</tr>
</tbody>
</table>

clGetSemaphoreInfoKHR returns CL_SUCCESS if the information is queried successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_SEMAPHORE_KHR**
  - if sema_object is not a valid semaphore

- **CL_INVALID_VALUE**
  - if param_name is not one of the attribute defined in the Semaphore Queries table or
  - if param_value_size is less than the size of Return Type of the corresponding param_name attribute as defined in the Semaphore Queries table.

- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.
5.14. Out-of-Order Execution of Kernels and Memory Object Commands

The OpenCL functions that are submitted to a command-queue are enqueued in the order the calls are made but can be configured to execute in-order or out-of-order. The properties argument in `clCreateCommandQueueWithProperties` or `clCreateCommandQueue` can be used to specify the execution order.

If the `CL_QUEUE_OUT_OF_ORDER_EXEC_MODE_ENABLE` property of a command-queue is not set, the commands enqueued to a command-queue execute in-order. For example, if an application calls `clEnqueueNDRangeKernel` to execute kernel A followed by a `clEnqueueNDRangeKernel` to execute kernel B, the application can assume that kernel A finishes first and then kernel B is executed. If the memory objects output by kernel A are inputs to kernel B then kernel B will see the correct data in memory objects produced by execution of kernel A. If the `CL_QUEUE_OUT_OF_ORDER_EXEC_MODE_ENABLE` property of a command-queue is set, then there is no guarantee that kernel A will finish before kernel B starts execution.

Applications can configure the commands enqueued to a command-queue to execute out-of-order by setting the `CL_QUEUE_OUT_OF_ORDER_EXEC_MODE_ENABLE` property of the command-queue. This can be specified when the command-queue is created. In out-of-order execution mode there is no guarantee that the enqueued commands will finish execution in the order they were queued. As there is no guarantee that kernels will be executed in-order, i.e. based on when the `clEnqueueNDRangeKernel` or `clEnqueueTask` calls are made within a command-queue, it is therefore possible that an earlier `clEnqueueNDRangeKernel` call to execute kernel A identified by event A may execute and/or finish later than a `clEnqueueNDRangeKernel` call to execute kernel B which was called by the application at a later point in time. To guarantee a specific order of execution of kernels, a wait on a particular event (in this case event A) can be used. The wait for event A can be specified in the `event_wait_list` argument to `clEnqueueNDRangeKernel` for kernel B.

In addition, a marker (`clEnqueueMarker` or `clEnqueueMarkerWithWaitList`) or a barrier (`clEnqueueBarrier` or `clEnqueueBarrierWithWaitList`) command can be enqueued to the command-queue. The marker command ensures that previously enqueued commands identified by the list of events to wait for (or all previous commands) have finished. A barrier command is similar to a marker command, but additionally guarantees that no later-enqueued commands will execute until the waited-for commands have executed.

Similarly, commands to read, write, copy or map memory objects that are enqueued after `clEnqueueNDRangeKernel`, `clEnqueueTask` or `clEnqueueNativeKernel` commands are not guaranteed to wait for kernels scheduled for execution to have completed (if the `CL_QUEUE_OUT_OF_ORDER_EXEC_MODE_ENABLE` property is set). To ensure correct ordering of commands, the event object returned by `clEnqueueNDRangeKernel`, `clEnqueueTask` or `clEnqueueNativeKernel` can be used to enqueue a wait for event or a barrier command can be enqueued that must complete before reads or writes to the memory object(s) occur.
5.15. Profiling Operations on Memory Objects and Kernels

This section describes the profiling of OpenCL functions that are enqueued as commands to a
command-queue. Profiling of OpenCL commands can be enabled by using a command-queue
created with the \texttt{CL\_QUEUE\_PROFILING\_ENABLE} flag set in the \texttt{CL\_QUEUE\_PROPERTIES} bitfield in the
\texttt{properties} argument to \texttt{clCreateCommandQueueWithProperties}, or in the \texttt{properties} argument to
\texttt{clCreateCommandQueue}. When profiling is enabled, the event objects that are created from
enqueuing a command store a timestamp for each of their state transitions.

To return profiling information for a command associated with an event when profiling is enabled,
call the function

```c
// Provided by CL\_VERSION\_1\_0
cl\_int clGetEventProfilingInfo(
    cl\_event event,
    cl\_profiling\_info param\_name,
    size\_t param\_value\_size,
    void* param\_value,
    size\_t* param\_value\_size\_ret);
```

- \texttt{event} specifies the event object.
- \texttt{param\_name} specifies the profiling data to query. The list of supported \texttt{param\_name} types and
the information returned in \texttt{param\_value} by \texttt{clGetEventProfilingInfo} is described in the Event
Profiling Queries table.
- \texttt{param\_value} is a pointer to memory where the appropriate result being queried is returned. If
\texttt{param\_value} is \texttt{NULL}, it is ignored.
- \texttt{param\_value\_size} is used to specify the size in bytes of memory pointed to by \texttt{param\_value}. This
size must be \(\geq\) size of return type as described in the Event Profiling Queries table.
- \texttt{param\_value\_size\_ret} returns the actual size in bytes of data being queried by \texttt{param\_name}. If
\texttt{param\_value\_size\_ret} is \texttt{NULL}, it is ignored.

\textit{Table 56. List of supported \texttt{param\_name}s by \texttt{clGetEventProfilingInfo}}
<table>
<thead>
<tr>
<th>Event Profiling Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_PROFILING_COMMAND_QUEUED</td>
<td>cl_ulong</td>
<td>A 64-bit value that describes the current device time counter in nanoseconds when the command identified by event is enqueued in a command-queue by the host. If the cl_khr_command_buffer_multi_device extension is supported, for events returned by a command-buffer enqueue operation to multiple command-queues, the host time when the command-buffer has been enqueued across the command-queues is used.</td>
</tr>
<tr>
<td>CL_PROFILING_COMMAND_SUBMIT</td>
<td>cl_ulong</td>
<td>A 64-bit value that describes the current device time counter in nanoseconds when the command identified by event that has been enqueued is submitted by the host to the device associated with the command-queue. If the cl_khr_command_buffer_multi_device extension is supported, for events returned by a command-buffer enqueue operation to multiple command-queues, the host time is used when command-buffer commands have been submitted to any command-queue.</td>
</tr>
<tr>
<td>CL_PROFILING_COMMAND_START</td>
<td>cl_ulong</td>
<td>A 64-bit value that describes the current device time counter in nanoseconds when the command identified by event starts execution on the device. If the cl_khr_command_buffer_multi_device extension is supported, for events returned by a command-buffer enqueue operation to multiple command-queues, the host time is used when any device starts executing a command-buffer command.</td>
</tr>
<tr>
<td>CL_PROFILING_COMMAND_END</td>
<td>cl_ulong</td>
<td>A 64-bit value that describes the current device time counter in nanoseconds when the command identified by event has finished execution on the device. If the cl_khr_command_buffer_multi_device extension is supported, for events returned by a command-buffer enqueue operation to multiple command-queues, the host time is used when the last command-buffer command finishes execution on any device.</td>
</tr>
</tbody>
</table>
Event Profiling Info | Return Type | Description
---|---|---
CL_PROFILING_COMMAND_COMPLETE | cl_ulong | A 64-bit value that describes the current device time counter in nanoseconds when the command identified by event and any child commands enqueued by this command on the device have finished execution. If the cl_khr_command_buffer_multi_device extension is supported, for events returned by a command-buffer enqueue operation to multiple command-queues, the host time is used when the command-buffer has completed execution across all command-queues.

The unsigned 64-bit values returned can be used to measure the time in nano-seconds consumed by OpenCL commands.

OpenCL devices are required to correctly track time across changes in device frequency and power states. The CL_DEVICE_PROFILING_TIMER_RESOLUTION specifies the resolution of the timer i.e. the number of nanoseconds elapsed before the timer is incremented.

If the cl_khr_command_buffer_multi_device extension is supported, and if no reliable device timer sources are available to inform the host side, or parallel runtime scheduling makes it impossible to identify a first/last command, then an implementation may fallback to reporting CL_PROFILING_COMMAND_SUBMIT and CL_PROFILING_COMMAND_COMPLETE for CL_PROFILING_COMMAND_START and CL_PROFILING_COMMAND_END respectively.

clGetEventProfilingInfo returns CL_SUCCESS if the function is executed successfully and the profiling information has been recorded. Otherwise, it returns one of the following errors:

- CL_PROFILING_INFO_NOT_AVAILABLE if the CL_QUEUE_PROFILING_ENABLE flag is not set for the command-queue, if the execution status of the command identified by event is not CL_COMPLETE or if event is a user event object. Prior to OpenCL 3.0, implementations may return CL_PROFILING_INFO_NOT_AVAILABLE for an event created by clEnqueueSVMFree.
  If the cl_khr_command_buffer_multi_device extension is supported, and if event was created from a call to clEnqueueCommandBufferKHR, CL_PROFILING_INFO_NOT_AVAILABLE is returned if all the queues passed do not have CL_QUEUE_PROFILING_ENABLE set.

- CL_INVALID_VALUE if param_name is not valid, or if size in bytes specified by param_value_size is < size of return type as described in the Event Profiling Queries table and param_value is not NULL.

- CL_INVALID_EVENT if event is a not a valid event object.

- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.

- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.
5.16. Flush and Finish

To flush commands to a device, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clFlush(
    cl_command_queue command_queue);
```

- `command_queue` is the command-queue to flush.

All previously queued OpenCL commands in `command_queue` are issued to the device associated with `command_queue`. `clFlush` only guarantees that all queued commands to `command_queue` will eventually be submitted to the appropriate device. There is no guarantee that they will be complete after `clFlush` returns.

Any blocking commands queued in a command-queue and `clReleaseCommandQueue` perform an implicit flush of the command-queue. These blocking commands are `clEnqueueReadBuffer`, `clEnqueueReadBufferRect`, `clEnqueueReadImage`, with `blocking_read` set to `CL_TRUE`; `clEnqueueWriteBuffer`, `clEnqueueWriteBufferRect`, `clEnqueueWriteImage` with `blocking_write` set to `CL_TRUE`; `clEnqueueMapBuffer`, `clEnqueueMapImage` with `blocking_map` set to `CL_TRUE`; `clEnqueueSVMMemcpy` with `blocking_copy` set to `CL_TRUE`; `clEnqueueSVMMemcpy` with `blocking_map` set to `CL_TRUE` or `clWaitForEvents`.

To use event objects that refer to commands enqueued in a command-queue as event objects to wait on by commands enqueued in a different command-queue, the application must call a `clFlush` or any blocking commands that perform an implicit flush of the command-queue where the commands that refer to these event objects are enqueued.

`clFlush` returns `CL_SUCCESS` if the function call was executed successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_COMMAND_QUEUE` if `command_queue` is not a valid host command-queue.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

To wait for completion of commands on a device, call the function

```c
// Provided by CL_VERSION_1_0
cl_int clFinish(
    cl_command_queue command_queue);
```

- `command_queue` is the command-queue to wait for.

All previously queued OpenCL commands in `command_queue` are issued to the associated device, and the function blocks until all previously queued commands have completed. `clFinish` does not
return until all previously queued commands in `command_queue` have been processed and completed. `clFinish` is also a synchronization point.

`clFinish` returns `CL_SUCCESS` if the function call was executed successfully. Otherwise, it returns one of the following errors:

- `CL_INVALID_COMMAND_QUEUE` if `command_queue` is not a valid host command-queue.
- `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL implementation on the device.
- `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL implementation on the host.

5.17. Command-Buffers

A `command-buffer` object represents a series of operations to be enqueued on one or more command-queues without any application code interaction. Grouping the operations together allows efficient enqueuing of repetitive operations, as well as enabling driver optimizations.

Command-buffers are sequential use by default, but may also be set to simultaneous use on creation if the device optionally supports this capability. A sequential use command-buffer must have a Pending Count of 0 or 1. The simultaneous use capability removes this restriction and allows command-buffers to have a Pending Count greater than 1.

Command-buffers are created using an ordered list of command-queues that commands are recorded to and execute on by default. These command-queues can be replaced on command-buffer enqueue with different command-queues, provided for each element in the replacement list the substitute command-queue is compatible with the command-queue used on command-buffer creation. A compatible command-queue is defined as a command-queue with identical properties targeting the same device and in the same OpenCL context.

While constructing a command-buffer it is valid for the user to interleave calls to the same queue which create commands, such as `clCommandNDRangeKernelKHR`, with queue submission calls, such as `clEnqueueNDRangeKernel` or `clEnqueueCommandBufferKHR`. That is, there is no effect on queue state from recording commands. The purpose of the queue parameter is to define the device and properties of the command, which are constant queries on the queue object.

A command-buffer object should increment the reference count of attached OpenCL objects such as queues, buffers, images, and kernels referenced in commands recorded to the command-buffer. This enables correct behavior of the command-buffer when its attached objects have been released. On destruction of the command-buffer it should decrement these reference counts, allowing the attached objects to be freed if appropriate.

A command-buffer object does not update the reference count of objects set as arguments on kernels recorded into the command-buffer. This is consistent with the reference counting behavior of `clSetKernelArg`.

Applications should ensure that objects passed as arguments to kernels recorded to a command-buffer are not deleted until the command-buffer has been released.
Undefined behavior may result from the failure to follow this usage requirement for all the command-buffers an object is used as a kernel argument in.

If using layered extension `cl_khr_command_buffer_mutable_dispatch`, see related note on safe usage.

### 5.17.1. Command-Buffers and Multiple Devices

If the `cl_khr_command_buffer_multi_device` extension is supported, a command-buffer can contain commands recorded to the queues of different devices if a vendor provides support for inter-device `cl_sync_point_khr` synchronization. This feature is reported either through `CL_DEVICE_COMMAND_BUFFER_SYNC_DEVICES_KHR`, which informs the user what devices can synchronize with each other natively on the device-side, or through `CL_COMMAND_BUFFER_PLATFORM_UNIVERSAL_SYNC_KHR`, which allows synchronization between all devices in a platform, falling back to host-side synchronization when device-side synchronization is not available. These two mechanisms are referred to as **device-side sync** and **universal sync** respectively.

If these mechanisms do not report that more than one device can be used in a command-buffer, it will still be possible to perform multiple queue recording in a command-buffer if the `CL_COMMAND_BUFFER_CAPABILITY_MULTIPLE_QUEUE_KHR` capability is reported for a device. However, with this capability all the queues commands are recorded to must target the same device.

Commands recorded to different command-queues in the same command-buffer may be executed concurrently to each other unless synchronized explicitly with sync-points. Ordering of other commands submitted to the same command-queues as used to enqueue a command-buffer is the responsibility of the programmer. A command-buffer enqueue spanning multiple queues can return an event to use for synchronization, which will complete once all commands in the command-buffer have completed. If ordering restrictions are required, this event (or command-queue barriers) may be used by the user to synchronize the command-buffer enqueue with regular commands, or another command-buffer enqueue.

### 5.17.2. Command-Buffer Lifecycle

A command-buffer is always in one of the following states:

**Recording**

Initial state of a command-buffer on creation, where commands can be recorded to the command-buffer.

**Executable**

State after command recording has finished with `clFinalizeCommandBufferKHR` and the command-buffer may be enqueued.

**Pending**

Once a command-buffer has been enqueued to a command-queue it enters the Pending state until completion, at which point it moves back to the **Executable** state.
The Pending Count is the number of copies of the command buffer in the Pending state. By default a command-buffer's Pending Count must be 0 or 1. If the command-buffer was created with `CL_COMMAND_BUFFER_SIMULTANEOUS_USE_KHR` then the command-buffer may have a Pending Count greater than 1.

### 5.17.3. Creating Command-Buffer Objects

To create a command-buffer that can record commands to the specified queues, call the function

```c
// Provided by cl_khr_command_buffer
cl_command_buffer_khr clCreateCommandBufferKHR(
    cl_uint num_queues,
    const cl_command_queue* queues,
    const cl_command_buffer_properties_khr* properties,
    cl_int* errcode_ret);
```

`clCreateCommandBufferKHR` is provided by the `cl_khr_command_buffer` extension.

- `num_queues` is the number of command-queues listed in `queues`. If the `cl_khr_command_buffer_multi_device` extension is not supported, this must be one.
- `queues` is a pointer to a list of command-queues that the command-buffer commands will be recorded to. `queues` must be a non-NULL value and the length of the list equal to `num_queues`.
- `properties` specifies a list of properties for the command-buffer and their corresponding values. Each property name is immediately followed by the corresponding desired value. The list is terminated with 0. The list of supported properties is described in the table below. If a
supported property and its value is not specified in properties, its default value will be used. 

properties can be **NULL** in which case the default values for supported command-buffer properties will be used.

**Table 57. clCreateCommandBufferKHR properties**

<table>
<thead>
<tr>
<th>Recording Properties</th>
<th>Property Value</th>
<th>Description</th>
</tr>
</thead>
</table>
| CL_COMMAND_BUFFER_FLAGS_KHR | cl_command_buffer_flags_khr | This is a bitfield and can be set to a combination of the following values: 

- **CL_COMMAND_BUFFER_SIMULTANEOUS_USE_KHR** - Allow multiple instances of the command-buffer to be submitted to the device for execution. If set, devices must support **CL_COMMAND_BUFFER_CAPABILITY_SIMULTANEOUS_USE_KHR**.

provided by the cl_khr_command_buffer extension.

- **CL_COMMAND_BUFFER_DEVICE_SIDE_SYNC_KHR** - All commands in the command-buffer must use native synchronization, as reported by **CL_DEVICE_COMMAND_BUFFER_SYNC_DEVICES_KHR**. This can be used as a safeguard for performant applications that do not want to accidentally fallback to host synchronization when passing multiple queues.

provided by the cl_khr_command_buffer_multi_device extension.

- **CL_COMMAND_BUFFER_MUTABLE_KHR** - Enables modification of the command-buffer, by default command-buffers are immutable. If set, commands in the command-buffer may be updated via **clUpdateMutableCommandsKHR**.

provided by the cl_khr_command_buffer_mutable_dispatch extension.

The default value of this property is 0.
<table>
<thead>
<tr>
<th>Recording Properties</th>
<th>Property Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>CL_COMMAND_BUFFER_MUTABLE_DISPATCH_ASSERTS_KHR</strong></td>
<td>cl_mutable_dispatch_asserts_khr</td>
<td>This is a bitfield and can be set to a combination of the following values:</td>
</tr>
<tr>
<td>provided by the cl_khr_command_buffer_mutable_dispatch extension.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

- `errcode_ret` will return an appropriate error code. If `errcode_ret` is **NULL**, no error code is returned.

**Table 58. Summary of command-buffer creation configurations, for the cl_khr_command_buffer_multi_device extension**

<table>
<thead>
<tr>
<th>All Devices Associated With Queues can Device-side Sync</th>
<th>Platform Supports Universal Sync</th>
<th>Condition</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>Yes or No</td>
<td>Any device does not support the multi-queue capability, and has more than one queue targeting it</td>
<td>Error - <strong>CL_INCOMPATIBLE_COMMAND_QUEUE_KHR</strong></td>
</tr>
<tr>
<td></td>
<td></td>
<td>User sets <strong>CL_COMMAND_BUFFER_DEVICE_SIDE_SYNC_KHR</strong> flag</td>
<td>OK</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Otherwise</td>
<td>OK</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Yes or No</th>
<th>Yes or No</th>
<th>Any device does not support the multi-queue capability, and has more than one queue targeting it</th>
<th>Error - <strong>CL_INCOMPATIBLE_COMMAND_QUEUE_KHR</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td>User sets <strong>CL_COMMAND_BUFFER_DEVICE_SIDE_SYNC_KHR</strong> flag</td>
<td>OK</td>
<td>Otherwise</td>
<td>OK</td>
</tr>
<tr>
<td>All Devices Associated With Queues can Device-side Sync</td>
<td>Platform Supports Universal Sync</td>
<td>Condition</td>
<td>Result</td>
</tr>
<tr>
<td>--------------------------------------------------------</td>
<td>---------------------------------</td>
<td>-----------</td>
<td>--------</td>
</tr>
<tr>
<td>No</td>
<td>Yes</td>
<td>Any device does not support the multi-queue capability, and has more than one queue targeting it</td>
<td>Error - CL_INCOMPATIBLE_COMMAND_QUEUE_KHR</td>
</tr>
<tr>
<td></td>
<td></td>
<td>User sets CL_COMMAND_BUFFER_DEVICE_SIDE_SYNC_KHR flag</td>
<td>Error - CL_INCOMPATIBLE_COMMAND_QUEUE_KHR</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Otherwise</td>
<td>OK - May be performance implications when synchronizing commands between devices without device-side sync support.</td>
</tr>
<tr>
<td>No</td>
<td>No</td>
<td>Always</td>
<td>Error - CL_INCOMPATIBLE_COMMAND_QUEUE_KHR</td>
</tr>
</tbody>
</table>

Upon creation the command-buffer is defined as being in the **Recording** state, in order for the command-buffer to be enqueued it must first be finalized using `clFinalizeCommandBufferKHR` after which no further commands can be recorded. A command-buffer is submitted for execution on command-queues with a call to `clEnqueueCommandBufferKHR`.

`clCreateCommandBufferKHR` returns a valid non-zero command-buffer and `errcode_ret` is set to **CL_SUCCESS** if the command-buffer is created successfully. Otherwise, it returns a **NULL** value with one of the following error values returned in `errcode_ret`:

- **CL_INVALID_COMMAND_QUEUE** if any command-queue in `queues` is not a valid command-queue.
- **CL_INCOMPATIBLE_COMMAND_QUEUE_KHR** if any command-queue in `queues` is an out-of-order command-queue and the device associated with the command-queue does not support the `CL_COMMAND_BUFFER_CAPABILITY_OUT_OF_ORDER_KHR` capability.
- **CL_INCOMPATIBLE_COMMAND_QUEUE_KHR** if the properties of any command-queue in `queues` does not contain the minimum properties specified by `CL_DEVICE_COMMAND_BUFFER_REQUIRED_QUEUE_PROPERTIES_KHR`.
- **CL_INVALID_CONTEXT** if all the command-queues in `queues` do not have the same OpenCL context.
- **CL_INVALID_VALUE** if the `cl_khr_command_buffer_multi_device` extension is supported and `num_queues` is zero, or if the `cl_khr_command_buffer_multi_device` extension is not supported and `num_queues` is not one.
- **CL_INVALID_VALUE** if `queues` is **NULL**.
• **CL_INVALID_VALUE** if values specified in *properties* are not valid, or if the same property name is specified more than once.

• **CL_INVALID_PROPERTY** if values specified in *properties* are valid but are not supported by all the devices associated with command-queues in *queues*.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

If the **cl_khr_command_buffer_multi_device** extension is supported:

• **CL_INCOMPATIBLE_COMMAND_QUEUE_KHR** if *queues* includes more than one command-queue associated with a device that does not support capability **CL_COMMAND_BUFFER_CAPABILITY_MULTIPLE_QUEUE_KHR**.

• **CL_INCOMPATIBLE_COMMAND_QUEUE_KHR** if the **CL_COMMAND_BUFFER_DEVICE_SIDE_SYNC_KHR** flag is set, and any device associated with a command-queue in *queues* cannot natively synchronize with the other devices associated with *queues* as reported by **CL_DEVICE_COMMAND_BUFFER_SYNC_DEVICES_KHR**.

• **CL_INCOMPATIBLE_COMMAND_QUEUE_KHR** if the platform does not support the **CL_COMMAND_BUFFER_PLATFORM_UNIVERSAL_SYNC_KHR** capability, and any device associated with a command-queue in *queues* cannot natively synchronize with the other devices associated with *queues* as reported by **CL_DEVICE_COMMAND_BUFFER_SYNC_DEVICES_KHR**.

To increment a command-buffer's reference count, call the function

```c
// Provided by cl_khr_command_buffer
cl_int clRetainCommandBufferKHR(
    cl_command_buffer_khr command_buffer);
```

**clRetainCommandBufferKHR** is provided by the **cl_khr_command_buffer** extension.

• *command_buffer* specifies the command-buffer to retain.

**clRetainCommandBufferKHR** returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:

• **CL_INVALID_COMMAND_BUFFER_KHR** if *command_buffer* is not a valid command-buffer.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To decrement a command-buffer's reference count, call the function
clReleaseCommandBufferKHR is provided by the cl_khr_command_buffer extension.

- command_buffer specifies the command-buffer to release.

After the command_buffer reference count becomes zero and has finished execution, the command-buffer is deleted.

clReleaseCommandBufferKHR returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:

- CL_INVALID_COMMAND_BUFFER_KHR if command_buffer is not a valid command-buffer.
- CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
- CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

5.17.4. Enqueuing a Command-Buffer

To finalize command recording ready for enqueuing a command-buffer on a command-queue, call the function

clFinalizeCommandBufferKHR is provided by the cl_khr_command_buffer extension.

- command_buffer refers to a valid command-buffer object.

clFinalizeCommandBufferKHR places the command-buffer in the Executable state where commands can no longer be recorded, at this point the command-buffer is ready to be enqueued.

clFinalizeCommandBufferKHR returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:

- CL_INVALID_COMMAND_BUFFER_KHR if command_buffer is not a valid command-buffer.
- CL_INVALID_OPERATION if command_buffer is not in the Recording state.
• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To enqueue a command-buffer to execute on command-queues, call the function

```c
// Provided by cl_khr_command_buffer
cl_int clEnqueueCommandBufferKHR(
    cl_uint num_queues,
    cl_command_queue* queues,
    cl_command_buffer_khr command_buffer,
    cl_uint num_events_in_wait_list,
    const cl_event* event_wait_list,
    cl_event* event);
```

**clEnqueueCommandBufferKHR** is provided by the **cl_khr_command_buffer** extension.

• *num_queues* is the number of command-queues listed in *queues*.

• *queues* is a pointer to an ordered list of command-queues compatible with the command-queues used on recording. *queues* can be **NULL**, in which case the default command-queues used on command-buffer creation are used and *num_queues* must be 0.

• *command_buffer* refers to a valid command-buffer object.

• *event_wait_list*, *num_events_in_wait_list* specify events that need to complete before this particular command can be executed. If *event_wait_list* is **NULL**, then this particular command does not wait on any event to complete. If *event_wait_list* is **NULL**, *num_events_in_wait_list* must be 0. If *event_wait_list* is not **NULL**, the list of events pointed to by *event_wait_list* must be valid and *num_events_in_wait_list* must be greater than 0. The events specified in *event_wait_list* act as synchronization points. The context associated with events in *event_wait_list* and *command_queue* must be the same. The memory associated with *event_wait_list* can be reused or freed after the function returns.

• *event* will return an event object that identifies this command and can be used to query for profiling information or queue a wait for this particular command to complete. *event* can be **NULL** in which case it will not be possible for the application to wait on this command or query it for profiling information.

To enqueue a command-buffer it must be in a **Executable** state, see **clFinalizeCommandBufferKHR**.

**clEnqueueCommandBufferKHR** returns **CL_SUCCESS** if the command-buffer execution was successfully queued, or one of the errors below:

• **CL_INVALID_COMMAND_BUFFER_KHR** if *command_buffer* is not a valid command-buffer.

• **CL_INVALID_OPERATION** if *command_buffer* has not been finalized.
• CL_INVALID_OPERATION if `command_buffer` was not created with the CL_COMMAND_BUFFER_SIMULTANEOUS_USE_KHR flag and is in the Pending state.

• CL_INVALID_VALUE if `queues` is NULL and `num_queues` is > 0, or `queues` is not NULL and `num_queues` is 0.

• CL_INVALID_VALUE if `num_queues` is > 0 and not the same value as `num_queues` set on `command_buffer` creation.

• CL_INVALID_COMMAND_QUEUE if any element of `queues` is not a valid command-queue.

• CL_INCOMPATIBLE_COMMAND_QUEUE_KHR if any element of `queues` is not compatible with the command-queue set on `command_buffer` creation at the same list index.

• CL_INVALID_CONTEXT if any element of `queues` does not have the same context as the command-queue set on `command_buffer` creation at the same list index.

• CL_INVALID_CONTEXT if context associated with `command_buffer` and events in `event_wait_list` are not the same.

• CL_OUT_OF_RESOURCES if there is a failure to queue the execution instance of `command_buffer` on the command-queues because of insufficient resources needed to execute `command_buffer`.

• CL_INVALID_EVENT_WAIT_LIST if `event_wait_list` is NULL and `num_events_in_wait_list` > 0, or `event_wait_list` is not NULL and `num_events_in_wait_list` is 0, or if event objects in `event_wait_list` are not valid events.

• CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.

• CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.17.5. Recording Commands to a Command-Buffer

To record a barrier operation used as a synchronization point, call the function

```c
// Provided by cl_khr_command_buffer
cl_int clCommandBarrierWithWaitListKHR(
    cl_command_buffer_khr command_buffer,
    cl_command_queue command_queue,
    cl_uint num_sync_points_in_wait_list,
    const cl_sync_point_khr* sync_point_wait_list,
    cl_sync_point_khr* sync_point,
    cl_mutable_command_khr* mutable_handle);
```

**clCommandBarrierWithWaitListKHR** is provided by the cl_khr_command_buffer extension.

- `command_buffer` refers to a valid command-buffer object.

- `command_queue` specifies the command-queue the command will be recorded to. This parameter is unused, as only a single command-queue is supported, and must be NULL.
• **sync_point_wait_list, num_sync_points_in_wait_list** specify synchronization-points that need to complete before this particular command can be executed.

If **sync_point_wait_list** is **NULL**, **num_sync_points_in_wait_list** must be 0. If **sync_point_wait_list** is not **NULL**, the list of synchronization-points pointed to by **sync_point_wait_list** must be valid and **num_sync_points_in_wait_list** must be greater than 0. The synchronization-points specified in **sync_point_wait_list** are **device-side** synchronization-points. The command-buffer associated with synchronization-points in **sync_point_wait_list** must be the same as **command_buffer**. The memory associated with **sync_point_wait_list** can be reused or freed after the function returns.

If **sync_point_wait_list** is **NULL**, then this particular command waits until all previous recorded commands to **command_queue** have completed.

• **sync_point** returns a synchronization-point ID that identifies this particular command. Synchronization-point objects are unique and can be used to identify this barrier command later on. **sync_point** can be **NULL** in which case it will not be possible for the application to record a wait for this command to complete. If the **sync_point_wait_list** and the **sync_point** arguments are not **NULL**, the **sync_point** argument should not refer to an element of the **sync_point_wait_list** array.

• **mutable_handle** returns a handle to the command. This parameter is unused, and **must** be **NULL**.

**clCommandBarrierWithWaitListKHR** waits for either a list of synchronization-points to complete, or if the list is empty it waits for all commands previously recorded in **command_buffer** to complete before it completes. This command blocks command execution, that is, any following commands recorded after it do not execute until it completes.

**clCommandBarrierWithWaitListKHR** returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns one of the following errors:

• **CL_INVALID_COMMAND_QUEUE** if **command_queue** is not **NULL**.

• **CL_INVALID_COMMAND_BUFFER_KHR** if **command_buffer** is not a valid command-buffer.

• **CL_INVALID_CONTEXT** if the context associated with **command_queue** and **command_buffer** is not the same.

• **CL_INVALID_OPERATION** if **command_buffer** has been finalized.

• **CL_INVALID_VALUE** if **mutable_handle** is not **NULL**.

• **CL_INVALID_SYNC_POINT_WAIT_LIST_KHR** if **sync_point_wait_list** is **NULL** and **num_sync_points_in_wait_list** is > 0, or **sync_point_wait_list** is not **NULL** and **num_sync_points_in_wait_list** is 0, or if synchronization-point objects in **sync_point_wait_list** are not valid synchronization-points.

• **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.

• **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To record a command to copy from one buffer object to another, call the function
clCommandCopyBufferKHR is provided by the cl_khr_command_buffer extension.

- **command_buffer** refers to a valid command-buffer object.
- **command_queue** specifies the command-queue the command will be recorded to. If the cl_khr_command_buffer_multi_device extension is not supported, only a single command-queue is supported, and command_queue must be NULL. If the cl_khr_command_buffer_multi_device extension is supported and command_queue is NULL, then only one command-queue must have been set on command_buffer creation; otherwise, command_queue must not be NULL.
- **src_buffer, dst_buffer, src_offset, dst_offset, size** refer to clEnqueueCopyBuffer.
- **sync_point_wait_list, num_sync_points_in_wait_list** specify synchronization-points that need to complete before this particular command can be executed. If sync_point_wait_list is NULL, num_sync_points_in_wait_list must be 0. If sync_point_wait_list is not NULL, the list of synchronization-points pointed to by sync_point_wait_list must be valid and num_sync_points_in_wait_list must be greater than 0. The synchronization-points specified in sync_point_wait_list are device-side synchronization-points. The command-buffer associated with synchronization-points in sync_point_wait_list must be the same as command_buffer. The memory associated with sync_point_wait_list can be reused or freed after the function returns.
- **sync_point** returns a synchronization-point ID that identifies this particular command. Synchronization-point objects are unique and can be used to identify this command later on. sync_point can be NULL in which case it will not be possible for the application to record a wait for this command to complete. If the sync_point_wait_list and the sync_point arguments are not NULL, the sync_point argument should not refer to an element of the sync_point_wait_list array.
- **mutable_handle** returns a handle to the command. This parameter is unused, and must be NULL.

clCommandCopyBufferKHR returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns the errors defined by clEnqueueCopyBuffer except:

CL_INVALID_COMMAND_QUEUE is replaced with:

- CL_INVALID_COMMAND_QUEUE if the cl_khr_command_buffer_multi_device extension is not supported
and command_queue is not NULL.

- CL_INVALID_COMMAND_QUEUE if the cl_khr_command_buffer_multi_device extension is supported; and either command_queue is NULL and command_buffer was created with more than one queue, or command_queue is not NULL and not a command-queue listed on command_buffer creation.

CL_INVALID_CONTEXT is replaced with:

- CL_INVALID_CONTEXT if the context associated with command_queue, command_buffer, src_buffer, and dst_buffer are not the same.

CL_INVALID_EVENT_WAIT_LIST is replaced with:

- CL_INVALID_SYNC_POINT_WAIT_LIST_KHR if sync_point_wait_list is NULL and num_sync_points_in_wait_list is > 0, or sync_point_wait_list is not NULL and num_sync_points_in_wait_list is 0, or if synchronization-point objects in sync_point_wait_list are not valid synchronization-points.

New errors:

- CL_INVALID_COMMAND_BUFFER_KHR if command_buffer is not a valid command-buffer.
- CL_INVALID_OPERATION if command_buffer has been finalized.
- CL_INVALID_VALUE if mutable_handle is not NULL.

To record a command to copy a rectangular region from a buffer object to another buffer object, call the function

```c
// Provided by cl_khr_command_buffer
cl_int clCommandCopyBufferRectKHR(
    cl_command_buffer_khr command_buffer,
    cl_command_queue command_queue,
    cl_mem src_buffer,
    cl_mem dst_buffer,
    const size_t* src_origin,
    const size_t* dst_origin,
    const size_t* region,
    size_t src_row_pitch,
    size_t src_slice_pitch,
    size_t dst_row_pitch,
    size_t dst_slice_pitch,
    cl_uint num_sync_points_in_wait_list,
    const cl_sync_point_khr* sync_point_wait_list,
    cl_sync_point_khr* sync_point,
    cl_mutable_command_khr* mutable_handle);
```

clCommandCopyBufferRectKHR is provided by the cl_khr_command_buffer extension.

- command_buffer refers to a valid command-buffer object.
• `command_queue` specifies the command-queue the command will be recorded to. If the cl_khr_command_buffer_multi_device extension is not supported, only a single command-queue is supported, and `command_queue` must be `NULL`. If the cl_khr_command_buffer_multi_device extension is supported and `command_queue` is `NULL`, then only one command-queue must have been set on `command_buffer` creation; otherwise, `command_queue` must not be `NULL`.

• `src_origin`, `dst_origin`, `region`, `src_row_pitch`, `src_slice_pitch`, `dst_row_pitch`, `dst_slice_pitch` refer to `clEnqueueCopyBufferRect`.

• `sync_point_wait_list`, `num_sync_points_in_wait_list` specify synchronization-points that need to complete before this particular command can be executed.

If `sync_point_wait_list` is `NULL`, `num_sync_points_in_wait_list` must be 0. If `sync_point_wait_list` is not `NULL`, the list of synchronization-points pointed to by `sync_point_wait_list` must be valid and `num_sync_points_in_wait_list` must be greater than 0. The synchronization-points specified in `sync_point_wait_list` are device-side synchronization-points. The command-buffer associated with synchronization-points in `sync_point_wait_list` must be the same as `command_buffer`. The memory associated with `sync_point_wait_list` can be reused or freed after the function returns.

• `sync_point` returns a synchronization-point ID that identifies this particular command. Synchronization-point objects are unique and can be used to identify this command later on. `sync_point` can be `NULL` in which case it will not be possible for the application to record a wait for this command to complete. If the `sync_point_wait_list` and the `sync_point` arguments are not `NULL`, the `sync_point` argument should not refer to an element of the `sync_point_wait_list` array.

• `mutable_handle` returns a handle to the command. This parameter is unused, and must be `NULL`.

```c
clCommandCopyBufferRectKHR
```
records a command to copy a 2D or 3D rectangular region from the buffer object identified by `src_buffer` to a 2D or 3D region in the buffer object identified by `dst_buffer`. Copying begins at the source offset and destination offset which are computed as described in the description for `src_origin` and `dst_origin`.

Each byte of the region's width is copied from the source offset to the destination offset. After copying each width, the source and destination offsets are incremented by their respective source and destination row pitches. After copying each 2D rectangle, the source and destination offsets are incremented by their respective source and destination slice pitches.

`clCommandCopyBufferRectKHR` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns the errors defined by `clEnqueueCopyBufferRect` except:

- `CL_INVALID_COMMAND_QUEUE` is replaced with:
  - `CL_INVALID_COMMAND_QUEUE` if the cl_khr_command_buffer_multi_device extension is not supported and `command_queue` is not `NULL`.
  - `CL_INVALID_COMMAND_QUEUE` if the cl_khr_command_buffer_multi_device extension is supported; and either `command_queue` is `NULL` and `command_buffer` was created with more than one queue, or `command_queue` is not `NULL` and not a command-queue listed on `command_buffer` creation.
CL_INVALID_CONTEXT is replaced with:

- CL_INVALID_CONTEXT if the context associated with command_queue, command_buffer, src_buffer, and dst_buffer are not the same.

CL_INVALID_EVENT_WAIT_LIST is replaced with:

- CL_INVALID_SYNC_POINT_WAIT_LIST_KHR if sync_point_wait_list is NULL and num_sync_points_in_wait_list is > 0, or sync_point_wait_list is not NULL and num_sync_points_in_wait_list is 0, or if synchronization-point objects in sync_point_wait_list are not valid synchronization-points.

New errors:

- CL_INVALID_COMMAND_BUFFER_KHR if command_buffer is not a valid command-buffer.
- CL_INVALID_OPERATION if command_buffer has been finalized.
- CL_INVALID_VALUE if mutable_handle is not NULL.

To record a command to copy a buffer object to an image object, call the function

```c
// Provided by cl_khr_command_buffer
cl_int clCommandCopyBufferToImageKHR(
    cl_command_buffer_khr command_buffer,
    cl_command_queue command_queue,
    cl_mem src_buffer,
    cl_mem dst_image,
    size_t src_offset,
    const size_t* dst_origin,
    const size_t* region,
    cl_uint num_sync_points_in_wait_list,
    const cl_sync_point_khr* sync_point_wait_list,
    cl_sync_point_khr* sync_point,
    cl_mutable_command_khr* mutable_handle);
```

clCommandCopyBufferToImageKHR is provided by the cl_khr_command_buffer extension.

- command_buffer refers to a valid command-buffer object.
- command_queue specifies the command-queue the command will be recorded to.
  If the cl_khr_command_buffer_multi_device extension is not supported, only a single command-queue is supported, and command_queue must be NULL.
  If the cl_khr_command_buffer_multi_device extension is supported and command_queue is NULL, then only one command-queue must have been set on command_buffer creation; otherwise, command_queue must not be NULL.
- src_buffer, dst_image, src_offset, dst_origin, region refer to clEnqueueCopyBufferToImage
- sync_point_wait_list, num_sync_points_in_wait_list specify synchronization-points that need to complete before this particular command can be executed.
If `sync_point_wait_list` is `NULL`, `num_sync_points_in_wait_list` must be 0. If `sync_point_wait_list` is not `NULL`, the list of synchronization-points pointed to by `sync_point_wait_list` must be valid and `num_sync_points_in_wait_list` must be greater than 0. The synchronization-points specified in `sync_point_wait_list` are **device-side** synchronization-points. The command-buffer associated with synchronization-points in `sync_point_wait_list` must be the same as `command_buffer`. The memory associated with `sync_point_wait_list` can be reused or freed after the function returns.

- `sync_point` returns a synchronization-point ID that identifies this particular command. Synchronization-point objects are unique and can be used to identify this command later on. `sync_point` can be `NULL` in which case it will not be possible for the application to record a wait for this command to complete. If the `sync_point_wait_list` and the `sync_point` arguments are not `NULL`, the `sync_point` argument should not refer to an element of the `sync_point_wait_list` array.

- `mutable_handle` returns a handle to the command. This parameter is unused, and must be `NULL`.

`clCommandCopyBufferToImageKHR` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns the errors defined by `clEnqueueCopyBufferToImage` except:

**CL_INVALID_COMMAND_QUEUE** is replaced with:

- `CL_INVALID_COMMAND_QUEUE` if the `cl_khr_command_buffer_multi_device` extension is not supported and `command_queue` is not `NULL`.

- `CL_INVALID_COMMAND_QUEUE` if the `cl_khr_command_buffer_multi_device` extension is supported; and either `command_queue` is `NULL` and `command_buffer` was created with more than one queue, or `command_queue` is not `NULL` and not a command-queue listed on `command_buffer` creation.

**CL_INVALID_CONTEXT** is replaced with:

- `CL_INVALID_CONTEXT` if the context associated with `command_queue`, `command_buffer`, `src_buffer`, and `dst_image` are not the same.

**CL_INVALID_EVENT_WAIT_LIST** is replaced with:

- `CL_INVALID_SYNC_POINT_WAIT_LIST_KHR` if `sync_point_wait_list` is `NULL` and `num_sync_points_in_wait_list` is > 0, or `sync_point_wait_list` is not `NULL` and `num_sync_points_in_wait_list` is 0, or if synchronization-point objects in `sync_point_wait_list` are not valid synchronization-points.

New errors:

- `CL_INVALID_COMMAND_BUFFER_KHR` if `command_buffer` is not a valid command-buffer.

- `CL_INVALID_OPERATION` if `command_buffer` has been finalized.

- `CL_INVALID_VALUE` if `mutable_handle` is not `NULL`.

To record a command to copy between two image objects, call the function
// Provided by cl_khr_command_buffer
cl_int clCommandCopyImageKHR(
    cl_command_buffer_khr command_buffer,
    cl_command_queue command_queue,
    cl_mem src_image,
    cl_mem dst_image,
    const size_t* src_origin,
    const size_t* dst_origin,
    const size_t* region,
    cl_uint num_sync_points_in_wait_list,
    const cl_sync_point_khr* sync_point_wait_list,
    cl_sync_point_khr* sync_point,
    cl_mutable_command_khr* mutable_handle);

⚠️ clCommandCopyImageKHR is provided by the cl_khr_command_buffer extension.

- **command_buffer** refers to a valid command-buffer object.

- **command_queue** specifies the command-queue the command will be recorded to.
  If the cl_khr_command_buffer_multi_device extension is not supported, only a single command-queue is supported, and command_queue must be NULL.
  If the cl_khr_command_buffer_multi_device extension is supported and command_queue is NULL, then only one command-queue must have been set on command_buffer creation; otherwise, command_queue must not be NULL.

- **src_image**, **dst_image**, **src_origin**, **dst_origin**, **region** refer to clEnqueueCopyImage.

- **sync_point_wait_list**, **num_sync_points_in_wait_list** specify synchronization-points that need to complete before this particular command can be executed.
  If sync_point_wait_list is NULL, num_sync_points_in_wait_list must be 0. If sync_point_wait_list is not NULL, the list of synchronization-points pointed to by sync_point_wait_list must be valid and num_sync_points_in_wait_list must be greater than 0. The synchronization-points specified in sync_point_wait_list are device-side synchronization-points. The command-buffer associated with synchronization-points in sync_point_wait_list must be the same as command_buffer. The memory associated with sync_point_wait_list can be reused or freed after the function returns.

- **sync_point** returns a synchronization-point ID that identifies this particular command. Synchronization-point objects are unique and can be used to identify this command later on. sync_point can be NULL in which case it will not be possible for the application to record a wait for this command to complete. If the sync_point_wait_list and the sync_point arguments are not NULL, the sync_point argument should not refer to an element of the sync_point_wait_list array.

- **mutable_handle** returns a handle to the command. This parameter is unused, and must be NULL.

⚠️ It is currently a requirement that the **src_image** and **dst_image** image memory objects for clCommandCopyImageKHR must have the exact same image format, i.e. the cl_image_format descriptor specified when **src_image** and **dst_image** are created must match.
clCommandCopyImageKHR returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns the errors defined by clEnqueueCopyImage except:

**CL_INVALID_COMMAND_QUEUE** is replaced with:

- **CL_INVALID_COMMAND_QUEUE** if the cl_khr_command_buffer_multi_device extension is not supported and command_queue is not NULL.
- **CL_INVALID_COMMAND_QUEUE** if the cl_khr_command_buffer_multi_device extension is supported; and either command_queue is NULL and command_buffer was created with more than one queue, or command_queue is not NULL and not a command-queue listed on command_buffer creation.

**CL_INVALID_CONTEXT** is replaced with:

- **CL_INVALID_CONTEXT** if the context associated with command_queue, command_buffer, src_image, and dst_image are not the same.

**CL_INVALID_EVENT_WAIT_LIST** is replaced with:

- **CL_INVALID_SYNC_POINT_WAIT_LIST_KHR** if sync_point_wait_list is NULL and num_sync_points_in_wait_list is > 0, or sync_point_wait_list is not NULL and num_sync_points_in_wait_list is 0, or if synchronization-point objects in sync_point_wait_list are not valid synchronization-points.

New errors:

- **CL_INVALID_COMMAND_BUFFER_KHR** if command_buffer is not a valid command-buffer.
- **CL_INVALID_OPERATION** if command_buffer has been finalized.
- **CL_INVALID_VALUE** if mutable_handle is not NULL.

To record a command to copy an image object to a buffer object, call the function

```c
// Provided by cl_khr_command_buffer
cl_int clCommandCopyImageToBufferKHR(
    cl_command_buffer_khr command_buffer,
    cl_command_queue command_queue,
    cl_mem src_image,
    cl_mem dst_buffer,
    const size_t* src_origin,
    const size_t* region,
    size_t dst_offset,
    cl_uint num_sync_points_in_wait_list,
    const cl_sync_point_khr* sync_point_wait_list,
    cl_sync_point_khr* sync_point,
    cl_mutable_command_khr* mutable_handle);
```

**clCommandCopyImageToBufferKHR** is provided by the cl_khr_command_buffer extension.
• **command_buffer** refers to a valid command-buffer object.

• **command_queue** specifies the command-queue the command will be recorded to.
  - If the cl_khr_command_buffer_multi_device extension is not supported, only a single command-queue is supported, and **command_queue** must be **NULL**.
  - If the cl_khr_command_buffer_multi_device extension is supported and **command_queue** is **NULL**, then only one command-queue must have been set on **command_buffer** creation; otherwise, **command_queue** must not be **NULL**.

• **src_image**, **dst_buffer**, **src_origin**, **region**, **dst_offset** refer to **clEnqueueCopyImageToBuffer**.

• **sync_point_wait_list**, **num_sync_points_in_wait_list** specify synchronization-points that need to complete before this particular command can be executed.
  - If **sync_point_wait_list** is **NULL**, **num_sync_points_in_wait_list** must be 0. If **sync_point_wait_list** is not **NULL**, the list of synchronization-points pointed to by **sync_point_wait_list** must be valid and **num_sync_points_in_wait_list** must be greater than 0. The synchronization-points specified in **sync_point_wait_list** are **device-side** synchronization-points. The command-buffer associated with synchronization-points in **sync_point_wait_list** must be the same as **command_buffer**. The memory associated with **sync_point_wait_list** can be reused or freed after the function returns.

• **sync_point** returns a synchronization-point ID that identifies this particular command. Synchronization-point objects are unique and can be used to identify this command later on. **sync_point** can be **NULL** in which case it will not be possible for the application to record a wait for this command to complete. If the **sync_point_wait_list** and the **sync_point** arguments are not **NULL**, the **sync_point** argument should not refer to an element of the **sync_point_wait_list** array.

• **mutable_handle** returns a handle to the command. This parameter is unused, and **must** be **NULL**.

**clCommandCopyImageToBufferKHR** returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns the errors defined by **clEnqueueCopyImageToBuffer** except:

**CL_INVALID_COMMAND_QUEUE** is replaced by **clEnqueueCopyImageToBuffer** except:

• **CL_INVALID_COMMAND_QUEUE** if the cl_khr_command_buffer_multi_device extension is not supported and **command_queue** is not **NULL**.

• **CL_INVALID_COMMAND_QUEUE** if the cl_khr_command_buffer_multi_device extension is supported; and either **command_queue** is **NULL** and **command_buffer** was created with more than one queue, or **command_queue** is not **NULL** and a command-queue listed on **command_buffer** creation.

**CL_INVALID_CONTEXT** is replaced with:

• **CL_INVALID_CONTEXT** if the context associated with **command_queue**, **command_buffer**, **src_image**, and **dst_buffer** are not the same.

**CL_INVALID_EVENT_WAIT_LIST** is replaced with:

• **CL_INVALID_SYNC_POINT_WAIT_LIST_KHR** if **sync_point_wait_list** is **NULL** and **num_sync_points_in_wait_list** is > 0, or **sync_point_wait_list** is not **NULL** and **num_sync_points_in_wait_list** is 0, or if synchronization-point objects in **sync_point_wait_list** are not valid synchronization-points.
New errors:

- **CL_INVALID_COMMAND_BUFFER_KHR** if `command_buffer` is not a valid command-buffer.
- **CL_INVALID_OPERATION** if `command_buffer` has been finalized.
- **CL_INVALID_VALUE** if `mutable_handle` is not `NULL`.

To record a command to fill a buffer object with a pattern of a given pattern size, call the function

```c
// Provided by cl_khr_command_buffer
cl_int clCommandFillBufferKHR(
    cl_command_buffer_khr command_buffer,
    cl_command_queue command_queue,
    cl_mem buffer,
    const void* pattern,
    size_t pattern_size,
    size_t offset,
    size_t size,
    cl_uint num_sync_points_in_wait_list,
    const cl_sync_point_khr* sync_point_wait_list,
    cl_sync_point_khr* sync_point,
    cl_mutable_command_khr* mutable_handle);
```

- **clCommandFillBufferKHR** is provided by the `cl_khr_command_buffer` extension.

- The usage information which indicates whether the memory object can be read or written by a kernel and/or the host and is given by the `cl_mem_flags` argument value specified when `buffer` is created is ignored by `clCommandFillBufferKHR`.

- `command_buffer` refers to a valid command-buffer object.

- `command_queue` specifies the command-queue the command will be recorded to.
  If the `cl_khr_command_buffer_multi_device` extension is not supported, only a single command-queue is supported, and `command_queue` must be `NULL`.
  If the `cl_khr_command_buffer_multi_device` extension is supported and `command_queue` is `NULL`, then only one command-queue must have been set on `command_buffer` creation; otherwise, `command_queue` must not be `NULL`.

- `buffer`, `pattern`, `pattern_size`, `offset`, `size` refer to `clEnqueueFillBuffer`.

- `sync_point_wait_list`, `num_sync_points_in_wait_list` specify synchronization-points that need to complete before this particular command can be executed.

  If `sync_point_wait_list` is `NULL`, `num_sync_points_in_wait_list` must be 0. If `sync_point_wait_list` is not `NULL`, the list of synchronization-points pointed to by `sync_point_wait_list` must be valid and `num_sync_points_in_wait_list` must be greater than 0. The synchronization-points specified in `sync_point_wait_list` are `device-side` synchronization-points. The command-buffer associated with synchronization-points in `sync_point_wait_list` must be the same as `command_buffer`. The memory associated with `sync_point_wait_list` can be reused or freed after the function returns.
**sync_point** returns a synchronization-point ID that identifies this particular command. Synchronization-point objects are unique and can be used to identify this command later on. **sync_point** can be **NULL** in which case it will not be possible for the application to record a wait for this command to complete. If the **sync_point_wait_list** and the **sync_point** arguments are not **NULL**, the **sync_point** argument should not refer to an element of the **sync_point_wait_list** array.

**mutable_handle** returns a handle to the command. This parameter is unused, and must be **NULL**.

**clCommandFillBufferKHR** returns **CL_SUCCESS** if the function is executed successfully. Otherwise, it returns the errors defined by **clEnqueueFillBuffer** except:

**CL_INVALID_COMMAND_QUEUE** is replaced with:

- **CL_INVALID_COMMAND_QUEUE** if the **cl_khr_command_buffer_multi_device** extension is not supported and **command_queue** is not **NULL**.
- **CL_INVALID_COMMAND_QUEUE** if the **cl_khr_command_buffer_multi_device** extension is supported; and either **command_queue** is **NULL** and **command_buffer** was created with more than one queue, or **command_queue** is not **NULL** and not a command-queue listed on **command_buffer** creation.

**CL_INVALID_CONTEXT** is replaced with:

- **CL_INVALID_CONTEXT** if the context associated with **command_queue**, **command_buffer**, and **buffer** are not the same.

**CL_INVALID_EVENT_WAIT_LIST** is replaced with:

- **CL_INVALID_SYNC_POINT_WAIT_LIST_KHR** if **sync_point_wait_list** is **NULL** and **num_sync_points_in_wait_list** is > 0, or **sync_point_wait_list** is not **NULL** and **num_sync_points_in_wait_list** is 0, or if synchronization-point objects in **sync_point_wait_list** are not valid synchronization-points.

New errors:

- **CL_INVALID_COMMAND_BUFFER_KHR** if **command_buffer** is not a valid command-buffer.
- **CL_INVALID_OPERATION** if **command_buffer** has been finalized.
- **CL_INVALID_VALUE** if **mutable_handle** is not **NULL**.

To record a command to fill an image object with a specified color, call the function
// Provided by cl_khr_command_buffer
cl_int clCommandFillImageKHR(
    cl_command_buffer_khr command_buffer,
    cl_command_queue command_queue,
    cl_mem image,
    const void* fill_color,
    const size_t* origin,
    const size_t* region,
    cl_uint num_sync_points_in_wait_list,
    const cl_sync_point_khr* sync_point_wait_list,
    cl_sync_point_khr* sync_point,
    cl_mutable_command_khr* mutable_handle);

clCommandFillImageKHR is provided by the cl_khr_command_buffer extension.

The usage information which indicates whether the memory object can be read or
written by a kernel and/or the host and is given by the cl_mem_flags argument
value specified when image is created is ignored by clCommandFillImageKHR.

- **command_buffer** refers to a valid command-buffer object.
- **command_queue** specifies the command-queue the command will be recorded to.
  If the cl_khr_command_buffer_multi_device extension is not supported, only a single command-queue is supported, and **command_queue** must be NULL.
  If the cl_khr_command_buffer_multi_device extension is supported and **command_queue** is NULL, then only one command-queue must have been set on **command_buffer** creation; otherwise, **command_queue** must not be NULL.
- **image, fill_color, origin, region** refer to clEnqueueFillImage.
- **sync_point_wait_list, num_sync_points_in_wait_list** specify synchronization-points that need to complete before this particular command can be executed.
  If **sync_point_wait_list** is NULL, **num_sync_points_in_wait_list** must be 0. If **sync_point_wait_list** is not NULL, the list of synchronization-points pointed to by **sync_point_wait_list** must be valid and **num_sync_points_in_wait_list** must be greater than 0. The synchronization-points specified in **sync_point_wait_list** are device-side synchronization-points. The command-buffer associated with synchronization-points in **sync_point_wait_list** must be the same as **command_buffer**. The memory associated with **sync_point_wait_list** can be reused or freed after the function returns.
- **sync_point** returns a synchronization-point ID that identifies this particular command. Synchronization-point objects are unique and can be used to identify this command later on. **sync_point** can be NULL in which case it will not be possible for the application to record a wait for this command to complete. If the **sync_point_wait_list** and the **sync_point** arguments are not NULL, the **sync_point** argument should not refer to an element of the **sync_point_wait_list** array.
- **mutable_handle** returns a handle to the command. This parameter is unused, and **must** be NULL.

**clCommandFillImageKHR** returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns the errors defined by clEnqueueFillImage except:
CL_INVALID_COMMAND_QUEUE is replaced with:

- **CL_INVALID_COMMAND_QUEUE** if the cl_khr_command_buffer_multi_device extension is not supported and command_queue is not NULL.
- **CL_INVALID_COMMAND_QUEUE** if the cl_khr_command_buffer_multi_device extension is supported; and either command_queue is NULL and command_buffer was created with more than one queue, or command_queue is not NULL and not a command-queue listed on command_buffer creation.

CL_INVALID_CONTEXT is replaced with:

- **CL_INVALID_CONTEXT** if the context associated with command_queue, command_buffer, and image are not the same.

CL_INVALID_EVENT_WAIT_LIST is replaced with:

- **CL_INVALID_SYNC_POINT_WAIT_LIST_KHR** if sync_point_wait_list is NULL and num_sync_points_in_wait_list is > 0, or sync_point_wait_list is not NULL and num_sync_points_in_wait_list is 0, or if synchronization-point objects in sync_point_wait_list are not valid synchronization-points.

New errors:

- **CL_INVALID_COMMAND_BUFFER_KHR** if command_buffer is not a valid command-buffer.
- **CL_INVALID_OPERATION** if command_buffer has been finalized.
- **CL_INVALID_VALUE** if mutable_handle is not NULL.

To record a command to execute a kernel on a device, call the function

```c
// Provided by cl_khr_command_buffer
cl_int clCommandNDRangeKernelKHR(
    cl_command_buffer_khr command_buffer,
    cl_command_queue command_queue,
    const cl_ndrange_kernel_command_properties_khr* properties,
    cl_kernel kernel,
    cl_uint work_dim,
    const size_t* global_work_offset,
    const size_t* global_work_size,
    const size_t* local_work_size,
    cl_uint num_sync_points_in_wait_list,
    const cl_sync_point_khr* sync_point_wait_list,
    cl_sync_point_khr* sync_point,
    cl_mutable_command_khr* mutable_handle);
```

- **clCommandNDRangeKernelKHR** is provided by the cl_khr_command_buffer extension.
- **command_buffer** refers to a valid command-buffer object.
- **command_queue** specifies the command-queue the command will be recorded to.
If the cl_khr_command_buffer_multi_device extension is not supported, only a single command-queue is supported, and command_queue must be NULL.

If the cl_khr_command_buffer_multi_device extension is supported and command_queue is NULL, then only one command-queue must have been set on command_buffer creation; otherwise, command_queue must not be NULL.

- **properties** specifies a list of properties for the kernel command and their corresponding values. Each property name is immediately followed by the corresponding desired value. The list is terminated with 0. If a supported property and its value is not specified in properties, its default value will be used. properties may be NULL, in which case the default values for supported properties will be used. The cl_khr_command_buffer extension does not define any properties, but supported properties defined by extensions are defined in the List of supported properties by clCommandNDRangeKernelKHR table.

- **kernel** is a valid kernel object which must have its arguments set. Any changes to kernel after calling clCommandNDRangeKernelKHR, such as with clSetKernelArg or clSetKernelExecInfo, have no effect on the recorded command. If kernel is recorded to a following clCommandNDRangeKernelKHR command however, then that command will capture the updated state of kernel.

- **work_dim**, **global_work_offset**, **global_work_size**, **local_work_size** Refer to clEnqueueNDRangeKernel.

- **sync_point_wait_list**, **num_sync_points_in_wait_list** specify synchronization-points that need to complete before this particular command can be executed.

  If sync_point_wait_list is NULL, num_sync_points_in_wait_list must be 0. If sync_point_wait_list is not NULL, the list of synchronization-points pointed to by sync_point_wait_list must be valid and num_sync_points_in_wait_list must be greater than 0. The synchronization-points specified in sync_point_wait_list are device-side synchronization-points. The command-buffer associated with synchronization-points in sync_point_wait_list must be the same as command_buffer. The memory associated with sync_point_wait_list can be reused or freed after the function returns.

- **sync_point** returns a synchronization-point ID that identifies this particular command. Synchronization-point objects are unique and can be used to identify this command later on. sync_point can be NULL in which case it will not be possible for the application to record a wait for this command to complete. If the sync_point_wait_list and the sync_point arguments are not NULL, the sync_point argument should not refer to an element of the sync_point_wait_list array.

- **mutable_handle** returns a handle to the command. If the cl_khr_command_buffer_mutable_dispatch extension is supported, and mutable_handle is not NULL, it can be used in the cl_mutable_dispatch_config_khr struct to update the command configuration between recordings. The lifetime of this handle is tied to the parent command-buffer, such that freeing the command-buffer will also free this handle.

Table 59. List of supported properties by clCommandNDRangeKernelKHR
<table>
<thead>
<tr>
<th>Recording Properties</th>
<th>Property Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>CL_MUTABLE_DISPATCH_ASSERTS_KHR</strong>&lt;br&gt;provided by the cl_khr_command_buffer_mutable_dispatch extension.</td>
<td><strong>cl_mutable_dispatch_asserts_khr</strong></td>
<td>This is a bitfield and can be set to a combination of the following values:&lt;br&gt;&lt;br&gt;<strong>CL_MUTABLE_DISPATCH_ASSERT_NO_ADDITIONAL_WORK_GROUPS_KHR</strong>&lt;br&gt;An assertion by the user that the number of work-groups of this ND-range kernel will not be updated beyond the number defined when the ND-range kernel was recorded. The number of work-groups is defined as the product for each $i$ from 0 to $work_dim - 1$ of $\text{ceil}(global_work_size[i]/local_work_size[i])$.</td>
</tr>
<tr>
<td>Recording Properties</td>
<td>Property Value</td>
<td>Description</td>
</tr>
<tr>
<td>----------------------</td>
<td>----------------</td>
<td>-------------</td>
</tr>
<tr>
<td>CL_MUTABLE_DISPATCH_UPDATABLE_FIELDS_KHR</td>
<td>cl_mutable_dispatch_fields_khr</td>
<td>This is a bitfield and can be set to a combination of the following values:</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_MUTABLE_DISPATCH_GLOBAL_OFFSET_KHR</strong> determines whether the global_work_offset of kernel execution can be modified after recording. If set, the global_work_offset of the kernel execution can be changed with <strong>clUpdateMutableCommandsKHR</strong> using the cl_mutable_dispatch_config_khr field of the mutable_config parameter. Otherwise, the global_work_offset cannot be modified.</td>
</tr>
<tr>
<td>provided by the cl_khr_command_buffer_mutable_dispatch extension.</td>
<td></td>
<td><strong>CL_MUTABLE_DISPATCH_GLOBAL_SIZE_KHR</strong> determines whether the global_work_size of kernel execution can be modified after recording. If set, the global_work_size of the kernel execution can be changed with <strong>clUpdateMutableCommandsKHR</strong> using the cl_mutable_dispatch_config_khr field of the mutable_config parameter. Otherwise, the global_work_size cannot be modified.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_MUTABLE_DISPATCH_LOCAL_SIZE_KHR</strong> determines whether the local_work_size of kernel execution can be modified after recording. If set, the local_work_size of the kernel execution can be changed with <strong>clUpdateMutableCommandsKHR</strong> using the cl_mutable_dispatch_config_khr field of the mutable_config parameter. Otherwise, the local_work_size cannot be modified.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_MUTABLE_DISPATCH_ARGUMENTS_KHR</strong> determines whether the kernel arguments set on kernel can be updated between executions. If set, the kernel arguments normally set with <strong>clSetKernelArg</strong> and <strong>clSetKernelArgSVMPointer</strong> can be changed with <strong>clUpdateMutableCommandsKHR</strong> using the cl_mutable_dispatch_config_khr field of the mutable_config parameter. Otherwise, the kernel arguments cannot be modified between executions.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_MUTABLE_DISPATCH_EXEC_INFO_KHR</strong> determines whether the information passed to kernel can be updated between executions. If set, the execution information of the kernel can be changed with <strong>clUpdateMutableCommandsKHR</strong> using the cl_mutable_dispatch_config_khr field of the mutable_config parameter. Otherwise, the kernel execution information cannot be modified.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>If CL_MUTABLE_DISPATCH_UPDATABLE_FIELDS_KHR is not specified then it defaults to the value returned by the CL_DEVICE_MUTABLE_DISPATCH_CAPABILITIES_KHR device query.</td>
</tr>
</tbody>
</table>
The work-group size to be used for \textit{kernel} can also be specified in the program source using the \texttt{__attribute__((reqd_work_group_size(X, Y, Z)))} qualifier. In this case the size of work-group specified by \texttt{local_work_size} must match the value specified by the \texttt{reqd_work_group_size __attribute__} qualifier.

These work-group instances are executed in parallel across multiple compute units or concurrently on the same compute unit.

Each work-item is uniquely identified by a global identifier. The global ID, which can be read inside the kernel, is computed using the value given by \texttt{global_work_size} and \texttt{global_work_offset}. In addition, a work-item is also identified within a work-group by a unique local ID. The local ID, which can also be read by the kernel, is computed using the value given by \texttt{local_work_size}. The starting local ID is always (0, 0, \ldots 0).

\texttt{clCommandNDRangeKernelKHR} returns \texttt{CL_SUCCESS} if the function is executed successfully. Otherwise, it returns the errors defined by \texttt{clEnqueueNDRangeKernel} except:

\texttt{CL_INVALID_COMMAND_QUEUE} is replaced with:

- \texttt{CL_INVALID_COMMAND_QUEUE} if the \texttt{cl_khr_command_buffer_multi_device} extension is not supported and \texttt{command_queue} is not \texttt{NULL}.
- \texttt{CL_INVALID_COMMAND_QUEUE} if the \texttt{cl_khr_command_buffer_multi_device} extension is supported; and either \texttt{command_queue} is \texttt{NULL} and \texttt{command_buffer} was created with more than one queue, or \texttt{command_queue} is not \texttt{NULL} and not a command-queue listed on \texttt{command_buffer} creation.

\texttt{CL_INVALID_CONTEXT} is replaced with:

- \texttt{CL_INVALID_CONTEXT} if the context associated with \texttt{command_queue}, \texttt{command_buffer}, and \texttt{kernel} are not the same.

\texttt{CL_INVALID_EVENT_WAIT_LIST} is replaced with:

- \texttt{CL_INVALID_SYNC_POINT_WAIT_LIST_KHR} if \texttt{sync_point_wait_list} is \texttt{NULL} and \texttt{num_sync_points_in_wait_list} is > 0, or \texttt{sync_point_wait_list} is not \texttt{NULL} and \texttt{num_sync_points_in_wait_list} is 0, or if synchronization-point objects in \texttt{sync_point_wait_list} are not valid synchronization-points.

New errors:

- \texttt{CL_INVALID_COMMAND_BUFFER_KHR} if \texttt{command_buffer} is not a valid command-buffer.
- \texttt{CL_INVALID_VALUE} if values specified in \texttt{properties} are not valid
- \texttt{CL_INVALID_OPERATION} if \texttt{command_buffer} has been finalized.
- \texttt{CL_INVALID_VALUE} if the \texttt{cl_khr_command_buffer_mutable_dispatch} extension is not supported and \texttt{mutable_handle} is not \texttt{NULL}.
- \texttt{CL_INVALID_OPERATION} if the device associated with \texttt{command_queue} does not support \texttt{CL_COMMAND_BUFFER_CAPABILITY_KERNEL_PRINTF_KHR} and \texttt{kernel} contains a printf call.
• CL_INVALID_OPERATION if the device associated with command_queue does not support CL_COMMAND_BUFFER_CAPABILITY_DEVICE_SIDE_ENQUEUE_KHR and kernel contains a kernel-enqueue call.

If the cl_khr_command_buffer_mutable_dispatch extension is supported:

• CL_INVALID_OPERATION if the requested CL_MUTABLE_DISPATCH_UPDATABLE_FIELDS_KHR properties are not reported by CL_DEVICE_MUTABLE_DISPATCH_CAPABILITIES_KHR for the device associated with command_queue. If command_queue is NULL, the device associated with command_buffer must report support for these properties.

• CL_INVALID_VALUE if command_buffer was created with the CL_COMMAND_BUFFER_MUTABLE_DISPATCH_ASSERTS_KHR property with CL_MUTABLE_DISPATCH_ASSERT_NO_ADDITIONAL_WORK_GROUPS_KHR and local_work_size is NULL, or if properties includes the CL_MUTABLE_DISPATCH_ASSERTS_KHR property with CL_MUTABLE_DISPATCH_ASSERT_NO_ADDITIONAL_WORK_GROUPS_KHR and local_work_size is NULL.

To record a command to do an SVM memcpy operation, call the function

```c
// Provided by CL_VERSION_2_0 with cl_khr_command_buffer
cl_int clCommandSVMMemcpyKHR(
    cl_command_buffer_khr command_buffer,
    cl_command_queue command_queue,
    void* dst_ptr,
    const void* src_ptr,
    size_t size,
    cl_uint num_sync_points_in_wait_list,
    const cl_sync_point_khr* sync_point_wait_list,
    cl_sync_point_khr* sync_point,
    cl_mutable_command_khr* mutable_handle);
```

clCommandSVMMemcpyKHR is provided by the cl_khr_command_buffer extension.

• command_buffer refers to a valid command-buffer object.

• command_queue specifies the command-queue the command will be recorded to.

If the cl_khr_command_buffer_multi_device extension is not supported, only a single command-queue is supported, and command_queue must be NULL.

If the cl_khr_command_buffer_multi_device extension is supported and command_queue is NULL, then only one command-queue must have been set on command_buffer creation; otherwise, command_queue must not be NULL.

• dst_ptr is the pointer to a host (if the device supports system SVM) or SVM memory allocation where data is copied to.

• src_ptr is the pointer to a host (if the device supports system SVM) or SVM memory allocation where data is copied from.

• size is the size in bytes of data being copied.

• sync_point_wait_list, num_sync_points_in_wait_list specify synchronization-points that need to complete before this particular command can be executed.

If sync_point_wait_list is NULL, num_sync_points_in_wait_list must be 0. If sync_point_wait_list is
not NULL, the list of synchronization-points pointed to by sync_point_wait_list must be valid and num_sync_points_in_wait_list must be greater than 0. The synchronization-points specified in sync_point_wait_list are device-side synchronization-points. The command-buffer associated with synchronization-points in sync_point_wait_list must be the same as command_buffer. The memory associated with sync_point_wait_list can be reused or freed after the function returns.

- **sync_point** returns a synchronization-point ID that identifies this particular command. Synchronization-point objects are unique and can be used to identify this command later on. sync_point can be NULL in which case it will not be possible for the application to record a wait for this command to complete. If the sync_point_wait_list and the sync_point arguments are not NULL, the sync_point argument should not refer to an element of the sync_point_wait_list array.

- **mutable_handle** returns a handle to the command. This parameter is unused, and must be NULL.

**clCommandSVMMemcpyKHR** returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns the errors defined by clEnqueueSVMMemcpy except:

**CL_INVALID_COMMAND_QUEUE** is replaced with:

- **CL_INVALID_COMMAND_QUEUE** if the cl_khr_command_buffer_multi_device extension is not supported and command_queue is not NULL.
- **CL_INVALID_COMMAND_QUEUE** if the cl_khr_command_buffer_multi_device extension is supported; and either command_queue is NULL and command_buffer was created with more than one queue, or command_queue is not NULL and not a command-queue listed on command_buffer creation.

**CL_INVALID_CONTEXT** is replaced with:

- **CL_INVALID_CONTEXT** if the context associated with command_queue, command_buffer, and kernel are not the same.

**CL_INVALID_EVENT_WAIT_LIST** is replaced with:

- **CL_INVALID_SYNC_POINT_WAIT_LIST_KHR** if sync_point_wait_list is NULL and num_sync_points_in_wait_list is > 0, or sync_point_wait_list is not NULL and num_sync_points_in_wait_list is 0, or if synchronization-point objects in sync_point_wait_list are not valid synchronization-points.

New errors:

- **CL_INVALID_COMMAND_BUFFER_KHR** if command_buffer is not a valid command-buffer.
- **CL_INVALID_OPERATION** if command_buffer has been finalized.
- **CL_INVALID_VALUE** if mutable_handle is not NULL.

To record a command to fill a region in SVM with a pattern of a given pattern size, call the function
cl_int clCommandSVMMemFillKHR(
    cl_command_buffer_khr command_buffer,
    cl_command_queue command_queue,
    void* svm_ptr,
    const void* pattern,
    size_t pattern_size,
    size_t size,
    cl_uint num_sync_points_in_wait_list,
    const cl_sync_point_khr* sync_point_wait_list,
    cl_sync_point_khr* sync_point,
    cl_mutable_command_khr* mutable_handle);

clCommandSVMMemFillKHR is provided by the cl_khr_command_buffer extension.

- **command_buffer** refers to a valid command-buffer object.

- **command_queue** specifies the command-queue the command will be recorded to.  
If the cl_khr_command_buffer_multi_device extension is not supported, only a single command-queue is supported, and **command_queue** must be NULL.  
If the cl_khr_command_buffer_multi_device extension is supported and **command_queue** is NULL, then only one command-queue must have been set on **command_buffer** creation; otherwise, **command_queue** must not be NULL.

- **svm_ptr** is a pointer to a (if the device supports system SVM) or SVM memory region that will be filled with **pattern**. It must be aligned to **pattern_size** bytes. If **svm_ptr** is allocated using **clSVMAlloc**, then it must be allocated from the same context from which **command_queue** was created. Otherwise the behavior is undefined.

- **pattern** is a pointer to the data pattern of size **pattern_size** in bytes. **pattern** will be used to fill a region in **buffer** starting at **svm_ptr** and is **size** bytes in size. The data pattern must be a scalar or vector integer or floating-point data type supported by OpenCL. For example, if the region pointed to by **svm_ptr** is to be filled with a pattern of **float4** values, then **pattern** will be a pointer to a **cl_float4** value and **pattern_size** will be sizeof(cl_float4). The maximum value of **pattern_size** is the size of the largest integer or floating-point vector data type supported by the OpenCL device. The memory associated with **pattern** can be reused or freed after the function returns.

- **size** is the size in bytes of region being filled starting with **svm_ptr** and must be a multiple of **pattern_size**.

- **sync_point_wait_list**, **num_sync_points_in_wait_list** specify synchronization-points that need to complete before this particular command can be executed.

If **sync_point_wait_list** is NULL, **num_sync_points_in_wait_list** must be 0. If **sync_point_wait_list** is not NULL, the list of synchronization-points pointed to by **sync_point_wait_list** must be valid and **num_sync_points_in_wait_list** must be greater than 0. The synchronization-points specified in **sync_point_wait_list** are device-side synchronization-points. The command-buffer associated with synchronization-points in **sync_point_wait_list** must be the same as **command_buffer**. The memory associated with **sync_point_wait_list** can be reused or freed after the function returns.
sync_point returns a synchronization-point ID that identifies this particular command. Synchronization-point objects are unique and can be used to identify this command later on. sync_point can be NULL in which case it will not be possible for the application to record a wait for this command to complete. If the sync_point_wait_list and the sync_point arguments are not NULL, the sync_point argument should not refer to an element of the sync_point_wait_list array.

mutable_handle returns a handle to the command. This parameter is unused, and must be NULL.

clCommandSVMMemFillKHR returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns the errors defined by clEnqueueSVMMemFill except:

CL_INVALID_COMMAND_QUEUE is replaced with:

- CL_INVALID_COMMAND_QUEUE if the cl_khr_command_buffer_multi_device extension is not supported and command_queue is not NULL.
- CL_INVALID_COMMAND_QUEUE if the cl_khr_command_buffer_multi_device extension is supported; and either command_queue is NULL and command_buffer was created with more than one queue, or command_queue is not NULL and not a command-queue listed on command_buffer creation.

CL_INVALID_CONTEXT is replaced with:

- CL_INVALID_CONTEXT if the context associated with command_queue, command_buffer, and kernel are not the same.

CL_INVALID_EVENT_WAIT_LIST is replaced with:

- CL_INVALID_SYNC_POINT_WAIT_LIST_KHR if sync_point_wait_list is NULL and num_sync_points_in_wait_list is > 0, or sync_point_wait_list is not NULL and num_sync_points_in_wait_list is 0, or if synchronization-point objects in sync_point_wait_list are not valid synchronization-points.

New errors:

- CL_INVALID_COMMAND_BUFFER_KHR if command_buffer is not a valid command-buffer.
- CL_INVALID_OPERATION if command_buffer has been finalized.
- CL_INVALID_VALUE if mutable_handle is not NULL.

5.17.6. Remapping Command-Buffers

If the cl_khr_command_buffer_multi_device extension is supported, platforms reporting the CL_COMMAND_BUFFER_PLATFORM_REMAP_QUEUES_KHR capability support generating a deep copy of a command-buffer with its commands remapped to a list of command-queues that are potentially incompatible with the queues used to create the command-buffer. That is, the remapped command-buffer can execute on queues that differ in terms of properties and/or associated device from the original command-buffer queues.

This functionality is invoked through a new synchronous entry-point clRemapCommandBufferKHR which takes a list of queues to which the commands should now target. It then returns a command-buffer containing the same commands as the original, with the same command dependencies, but targeting different queues. A list of command handles may also
be passed to the entry-point, which allows handles to the equivalent commands in the remapped command-buffer to be returned by an output parameter.

Device properties restrict remapping possibilities, as existing commands can have a configuration which is not supported by another device, and so remapping may fail with an error relating to this incompatibility. Examples of command configurations which can introduce incompatibilities when trying to map to a new device are:

- Program language features used in a kernel not supported by the new device.
- ND-Range configuration, e.g. exceeds new the device max work-group size.
- Misalignment of sub-buffers based on minimum alignment of new device.

In addition to this functionality, platforms reporting `CL_COMMAND_BUFFER_PLATFORM_AUTOMATIC_REMAP_KHR` allow the user to create a remapped command-buffer where the mapping of queues to commands is determined by the OpenCL runtime in a way it determines as optimal. This is particularly useful in hot plugging environments where devices may appear and disappear during runtime.

To create a deep copy of the input command-buffer with the copied commands remapped to target the passed command-queues, call the function

```c
// Provided by cl_khr_command_buffer_multi_device
cl_command_buffer_khr clRemapCommandBufferKHR(
    cl_command_buffer_khr command_buffer,
    cl_bool automatic,
    cl_uint num_queues,
    const cl_command_queue* queues,
    cl_uint num_handles,
    const cl.mutable_command_khr* handles,
    clmutable_command_khr* handles_ret,
    cl_int* errcode_ret);
```

- `command_buffer` specifies the command-buffer to create a remapped deep copy of.
- `automatic` indicates if the remapping is done explicitly by the user, or automatically by the OpenCL runtime. If `automatic` is `CL_FALSE`, then each element of `queues` will replace the queue used on `command_buffer` creation at the same index. If `CL_TRUE` and `CL_COMMAND_BUFFER_PLATFORM_AUTOMATIC_REMAP_KHR` is supported, then the OpenCL runtime will decide in a way it determines optimal which of the elements in `queues` each command in the returned command-buffer will be associated with.
- `num_queues` is the number of command-queues listed in `queues`, must not be 0.
- `queues` is a pointer to an ordered list of command-queues for the returned command-buffer to target, must be a non-`NULL` value.
- `num_handles` is the number of command handles passed in both `handles` and `handles_ret` lists,
 handles is an ordered list of handles belonging to command_buffer to create remapped copies of, may be NULL.

* handles_ret returns an ordered list of handles where each handle is equivalent to the handle at the same index in handles, but belonging to the returned command-buffer.

* errcode_ret returns an appropriate error code. If errcode_ret is NULL, no error code is returned.

The returned command-buffer has the same state as the input command-buffer, unless the input command-buffer is in the Pending state, in which case the returned command-buffer has state Executable.

clRemapCommandBufferKHR returns a valid command-buffer with errcode_ret set to CL_SUCCESS if the command-buffer is created successfully. Otherwise, it returns a NULL value without setting handles_ret, and with one of the following error values returned in errcode_ret:

* CL_INVALID_COMMAND_BUFFER_KHR if command_buffer is not a valid command-buffer.
* CL_INVALID_VALUE if num_queues is 0, or if queues is NULL.
* CL_INVALID_VALUE if automatic is CL_FALSE and num_queues is not equal to the number of queues used on creation of command_buffer.
* CL_INVALID_VALUE if handles or handles_ret is NULL and num_handles is > 0, or either handles or handles_ret is not NULL and num_handles is 0.
* CL_INVALID_VALUE if any handle in handles is not a valid command handle belonging to command_buffer.
* CL_INVALID_COMMAND_QUEUE if any command-queue in queues is not a valid command-queue.
* CL_INVALID_CONTEXT if command_buffer and all the command-queues in queues do not have the same OpenCL context.
* CL_INVALID_OPERATION if the platform does not support the CL_COMMAND_BUFFER_PLATFORM_REMAP_QUEUES_KHR flag.
* CL_INVALID_OPERATION if the platform does not support the CL_COMMAND_BUFFER_PLATFORM_AUTOMATIC_REMAP_KHR flag and automatic is CL_TRUE.
* CL_INCOMPATIBLE_COMMAND_QUEUE_KHR if such an error would be returned by passing queues to clCreateCommandBufferKHR.

Any error relating to device support that can be returned by a command recording entry-point may also be returned. As a command in command_buffer can have a configuration that is not supported by a device that is associated with the queue in queues the command is being remapped to.

* CL_OUT_OF_RESOURCES if there is a failure to allocate resources required by the OpenCL implementation on the device.
* CL_OUT_OF_HOST_MEMORY if there is a failure to allocate resources required by the OpenCL implementation on the host.
5.17.7. Mutable Commands:

A generic `cl_mutable_command_khr` handle is called a *mutable-command* object as it can be returned from any command recording entry-point in the `cl_khr_command_buffer` family of extensions. The mutable-command handles returned by `clCommandNDRangeKernelKHR` in particular are referred to as *mutable-dispatch* objects, and can be modified through the fields of `cl_mutable_dispatch_config_khr`.

Mutable-command handles are updated between enqueues using entry-point `clUpdateMutableCommandsKHR`. To enable performant usage, all aspects of mutation are encapsulated inside a single `cl_mutable_base_config_khr` parameter. This means that the runtime has access to all the information about how the command-buffer will change, allowing the command-buffer to be rebuilt as efficiently as possible. Any modifications to the arguments or execution info of a mutable-dispatch handle using `cl_mutable_dispatch_arg_khr` or `cl_mutable_dispatch_exec_info_khr` have no affect on the original kernel object used when the command was recorded, and only influence the `clCommandNDRangeKernelKHR` command associated with the mutable-dispatch.

The base `cl_khr_command_buffer` extension notes that a command-buffer does not update the reference count of objects set as arguments on kernels recorded into the command-buffer.

The implications for applications using `clUpdateMutableCommandsKHR` is that it is safe to delete objects used as kernel command arguments, if all the kernel commands using that object as an argument have had their arguments replaced with a different object.

To facilitate performant usage for pipelined work flows, where applications repeatedly call command-buffer update then enqueue, implementations may defer some of the work to allow `clUpdateMutableCommandsKHR` to return immediately. Deferring any recompilation until `clEnqueueCommandBufferKHR` avoids blocking in host code and keeps device occupancy high. This is only possible with a command-buffer created with the `CL_COMMAND_BUFFER_SIMULTANEOUS_USE_KHR` flag, as without this the enqueued command-buffer must complete before any modification occurs.

To modify the configuration of mutable-command handles returned during `command_buffer` recording, updating the behavior of those commands in future enqueues of `command_buffer`, call the function

```c
// Provided by cl_khr_command_buffer_mutable_dispatch
cl_int clUpdateMutableCommandsKHR(
    cl_command_buffer_khr command_buffer,
    const cl_mutable_base_config_khr* mutable_config);
```

`clUpdateMutableCommandsKHR` is provided by the `cl_khr_command_buffer_mutable_dispatch` extension.

* `command_buffer` refers to a valid command-buffer object.
• `mutable_config` is a pointer to a `cl_mutable_base_config_khr` structure defining updates to make
to mutable-commands.

`clUpdateMutableCommandsKHR` returns `CL_SUCCESS` if all the mutable-command objects were
updated successfully. Otherwise, none of the updates to mutable-command objects are preserved
and one of the errors below is returned:

• `CL_INVALID_COMMAND_BUFFER_KHR` if `command_buffer` is not a valid command-buffer.
• `CL_INVALID_OPERATION` if `command_buffer` has not been finalized.
• `CL_INVALID_OPERATION` if `command_buffer` was not created with the `CL_COMMAND_BUFFER_MUTABLE_KHR`
flag.
• `CL_INVALID_VALUE` if the `type` member of `mutable_config` is not `CL_STRUCTURE_TYPE_MUTABLE_BASE_ CONFIG_KHR`.
• `CL_INVALID_VALUE` if the `mutable_dispatch_list` member of `mutable_config` is `NULL` and
`num_mutable_dispatch` > 0, or `mutable_dispatch_list` is not `NULL` and `num_mutable_dispatch` is 0.
• `CL_INVALID_VALUE` if the `next` member of `mutable_config` is not `NULL` and any iteration of the
structure pointer chain does not contain valid `type` and `next` members.
• `CL_INVALID_VALUE` if `mutable_config` is `NULL`, or if both `next` and `mutable_dispatch_list`
members of `mutable_config` are `NULL`.
• `CL_OUT_OF_RESOURCES` if there is a failure to allocate resources required by the OpenCL
implementation on the device.
• `CL_OUT_OF_HOST_MEMORY` if there is a failure to allocate resources required by the OpenCL
implementation on the host.

Using this function when `command_buffer` is in the `pending` state and not created with the
`CL_COMMAND_BUFFER_SIMULTANEOUS_USE_KHR` flag causes undefined behavior.

Performant usage is to call `clUpdateMutableCommandsKHR` only when the
desired state of all commands is known, rather than iteratively updating each
command individually.

If the command buffer has been created with `CL_MUTABLE_DISPATCH_ASSERT_NO_ ADDITIONAL_WORK_GROUPS_KHR`, or the updated ND-range command has been recorded
with this flag, and the ND-range parameters are updated so that the new number
of work-groups exceeds the number when the ND-range command was recorded,
the behavior is undefined.

If the `mutable_dispatch_list` member of `mutable_config` is non-`NULL`, then errors defined by
`clEnqueueNDRangeKernel`, `clSetKernelExecInfo`, `clSetKernelArg`, and
`clSetKernelArgSVMPointer` are returned by `clUpdateMutableCommandsKHR` if any of the array
elements are set to an invalid value. Additionally, the following errors are returned if any `cl_mutable_dispatch_config_khr` element of the array violates the defined conditions:

• `CL_INVALID_MUTABLE_COMMAND_KHR` if `command` is not a valid mutable command object, or created
from `command_buffer`.

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• **CL_INVALID_VALUE** if `type` is not `CL_STRUCTURE_TYPE_MUTABLE_DISPATCH_CONFIG_KHR`.

• **CL_INVALID_OPERATION** if the values of `local_work_size` and/or `global_work_size` result in a change to work-group uniformity.

• **CL_INVALID_OPERATION** if the `work_dim` is different from the `work_dim` set on command recording.

• **CL_INVALID_OPERATION** if the `CL_MUTABLE_DISPATCH_GLOBAL_OFFSET_KHR` property was not set on command recording and `global_work_offset` is not NULL.

• **CL_INVALID_OPERATION** if the `CL_MUTABLE_DISPATCH_GLOBAL_SIZE_KHR` property was not set on command recording and `global_work_size` is not NULL.

• **CL_INVALID_OPERATION** if the `CL_MUTABLE_DISPATCH_LOCAL_SIZE_KHR` property was not set on command recording and `local_work_size` is not NULL.

• **CL_INVALID_OPERATION** if the `CL_MUTABLE_DISPATCH_ARGUMENTS_KHR` property was not set on command recording and `num_args` or `num_svm_args` is non-zero.

• **CL_INVALID_OPERATION** if the `CL_MUTABLE_DISPATCH_EXEC_INFO_KHR` property was not set on command recording and `num_exec_infos` is non-zero.

• **CL_INVALID_VALUE** if `arg_list` is NULL and `num_args` > 0, or `arg_list` is not NULL and `num_args` is 0.

• **CL_INVALID_VALUE** if `arg_svm_list` is NULL and `num_svm_args` > 0, or `arg_svm_list` is not NULL and `num_svm_args` is 0.

• **CL_INVALID_VALUE** if `exec_info_list` is NULL and `num_exec_infos` > 0, or `exec_info_list` is not NULL and `num_exec_infos` is 0.

The `cl_mutable_base_config_khr` structure encapsulates all aspects of mutation and is defined as:

```c
// Provided by cl_khr_command_buffer_mutable_dispatch
typedef struct cl_mutable_base_config_khr {
    cl_command_buffer_structure_type_khr type;
    const void* next;
    cl_uint num_mutable_dispatch;
    const cl_mutable_dispatch_config_khr* mutable_dispatch_list;
} cl_mutable_base_config_khr;
```

• `type` is the type of this structure, and must be **CL_STRUCTURE_TYPE_MUTABLE_BASE_CONFIG_KHR**

• `next` is **NULL** or a pointer to an extending structure.

• `num_mutable_dispatch` is the number of mutable-dispatch objects to configure in this enqueue of the command-buffer.

• `mutable_dispatch_list` is an array containing `num_mutable_dispatch` elements describing the configurations of mutable kernel execution commands in the command-buffer. For a description of struct members making up each array element see `cl_mutable_dispatch_config_khr`.

The `cl_mutable_dispatch_arg_khr` structure is passed to `clUpdateMutableCommandsKHR` to set the kernel configuration of a mutable `clCommandNDRangeKernelKHR` command, and is defined as:
// Provided by cl_khr_command_buffer_mutable_dispatch
typedef struct cl_mutable_dispatch_config_khr {
    cl_command_buffer_structure_type_khr type;
    const void* next;
    cl_mutable_command_khr command;
    cl_uint num_args;
    cl_uint num_svm_args;
    cl_uint num_exec_infos;
    cl_uint work_dim;
    const cl_mutable_dispatch_arg_khr* arg_list;
    const cl_mutable_dispatch_arg_khr* arg_svm_list;
    const cl_mutable_dispatch_exec_info_khr* exec_info_list;
    const size_t* global_work_offset;
    const size_t* global_work_size;
    const size_t* local_work_size;
} cl_mutable_dispatch_config_khr;

• type is the type of this structure, and must be CL_STRUCTURE_TYPE_MUTABLE_DISPATCH_CONFIG_KHR.
• next is NULL or a pointer to an extending structure.
• command is a mutable-command object returned by clCommandNDRangeKernelKHR representing a kernel execution as part of a command-buffer.
• num_args is the number of kernel arguments being changed.
• num_svm_args is the number of SVM kernel arguments being changed.
• num_exec_infos is the number of kernel execution info objects to set for this dispatch.
• work_dim is the number of dimensions used to specify the global work-items and work-items in the work-group. See clEnqueueNDRangeKernel for valid usage.
• arg_list is an array describing the new kernel arguments for this enqueque. It must contain num_args array elements, each of which encapsulates parameters passed to clSetKernelArg. See clSetKernelArg for usage of cl_mutable_dispatch_arg_khr members.
• arg_svm_list is an array describing the new SVM kernel arguments for this enqueue. It must contain num_svm_args array elements, each of which encapsulates parameters passed to clSetKernelArgSVMPointer. See clSetKernelArgSVMPointer for usage of cl_mutable_dispatch_arg_khr members, arg_size is ignored.
• exec_info_list is an array containing num_exec_infos elements specifying the list of execution info objects use for this command-buffer enqueue. See clSetKernelExecInfo for usage of cl_mutable_dispatch_exec_info_khr members.
• global_work_offset can be used to specify an array of work_dim unsigned values that describe the offset used to calculate the global ID of a work-item. If global_work_offset is NULL then the global offset of the dispatch is not changed. See clEnqueueNDRangeKernel for valid usage.
• global_work_size points to an array of work_dim unsigned values that describe the number of global work-items in work_dim dimensions that will execute the kernel function. If global_work_size is NULL then the number of global work-items in the dispatch is not changed. See clEnqueueNDRangeKernel for valid usage.
• `local_work_size` points to an array of `work_dim` unsigned values that describe the number of work-items that make up a work-group that will execute the kernel. If `local_work_size` is `NULL` then the number of local work-items in the dispatch is not changed. See `clEnqueueNDRangeKernel` for valid usage.

The `cl_mutable_dispatch_arg_khr` structure sets kernel arguments normally passed using `clSetKernelArg` and `clSetKernelArgSVMPointer`, and is defined as:

```c
// Provided by cl_khr_command_buffer_mutable_dispatch
typedef struct cl_mutable_dispatch_arg_khr {
    cl_uint arg_index;
    size_t arg_size;
    const void* arg_value;
} cl_mutable_dispatch_arg_khr;
```

The `cl_mutable_dispatch_exec_info_khr` structure sets kernel execution info normally passed using `clSetKernelExecInfo`, and is defined as:

```c
// Provided by cl_khr_command_buffer_mutable_dispatch
typedef struct cl_mutable_dispatch_exec_info_khr {
    cl_uint param_name;
    size_t param_value_size;
    const void* param_value;
} cl_mutable_dispatch_exec_info_khr;
```

`param_name` is of type `cl_uint` rather than `cl_kernel_exec_info` so that the extension can be implemented on OpenCL 1.2 where the `cl_kernel_exec_info` typedef is unavailable.

### 5.17.8. Command-Buffer Queries

To query information about a command-buffer, call the function

```c
// Provided by cl_khr_command_buffer
cl_int clGetCommandBufferInfoKHR(
    cl_command_buffer_khr command_buffer,
    cl_command_buffer_info_khr param_name,
    size_t param_value_size,
    void* param_value,
    size_t* param_value_size_ret);
```

`clGetCommandBufferInfoKHR` is provided by the `cl_khr_command_buffer` extension.

• `command_buffer` specifies the command-buffer being queried.
• `param_name` specifies the information to query.

• `param_value_size` specifies the size in bytes of memory pointed to by `param_value`. This size must be ≥ size of return type as described in the table below. If `param_value` is NULL, it is ignored.

• `param_value` is a pointer to a memory location where the appropriate result being queried is returned. If `param_value` is NULL, it is ignored.

• `param_value_size_ret` returns the actual size in bytes of data being queried by `param_value`. If `param_value_size_ret` is NULL, it is ignored.

The list of supported `param_name` values and the information returned in `param_value` by `clGetCommandBufferInfoKHR` is described in the table below.

Table 60. `clGetCommandBufferInfoKHR` values

<table>
<thead>
<tr>
<th>Command Buffer Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>CL_COMMAND_BUFFER_NUM_QUEUES_KHR</code></td>
<td><code>cl_uint</code></td>
<td>The number of command-queues specified when <code>command_buffer</code> was created.</td>
</tr>
<tr>
<td>provided by the <code>cl_khr_command_buffer</code> extension.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><code>CL_COMMAND_BUFFER_QUEUES_KHR</code></td>
<td><code>cl_command_queue[]</code></td>
<td>Return the list of command-queues specified when the <code>command_buffer</code> was created.</td>
</tr>
<tr>
<td>provided by the <code>cl_khr_command_buffer</code> extension.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><code>CL_COMMAND_BUFFER_REFERENCE_COUNT_KHR</code> [139]</td>
<td><code>cl_uint</code></td>
<td>Return the <code>command_buffer</code> reference count.</td>
</tr>
<tr>
<td>provided by the <code>cl_khr_command_buffer</code> extension.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Command Buffer Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>----------------------------------------------------------</td>
<td>------------------------------------</td>
<td>---------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td><strong>CL_COMMAND_BUFFER_STATE_KHR</strong></td>
<td>cl_command_buffer_state_khr</td>
<td>Return the state of command_buffer.</td>
</tr>
<tr>
<td>provided by the cl_khr_command_buffer extension.</td>
<td></td>
<td><strong>CL_COMMAND_BUFFER_STATE_RECORDING_KHR</strong> is returned when command_buffer has not been finalized.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_command_buffer extension.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_COMMAND_BUFFER_STATE_EXECUTABLE_KHR</strong> is returned when command_buffer has been finalized and there is not a Pending instance of command_buffer awaiting completion on a command_queue.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_command_buffer extension.</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>CL_COMMAND_BUFFER_STATE_PENDING_KHR</strong> is returned when an instance of command_buffer has been enqueued for execution but not yet completed.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>provided by the cl_khr_command_buffer extension.</td>
</tr>
<tr>
<td>Command Buffer Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>---------------------</td>
<td>-------------</td>
<td>-------------</td>
</tr>
<tr>
<td>CL_COMMAND_BUFFER_PROPERTIES_ ARRAY_KHR</td>
<td>cl_command_buffer_properties_khr[]</td>
<td>Return the <code>properties</code> argument specified in <code>clCreateCommandBufferKHR</code>. If the <code>properties</code> argument specified in <code>clCreateCommandBufferKHR</code> used to create <code>command_buffer</code> was not <code>NULL</code>, the implementation must return the values specified in the <code>properties</code> argument. If the <code>properties</code> argument specified in <code>clCreateCommandBufferKHR</code> used to create <code>command_buffer</code> was <code>NULL</code>, the implementation may return either a <code>param_value_size_ret</code> of 0 (i.e. there is are no properties to be returned), or the implementation may return a property value of 0 (where 0 is used to terminate the properties list).</td>
</tr>
<tr>
<td>CL_COMMAND_BUFFER_CONTEXT_KHR</td>
<td>cl_context</td>
<td>Return the context associated with <code>command_buffer</code>.</td>
</tr>
</tbody>
</table>

`clGetCommandBufferInfoKHR` returns `CL_SUCCESS` if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_COMMAND_BUFFER_KHR** if `command_buffer` is not a valid command-buffer.
- **CL_INVALID_VALUE** if `param_name` is not one of the supported values or if size in bytes specified by `param_value_size` is less than size of return type and `param_value` is not a `NULL` value.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

To query information about a mutable command object, call the function
clGetMutableCommandInfoKHR is provided by the cl_khr_command_buffer_mutable_dispatch extension.

- **command** specifies the mutable-command object being queried.
- **param_name** specifies the information to query. The list of supported **param_name** types and the information returned in **param_value** by clGetMutableCommandInfoKHR is described in the Mutable Command Object Queries table.
- **param_value_size** is used to specify the size in bytes of memory pointed to by **param_value**. This size must be \( \geq \) size of return type as described in the Mutable Command Object Queries table.
- **param_value** is a pointer to memory where the appropriate result being queried is returned. If **param_value** is NULL, it is ignored.
- **param_value_size_ret** returns the actual size in bytes of data being queried by **param_name**. If **param_value_size_ret** is NULL, it is ignored.

Table 61. Mutable Command Object Queries

<table>
<thead>
<tr>
<th>Mutable Command Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_MUTABLE_COMMAND_COMMAND_QUEUE_KHR</td>
<td>cl_command_queue</td>
<td>Return the command-queue associated with <strong>command</strong>. If NULL was passed as the queue when <strong>command</strong> was recorded, then the queue associated with the command-buffer that <strong>command</strong> belongs to is returned.</td>
</tr>
<tr>
<td>CL_MUTABLE_COMMAND_COMMAND_BUFFER_KHR</td>
<td>cl_command_buffer_khr</td>
<td>Return the command-buffer associated with <strong>command</strong>.</td>
</tr>
<tr>
<td>CL_MUTABLE_COMMAND_COMMAND_TYPE_KHR</td>
<td>cl_command_type</td>
<td>Return the command-type associated with <strong>command</strong>. The list of supported event command types defined by clGetEventInfo is used with the matching command.</td>
</tr>
<tr>
<td><strong>Mutable Command Info</strong></td>
<td><strong>Return Type</strong></td>
<td><strong>Description</strong></td>
</tr>
<tr>
<td>--------------------------</td>
<td>----------------</td>
<td>-----------------</td>
</tr>
<tr>
<td>CL_MUTABLE_DISPATCH_</td>
<td>cl_ndrange_</td>
<td>Return the properties argument specified on command recording with clCommandNDRangeKernelKHR.</td>
</tr>
<tr>
<td>PROPERTIES_ARRAY_KHR</td>
<td>kernel_command_</td>
<td>If the properties argument specified on creation of command was not NULL, the implementation must return the values specified in the properties argument in the same order and without including additional properties.</td>
</tr>
<tr>
<td>provided by the</td>
<td>properties_</td>
<td></td>
</tr>
<tr>
<td>cl_khr_command_buffer_mutable_dispatch extension.</td>
<td>khr[]</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_MUTABLE_DISPATCH_KERNEL_KHR</td>
<td>cl_kernel</td>
<td>Return the kernel associated with command when recorded with clCommandNDRangeKernelKHR.</td>
</tr>
<tr>
<td>provided by the</td>
<td></td>
<td>If command was not recorded from a clCommandNDRangeKernelKHR command, the implementation must return param_value_size_ret equal to 0, indicating that there are no properties to be returned.</td>
</tr>
<tr>
<td>cl_khr_command_buffer_mutable_dispatch extension.</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CL_MUTABLE_DISPATCH_DIMENSIONS_KHR</td>
<td>cl_uint</td>
<td>Return the number of work-item dimensions specified when command was created.</td>
</tr>
<tr>
<td>provided by the</td>
<td></td>
<td>If command was not recorded from a clCommandNDRangeKernelKHR command, the implementation must return param_value_size_ret equal to 0, indicating that the value returned in param_value is not valid.</td>
</tr>
<tr>
<td>cl_khr_command_buffer_mutable_dispatch extension.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Mutable Command Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>----------------------</td>
<td>-------------</td>
<td>-------------</td>
</tr>
<tr>
<td>CL_MUTABLE_DISPATCH_GLOBAL_WORK_OFFSET_KHR</td>
<td>size_t[]</td>
<td>Return the global work-item offset set on command creation, or from the most recent update via <code>clUpdateMutableCommandsKHR</code> where this value was modified. The output array contains <code>work_dim</code> values, where <code>work_dim</code> is returned by the query <code>CL_MUTABLE_DISPATCH_DIMENSIONS_KHR</code>. If a global work-item offset was not set, zero is returned for each element in the array. If command was not recorded from a <code>clCommandNDRangeKernelKHR</code> command, the implementation must return <code>param_value_size_ret</code> equal to 0, indicating that the value returned in <code>param_value</code> is not valid.</td>
</tr>
<tr>
<td>CL_MUTABLE_DISPATCH_GLOBAL_WORK_SIZE_KHR</td>
<td>size_t[]</td>
<td>Return the global work-item size set on command creation, or from the most recent update via <code>clUpdateMutableCommandsKHR</code> where this value was modified. The output array contains <code>work_dim</code> values, where <code>work_dim</code> is returned by the query <code>CL_MUTABLE_DISPATCH_DIMENSIONS_KHR</code>. If a global work-item size was not set, zero is returned for each element in the array. If command was not recorded from a <code>clCommandNDRangeKernelKHR</code> command, the implementation must return <code>param_value_size_ret</code> equal to 0, indicating that the value returned in <code>param_value</code> is not valid.</td>
</tr>
<tr>
<td>CL_MUTABLE_DISPATCH_LOCAL_WORK_SIZE_KHR</td>
<td>size_t[]</td>
<td>Return the local work-item size set on command creation, or from the most recent update via <code>clUpdateMutableCommandsKHR</code> where this value was modified. The output array contains <code>work_dim</code> values, where <code>work_dim</code> is returned by the query <code>CL_MUTABLE_DISPATCH_DIMENSIONS_KHR</code>. If a local work-item size was not set, zero is returned for each element in the array. If command was not recorded from a <code>clCommandNDRangeKernelKHR</code> command, the implementation must return <code>param_value_size_ret</code> equal to 0, indicating that the value returned in <code>param_value</code> is not valid.</td>
</tr>
</tbody>
</table>
clGetMutableCommandInfoKHR returns CL_SUCCESS if the function is executed successfully. Otherwise, it returns one of the following errors:

- **CL_INVALID_VALUE** if param_name is not valid, or if size in bytes specified by param_value_size is < size of return type as described in the Mutable Command Object Queries table and param_value is not NULL.
- **CL_INVALID_MUTABLE_COMMAND_KHR** if command is not a valid mutable command object.
- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device.
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

### 5.18. Querying Devices That Support Sharing With OpenGL

OpenCL device(s) corresponding to an OpenGL context may be queried. Such a device may not always exist (for example, if an OpenGL context is specified on a GPU not supporting OpenCL command-queues, but which does support shared OpenCL/OpenGL memory objects), and if it does exist, may change over time. When such a device does exist, acquiring and releasing shared OpenCL/OpenGL memory objects may be faster on a command-queue corresponding to this device than on command-queues corresponding to other devices available to an OpenCL context.

To query the OpenCL device corresponding to an OpenGL context, call the function

```c
// Provided by cl_khr_gl_sharing
cl_int clGetGLContextInfoKHR(
    const cl_context_properties* properties,
    cl_gl_context_info param_name,
    size_t param_value_size,
    void* param_value,
    size_t* param_value_size_ret);
```

- **properties** points to an property list whose format and valid contents are identical to the properties argument of clCreateContext. properties must identify a single valid GL context or GL share group object.
- **param_name** is a constant that specifies the device types to query, and must be one of the values shown in the Supported Device Types table below.
- **param_value** is a pointer to memory where the result of the query is returned, as described in the Supported Device Types table. If param_value is NULL, it is ignored.
- **param_value_size** specifies the size in bytes of memory pointed to by param_value. This size must be greater than or equal to the size of the return type described in the table below.
- **param_value_size_ret** returns the actual size in bytes of data being queried by param_value. If param_value_size_ret is NULL, it is ignored.
Table 62. Supported Device Types for clGetGLContextInfoKHR

<table>
<thead>
<tr>
<th>param_name</th>
<th>Return Type</th>
<th>Information returned in param_value</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_CURRENT_DEVICE_FOR_GL_CONTEXT_KHR provided by the cl_khr_gl_sharing extension.</td>
<td>cl_device_id</td>
<td>Return the OpenCL device currently associated with the specified OpenGL context.</td>
</tr>
<tr>
<td>CL_DEVICES_FOR_GL_CONTEXT_KHR provided by the cl_khr_gl_sharing extension.</td>
<td>cl_device_id[]</td>
<td>Return all OpenCL devices which may be associated with the specified OpenGL context.</td>
</tr>
</tbody>
</table>

clGetGLContextInfoKHR returns CL_SUCCESS if the function is executed successfully. If no device(s) exist corresponding to param_name, the call will not fail, but the value of param_value_size_ret will be zero. Otherwise, it returns one of the following errors:

- **CL_INVALID_GL_SHAREGROUP_REFERENCE_KHR** if a context was specified for an OpenGL or OpenGL ES implementation using the EGL, GLX, or WGL binding APIs, as described for clCreateContext; and any of the following conditions hold:
  - The specified display and context properties do not identify a valid OpenGL or OpenGL ES context.
  - The specified context does not support buffer and renderbuffer objects.
  - The specified context is not compatible with the OpenCL context being created (for example, it exists in a physically distinct address space, such as another hardware device; or it does not support sharing data with OpenCL due to implementation restrictions).

- **CL_INVALID_GL_SHAREGROUP_REFERENCE_KHR** if a share group was specified for a CGL-based OpenGL implementation by setting the property CL_CGL_SHAREGROUP_KHR, and the specified share group does not identify a valid CGL share group object.

- **CL_INVALID_OPERATION** if a context was specified as described above and any of the following conditions hold:
  - A context or share group object was specified for one of CGL, EGL, GLX, or WGL and the OpenGL implementation does not support that window-system binding API.
  - More than one of the properties CL_CGL_SHAREGROUP_KHR, CL_EGL_DISPLAY_KHR, CL_GLX_DISPLAY_KHR, and CL_WGL_HDC_KHR is set to a non-default value.
  - Both of the properties CL_CGL_SHAREGROUP_KHR and CL_GL_CONTEXT_KHR are set to non-default values.
  - Any of the devices specified in the <devices> argument cannot support OpenCL objects which share the data store of an OpenGL object.

- **CL_INVALID_VALUE** if an property name other than those specified in table 4.5 is specified in properties.

- **CL_INVALID_VALUE** if param_name is not one of the values listed in the GL context information that can be queried with clGetGLContextInfoKHR table, or if the size in bytes specified by param_value_size is less than the size of the return type shown in the table and param_value is
not a NULL value

- **CL_OUT_OF_RESOURCES** if there is a failure to allocate resources required by the OpenCL implementation on the device
- **CL_OUT_OF_HOST_MEMORY** if there is a failure to allocate resources required by the OpenCL implementation on the host.

[1] Only out-of-order device queues are supported.

[2] The application must create a default device queue if any kernels containing calls to `get_default_queue` are enqueued. There can only be one default device queue for each device within a context. If a default device queue has already been created, calling `clCreateCommandQueueWithProperties` with `CL_QUEUE_PROPERTIES` set to `CL_QUEUE_ON_DEVICE` and `CL_QUEUE_ON_DEVICE_DEFAULT` will return the default device queue that has already been created and increment its reference count by 1.

[3] The reference count returned should be considered immediately stale. It is unsuitable for general use in applications. This feature is provided for identifying memory leaks.

[4] Note that reading and writing 2D image arrays from a kernel with `image_array_size` equal to one may perform worse than 2D images.

[5] To create a 2D image from a buffer object that share the data store between the image and buffer object.

[6] To create an image object from another image object that share the data store between these image objects.

[7] Support for the `CLDEPTH` image channel order is required only for 2D images and 2D image arrays.

[8] Support for reading from the `CL_SRGB` image channel order is optional for 1D image buffers. Support for writing to the `CL_SRGB` image channel order is optional for all image types.

[9] The map count returned should be considered immediately stale. It is unsuitable for general use in applications. This feature is provided for debugging.

[10] The reference count returned should be considered immediately stale. It is unsuitable for general use in applications. This feature is provided for identifying memory leaks.

[11] The reference count returned should be considered immediately stale. It is unsuitable for general use in applications. This feature is provided for identifying memory leaks.

[12] As per the definition of `-cl-denorms-are-zero`, the inclusion of this option with `-cl-unsafe-math-optimizations` means that the implementation may flush denormal numbers to zero but is not required to.

[13] The reference count returned should be considered immediately stale. It is unsuitable for general use in applications. This feature is provided for identifying memory leaks.

[14] Implementations are encouraged to favor this option as it makes it more likely that errors will be managed by applications.

[15] The reference count returned should be considered immediately stale. It is unsuitable for general use in applications. This feature is provided for identifying memory leaks.

[16] The error code values are negative, and event state values are positive. The event state values are ordered from the largest value `CL_QUEUED` for the first or initial state to the smallest value (`CL_COMPLETE` or negative integer value) for the last or complete state. The value of `CL_COMPLETE` and `CL_SUCCESS` are the same.

[17] The reference count returned should be considered immediately stale. It is unsuitable for general use in applications. This feature is provided for identifying memory leaks.

[18] The reference count returned should be considered immediately stale. It is unsuitable for general use in applications. This feature is provided for identifying memory leaks.

[19] The reference count returned should be considered immediately stale. It is unsuitable for general use in applications. This feature is provided for identifying memory leaks.
Chapter 6. Associated OpenCL specification

6.1. SPIR-V Intermediate Language

OpenCL 2.1 and 2.2 require support for the SPIR-V intermediate language that allows offline compilation to a binary format that may be consumed by the `clCreateProgramWithIL` interface.

The OpenCL specification includes a specification for the SPIR-V intermediate language as a cross-platform input language. In addition, platform vendors may support their own IL if this is appropriate. The OpenCL runtime will return a list of supported IL versions using the `CL_DEVICE_IL_VERSION` or `CL_DEVICE_ILS_WITH_VERSION` parameter to the `clGetDeviceInfo` query.

6.2. Extensions to OpenCL

In addition to the specification of core features, OpenCL provides a number of extensions to the API, kernel language or intermediate representation. These features are defined in the OpenCL extension specification document.

Extensions defined against earlier versions of the OpenCL specifications, whether the API or language specification, are defined in the matching versions of the extension specification document.

6.3. The OpenCL C Kernel Language

The OpenCL C kernel language is not defined in the OpenCL unified specification. The OpenCL C kernel languages are instead defined in the OpenCL 1.0, OpenCL 1.1, OpenCL 1.2, OpenCL C 2.0 Kernel Language, and OpenCL C 3.0 Kernel Language specifications. When OpenCL devices support one or more versions of the OpenCL C kernel language (see `CL_DEVICE_OPENCL_C_VERSION` and `CL_DEVICE_OPENCL_C_ALL_VERSIONS`), OpenCL program objects may be created by passing OpenCL C source strings to `clCreateProgramWithSource`.
Chapter 7. OpenCL Embedded Profile

The OpenCL specification describes the feature requirements for desktop platforms. This section describes the OpenCL embedded profile that allows us to target a subset of the OpenCL specification for handheld and embedded platforms. The optional extensions defined in the OpenCL Extension Specification apply to both profiles.

The OpenCL embedded profile has the following restrictions until version 2.0 (i.e. the optionality described below was deprecated by version 2.0):

1. Support for 3D images is optional.

   If `CL_DEVICE_IMAGE3D_MAX_WIDTH`, `CL_DEVICE_IMAGE3D_MAX_HEIGHT` and `CL_DEVICE_IMAGE3D_MAX_DEPTH` are zero, calls to `clCreateImage` or `clCreateImageWithProperties` will fail to create the 3D image, and the `errcode_ret` argument will return `CL_INVALID_OPERATION`. Declaring arguments of type `image3d_t` in a kernel will result in a compilation error.

   If `CL_DEVICE_IMAGE3D_MAX_WIDTH`, `CL_DEVICE_IMAGE3D_MAX_HEIGHT` and `CL_DEVICE_IMAGE3D_MAX_DEPTH` are greater than zero 0, calls to `clCreateImage` and `clCreateImageWithProperties` will behave as described for full profile implementations, and the `image3d_t` data type can be used in a kernel.

2. Support for 2D image array writes is optional. If the `cles_khr_2d_image_array_writes` extension is supported by the embedded profile, writes to 2D image arrays are supported.

3. Image and image arrays created with an `image_channel_data_type` value of `CL_FLOAT` or `CL_HALF_FLOAT` can only be used with samplers that use a filter mode of `CL_FILTER_NEAREST`. The values returned by `read_imagef`\(^1\) for 2D and 3D images if `image_channel_data_type` value is `CL_FLOAT` or `CL_HALF_FLOAT` and sampler with filter_mode = `CL_FILTER_LINEAR` are undefined.

Furthermore, the OpenCL embedded profile has the following restrictions for all versions:

1. 64 bit integers i.e. long, ulong including the appropriate vector data types and operations on 64-bit integers are optional. The `cles_khr_int64`\(^2\) extension string will be reported if the embedded profile implementation supports 64-bit integers. If double precision is supported i.e. `CL_DEVICE_DOUBLE_FP_CONFIG` is not zero, then `cles_khr_int64` must also be supported.

2. The mandated minimum single precision floating-point capability given by `CL_DEVICE_SINGLE_FP_CONFIG` is `CL_FP_ROUND_TO_ZERO` or `CL_FP_ROUND_TO_NEAREST`. If `CL_FP_ROUND_TO_NEAREST` is supported, the default rounding mode will be round to nearest even; otherwise the default rounding mode will be round to zero.

3. The single precision floating-point operations (addition, subtraction and multiplication) shall be correctly rounded. Zero results may always be positive 0.0. The accuracy of division and sqrt are given in the OpenCL C and OpenCL SPIR-V Environment specifications.

   If `CL_FP_INF_NAN` is not set in `CL_DEVICE_SINGLE_FP_CONFIG`, and one of the operands or the result of addition, subtraction, multiplication or division would signal the overflow or invalid exception (see IEEE 754 specification), the value of the result is implementation-defined. Likewise, single precision comparison operators (<, >, <=, >=, ==, !) return implementation-defined values when one or more operands is a NaN.
In all cases, conversions (see the OpenCL C and OpenCL SPIR-V Environment specifications) shall be correctly rounded as described for the FULL_PROFILE, including those that consume or produce an INF or NaN. The built-in math functions shall behave as described for the FULL_PROFILE, including edge case behavior, but with slightly different accuracy rules. Edge case behavior and accuracy rules are described in the OpenCL C and OpenCL SPIR-V Environment specifications.

If addition, subtraction and multiplication have default round to zero rounding mode, then \texttt{fract}, \texttt{fma} and \texttt{fdim} shall produce the correctly rounded result for round to zero rounding mode.

This relaxation of the requirement to adhere to IEEE 754 requirements for basic floating-point operations, though extremely undesirable, is to provide flexibility for embedded devices that have lot stricter requirements on hardware area budgets.

4. Denormalized numbers for the half data type which may be generated when converting a float to a half using variants of the \texttt{vstore\_half} function or when converting from a half to a float using variants of the \texttt{vload\_half} function can be flushed to zero. The OpenCL SPIR-V Environment Specification for details.

5. The precision of conversions from \texttt{CL\_UNORM\_INT8}, \texttt{CL\_SNORM\_INT8}, \texttt{CL\_UNORM\_INT16}, \texttt{CL\_SNORM\_INT16}, \texttt{CL\_UNORM\_INT\_101010}, and \texttt{CL\_UNORM\_INT\_101010\_2} to float is $\leq 2$ ulp for the embedded profile instead of $\leq 1.5$ ulp as defined in the full profile. The exception cases described in the full profile and given below apply to the embedded profile.

For \texttt{CL\_UNORM\_INT8}

- 0 must convert to 0.0f and
- 255 must convert to 1.0f

For \texttt{CL\_UNORM\_INT16}

- 0 must convert to 0.0f and
- 65535 must convert to 1.0f

For \texttt{CL\_SNORM\_INT8}

- -128 and -127 must convert to -1.0f,
- 0 must convert to 0.0f and
- 127 must convert to 1.0f

For \texttt{CL\_SNORM\_INT16}

- -32768 and -32767 must convert to -1.0f,
- 0 must convert to 0.0f and
- 32767 must convert to 1.0f
For **CL_UNORM_INT_101010**
- 0 must convert to 0.0f and
- 1023 must convert to 1.0f

For **CL_UNORM_INT_101010_2**
- 0 must convert to 0.0f and
- 1023 must convert to 1.0f (for RGB)
- 3 must convert to 1.0f (for A)

**CL_PLATFORM_PROFILE** defined in the OpenCL Platform Queries table will return the string EMBEDDED_PROFILE if the OpenCL implementation supports the embedded profile only.

The minimum maximum values specified in the OpenCL Device Queries table that have been modified for the OpenCL embedded profile are listed in the OpenCL Embedded Device Queries table.

**Table 63. List of supported param_names by clGetDeviceInfo for embedded profile**

<table>
<thead>
<tr>
<th>Device Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_DEVICE_MAX_READ_IMAGE_ARGS</td>
<td>cl_uint</td>
<td>Max number of image objects arguments of a kernel declared with the read_only qualifier. The minimum value is 8 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_MAX_WRITE_IMAGE_ARGS</td>
<td>cl_uint</td>
<td>Max number of image objects arguments of a kernel declared with the write_only qualifier. The minimum value is 8 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_MAX_READ_WRITE_IMAGE_ARGS</td>
<td>cl_uint</td>
<td>Max number of image objects arguments of a kernel declared with the write_only or read_write qualifier. The minimum value is 8 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_IMAGE2D_MAX_WIDTH</td>
<td>size_t</td>
<td>Max width of 2D image in pixels. The minimum value is 2048 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_IMAGE2D_MAX_HEIGHT</td>
<td>size_t</td>
<td>Max height of 2D image in pixels. The minimum value is 2048 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_IMAGE3D_MAX_WIDTH</td>
<td>size_t</td>
<td>Max width of 3D image in pixels. The minimum value is 2048 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_IMAGE3D_MAX_HEIGHT</td>
<td>size_t</td>
<td>Max height of 3D image in pixels. The minimum value is 2048 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>------------------------------------------------</td>
<td>-------------</td>
<td>-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_DEVICE_IMAGE3D_MAX_DEPTH</td>
<td>size_t</td>
<td>Max depth of 3D image in pixels. The minimum value is 2048 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_IMAGE_MAX_BUFFER_SIZE</td>
<td>size_t</td>
<td>Max number of pixels for a 1D image created from a buffer object. The minimum value is 2048 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_IMAGE_MAX_ARRAY_SIZE</td>
<td>size_t</td>
<td>Max number of images in a 1D or 2D image array. The minimum value is 256 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_MAX_SAMPLERS</td>
<td>cl_uint</td>
<td>Maximum number of samplers that can be used in a kernel. The minimum value is 8 if CL_DEVICE_IMAGE_SUPPORT is CL_TRUE, the value is 0 otherwise.</td>
</tr>
<tr>
<td>CL_DEVICE_MAX_PARAMETER_SIZE</td>
<td>size_t</td>
<td>Max size in bytes of all arguments that can be passed to a kernel. The minimum value is 256 bytes for devices that are not of type CL_DEVICE_TYPE_CUSTOM. A maximum of 255 arguments can be passed to a kernel.</td>
</tr>
<tr>
<td>Device Info</td>
<td>Return Type</td>
<td>Description</td>
</tr>
<tr>
<td>------------------------------</td>
<td>-------------</td>
<td>-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
</tbody>
</table>
| CL_DEVICE_SINGLE_FP_CONFIG   | cl_device_fp_config | Describes single precision floating-point capability of the device. This is a bit-field that describes one or more of the following values:  

  - **CL_FP_DENORM** - denorms are supported  
  - **CL_FP_INF_NAN** - INF and quiet NaNs are supported.  
  - **CL_FP_ROUND_TO_NEAREST** - round to nearest even rounding mode supported  
  - **CL_FP_ROUND_TO_ZERO** - round to zero rounding mode supported  
  - **CL_FP_ROUND_TO_INF** - round to positive and negative infinity rounding modes supported  
  - **CL_FP_FMA** - IEEE754-2008 fused multiply-add is supported.  
  - **CL_FP_CORRECTLY_ROUNDED_DIVIDE_SQRT** - divide and sqrt are correctly rounded as defined by the IEEE754 specification.  
  - **CL_FP_SOFT_FLOAT** - Basic floating-point operations (such as addition, subtraction, multiplication) are implemented in software.  

  The mandated minimum floating-point capability is: **CL_FP_ROUND_TO_ZERO** or **CL_FP_ROUND_TO_NEAREST** for devices that are not of type **CL_DEVICE_TYPE_CUSTOM**. |
<p>| CL_DEVICE_MAX_CONSTANT_BUFFER_SIZE | cl_ulong     | Max size in bytes of a constant buffer allocation. The minimum value is 1 KB for devices that are not of type <strong>CL_DEVICE_TYPE_CUSTOM</strong>. |
| CL_DEVICE_MAX_CONSTANT_ARGS    | cl_uint      | Max number of arguments declared with the <strong>__constant</strong> qualifier in a kernel. The minimum value is 4 for devices that are not of type <strong>CL_DEVICE_TYPE_CUSTOM</strong>. |
| CL_DEVICE_LOCAL_MEM_SIZE      | cl_ulong     | Size of local memory arena in bytes. The minimum value is 1 KB for devices that are not of type <strong>CL_DEVICE_TYPE_CUSTOM</strong>. |</p>
<table>
<thead>
<tr>
<th>Device Info</th>
<th>Return Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_DEVICE_COMPILER_AVAILABLE</td>
<td>cl_bool</td>
<td>Is <strong>CL_FALSE</strong> if the implementation does not have a compiler available to compile the program source.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Is <strong>CL_TRUE</strong> if the compiler is available. This can be <strong>CL_FALSE</strong> for the embedded platform profile only.</td>
</tr>
<tr>
<td>CL_DEVICE_LINKER_AVAILABLE</td>
<td>cl_bool</td>
<td>Is <strong>CL_FALSE</strong> if the implementation does not have a linker available. Is <strong>CL_TRUE</strong> if the linker is available.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>This can be <strong>CL_FALSE</strong> for the embedded platform profile only.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>This must be <strong>CL_TRUE</strong> if CL_DEVICE_COMPILER_AVAILABLE is <strong>CL_TRUE</strong>.</td>
</tr>
<tr>
<td>CL_DEVICE_QUEUE_ON_DEVICE_MAX_SIZE</td>
<td>cl_uint</td>
<td>The max. size of the device queue in bytes. The minimum value is 64 KB for the embedded profile</td>
</tr>
<tr>
<td>CL_DEVICE_PRINTF_BUFFER_SIZE</td>
<td>size_t</td>
<td>Maximum size in bytes of the internal buffer that holds the output of printf calls from a kernel. The minimum value for the EMBEDDED profile is 1 KB.</td>
</tr>
</tbody>
</table>

If CL_DEVICE_IMAGE_SUPPORT specified in the OpenCL Device Queries table is **CL_TRUE**, the values assigned to CL_DEVICE_MAX_READ_IMAGE_ARGS, CL_DEVICE_MAX_WRITE_IMAGE_ARGS, CL_DEVICE_IMAGE2D_MAX_WIDTH, CL_DEVICE_IMAGE2D_MAX_HEIGHT, CLDEVICE_IMAGE3D_MAX_WIDTH, CL_DEVICE_IMAGE3D_MAX_HEIGHT, CL_DEVICE_IMAGE3D_MAX_DEPTH, and CL_DEVICE_MAX_SAMPLERS by the implementation must be greater than or equal to the minimum values specified in the OpenCL Embedded Device Queries table.

If CL_DEVICE_IMAGE_SUPPORT specified in the OpenCL Device Queries table is **CL_TRUE**, the minimum list of supported image formats for either reading or writing in a kernel for embedded profile devices is:

*Table 64. Minimum list of supported image formats for reading or writing (embedded profile)*
<table>
<thead>
<tr>
<th>num_channels</th>
<th>channel_order</th>
<th>channel_data_type</th>
</tr>
</thead>
<tbody>
<tr>
<td>4</td>
<td>CL_RGBA</td>
<td>CL_UNORM_INT8</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_UNORM_INT16</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_SIGNED_INT8</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_SIGNED_INT16</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_SIGNED_INT32</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_UNSIGNED_INT8</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_UNSIGNED_INT16</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_UNSIGNED_INT32</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_HALF_FLOAT</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CL_FLOAT</td>
</tr>
</tbody>
</table>

For embedded profiles devices that support reading from and writing to the same image object from the same kernel instance (see `CL_DEVICE_MAX_READ_WRITE_IMAGE_ARGS`) there is no required minimum list of supported image formats.

[1] And `read_imageh`, if the `cl_khr_fp16` extension is supported.

[2] Note that the performance of 64-bit integer arithmetic can vary significantly between embedded devices.
Appendix A: Host environment and thread safety

Shared OpenCL Objects

This section describes which objects can be shared across multiple command-queues created within a host process.

OpenCL memory objects, program objects and kernel objects are created using a context and can be shared across multiple command-queues created using the same context. Event objects can be created when a command is queued to a command-queue. These event objects can be shared across multiple command-queues created using the same context.

The application needs to implement appropriate synchronization across threads on the host processor to ensure that the changes to the state of a shared object (such as a command-queue object, memory object, program or kernel object) happen in the correct order (deemed correct by the application) when multiple command-queues in multiple threads are making changes to the state of a shared object.

A command-queue can cache changes to the state of a memory object on the device associated with the command-queue. To synchronize changes to a memory object across command-queues, the application must do the following:

In the command-queue that includes commands that modify the state of a memory object, the application must do the following:

- Get appropriate event objects for commands that modify the state of the shared memory object.
- Call the `clFlush` (or `clFinish`) API to issue any outstanding commands from this command-queue.

In the command-queue that wants to synchronize to the latest state of a memory object, commands queued by the application must use the appropriate event objects that represent commands that modify the state of the shared memory object as event objects to wait on. This is to ensure that commands that use this shared memory object complete in the previous command-queue before the memory objects are used by commands executing in this command-queue.

The results of modifying a shared resource in one command-queue while it is being used by another command-queue are undefined.

Multiple Host Threads

All OpenCL API calls are thread-safe [1] except those that modify the state of `cl_kernel` objects: `clSetKernelArg`, `clSetKernelArgSVMPointer`, `clSetKernelExecInfo` and `clCloneKernel`. `clSetKernelArg`, `clSetKernelArgSVMPointer`, `clSetKernelExecInfo` and `clCloneKernel` are safe to call from any host thread, and safe to call re-entrantly so long as concurrent calls to any combination of these API calls operate on different `cl_kernel` objects. The state of the `cl_kernel` object is undefined if `clSetKernelArg`, `clSetKernelArgSVMPointer`, `clSetKernelExecInfo` or
clCloneKernel are called from multiple host threads on the same cl_kernel object at the same time \[1\]. Please note that there are additional limitations as to which OpenCL APIs may be called from OpenCL callback functions.

The behavior of OpenCL APIs called from an interrupt or signal handler is implementation-defined for the OpenCL implementation.

The OpenCL implementation should be able to create multiple command-queues for a given OpenCL context and multiple OpenCL contexts in an application running on the host processor.

## Global Constructors and Destructors

The execution order of global constructors and destructors is left undefined by the C and C++ standards. It is therefore not possible to know the relative execution order of an OpenCL implementation’s global constructors and destructors with respect to an OpenCL application’s or library’s.

The behavior of OpenCL API functions called from global constructors or destructors is therefore implementation-defined.

\[1\] Please refer to the OpenCL glossary for the OpenCL definition of thread-safe. This definition may be different from usage of the term in other contexts.

\[2\] There is an inherent race condition in the design of OpenCL that occurs between setting a kernel argument and using the kernel with clEnqueueNDRangeKernel. Another host thread might change the kernel arguments between when a host thread sets the kernel arguments and then enqueues the kernel, causing the wrong kernel arguments to be enqueued. Rather than attempt to share cl_kernel objects among multiple host threads, applications are strongly encouraged to make additional cl_kernel objects for kernel functions for each host thread.
Appendix B: Portability

OpenCL is designed to be portable to other architectures and hardware designs. OpenCL has used at its core a C99 based programming language and follows rules based on that heritage. Floating-point arithmetic is based on the IEEE-754 and IEEE-754-2008 standards. The memory objects, pointer qualifiers and weakly ordered memory are designed to provide maximum compatibility with discrete memory architectures implemented by OpenCL devices. Command-queues and barriers allow for synchronization between the host and OpenCL devices. The design, capabilities and limitations of OpenCL are very much a reflection of the capabilities of underlying hardware.

Unfortunately, there are a number of areas where idiosyncrasies of one hardware platform may allow it to do some things that do not work on another. By virtue of the rich operating system resident on the CPU, on some implementations the kernels executing on a CPU may be able to call out to system services whereas the same calls on the GPU will likely fail for now. Since there is some advantage to having these services available for debugging purposes, implementations can use the OpenCL extension mechanism to implement these services.

Likewise, the heterogeneity of computing architectures might mean that a particular loop construct might execute at an acceptable speed on the CPU but very poorly on a GPU, for example. CPUs are designed in general to work well on latency sensitive algorithms on single threaded tasks, whereas common GPUs may encounter extremely long latencies, potentially orders of magnitude worse. Developers interested in writing portable code may need to test their software on a diversity of hardware designs to make sure that key algorithms are structured in a way that works well on a diversity of hardware. We suggest favoring more work-items over fewer. It is anticipated that over the coming months and years experience will produce a set of best practices that will help foster a uniformly favorable experience on a diversity of computing devices.

Of somewhat more concern is the topic of endianness. Since a majority of devices supported by the initial implementation of OpenCL are little-endian, developers need to make sure that their kernels are tested on both big-endian and little-endian devices to ensure source compatibility with OpenCL devices now and in the future. The endian attribute qualifier is supported by the SPIR-V IL to allow developers to specify whether the data uses the endianness of the host or the OpenCL device. This allows the OpenCL compiler to do appropriate endian-conversion on load and store operations from or to this data.

We also describe how endianness can leak into an implementation causing kernels to produce unintended results:

When a big-endian vector machine (e.g. AltiVec, CELL SPE) loads a vector, the order of the data is retained. That is both the order of the bytes within each element and the order of the elements in the vector are the same as in memory. When a little-endian vector machine (e.g. SSE) loads a vector, the order of the data in register (where all the work is done) is reversed. Both the order of the bytes within each element and the order of the elements with respect to one another in the vector are reversed.

Memory:

uint4 a =
In register (big-endian):

\[
\begin{array}{cccc}
0x00010203 & 0x04050607 & 0x08090A0B & 0x0C0D0E0F \\
\end{array}
\]

\[
\text{uint4 } a = \\
0x00010203 \quad 0x04050607 \quad 0x08090A0B \quad 0x0C0D0E0F
\]

In register (little-endian):

\[
\begin{array}{cccc}
0x0F0E0D0C & 0x0B0A0908 & 0x07060504 & 0x03020100 \\
\end{array}
\]

\[
\text{uint4 } a = \\
0x0F0E0D0C \quad 0x0B0A0908 \quad 0x07060504 \quad 0x03020100
\]

This allows little-endian machines to use a single vector load to load little-endian data, regardless of how large each piece of data is in the vector. That is the transformation is equally valid whether that vector was a \texttt{uchar16} or a \texttt{ulong2}. Of course, as is well known, little-endian machines actually store their data in reverse byte order to compensate for the little-endian storage format of the array elements:

Memory (big-endian):

\[
\begin{array}{cccc}
0x00010203 & 0x04050607 & 0x08090A0B & 0x0C0D0E0F \\
\end{array}
\]

\[
\text{uint4 } a = \\
0x00010203 \quad 0x04050607 \quad 0x08090A0B \quad 0x0C0D0E0F
\]

Memory (little-endian):

\[
\begin{array}{cccc}
0x03020100 & 0x07060504 & 0x0B0A0908 & 0x0F0E0D0C \\
\end{array}
\]

\[
\text{uint4 } a = \\
0x03020100 \quad 0x07060504 \quad 0x0B0A0908 \quad 0x0F0E0D0C
\]

Once that data is loaded into a vector, we end up with this:

In register (big-endian):

\[
\begin{array}{cccc}
0x00010203 & 0x04050607 & 0x08090A0B & 0x0C0D0E0F \\
\end{array}
\]

\[
\text{uint4 } a = \\
0x00010203 \quad 0x04050607 \quad 0x08090A0B \quad 0x0C0D0E0F
\]

In register (little-endian):

\[
\begin{array}{cccc}
0x0C0D0E0F & 0x08090A0B & 0x04050607 & 0x00010203 \\
\end{array}
\]

\[
\text{uint4 } a = \\
0x0C0D0E0F \quad 0x08090A0B \quad 0x04050607 \quad 0x00010203
\]

That is, in the process of correcting the endianness of the bytes within each element, the machine ends up reversing the order that the elements appear in the vector with respect to each other within the vector. 0x00010203 appears at the left of the big-endian vector and at the right of the little-endian vector.
When the host and device have different endianness, the developer must ensure that kernel argument values are processed correctly. The implementation may or may not automatically convert endianness of kernel arguments. Developers should consult vendor documentation for guidance on how to handle kernel arguments in these situations.

OpenCL provides a consistent programming model across architectures by numbering elements according to their order in memory. Concepts such as even/odd and high/low follow accordingly. Once the data is loaded into registers, we find that element 0 is at the left of the big-endian vector and element 0 is at the right of the little-endian vector:

```c
float x[4];
float4 v = vload4( 0, x );
```

**Big-endian:**

```
v contains { x[0], x[1], x[2], x[3] }
```

**Little-endian:**

```
v contains { x[3], x[2], x[1], x[0] }
```

The compiler is aware that this swap occurs and references elements accordingly. So long as we refer to them by a numeric index such as .s0123456789abcdef or by descriptors such as .xyzw, .hi, .lo, .even and .odd, everything works transparently. Any ordering reversal is undone when the data is stored back to memory. The developer should be able to work with a big-endian programming model and ignore the element ordering problem in the vector ... for most problems. This mechanism relies on the fact that we can rely on a consistent element numbering. Once we change numbering system, for example by conversion-free casting (using as_type_n) a vector to another vector of the same size but a different number of elements, then we get different results on different implementations depending on whether the system is big-endian, or little-endian or indeed has no vector unit at all. (Thus, the behavior of bitcasts to vectors of different numbers of elements is implementation-defined, see section 6.4.4 of OpenCL C specification.)

An example follows:

```c
float x[4] = { 0.0f, 1.0f, 2.0f, 3.0f };
float4 v = vload4( 0, x );
uint4 y = as_uint4(v);    // legal, portable
ushort8 z = as_ushort8(v); // legal, not portable
                    // element size changed
```

**Big-endian:**

```
v contains { 0.0f, 1.0f, 2.0f, 3.0f }
y contains { 0x00000000, 0x3f800000, 431
```
Little-endian:

v contains { 3.0f, 2.0f, 1.0f, 0.0f }
y contains { 0x40400000, 0x40000000, 0x3f800000, 0x00000000 }
z contains { 0x4040, 0x0000, 0x4000, 0x0000, 0x3f80, 0x0000, 0x4040, 0x0000 }
z.z is 0

Here, the value in z.z is not the same between big- and little-endian vector machines.

OpenCL could have made it illegal to do a conversion free cast that changes the number of elements in the name of portability. However, while OpenCL provides a common set of operators drawing from the set that are typically found on vector machines, it cannot provide access to everything every ISA may offer in a consistent uniform portable manner. Many vector ISAs provide special purpose instructions that greatly accelerate specific operations such as DCT, SAD, or 3D geometry. It is not intended for OpenCL to be so heavy handed that time-critical performance sensitive algorithms cannot be written by knowledgeable developers to perform at near peak performance. Developers willing to throw away portability should be able to use the platform-specific instructions in their code. For this reason, OpenCL is designed to allow traditional vector C language programming extensions, such as the AltiVec C Programming Interface or the Intel C programming interfaces (such as those found in _emmintrin.h) to be used directly in OpenCL with OpenCL data types as an extension to OpenCL. As these interfaces rely on the ability to do conversion-free casts that change the number of elements in the vector to function properly, OpenCL allows them too.

As a general rule, any operation that operates on vector types in segments that are not the same size as the vector element size may break on other hardware with different endianness or different vector architecture.

Examples might include:

- Combining two _uchar8's containing high and low bytes of a ushort, to make a _ushort8 using .even and .odd operators (please use upsample() for this)
- Any bitcast that changes the number of elements in the vector. (Operations on the new type are non-portable.)
- Swizzle operations that change the order of data using chunk sizes that are not the same as the element size

Examples of operations that are portable:

- Combining two _uint8's to make a _uchar16 using .even and .odd operators. For example to interleave left and right audio streams.
• Any bitcast that does not change the number of elements (e.g. \texttt{(float4) uint4})—we define the storage format for floating-point types

• Swizzle operations that swizzle elements of the same size as the elements of the vector.

OpenCL has made some additions to C to make application behavior more dependable than C. Most notably in a few cases OpenCL defines the behavior of some operations that are undefined in C99:

• OpenCL provides \texttt{convert\_} functions for conversion between all types. C99 does not define what happens when a floating-point type is converted to an integer type and the floating-point value lies outside the representable range of the integer type after rounding. When the \texttt{sat} variant of the conversion is used, the float shall be converted to the nearest representable integer value. Similarly, OpenCL also makes recommendations about what should happen with NaN. Hardware manufacturers that provide the saturated conversion in hardware may use the saturated conversion hardware for both the saturated and non-saturated versions of the OpenCL \texttt{convert\_} functions. OpenCL does not define what happens for the non-saturated conversions when floating-point operands are outside the range representable integers after rounding.

• The format of \texttt{half}, \texttt{float}, and \texttt{double} types is defined to be the binary16, binary32 and binary64 formats in the draft IEEE-754 standard. (The latter two are identical to the existing IEEE-754 standard.) You may depend on the positioning and meaning of the bits in these types.

• OpenCL defines behavior for oversized shift values. Shift operations that shift greater than or equal to the number of bits in the first operand reduce the shift value modulo the number of bits in the element. For example, if we shift an \texttt{int4} left by 33 bits, OpenCL treats this as shift left by $33 \mod 32 = 1$ bit.

• A number of edge cases for math library functions are more rigorously defined than in C99. Please see section 7.5 of the OpenCL C specification.

\footnote{Note that we are talking about the programming model here. In reality, little endian systems might choose to simply address their bytes from “the right” or reverse the “order” of the bits in the byte. Either of these choices would mean that no big swap would need to occur in hardware.}
Appendix C: Application Data Types

This section documents the provided host application types and constant definitions. The documented material describes the commonly defined data structures, types and constant values available to all platforms and architectures. The addition of these details demonstrates our commitment to maintaining a portable programming environment and potentially deters changes to the supplied headers.

Supported Application Scalar Data Types

The following application scalar types are provided for application convenience.

\[
\begin{align*}
\text{cl}_\text{char} & \\
\text{cl}_\text{uchar} & \\
\text{cl}_\text{short} & \\
\text{cl}_\text{ushort} & \\
\text{cl}_\text{int} & \\
\text{cl}_\text{uint} & \\
\text{cl}_\text{long} & \\
\text{cl}_\text{ulong} & \\
\text{cl}_\text{half} & \\
\text{cl}_\text{float} & \\
\text{cl}_\text{double} & \\
\end{align*}
\]

Supported Application Vector Data Types

Application vector types are unions used to create vectors of the above application scalar types. The following application vector types are provided for application convenience.

\[
\begin{align*}
\text{cl}_\text{char}\langle n \rangle & \\
\text{cl}_\text{uchar}\langle n \rangle & \\
\text{cl}_\text{short}\langle n \rangle & \\
\text{cl}_\text{ushort}\langle n \rangle & \\
\text{cl}_\text{int}\langle n \rangle & \\
\text{cl}_\text{uint}\langle n \rangle & \\
\text{cl}_\text{long}\langle n \rangle & \\
\text{cl}_\text{ulong}\langle n \rangle & \\
\text{cl}_\text{half}\langle n \rangle & \\
\text{cl}_\text{float}\langle n \rangle & \\
\text{cl}_\text{double}\langle n \rangle & \\
\end{align*}
\]

\(n\) can be 2, 3, 4, 8 or 16.

The application scalar and vector data types are defined in the cl_platform.h header file.
Alignment of Application Data Types

The user is responsible for ensuring that pointers passed into and out of OpenCL kernels are natively aligned relative to the data type of the parameter as defined in the kernel language and SPIR-V specifications. This implies that OpenCL buffers created with `CL_MEM_USE_HOST_PTR` need to provide an appropriately aligned host memory pointer that is aligned to the data types used to access these buffers in a kernel(s), that SVM allocations must correctly align and that pointers into SVM allocations must also be correctly aligned. The user is also responsible for ensuring image data passed is aligned to the granularity of the data representing a single pixel (e.g. `image_num_channels * sizeof(image_channel_data_type)` except for `CL_RGB` and `CL_RGBx` images where the data must be aligned to the granularity of a single channel in a pixel (i.e. `sizeof(image_channel_data_type)`). This implies that OpenCL images created with `CL_MEM_USE_HOST_PTR` must align correctly. The image alignment value can be queried using the `CL_DEVICE_IMAGE_BASE_ADDRESS_ALIGNMENT` query. In addition, source pointers for `clEnqueueWriteImage` and other operations that copy to the OpenCL runtime, as well as destination pointers for `clEnqueueReadImage` and other operations that copy from the OpenCL runtime must follow the same alignment rules.

OpenCL makes no requirement about the alignment of OpenCL application defined data types outside of buffers and images, except that the underlying vector primitives (e.g. `__cl_float4`) where defined shall be directly accessible as such using appropriate named fields in the `cl_type` union (see Vector Components). Nevertheless, it is recommended that the `cl_platform.h` header should attempt to naturally align OpenCL defined application data types (e.g. `cl_float4`) according to their type.

Vector Literals

Application vector literals may be used in assignments of individual vector components. Literal usage follows the convention of the underlying application compiler.

```
cl_float2 foo = { .s[1] = 2.0f };  
cl_int8 bar = {{ 2, 4, 6, 8, 10, 12, 14, 16 }};
```

Vector Components

The components of application vector types can be addressed using the `<vector_name>.s[<index>]` notation.

For example:

```
foo.s[0] = 1.0f;  // Sets the 1st vector component of foo
pos.s[6] = 2;     // Sets the 7th vector component of bar
```

In some cases vector components may also be accessed using the following notations. These notations are not guaranteed to be supported on all implementations, so their use should be accompanied by a check of the corresponding preprocessor symbol.
Named Vector Components Notation

Vector data type components may be accessed using the `.sN`, `.sn` or `.xyzw` field naming convention, similar to how they are used within the OpenCL C language. Use of the `.xyzw` field naming convention only allows accessing of the first 4 component fields. Support of these notations is identified by the `CL_HAS_NAMED_VECTOR_FIELDS` preprocessor symbol. For example:

```c
#ifdef CL_HAS_NAMED_VECTOR_FIELDS
    cl_float4 foo;
    cl_int16 bar;
    foo.x = 1.0f; // Set first component
    foo.s0 = 1.0f; // Same as above
    bar.z = 3; // Set third component
    bar.se = 11; // Same as bar.s[0xe]
    bar.sD = 12; // Same as bar.s[0xd]
#endif
```

Vector data type components may also be accessed using the `.rgba` field naming convention, similar to how they are used within the OpenCL C 3.0 language. Use of the `.rgba` field naming convention only allows accessing of the first 4 component fields. Support of these notations is identified by the `CL_HAS_NAMED_RGBA_VECTOR_FIELDS` preprocessor symbol. For example:

```c
#ifdef CL_HAS_NAMED_RGBA_VECTOR_FIELDS
    cl_float4 foo;
    cl_int16 bar;
    foo.r = 1.0f; // Set first component
    bar.b = 3; // Set third component
#endif
```

Unlike the OpenCL C language type usage of named vector fields, only one component field may be accessed at a time. This restriction prevents the ability to swizzle or replicate components as is possible with the OpenCL C language types. Attempting to access beyond the number of components for a type also results in a failure.

```c
foo.xy // illegal - illegal field name combination
bar.s1234 // illegal - illegal field name combination
foo.s7 // illegal - no component s7
```

High/Low Vector Component Notation

Vector data type components may be accessed using the `.hi` and `.lo` notation similar to that supported within the language types. Support of this notation is identified by the `CL_HAS_HI_LO_VECTOR_FIELDS` preprocessor symbol. For example:

```c
#ifdef CL_HAS_HI_LO_VECTOR_FIELDS
    cl_float4 foo;
#endif
```
Native Vector Type Notation

Certain native vector types are defined for providing a mapping of vector types to architecturally built-in vector types. Unlike the above described application vector types, these native types are supported on a limited basis depending on the supporting architecture and compiler.

These types are not unions, but rather convenience mappings to the underlying architectures’ built-in vector types. The native types share the name of their application counterparts but are preceded by a double underscore "__".

For example, __cl_float4 is the native built-in vector type equivalent of the cl_float4 application vector type. The __cl_float4 type may provide direct access to the architectural built-in __m128 or vector float type, whereas the cl_float4 is treated as a union.

In addition, the above described application data types may have native vector data type members for access convenience. The native components are accessed using the .vN sub-vector notation, where N is the number of elements in the sub-vector. In cases where the native type is a subset of a larger type (more components), the notation becomes an index based array of the sub-vector type.

Support of the native vector types is identified by a __CL_TYPEN__ preprocessor symbol matching the native type name. For example:

```
#include __CL_TYPEN__ // Check for native cl_float4 type

cl_float8 foo;
__cl_float4 bar; // Use of native type
bar = foo.v4[1]; // Access the second native float4 vector
```

Implicit Conversions

Implicit conversions between application vector types are not supported.

Explicit Casts

Explicit casting of application vector types (cl_typen) is not supported. Explicit casting of native vector types (__cl_typen) is defined by the external compiler.

Other Operators and Functions

The behavior of standard operators and function on both application vector types (cl_typen) and native vector types (__cl_typen) is defined by the external compiler.
**Application Constant Definitions**

In addition to the above application type definitions, the following literal definitions are also available.

<table>
<thead>
<tr>
<th>Constant</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_CHAR_BIT</td>
<td>Bit width of a character</td>
</tr>
<tr>
<td>CL_SCHAR_MAX</td>
<td>Maximum value of a type <code>cl_char</code></td>
</tr>
<tr>
<td>CL_SCHAR_MIN</td>
<td>Minimum value of a type <code>cl_char</code></td>
</tr>
<tr>
<td>CL_CHAR_MAX</td>
<td>Maximum value of a type <code>cl_char</code></td>
</tr>
<tr>
<td>CL_CHAR_MIN</td>
<td>Minimum value of a type <code>cl_char</code></td>
</tr>
<tr>
<td>CL_UCHAR_MAX</td>
<td>Maximum value of a type <code>cl_uchar</code></td>
</tr>
<tr>
<td>CL_SHRT_MAX</td>
<td>Maximum value of a type <code>cl_short</code></td>
</tr>
<tr>
<td>CL_SHRT_MIN</td>
<td>Minimum value of a type <code>cl_short</code></td>
</tr>
<tr>
<td>CL_USHRT_MAX</td>
<td>Maximum value of a type <code>cl_ushort</code></td>
</tr>
<tr>
<td>CL_INT_MAX</td>
<td>Maximum value of a type <code>cl_int</code></td>
</tr>
<tr>
<td>CL_INT_MIN</td>
<td>Minimum value of a type <code>cl_int</code></td>
</tr>
<tr>
<td>CL_UINT_MAX</td>
<td>Maximum value of a type <code>cl_uint</code></td>
</tr>
<tr>
<td>CL_LONG_MAX</td>
<td>Maximum value of a type <code>cl_long</code></td>
</tr>
<tr>
<td>CL_LONG_MIN</td>
<td>Minimum value of a type <code>cl_long</code></td>
</tr>
<tr>
<td>CL_ULONG_MAX</td>
<td>Maximum value of a type <code>cl_ulong</code></td>
</tr>
<tr>
<td>CL_FLT_DIG</td>
<td>Number of decimal digits of precision for the type <code>cl_float</code></td>
</tr>
<tr>
<td>CL_FLT_MANT_DIG</td>
<td>Number of digits in the mantissa of type <code>cl_float</code></td>
</tr>
<tr>
<td>CL_FLT_MAX_10_EXP</td>
<td>Maximum positive integer such that 10 raised to this power minus one can be represented as a normalized floating-point number of type <code>cl_float</code></td>
</tr>
<tr>
<td>CL_FLT_MAX_EXP</td>
<td>Maximum exponent value of type <code>cl_float</code></td>
</tr>
<tr>
<td>CL_FLT_MIN_10_EXP</td>
<td>Minimum negative integer such that 10 raised to this power minus one can be represented as a normalized floating-point number of type <code>cl_float</code></td>
</tr>
<tr>
<td>CL_FLT_MIN_EXP</td>
<td>Minimum exponent value of type <code>cl_float</code></td>
</tr>
<tr>
<td>CL_FLT_RADIX</td>
<td>Base value of type <code>cl_float</code></td>
</tr>
<tr>
<td>CL_FLT_MAX</td>
<td>Maximum value of type <code>cl_float</code></td>
</tr>
<tr>
<td>CL_FLT_MIN</td>
<td>Minimum value of type <code>cl_float</code></td>
</tr>
<tr>
<td>Symbol</td>
<td>Description</td>
</tr>
<tr>
<td>----------------------</td>
<td>-----------------------------------------------------------------------------</td>
</tr>
<tr>
<td><code>CL_CHAR_BIT</code></td>
<td>Bit width of a character</td>
</tr>
<tr>
<td><code>CL_FLT_EPSILON</code></td>
<td>Minimum positive floating-point number of type <code>cl_float</code> such that <code>1.0 + CL_FLT_EPSILON != 1</code> is true.</td>
</tr>
<tr>
<td><code>CL_DBL_DIG</code></td>
<td>Number of decimal digits of precision for the type <code>cl_double</code></td>
</tr>
<tr>
<td>missing before version 1.2. Also see <code>cl_khr_fp64</code>.</td>
<td></td>
</tr>
<tr>
<td><code>CL_DBL_MANT_DIG</code></td>
<td>Number of digits in the mantissa of type <code>cl_double</code></td>
</tr>
<tr>
<td>missing before version 1.2. Also see <code>cl_khr_fp64</code>.</td>
<td></td>
</tr>
<tr>
<td><code>CL_DBL_MAX_10_EXP</code></td>
<td>Maximum positive integer such that 10 raised to this power minus one can be represented as a normalized floating-point number of type <code>cl_double</code></td>
</tr>
<tr>
<td>missing before version 1.2. Also see <code>cl_khr_fp64</code>.</td>
<td></td>
</tr>
<tr>
<td><code>CL_DBL_MAX_EXP</code></td>
<td>Maximum exponent value of type <code>cl_double</code></td>
</tr>
<tr>
<td>missing before version 1.2. Also see <code>cl_khr_fp64</code>.</td>
<td></td>
</tr>
<tr>
<td><code>CL_DBL_MIN_10_EXP</code></td>
<td>Minimum negative integer such that 10 raised to this power minus one can be represented as a normalized floating-point number of type <code>cl_double</code></td>
</tr>
<tr>
<td>missing before version 1.2. Also see <code>cl_khr_fp64</code>.</td>
<td></td>
</tr>
<tr>
<td><code>CL_DBL_MIN_EXP</code></td>
<td>Minimum exponent value of type <code>cl_double</code></td>
</tr>
<tr>
<td>missing before version 1.2. Also see <code>cl_khr_fp64</code>.</td>
<td></td>
</tr>
<tr>
<td><code>CL_DBL_RADIX</code></td>
<td>Base value of type <code>cl_double</code></td>
</tr>
<tr>
<td>missing before version 1.2. Also see <code>cl_khr_fp64</code>.</td>
<td></td>
</tr>
<tr>
<td><code>CL_DBL_MAX</code></td>
<td>Maximum value of type <code>cl_double</code></td>
</tr>
<tr>
<td>missing before version 1.2. Also see <code>cl_khr_fp64</code>.</td>
<td></td>
</tr>
<tr>
<td><code>CL_DBL_MIN</code></td>
<td>Minimum value of type <code>cl_double</code></td>
</tr>
<tr>
<td>missing before version 1.2. Also see <code>cl_khr_fp64</code>.</td>
<td></td>
</tr>
<tr>
<td><code>CL_DBL_EPSILON</code></td>
<td>Minimum positive floating-point number of type <code>cl_double</code> such that <code>1.0 + CL_DBL_EPSILON != 1</code> is true.</td>
</tr>
<tr>
<td>missing before version 1.2. Also see <code>cl_khr_fp64</code>.</td>
<td></td>
</tr>
<tr>
<td><code>CL_NAN</code></td>
<td>Macro expanding to a value representing NaN</td>
</tr>
<tr>
<td>missing before version 1.1.</td>
<td></td>
</tr>
<tr>
<td><code>CL_HUGE_VALF</code></td>
<td>Largest representative value of type <code>cl_float</code></td>
</tr>
<tr>
<td>missing before version 1.1.</td>
<td></td>
</tr>
<tr>
<td>Symbol</td>
<td>Description</td>
</tr>
<tr>
<td>----------------------</td>
<td>-------------------------------------------------------</td>
</tr>
<tr>
<td>CL_CHAR_BIT</td>
<td>Bit width of a character</td>
</tr>
<tr>
<td>CL_HUGE_VAL</td>
<td>Largest representative value of type <code>cl_double</code></td>
</tr>
<tr>
<td>missing before version 1.1</td>
<td></td>
</tr>
<tr>
<td>CL_MAXFLOAT</td>
<td>Maximum value of type <code>cl_float</code></td>
</tr>
<tr>
<td>missing before version 1.1</td>
<td></td>
</tr>
<tr>
<td>CL_INFINITY</td>
<td>Macro expanding to a value representing infinity</td>
</tr>
<tr>
<td>missing before version 1.1</td>
<td></td>
</tr>
</tbody>
</table>

These literal definitions are defined in the `cl_platform.h` header.
Appendix D: Checking for Memory Copy Overlap

The following code describes how to determine if there is overlap between the source and destination rectangles specified to clEnqueueCopyBufferRect provided the source and destination buffers refer to the same buffer object.

```c
unsigned int
check_copy_overlap(const size_t src_origin[],
                     const size_t dst_origin[],
                     const size_t region[],
                     const size_t row_pitch,
                     const size_t slice_pitch)
{
    const size_t slice_size = (region[1] - 1) * row_pitch + region[0];
    const size_t block_size = (region[2] - 1) * slice_pitch + slice_size;
    const size_t src_start = src_origin[2] * slice_pitch + src_origin[1] * row_pitch + src_origin[0];
    const size_t src_end = src_start + block_size;
    const size_t dst_start = dst_origin[2] * slice_pitch + dst_origin[1] * row_pitch + dst_origin[0];
    const size_t dst_end = dst_start + block_size;

    /* No overlap if dst ends before src starts or if src ends before dst starts. */
    if((dst_end <= src_start) || (src_end <= dst_start)){
        return 0;
    }

    /* No overlap if region[0] for dst or src fits in the gap between region[0] and row_pitch. */
    {
        const size_t src_dx = src_origin[0] % row_pitch;
        const size_t dst_dx = dst_origin[0] % row_pitch;

        if( (((dst_dx >= src_dx + region[0]) ||
            (dst_dx + region[0] <= src_dx + row_pitch)) ||
            ((src_dx >= dst_dx + region[0]) ||
            (src_dx + region[0] <= dst_dx + row_pitch))) )
            {
                return 0;
            }
    }
}
```
/* No overlap if region[1] for dst or src fits in the gap 
* between region[1] and slice_pitch. 
*/
{
    const size_t src_dy =
        (src_origin[1] * row_pitch + src_origin[0]) % slice_pitch;
    const size_t dst_dy =
        (dst_origin[1] * row_pitch + dst_origin[0]) % slice_pitch;

    if( ((dst_dy >= src_dy + slice_size) &&
        (dst_dy + slice_size <= src_dy + slice_pitch)) ||
        ((src_dy >= dst_dy + slice_size) &&
        (src_dy + slice_size <= dst_dy + slice_pitch)) ){
        return 0;
    }
}

/* Otherwise src and dst overlap. */
return 1;
Appendix E: Changes to OpenCL

Changes to the OpenCL API and OpenCL C specifications between successive versions are summarized below.

Summary of Changes from OpenCL 1.0 to OpenCL 1.1

The following features are added to the OpenCL 1.1 platform layer and runtime (sections 4 and 5):

- Following queries to table 4.3
  - `CL_DEVICE_NATIVE_VECTOR_WIDTH_CHAR`, `CL_DEVICE_NATIVE_VECTOR_WIDTH_SHORT`, `CL_DEVICE_NATIVE_VECTOR_WIDTH_INT`, `CL_DEVICE_NATIVE_VECTOR_WIDTH_LONG`, `CL_DEVICE_NATIVE_VECTOR_WIDTH_FLOAT`, `CL_DEVICE_NATIVE_VECTOR_WIDTH_DOUBLE`, `CL_DEVICE_NATIVE_VECTOR_WIDTH_HALF`
  - `CL_DEVICE_HOST_UNIFIED_MEMORY`
  - `CL_DEVICE_OPENCL_C_VERSION`

- CL_CONTEXT_NUM_DEVICES to the list of queries specified to `clGetContextInfo`.

- Optional image formats: `CL_Rx`, `CL_RGx`, and `CL_RGBx`.

- Support for sub-buffer objects ability to create a buffer object that refers to a specific region in another buffer object using `clCreateSubBuffer`.

- `clEnqueueReadBufferRect`, `clEnqueueWriteBufferRect` and `clEnqueueCopyBufferRect` APIs to read from, write to and copy a rectangular region of a buffer object respectively.

- `clSetMemObjectDestructorCallback` API to allow a user to register a callback function that will be called when the memory object is deleted and its resources freed.

- Options that control the OpenCL C version used when building a program executable.

- `CL_KERNEL_PREFERRED_WORK_GROUP_SIZE_MULTIPLE` to the list of queries specified to `clGetKernelWorkGroupInfo`.

- Support for user events. User events allow applications to enqueue commands that wait on a user event to finish before the command is executed by the device. Following new APIs are added - `clCreateUserEvent` and `clSetUserEventStatus`.

- `clSetEventCallback` API to register a callback function for a specific command execution status.

The following modifications are made to the OpenCL 1.1 platform layer and runtime (sections 4 and 5):

- Following queries in table 4.3
  - The minimum FULL_PROFILE value for `CL_DEVICE_MAX_PARAMETER_SIZE` increased from 256 to 1024 bytes
  - The minimum FULL_PROFILE value for `CL_DEVICE_LOCAL_MEM_SIZE` increased from 16 KB to 32 KB.

- The `global_work_offset` argument in `clEnqueueNDRangeKernel` can be a non-NULL value.

- All API calls except `clSetKernelArg` are thread-safe.
The following features are added to the OpenCL C programming language (section 6) in OpenCL 1.1:

- 3-component vector data types.
- New built-in functions
  - `get_global_offset` work-item function defined in section 6.15.1.
  - `minmag`, `maxmag` math functions defined in section 6.15.2.
  - `clamp` integer function defined in section 6.15.3.
  - (vector, scalar) variant of integer functions `min` and `max` in section 6.12.3.
  - `async_work_group_strided_copy` defined in section 6.15.11.
  - `vec_step`, `shuffle` and `shuffle2` defined in section 6.15.13.
- `cl_khr_byte_addressable_store` extension is a core feature.
- `cl_khr_global_int32_base_atomics`, `cl_khr_global_int32_extended_atomics`, `cl_khr_local_int32_base_atomics` and `cl_khr_local_int32_extended_atomics` extensions are core features. The built-in atomic function names are changed to use the `atomic_` prefix instead of `atom_`.
- Macros `CL_VERSION_1_0` and `CL_VERSION_1_1`.

The following features in OpenCL 1.0 are deprecated (see glossary) in OpenCL 1.1:

- The `clSetCommandQueueProperty` API is deprecated, which simplifies implementations and possibly improves performance by enforcing that command-queue properties are invariant. Applications are encouraged to create multiple command-queues with different properties versus modifying the properties of a single command-queue.
- The `-cl-strict-aliasing` build option has been deprecated. It is no longer required after defining type-based aliasing rules.
- The `cl_khr_select_fprounding_mode` extension is deprecated and its use is no longer recommended.

The following new extensions are added to section 9 in OpenCL 1.1:

- `cl_khr_gl_event` for creating a CL event object from a GL sync object.
- `cl_khr_d3d10_sharing` for sharing memory objects with Direct3D 10.

The following modifications are made to the OpenCL ES Profile described in section 10 in OpenCL 1.1:

- 64-bit integer support is optional.

**Summary of Changes from OpenCL 1.1 to OpenCL 1.2**

The following features are added to the OpenCL 1.2 platform layer and runtime (sections 4 and 5):

- Custom devices and built-in kernels are supported. `clCreateProgramWithBuiltInKernels` has been added to allow creation of a `cl_program` using built-in kernels.
- Device partitioning that allows a device to be partitioned based on a number of partitioning
schemes supported by the device. This is done by using clCreateSubDevices to create a new cl_device_id based on a partitioning.

- clCompileProgram and clLinkProgram to allow handling these aspects clBuildProgram separately.

- Extend cl_mem_flags to describe how the host accesses the data in a cl_mem object.

- clEnqueueFillBuffer and clEnqueueFillImage to support filling a buffer with a pattern or an image with a color.

- Add CL_MAP_WRITE_INVALIDATE_REGION to cl_map_flags. Appropriate clarification to the behavior of CL_MAP_WRITE has been added to the spec.

- New image types: 1D image, 1D image from a buffer object, 1D image array and 2D image arrays.

- clCreateImage to create an image object.

- clEnqueueMigrateMemObjects API that allows a developer to have explicit control over the location of memory objects or to migrate a memory object from one device to another.

- Support separate compilation and linking of programs.

- Additional queries to get the number of kernels and kernel names in a program have been added to clGetProgramInfo.

- Additional queries to get the compile and link status and options have been added to clGetProgramBuildInfo.

- clGetKernelArgInfo API that returns information about the arguments of a kernel.

- clEnqueueMarkerWithWaitList and clEnqueueBarrierWithWaitList APIs.

- clUnloadPlatformCompiler to request that a single platform's compiler is unloaded. This is compatible with the cl_khr_icd extension if that is supported, unlike clUnloadCompiler.

The following features are added to the OpenCL C programming language (section 6) in OpenCL 1.2:

- Double-precision is now an optional core feature instead of an extension.

- New built in image types: image1d_t, image1d_buffer_t, image1d_array_t, and image2d_array_t.

- New built-in functions
  - Functions to read from and write to a 1D image, 1D and 2D image arrays described in sections 6.15.15.2, 6.15.15.3 and 6.15.15.4.
  - Sampler-less image read functions described in section 6.15.15.3.
  - popcount integer function described in section 6.15.3.
  - printf function described in section 6.15.14.

- Storage class specifiers extern and static as described in section 6.10.

- Macros CL_VERSION_1_2 and __OPENCL_C_VERSION__.

The following APIs in OpenCL 1.1 are deprecated (see glossary) in OpenCL 1.2:

- The clEnqueueMarker, clEnqueueBarrier and clEnqueueWaitForEvents APIs are deprecated.
to simplify the API. The `clEnqueueMarkerWithWaitList` and `clEnqueueBarrierWithWaitList` APIs provide equivalent functionality and support explicit event wait lists.

- The `clCreateImage2D`, `clCreateImage3D`, `clCreateFromGLTexture2D` and `clCreateFromGLTexture3D` APIs are deprecated to simplify the API. The `clCreateImage` and `clCreateFromGLTexture` APIs provide equivalent functionality and support additional image types and properties.

- `clUnloadCompiler` and `clGetExtensionFunctionAddress` APIs are deprecated. The `clUnloadPlatformCompiler` and `clGetExtensionFunctionAddressForPlatform` APIs provide equivalent functionality and are compatible with the `cl_khr_icd` extension.

The following queries are deprecated (see glossary) in OpenCL 1.2:

- The `CL_DEVICE_MIN_DATA_TYPE_ALIGN_SIZE` query is deprecated. The minimum data type alignment can be derived from `CL_DEVICE_MEM_BASE_ADDR_ALIGN`.

**Summary of Changes from OpenCL 1.2 to OpenCL 2.0**

The following features are added to the OpenCL 2.0 platform layer and runtime (sections 4 and 5):

- Shared virtual memory. The associated API additions are:
  - `clSetKernelArgSVMPointer` to control which shared virtual memory (SVM) pointer to associate with a kernel instance.
  - `clSVMAlloc`, `clSVMFree` and `clEnqueueSVMFree` to allocate and free memory for use with SVM.
  - `clEnqueueSVMMap` and `clEnqueueSVMUnmap` to map and unmap to update regions of an SVM buffer from host.
  - `clEnqueueSVMMemcpy` and `clEnqueueSVMMemFill` to copy or fill SVM memory regions.

- Device queues used to enqueue kernels on the device.
  - `clCreateCommandQueueWithProperties` is added to allow creation of a command-queue with properties that affect both host command-queues and device queues.

- Pipes.
  - `clCreatePipe` and `clGetPipeInfo` have been added to the API for host side creation and querying of pipes.

- Images support for 2D image from buffer, depth images and sRGB images.

- `clCreateSamplerWithProperties`.

The following modifications are made to the OpenCL 2.0 platform layer and runtime (sections 4 and 5):

- All API calls except `clSetKernelArg`, `clSetKernelArgSVMPointer` and `clSetKernelExecInfo` are thread-safe. Note that this statement does not imply that other API calls were not thread-safe in earlier versions of the specification.

The following features are added to the OpenCL C programming language (section 6) in OpenCL 2.0:
- Clang Blocks.
- Kernels enqueuing kernels to a device queue.
- Program scope variables in global address space.
- Generic address space.
- C1x atomics.
- New built-in functions (sections 6.15.10, 6.15.12, and 6.15.16).
- Support images with the read_write qualifier.
- 3D image writes are a core feature.
- The CL_VERSION_2_0 and NULL macros.
- The opencl_unroll_hint attribute.

The following APIs are deprecated (see glossary) in OpenCL 2.0:

- The clCreateCommandQueue API has been deprecated to simplify the API. The clCreateCommandQueueWithProperties API provides equivalent functionality and supports specifying additional command-queue properties.
- The clCreateSampler API has been deprecated to simplify the API. The clCreateSamplerWithProperties API provides equivalent functionality and supports specifying additional sampler properties.
- The clEnqueueTask API has been deprecated to simplify the API. The clEnqueueNDRangeKernel API provides equivalent functionality.

The following queries are deprecated (see glossary) in OpenCL 2.0:

- The CL_DEVICE_HOST_UNIFIED_MEMORY query is deprecated. This query was purely informational and had different meanings for different implementations. Its use is no longer recommended.
- The CL_IMAGE_BUFFER query has been deprecated to simplify the API. The CL_MEM_ASSOCIATED_MEMOBJECT query provides equivalent functionality.
- The CL_DEVICE_QUEUE_PROPERTIES query has been deprecated and replaced by CL_DEVICE_QUEUE_ON_HOST_PROPERTIES.

Atoms and Fences

- The Explicit Memory Fence Functions defined in section 6.12.9 of the OpenCL 1.2 specification have been deprecated to simplify the programming language. The atomic_work_item_fence function provides equivalent functionality. The deprecated functions are still described in section 6.15.9 of this specification.
- The Atomic Functions defined in section 6.12.11 of the OpenCL 1.2 specification have been deprecated to simplify the programming language. The atomic_fetch and modify functions provide equivalent functionality. The deprecated functions are still described in section 6.15.12.8 of this specification.
Summary of Changes from OpenCL 2.0 to OpenCL 2.1

The following features are added to the OpenCL 2.1 platform layer and runtime (sections 4 and 5):

- `clGetKernelSubGroupInfo` API call.
- `CL_KERNEL_MAX_NUM_SUB_GROUPS`, `CL_KERNEL_COMPILE_NUM_SUB_GROUPS` additions to table 5.21 of the API specification.
- `clCreateProgramWithIL` API call.
- `clGetHostTimer` and `clGetDeviceAndHostTimer` API calls.
- `clEnqueueSVMMigrateMem` API call.
- `clCloneKernel` API call.
- `clSetDefaultDeviceCommandQueue` API call.
- `CL_PLATFORM_HOST_TIMER_RESOLUTION` added to table 4.1 of the API specification.
- `CL_DEVICE_IL_VERSION`, `CL_DEVICE_MAX_NUM_SUB_GROUPS`, `CL_DEVICE_SUB_GROUP_INDEPENDENT_FORWARD_PROGRESS` added to table 4.3 of the API specification.
- `CL_PROGRAM_IL` to table 5.17 of the API specification.
- `CL_QUEUE_DEVICE_DEFAULT` added to table 5.2 of the API specification.
- Added table 5.22 to the API specification with the enums: `CL_KERNEL_MAX_SUB_GROUP_SIZE_FOR_NDRANGE`, `CL_KERNEL_SUB_GROUP_COUNT_FOR_NDRANGE` and `CL_KERNEL_LOCAL_SIZE_FOR_SUB_GROUP_COUNT`.

The following modifications are made to the OpenCL 2.1 platform layer and runtime (sections 4 and 5):

- All API calls except `clSetKernelArg`, `clSetKernelArgSVMPointer`, `clSetKernelExecInfo` and `clCloneKernel` are thread-safe. Note that this statement does not imply that other API calls were not thread-safe in earlier versions of the specification.

Note that the OpenCL C kernel language is not updated for OpenCL 2.1. The OpenCL 2.0 kernel language will still be consumed by OpenCL 2.1 runtimes.

The SPIR-V and OpenCL SPIR-V Environment specifications have been added.

Summary of Changes from OpenCL 2.1 to OpenCL 2.2

The following changes have been made to the OpenCL 2.2 execution model (section 3)

- Added the third prerequisite (executing non-trivial constructors for program scope global variables).

The following features are added to the OpenCL 2.2 platform layer and runtime (sections 4 and 5):

- `clSetProgramSpecializationConstant` API call
- `clSetProgramReleaseCallback` API call
- Queries for `CL_PROGRAM_SCOPE_GLOBAL_CTORS_PRESENT` and `CL_PROGRAM_SCOPE_GLOBAL_DTORS_PRESENT`
The following modifications are made to the OpenCL 2.2 platform layer and runtime (section 4 and 5):

- Modified description of `CL_DEVICE_MAX_CLOCK_FREQUENCY` query.
- Added a new error code `CL_MAX_SIZE_RESTRICTION_EXCEEDED` to `clSetKernelArg` API call

Added definition of Deprecation and Specialization constants to the glossary.

## Summary of Changes from OpenCL 2.2 to OpenCL 3.0

OpenCL 3.0 is a major revision that breaks backwards compatibility with previous versions of OpenCL, see [OpenCL 3.0 Backwards Compatibility](#) for details.

OpenCL 3.0 adds new queries to determine optional capabilities for a device:

- `CL_DEVICE_ATOMIC_MEMORY_CAPABILITIES` and `CL_DEVICE_ATOMIC_FENCE_CAPABILITIES` to determine the atomic memory and atomic fence capabilities of a device.
- `CL_DEVICE_NON_UNIFORM_WORK_GROUP_SUPPORT` to determine if a device supports non-uniform work-group sizes.
- `CL_DEVICE_WORK_GROUP_COLLECTIVE_FUNCTIONS_SUPPORT` to determine whether a device supports optional work-group collective functions, such as broadcasts, scans, and reductions.
- `CL_DEVICE_GENERIC_ADDRESS_SPACE_SUPPORT` to determine whether a device supports the generic address space.
- `CL_DEVICE_DEVICE_ENQUEUE_CAPABILITIES` to determine the device-side enqueue capabilities of a device.
- `CL_DEVICEPIPE_SUPPORT` to determine whether a device supports pipe memory objects.
- `CL_DEVICE_PREFERRED_WORK_GROUP_SIZE_MULTIPLE` to determine the preferred work-group size multiple for a device.

OpenCL 3.0 adds new queries to conveniently and precisely describe supported features and versions:

- `CL_PLATFORM_NUMERIC_VERSION` to describe the platform version as a numeric value.
- `CL_PLATFORM_EXTENSIONS_WITH_VERSION` to describe supported platform extensions and their supported version.
- `CL_DEVICE_NUMERIC_VERSION` to describe the device version as a numeric value.
- `CL_DEVICE_EXTENSIONS_WITH_VERSION` to describe supported device extensions and their supported version.
- `CL_DEVICE_ILS_WITH_VERSION` to describe supported intermediate languages (ILs) and their supported version.
- `CL_DEVICE_BUILT_IN KERNELS WITH_VERSION` to describe supported built-in kernels and their supported version.

OpenCL 3.0 adds a new API to register a function that will be called when a context is destroyed,
enabling an application to safely free user data associated with a context callback function.

- `clSetContextDestructorCallback`

OpenCL 3.0 adds two new APIs to support creating buffer and image memory objects with additional properties. Although no new properties are added in OpenCL 3.0, these APIs enable new buffer and image extensions to be added easily and consistently:

- `clCreateBufferWithProperties`
- `clCreateImageWithProperties`

OpenCL 3.0 adds new queries for the properties arrays specified when creating buffers, images, pipes, samplers, and command-queues:

- `CL_MEM_PROPERTIES`
- `CL_PIPE_PROPERTIES`
- `CL_SAMPLER_PROPERTIES`
- `CL_QUEUE_PROPERTIES_ARRAY`

Program initialization and clean-up kernels are not supported in OpenCL 3.0 due to implementation complexity and lack of demand. The following APIs and queries for program initialization and clean-up kernels are deprecated in OpenCL 3.0:

- `CL_PROGRAM_SCOPE_GLOBAL_CTORS_PRESENT`
- `CL_PROGRAM_SCOPE_GLOBAL_DTORS_PRESENT`
- `clSetProgramReleaseCallback`

OpenCL 3.0 adds the OpenCL 3.0 C kernel language, which includes feature macros to describe OpenCL C language support. Please refer to the OpenCL C specification for details.

Scalar input arguments to the `any` and `all` built-in functions have been deprecated in the OpenCL 3.0 C kernel language. These functions behaved inconsistently with the C language's use of scalar integers as logical values.

OpenCL 3.0 adds new queries to determine supported OpenCL C language versions and supported OpenCL C features:

- `CL_DEVICE_OPENCL_C_ALL_VERSIONS` to determine the set of OpenCL C language versions supported by a device.
- `CL_DEVICE_OPENCL_C_FEATURES` to determine optional OpenCL C language features supported by a device.

OpenCL 3.0 adds an event command type to identify events associated with the OpenCL 2.1 command `clEnqueueSVMMigrateMem`:

- `CL_COMMAND_SVM_MIGRATE_MEM`

OpenCL 3.0 adds a new query to determine the latest version of the conformance test suite that the
device has fully passed in accordance with the official conformance process:

- CL_DEVICE_LATEST_CONFORMANCE_VERSION_PASSED

**Summary of Changes from OpenCL 3.0**

The first non-provisional version of the OpenCL 3.0 specifications was v3.0.5.

Changes from **v3.0.5**:

- Fixed the calculation in "mapping work-items onto an ND-range".
- Added new extensions:
  - cl_khr_extended_versioning
  - cl_khr_subgroup_extended_types
  - cl_khr_subgroup_non_uniform_vote
  - cl_khr_subgroup_ballot
  - cl_khr_subgroup_non_uniform_arithmetic
  - cl_khr_subgroup_shuffle
  - cl_khr_subgroup_shuffle_relative
  - cl_khr_subgroup_clustered_reduce

Changes from **v3.0.6**:

- Removed erroneous condition for CL_INVALID_KERNEL_ARGS.
- Fixed the spelling of -cl-no-signed-zeros.
- Clarified the table structure in the backwards compatibility appendix.
- Clarified that -cl-unsafe-math-optimizations also implies -cl-denorms-are-zero.
- Added new extensions:
  - cl_khr_extended_bit_ops
  - cl_khr_pci_bus_info
  - cl_khr_spirv_extended_debug_info
  - cl_khr_spirv_linkonce_odr
  - cl_khr_suggested_local_work_size

Changes from **v3.0.7**:

- Clarified optionality support for double-precision literals.
- Removed unnecessary phrase from sub-group mask function descriptions.
- Added `input_slice_pitch` error condition for read and write image APIs.
- Added new extension:
  - cl_khr_integer_dot_product
Changes from v3.0.8:

- Added a missing error condition for `clGetKernelSuggestedLocalWorkSizeKHR`.
- Clarified requirements for `CL_DEVICE_DOUBLE_FP_CONFIG` prior to OpenCL 2.0.
- Clarified the behavior of ballot operations for remainder sub-groups.
- Added new extensions:
  - `cl_khr_integer_dot_product` (version 2)
  - `cl_khr_semaphore` (provisional)
  - `cl_khr_external_semaphore` (provisional)
  - `cl_khr_external_semaphore_dx_fence` (provisional)
  - `cl_khr_external_semaphore_opaque_fd` (provisional)
  - `cl_khr_external_semaphore_sync_fd` (provisional)
  - `cl_khr_external_semaphore_win32` (provisional)
  - `cl_khr_external_memory` (provisional)
  - `cl_khr_external_memory_dma_buf` (provisional)
  - `cl_khr_external_memory_dx` (provisional)
  - `cl_khr_external_memory_opaque_fd` (provisional)
  - `cl_khr_external_memory_win32` (provisional)

Changes from v3.0.9:

- Relaxed memory object acquire error checking requirements for OpenGL, EGL, and DirectX interop extensions.
- Added a missing error condition for `clGetSemaphoreHandleForTypeKHR`.
- Clarified that `clCompileProgram` is valid for programs created from SPIR.
- Documented the possible state of a kernel object after a failed call to `clSetKernelArg`.
- Added new extensions:
  - `cl_khr_async_work_group_copy_fence` (final)
  - `cl_khr_extended_async_copies` (final)
  - `cl_khr_expect_ASSUME`
  - `cl_khr_command_buffer` (provisional)

Changes from v3.0.10:

- Added a requirement for implementations supporting device-side enqueue to also support program scope global variables.
- Added missing device scope atomic feature guards to several atomic function overloads.
- Added a possible error condition for `clGetEventProfilingInfo` for pre-OpenCL 3.0 devices.
- Added several missing error conditions for `clGetKernelSubGroupInfo`.
• Clarified the expected return value for the `CL_IMAGE_ROW_PITCH` and `CL_IMAGE_SLICE_PITCH` queries.

• Updated descriptions of the extended async copies functions to remove references to nonexistent function arguments.

• Clarified that the extended versioning extension is a core OpenCL 3.0 feature.

• Clarified sub-group clustered reduction behavior when the cluster size is not an integer constant or a power of two.

• Added new extensions:
  ◦ `cl_khr_subgroup_rotate`
  ◦ `cl_khr_work_group_uniform_arithmetic`

Changes from **v3.0.11**:

• Added a definition for a valid object and requirements for testing for valid objects.

• Added a maximum limit for the number of arguments supported by a kernel.

• Clarified requirements for comparability and uniqueness of object handles.

• Clarified behavior for invalid device-side enqueue `clk_event_t` handles.

• Clarified `cl_khr_command_buffer` interactions with other extensions.

• Specified error behavior when a command buffer is finalized multiple times.

• Added new extension:
  ◦ `cl_khr_command_buffer_mutable_dispatch` (provisional)

Changes from **v3.0.12**:

• Fixed the accuracy requirements description for half-precision math functions (those prefixed by `half`).

• Clarified that the semaphore type must always be provided when creating a semaphore.

• Removed an unnecessary and contradictory error condition when creating a semaphore.

• Added an issue regarding non-linear image import to the `cl_khr_external_memory` extension.

• Added missing calls to `clBuildProgram` to the `cl_khr_command_buffer` and `cl_khr_command_buffer_mutable_dispatch` sample code.

• Fixed a copy-paste error in the extensions quick reference appendix.

• Fixed typos and improved formatting consistency in the extensions spec.

Changes from **v3.0.13**:

• Corrected the precision for `cross` and `dot` to be based on `HALF_EPSILON` in `cl_khr_fp16`, see #893.

• Added a context query for command-buffers to `cl_khr_command_buffer`, see #899.

• Updated the semaphore wait and signal rules for binary semaphores in `cl_khr_semaphore`, see #882.

• Removed redundant error conditions from `cl_khr_external_semaphore` and `cl_khr_external_
memory, see #903 and #904.

- Added new extension:
  - `cl_khr_command_buffer_multi_device` (provisional)

Changes from v3.0.14:

- Clarified which error code should be returned when calling `clCreateBuffer` with a pointer to an SVM allocation that is too small, see #879.
- Improved capitalization and hyphenation consistency throughout the specs, see #902.
- Clarified that SVM is optional for all OpenCL 3.0 devices, see #913.
- Clarified that `clSetCommandQueueProperty` is only required for OpenCL 1.0 devices and may return an error otherwise, see #980.
- Clarified that the application must ensure the free function passed to `clEnqueueSVMFree` is thread safe, see #1016.
- Clarified that the application must ensure the user function passed to `clEnqueueNativeKernel` is thread safe, see #1026.
- `cl_khr_command_buffer` (provisional):
  - Removed the "invalid" command buffer state, see #885.
  - Added support for recording SVM memory copies and memory fills in a command buffer, see #915.
- `cl_khr_command_buffer_multi_device` (provisional):
  - Clarified that the sync devices query should only return root devices, see #925.
- `cl_khr_external_memory` (provisional):
  - Disallowed specifying a device handle list without also specifying an external memory handle, see #922.
  - Added a query to determine the handle types an implementation will assume have a linear memory layout, see #940.
  - Added an external memory-specific device handle list enum, see #956.
  - Clarified that implementations may acquire information about an image from an external memory handle when the image is created, see #970.
- `cl_khr_external_semaphore` (provisional):
  - Added the ability to re-import "sync fd" handles into an existing semaphore, see #939.
  - Clarified that a semaphore may only export one handle type, and that a semaphore created from an external handle cannot also export a handle, see #975.
  - Clarified that `cl_khr_external_semaphore` requires support for `cl_khr_semaphore`, see #976.
  - Added a query to determine if a semaphore may export an external handle, see #997.
- `cl_khr_semaphore` (provisional):
  - Added a semaphore-specific device handle list enum, see #956.
  - Restricted semaphores to a single associated device, see #996.
• **cl_khr_subgroup_rotate:**
  ◦ Clarified that only rotating within a subgroup is supported, see #967.

**Changes from v3.0.15:**

• Moved all KHR extension text out of the OpenCL Extension specification and into the main specifications. The OpenCL Extension specification will be removed in a subsequent revision.

• Clarified several error conditions that could return `CL_INVALID_PLATFORM`, see #1063.

• Strengthened requirements for the `CL_DEVICE_TYPE` query, see #1069.

• Clarified `clSetEventCallback` behavior for command errors, see #1071.

• Moved footnote text for `CL_KERNEL_ARG_TYPE_QUALIFIER` into the main spec, see #1097.

• **cl_khr_command_buffer_mutable_dispatch** (provisional):
  ◦ Added `CL_MUTABLE_DISPATCH_ASSERTS_KHR`, see #992.

• **cl_khr_semaphore**:
  ◦ Removed a redundant error condition, see #1052

• **The following extensions have been finalized and are no longer provisional:**
  ◦ `cl_khr_semaphore`
  ◦ `cl_khr_external_semaphore`
  ◦ `cl_khr_external_semaphore_opaque_fd`
  ◦ `cl_khr_external_semaphore_sync_fd`
  ◦ `cl_khr_external_memory`
  ◦ `cl_khr_external_memory_dma_buf`
  ◦ `cl_khr_external_memory_opaque_fd`
  ◦ `cl_khr_external_memory_win32`

• **Added new extension:**
  ◦ `cl_khr_kernel_clock` (provisional)
## Appendix F: Error Codes

This section lists OpenCL error codes and their meanings.

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Brief Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_SUCCESS</td>
<td>This is a special error code to indicate that the API executed successfully, without errors.</td>
</tr>
<tr>
<td>CL_BUILD_PROGRAM_FAILURE</td>
<td>Returned when <code>clBuildProgram</code> failed to build the specified program.</td>
</tr>
<tr>
<td>CL_COMPILE_PROGRAM_FAILURE</td>
<td>Returned when <code>clCompileProgram</code> failed to compile the specified program.</td>
</tr>
<tr>
<td>CL_COMPILER_NOT_AVAILABLE</td>
<td>Returned when compiling or building a program from source or IL when <code>CL_DEVICE_COMPILER_AVAILABLE</code> is <code>CL_FALSE</code>.</td>
</tr>
<tr>
<td>CL_DEVICE_NOT_FOUND</td>
<td>Returned when no devices were found that match the specified device type.</td>
</tr>
<tr>
<td>CL_DEVICE_NOT_AVAILABLE</td>
<td>Returned when attempting to use a device when <code>CL_DEVICE_AVAILABLE</code> is <code>CL_FALSE</code>.</td>
</tr>
<tr>
<td>CL_DEVICE_PARTITION_FAILED</td>
<td>Returned when device partitioning is supported but the device could not be further partitioned.</td>
</tr>
<tr>
<td>CL_EXEC_STATUS_ERROR_FOR_EVENTS_IN_WAIT_LIST</td>
<td>Returned by blocking APIs when an event in the event wait list has a negative value, indicating it is in an error state.</td>
</tr>
<tr>
<td>CL_IMAGE_FORMAT_MISMATCH</td>
<td>Returned when attempting to copy images that do not use the same image format.</td>
</tr>
<tr>
<td>CL_IMAGE_FORMAT_NOT_SUPPORTED</td>
<td>Returned when attempting to create or use an image format that is not supported.</td>
</tr>
<tr>
<td>CL_INVALID_ARG_INDEX</td>
<td>Returned when attempting to get or set a kernel argument using an invalid index for the specified kernel.</td>
</tr>
<tr>
<td>CL_INVALID_ARG_SIZE</td>
<td>Returned when the specified size of a kernel argument does not match the size of the kernel argument.</td>
</tr>
<tr>
<td>CL_INVALID_ARG_VALUE</td>
<td>Returned when attempting to set a kernel argument that is not valid.</td>
</tr>
<tr>
<td>CL_INVALID_BINARY</td>
<td>Returned when a program binary is not valid for a device.</td>
</tr>
<tr>
<td>CL_INVALID_BUFFER_SIZE</td>
<td>Returned when attempting to create a buffer or a sub-buffer with an invalid size.</td>
</tr>
<tr>
<td>CL_INVALID_BUILD_OPTIONS</td>
<td>Returned when build options passed to <code>clBuildProgram</code> are not valid.</td>
</tr>
<tr>
<td>Error Code</td>
<td>Brief Description</td>
</tr>
<tr>
<td>------------------------------------------</td>
<td>-----------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_INVALID_COMMAND_QUEUE</td>
<td>Returned when the specified command-queue is not a valid command-queue.</td>
</tr>
<tr>
<td>CL_INVALID_COMPILER_OPTIONS</td>
<td>Returned when compiler options passed to clCompileProgram are not valid.</td>
</tr>
<tr>
<td>missing before version 1.2.</td>
<td></td>
</tr>
<tr>
<td>CL_INVALID_CONTEXT</td>
<td>Returned when a specified context is not a valid context, or when mixing objects from multiple contexts.</td>
</tr>
<tr>
<td>CL_INVALID_DEVICE</td>
<td>Returned when a specified device is not a valid device.</td>
</tr>
<tr>
<td>CL_INVALID_DEVICE_PARTITION_COUNT</td>
<td>Returned when the requested device partitioning using CL_DEVICE_PARTITION_BY_COUNTS is not valid.</td>
</tr>
<tr>
<td>missing before version 1.2.</td>
<td></td>
</tr>
<tr>
<td>CL_INVALID_DEVICE_QUEUE</td>
<td>Returned when setting a device queue kernel argument to a value that is not a valid device command-queue.</td>
</tr>
<tr>
<td>missing before version 2.0.</td>
<td></td>
</tr>
<tr>
<td>CL_INVALID_DEVICE_TYPE</td>
<td>Returned when the requested device type is not a valid value.</td>
</tr>
<tr>
<td>CL_INVALID_EVENT</td>
<td>Returned when a specified event object is not a valid event object.</td>
</tr>
<tr>
<td>CL_INVALID_EVENT_WAIT_LIST</td>
<td>Returned when the specified event wait list or number of events in the wait list is not valid.</td>
</tr>
<tr>
<td>CL_INVALID_GLOBAL_OFFSET</td>
<td>Returned when the specified global offset and global work size exceeds the limits of the device.</td>
</tr>
<tr>
<td>CL_INVALID_GLOBAL_WORK_SIZE</td>
<td>Returned when the specified global work size exceeds the limits of the device.</td>
</tr>
<tr>
<td>CL_INVALID_HOST_PTR</td>
<td>Returned when the specified host pointer is not valid for the specified flags.</td>
</tr>
<tr>
<td>CL_INVALID_IMAGE_DESCRIPTOR</td>
<td>Returned when the specified image descriptor is NULL or specifies invalid values.</td>
</tr>
<tr>
<td>missing before version 1.2.</td>
<td></td>
</tr>
<tr>
<td>CL_INVALID_IMAGE_FORMAT_DESCRIPTOR</td>
<td>Returned when the specified image format descriptor is NULL or specifies invalid value.</td>
</tr>
<tr>
<td>CL_INVALID_IMAGE_SIZE</td>
<td>Returned when the specified image dimensions exceed the maximum dimensions for a device or all devices in a context.</td>
</tr>
<tr>
<td>CL_INVALID_KERNEL</td>
<td>Returned when the specified kernel is not a valid kernel object.</td>
</tr>
<tr>
<td>CL_INVALID_KERNEL_ARGS</td>
<td>Returned when enqueuing a kernel when some kernel arguments have not been set or are invalid.</td>
</tr>
<tr>
<td>Error Code</td>
<td>Brief Description</td>
</tr>
<tr>
<td>------------------------------------</td>
<td>---------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_INVALID_KERNEL_DEFINITION</td>
<td>Returned when creating a kernel for multiple devices where the number of kernel arguments or kernel argument types are not the same for all devices.</td>
</tr>
<tr>
<td>CL_INVALID_KERNEL_NAME</td>
<td>Returned when creating a kernel when no kernel with the specified name exists in the program object.</td>
</tr>
<tr>
<td>CL_INVALID_LINKER_OPTIONS</td>
<td>Returned when build options passed to clLinkProgram are not valid.</td>
</tr>
<tr>
<td>missing before version 1.2.</td>
<td></td>
</tr>
<tr>
<td>CL_INVALID_MEM_OBJECT</td>
<td>Returned when a specified memory object is not a valid memory object.</td>
</tr>
<tr>
<td>CL_INVALID_OPERATION</td>
<td>This is a generic error code that is returned when the requested operation is not a valid operation.</td>
</tr>
<tr>
<td>CL_INVALID_PIPE_SIZE</td>
<td>Returned when attempting to create a pipe with an invalid packet size or number of packets.</td>
</tr>
<tr>
<td>missing before version 2.0.</td>
<td></td>
</tr>
<tr>
<td>CL_INVALID_PLATFORM</td>
<td>Returned when the specified platform is not a valid platform.</td>
</tr>
<tr>
<td>CL_INVALID_PROGRAM</td>
<td>Returned when a specified program is not a valid program object.</td>
</tr>
<tr>
<td>CL_INVALID_PROGRAM_EXECUTABLE</td>
<td>Returned when the specified program is valid but has not been successfully built.</td>
</tr>
<tr>
<td>CL_INVALID_PROPERTY</td>
<td>Returned when a specified property name is invalid, when the value for a property name is invalid, or when the same property name is specified more than once.</td>
</tr>
<tr>
<td>missing before version 1.1.</td>
<td></td>
</tr>
<tr>
<td>CL_INVALID_QUEUE_PROPERTIES</td>
<td>Returned when specified queue properties are valid but are not supported by the device.</td>
</tr>
<tr>
<td>CL_INVALID_SAMPLER</td>
<td>Returned when a specified sampler is not a valid sampler object.</td>
</tr>
<tr>
<td>CL_INVALID_SPEC_ID</td>
<td>Returned when the specified specialization constant ID is not valid for the specified program.</td>
</tr>
<tr>
<td>missing before version 2.2.</td>
<td></td>
</tr>
<tr>
<td>CL_INVALID_VALUE</td>
<td>This is a generic error that is returned when a specified value is not a valid value.</td>
</tr>
<tr>
<td>CL_INVALID_WORK_DIMENSION</td>
<td>Returned by clEnqueueNDRangeKernel when the specified work dimension is not valid.</td>
</tr>
<tr>
<td>CL_INVALID_WORK_GROUP_SIZE</td>
<td>Returned by clEnqueueNDRangeKernel when the specified total work-group size is not valid for the specified kernel or device.</td>
</tr>
<tr>
<td>Error Code</td>
<td>Brief Description</td>
</tr>
<tr>
<td>------------------------------------------------</td>
<td>--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_INVALID_WORK_ITEM_SIZE</td>
<td>Returned by <code>clEnqueueNDRangeKernel</code> when the specified work-group size in one dimension is not valid for the device.</td>
</tr>
<tr>
<td>CL_KERNEL_ARG_INFO_NOT_AVAILABLE</td>
<td>Returned by <code>clGetKernelArgInfo</code> when kernel argument information is not available for the specified kernel.</td>
</tr>
<tr>
<td>CL_KERNEL_ARG_INFO_NOT_AVAILABLE</td>
<td>missing before version 1.2.</td>
</tr>
<tr>
<td>CL_LINK_PROGRAM_FAILURE</td>
<td>Returned by <code>clLinkProgram</code> when there is a failure to link the specified binaries or libraries.</td>
</tr>
<tr>
<td>CL_LINK_PROGRAM_FAILURE</td>
<td>missing before version 1.2.</td>
</tr>
<tr>
<td>CL_LINKER_NOT_AVAILABLE</td>
<td>Returned by <code>clLinkProgram</code> when <code>CL_DEVICE_LINKER_AVAILABLE</code> is <code>CL_FALSE</code>.</td>
</tr>
<tr>
<td>CL_LINKER_NOT_AVAILABLE</td>
<td>missing before version 1.2.</td>
</tr>
<tr>
<td>CL_MAP_FAILURE</td>
<td>Returned when there is a failure to map the specified region into the host address space.</td>
</tr>
<tr>
<td>CL_MEM_COPY_OVERLAP</td>
<td>Returned when copying from one region of a memory object to another where the source and destination regions overlap.</td>
</tr>
<tr>
<td>CL_MEM_OBJECT_ALLOCATION_FAILURE</td>
<td>Returned when there is a failure to allocate memory for a memory object.</td>
</tr>
<tr>
<td>CL_MISALIGNED_SUB_BUFFER_OFFSET</td>
<td>Returned when a sub-buffer object is created or used that is not aligned to <code>CL_DEVICE_MEM_BASE_ADDR_ALIGN</code> for the device.</td>
</tr>
<tr>
<td>CL_MISALIGNED_SUB_BUFFER_OFFSET</td>
<td>missing before version 1.1.</td>
</tr>
<tr>
<td>CL_OUT_OF_HOST_MEMORY</td>
<td>This is a generic error that is returned when memory could not be allocated on the host.</td>
</tr>
<tr>
<td>CL_OUT_OF_RESOURCES</td>
<td>This is a generic error that is returned when resources could not be allocated on the device.</td>
</tr>
<tr>
<td>CL_MAX_SIZE_RESTRICTION_EXCEEDED</td>
<td>Returned when the size of the specified kernel argument value exceeds the maximum size defined for the kernel argument.</td>
</tr>
<tr>
<td>CL_MAX_SIZE_RESTRICTION_EXCEEDED</td>
<td>missing before version 2.2.</td>
</tr>
<tr>
<td>CL_PROFILING_INFO_NOT_AVAILABLE</td>
<td>Returned by <code>clGetEventProfilingInfo</code> when the command associated with the specified event was not enqueued into a command-queue with <code>CL_QUEUE_PROFILING_ENABLE</code>.</td>
</tr>
<tr>
<td>CL_PROFILING_INFO_NOT_AVAILABLE</td>
<td></td>
</tr>
<tr>
<td>CL_INVALID_COMMAND_BUFFER_KHR</td>
<td>Returned when the specified command-buffer is not a valid command-buffer.</td>
</tr>
<tr>
<td>CL_INVALID_COMMAND_BUFFER_KHR</td>
<td>provided by the <code>cl_khr_command_buffer</code> extension.</td>
</tr>
<tr>
<td>CL_INVALID_SYNC_POINT_WAIT_LIST_KHR</td>
<td>Returned when the specified sync point wait list or number of sync points in the wait list is not valid.</td>
</tr>
<tr>
<td>CL_INVALID_SYNC_POINT_WAIT_LIST_KHR</td>
<td>provided by the <code>cl_khr_command_buffer</code> extension.</td>
</tr>
<tr>
<td>Error Code</td>
<td>Brief Description</td>
</tr>
<tr>
<td>------------------------------------------------</td>
<td>----------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>CL_INCOMPATIBLE_COMMAND_QUEUE_KHR</td>
<td>Returned when one or more command-queues is incompatible with a command-buffer.</td>
</tr>
<tr>
<td>provided by the cl_khr_command_buffer extension.</td>
<td></td>
</tr>
<tr>
<td>CL_INVALID_MUTABLE_COMMAND_KHR</td>
<td>Returned when a specified command is not a valid mutable-command object.</td>
</tr>
<tr>
<td>provided by the cl_khr_command_buffer_mutable_dispatch extension.</td>
<td></td>
</tr>
<tr>
<td>CL_INVALID_D3D10_DEVICE_KHR</td>
<td>Returned when a Direct3D 10 device cannot interoperate with OpenCL device IDs.</td>
</tr>
<tr>
<td>provided by the cl_khr_d3d10_sharing extension.</td>
<td></td>
</tr>
<tr>
<td>CL_INVALID_D3D10_RESOURCE_KHR</td>
<td>Returned when an OpenCL object cannot be created from a Direct3D 10 resource.</td>
</tr>
<tr>
<td>provided by the cl_khr_d3d10_sharing extension.</td>
<td></td>
</tr>
<tr>
<td>CL_D3D10_RESOURCE_ALREADY_ACQUIRED_KHR</td>
<td>Returned when attempting to acquire an OpenCL object created from a Direct3D 10 resource that was already acquired.</td>
</tr>
<tr>
<td>provided by the cl_khr_d3d10_sharing extension.</td>
<td></td>
</tr>
<tr>
<td>CL_D3D10_RESOURCE_NOT_ACQUIRED_KHR</td>
<td>Returned when attempting to release an OpenCL object created from a Direct3D 10 resource that has not been acquired.</td>
</tr>
<tr>
<td>provided by the cl_khr_d3d10_sharing extension.</td>
<td></td>
</tr>
<tr>
<td>CL_INVALID_D3D11_DEVICE_KHR</td>
<td>Returned when a Direct3D 11 device cannot interoperate with OpenCL device IDs.</td>
</tr>
<tr>
<td>provided by the cl_khr_d3d11_sharing extension.</td>
<td></td>
</tr>
<tr>
<td>CL_INVALID_D3D11_RESOURCE_KHR</td>
<td>Returned when an OpenCL object cannot be created from a Direct3D 11 resource.</td>
</tr>
<tr>
<td>provided by the cl_khr_d3d11_sharing extension.</td>
<td></td>
</tr>
<tr>
<td>CL_D3D11_RESOURCE_ALREADY_ACQUIRED_KHR</td>
<td>Returned when attempting to acquire an OpenCL object created from a Direct3D 11 resource that was already acquired.</td>
</tr>
<tr>
<td>provided by the cl_khr_d3d11_sharing extension.</td>
<td></td>
</tr>
<tr>
<td>CL_D3D11_RESOURCE_NOT_ACQUIRED_KHR</td>
<td>Returned when attempting to release an OpenCL object created from a Direct3D 11 resource that has not been acquired.</td>
</tr>
<tr>
<td>provided by the cl_khr_d3d11_sharing extension.</td>
<td></td>
</tr>
<tr>
<td>Error Code</td>
<td>Brief Description</td>
</tr>
<tr>
<td>------------------------------------------------</td>
<td>-----------------------------------------------------------------------------------</td>
</tr>
<tr>
<td><code>CL_INVALID_DX9_MEDIA_ADAPTER_KHR</code></td>
<td>Returned when a DirectX 9 media adapter cannot interoperate with OpenCL device IDs.</td>
</tr>
<tr>
<td>provided by the cl_khr_dx9_media_sharing extension.</td>
<td></td>
</tr>
<tr>
<td><code>CL_INVALID_DX9_MEDIA_SURFACE_KHR</code></td>
<td>Returned when an OpenCL object cannot be created from a DirectX 9 media surface.</td>
</tr>
<tr>
<td>provided by the cl_khr_dx9_media_sharing extension.</td>
<td></td>
</tr>
<tr>
<td><code>CL_DX9_MEDIA_SURFACE_ALREADY_ACQUIRED_KHR</code></td>
<td>Returned when attempting to acquire an OpenCL object created from a DirectX 9 media surface that was already acquired.</td>
</tr>
<tr>
<td>provided by the cl_khr_dx9_media_sharing extension.</td>
<td></td>
</tr>
<tr>
<td><code>CL_DX9_MEDIA_SURFACE_NOT_ACQUIRED_KHR</code></td>
<td>Returned when attempting to release an OpenCL object created from a DirectX 9 media surface that has not been acquired.</td>
</tr>
<tr>
<td>provided by the cl_khr_dx9_media_sharing extension.</td>
<td></td>
</tr>
<tr>
<td><code>CL_EGL_RESOURCE_NOT_ACQUIRED_KHR</code></td>
<td>Possible event status if an EGL resource is used without being acquired.</td>
</tr>
<tr>
<td>provided by the cl_khr_egl_image extension.</td>
<td></td>
</tr>
<tr>
<td><code>CL_INVALID_EGL_OBJECT_KHR</code></td>
<td>Returned when the specified EGL object is not valid.</td>
</tr>
<tr>
<td>provided by the cl_khr_egl_image extension.</td>
<td></td>
</tr>
<tr>
<td><code>CL_INVALID_GL_OBJECT</code></td>
<td>Returned when the specified OpenGL object is not valid, or when there is no associated OpenGL object for an OpenCL object.</td>
</tr>
<tr>
<td><code>CL_INVALID_GL_SHAREGROUP_REFERENCE_KHR</code></td>
<td>Returned when the specified OpenGL sharing context creation property is not valid.</td>
</tr>
<tr>
<td>provided by the cl_khr_gl_sharing extension.</td>
<td></td>
</tr>
<tr>
<td><code>CL_PLATFORM_NOT_FOUND_KHR</code></td>
<td>Returned by <code>clGetPlatformIDs</code> when no platforms are available.</td>
</tr>
<tr>
<td>provided by the cl_khr_icd extension.</td>
<td></td>
</tr>
<tr>
<td><code>CL_INVALID_SEMAPHORE_KHR</code></td>
<td>Returned when the specified semaphore is not a valid semaphore.</td>
</tr>
<tr>
<td>provided by the cl_khr_semaphore extension.</td>
<td></td>
</tr>
<tr>
<td>Error Code</td>
<td>Brief Description</td>
</tr>
<tr>
<td>------------</td>
<td>------------------</td>
</tr>
<tr>
<td>CL_CONTEXT_TERMINATED_KHR</td>
<td>Returned when the specified context has already been terminated, or as an event status for terminated commands.</td>
</tr>
</tbody>
</table>

provided by the cl_khr_terminate_context extension.
## Appendix G: Other Miscellaneous Enums

This section lists other miscellaneous OpenCL enumerants and their meanings.

<table>
<thead>
<tr>
<th>Enumerant</th>
<th>Brief Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CL_TRUE</td>
<td>Indicates a boolean &quot;true&quot; value.</td>
</tr>
<tr>
<td>CL_FALSE</td>
<td>Indicates a boolean &quot;false&quot; value.</td>
</tr>
<tr>
<td>CL_NONE</td>
<td>Indicates that none of the other enumerations or conditions are applicable.</td>
</tr>
<tr>
<td><strong>CL_BLOCKING</strong></td>
<td><strong>missing before</strong> version 1.2. **Alias of CL_TRUE that can be used to improve the</td>
</tr>
<tr>
<td></td>
<td>readability of calls to enqueue functions that can block.</td>
</tr>
<tr>
<td><strong>CL_NON_BLOCKING</strong></td>
<td><strong>missing before</strong> version 1.2. **Alias of CL_FALSE that can be used to improve the</td>
</tr>
<tr>
<td></td>
<td>readability of calls to enqueue function that can block.</td>
</tr>
</tbody>
</table>
Appendix H: OpenCL 3.0 Backwards Compatibility

OpenCL 3.0 breaks backwards compatibility with earlier versions of OpenCL by making some features that were previously required for FULL_PROFILE or EMBEDDED_PROFILE devices optional. This appendix describes the features that were previously required that are now optional, how to detect whether an optional feature is supported, and expected behavior when an optional feature is not supported.

Informally, in the tables below the first row usually describes a feature detection mechanism ("May return this value indicating that the feature is not supported") and subsequent rows usually describe behavior when a feature is not supported ("Returns this value if the feature is not supported").

Shared Virtual Memory

Shared Virtual Memory (SVM) is optional for devices supporting OpenCL 3.0. When Shared Virtual Memory is not supported:

<table>
<thead>
<tr>
<th>API</th>
<th>Behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td>clGetDeviceInfo, passing CL_DEVICE_SVM_CAPABILITIES</td>
<td>May return 0, indicating that device does not support Shared Virtual Memory.</td>
</tr>
<tr>
<td>clGetMemObjectInfo, passing CL_MEM_USES_SVM_POINTER</td>
<td>Returns CL_FALSE if no devices in the context associated with memobj support Shared Virtual Memory.</td>
</tr>
<tr>
<td>clSVMAlloc</td>
<td>Returns NULL if no devices in context support Shared Virtual Memory.</td>
</tr>
<tr>
<td>clSVMMalloc</td>
<td>Is a NOP if no devices in context support Shared Virtual Memory.</td>
</tr>
<tr>
<td>clEnqueueSVMMalloc, clEnqueueSVMMemcopy, clEnqueueSVMMemFill, clEnqueueSVMMemFill, clEnqueueSVMMemMap, clEnqueueSVMMemUnmap, clEnqueueSVMMigrateMem</td>
<td>Returns CL_INVALID_OPERATION if the device associated with command_queue does not support Shared Virtual Memory.</td>
</tr>
<tr>
<td>clSetKernelArgSVMPointer, clSetKernelExecInfo</td>
<td>Returns CL_INVALID_OPERATION if no devices in the context associated with kernel support Shared Virtual Memory.</td>
</tr>
</tbody>
</table>

Memory Consistency Model

Some aspects of the OpenCL memory consistency model are optional for devices supporting OpenCL 3.0. New device queries were added to clGetDeviceInfo to allow capabilities to be precisely reported. When the full memory consistency model is not supported:
<table>
<thead>
<tr>
<th>API</th>
<th>Behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>clGetDeviceInfo</strong>, passing</td>
<td>May return:</td>
</tr>
<tr>
<td>CL_DEVICE_ATOMIC_MEMORY_CAPABILITIES</td>
<td>CL_DEVICE_ATOMIC_ORDER_RELAXED</td>
</tr>
<tr>
<td></td>
<td>CL_DEVICE_ATOMIC_SCOPE_WORK_GROUP</td>
</tr>
<tr>
<td></td>
<td>indicating that <em>device</em> does not support the full memory consistency</td>
</tr>
<tr>
<td></td>
<td>model for atomic memory operations.</td>
</tr>
<tr>
<td></td>
<td>Note that a device that provides the same level of capabilities as an</td>
</tr>
<tr>
<td></td>
<td>OpenCL 2.x device would be expected to return:</td>
</tr>
<tr>
<td></td>
<td>CL_DEVICE_ATOMIC_ORDER_RELAXED</td>
</tr>
<tr>
<td></td>
<td>CL_DEVICE_ATOMIC_ORDER_ACQ_REL</td>
</tr>
<tr>
<td></td>
<td>CL_DEVICE_ATOMIC_ORDER_SEQ_CST</td>
</tr>
<tr>
<td></td>
<td>CL_DEVICE_ATOMIC_SCOPE_WORK_GROUP</td>
</tr>
<tr>
<td></td>
<td>CL_DEVICE_ATOMIC_SCOPE_DEVICE</td>
</tr>
<tr>
<td></td>
<td>CL_DEVICE_ATOMIC_SCOPE_ALL_DEVICES</td>
</tr>
<tr>
<td><strong>clGetDeviceInfo</strong>, passing</td>
<td>May return:</td>
</tr>
<tr>
<td>CL_DEVICE_ATOMIC_FENCE_CAPABILITIES</td>
<td>CL_DEVICE_ATOMIC_ORDER_RELAXED</td>
</tr>
<tr>
<td></td>
<td>CL_DEVICE_ATOMIC_ORDER_ACQ_REL</td>
</tr>
<tr>
<td></td>
<td>CL_DEVICE_ATOMIC_ORDER_SEQ_CST</td>
</tr>
<tr>
<td></td>
<td>CL_DEVICE_ATOMIC_SCOPE_WORK_GROUP</td>
</tr>
<tr>
<td></td>
<td>indicating that <em>device</em> does not support the full memory consistency</td>
</tr>
<tr>
<td></td>
<td>model for atomic fence operations.</td>
</tr>
<tr>
<td></td>
<td>Note that a device that provides the same level of capabilities as an</td>
</tr>
<tr>
<td></td>
<td>OpenCL 2.x device would be expected to return:</td>
</tr>
<tr>
<td></td>
<td>CL_DEVICE_ATOMIC_ORDER_RELAXED</td>
</tr>
<tr>
<td></td>
<td>CL_DEVICE_ATOMIC_ORDER_ACQ_REL</td>
</tr>
<tr>
<td></td>
<td>CL_DEVICE_ATOMIC_ORDER_SEQ_CST</td>
</tr>
<tr>
<td></td>
<td>CL_DEVICE_ATOMIC_SCOPE_WORK_ITEM</td>
</tr>
<tr>
<td></td>
<td>CL_DEVICE_ATOMIC_SCOPE_WORK_GROUP</td>
</tr>
<tr>
<td></td>
<td>CL_DEVICE_ATOMIC_SCOPE_DEVICE</td>
</tr>
<tr>
<td></td>
<td>CL_DEVICE_ATOMIC_SCOPE_ALL_DEVICES</td>
</tr>
</tbody>
</table>

OpenCL C compilers supporting atomics orders or scopes beyond the mandated minimum will define some or all of following feature macros as appropriate:

- `__opencl_c_atomic_order_` — Indicating atomic operations support acquire-release orderings.
- `__opencl_c_atomic_order_seq_cst` — Indicating atomic operations and fences support acquire sequentially consistent orderings.
---opencl_c_atomic_scope_device—Indicating atomic operations and fences support device-wide memory ordering constraints.

---opencl_c_atomic_scope_all_devices—Indicating atomic operations and fences support all-device memory ordering constraints, across any host threads and all devices that can share SVM memory with each other and the host process.

## Device-Side Enqueue

Device-side enqueue and on-device queues are optional for devices supporting OpenCL 3.0. When device-side enqueue is not supported:

<table>
<thead>
<tr>
<th>API</th>
<th>Behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td>clGetDeviceInfo, passing</td>
<td>May return 0, indicating that device does not support device-side enqueue and on-device queues.</td>
</tr>
<tr>
<td>CL_DEVICE_DEVICE_ENQUEUE_CAPABILITIES</td>
<td></td>
</tr>
<tr>
<td>clGetDeviceInfo, passing</td>
<td>Returns 0 if device does not support device-side enqueue and on-device queues.</td>
</tr>
<tr>
<td>CL_DEVICE_QUEUE_ON_DEVICE_PROPERTIES</td>
<td></td>
</tr>
<tr>
<td>clGetDeviceInfo, passing</td>
<td>Returns 0 if device does not support device-side enqueue and on-device queues.</td>
</tr>
<tr>
<td>CL_DEVICE_QUEUE_ON_DEVICE_PREFERRED_SIZE,</td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_QUEUE_ON_DEVICE_MAX_SIZE,</td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_MAX_ON_DEVICE_QUEUES,</td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_MAX_ON_DEVICE_EVENTS</td>
<td></td>
</tr>
<tr>
<td>clGetCommandQueueInfo, passing</td>
<td>Returns CL_INVALID_COMMAND_QUEUE since command_queue cannot be a valid device command-queue.</td>
</tr>
<tr>
<td>CL_QUEUE_SIZE</td>
<td></td>
</tr>
<tr>
<td>clGetCommandQueueInfo, passing</td>
<td>Returns NULL if the device associated with command_queue does not support on-device queues.</td>
</tr>
<tr>
<td>CL_QUEUE_DEVICE_DEFAULT</td>
<td></td>
</tr>
<tr>
<td>clGetEventProfilingInfo, passing</td>
<td>Returns a value equivalent to passing CL_PROFILING_COMMAND_END if the device associated with event does not support device-side enqueue.</td>
</tr>
<tr>
<td>CL_PROFILING_COMMAND_COMPLETE</td>
<td></td>
</tr>
<tr>
<td>clSetDefaultDeviceCommandQueue</td>
<td>Returns CL_INVALID_OPERATION if device does not support on-device queues.</td>
</tr>
</tbody>
</table>

When device-side enqueue is supported but a replaceable default on-device queue is not supported:

<table>
<thead>
<tr>
<th>API</th>
<th>Behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td>clGetDeviceInfo, passing</td>
<td>May omit CL_DEVICE_QUEUE_REPLACEABLE_DEFAULT, indicating that device does not support a replaceable default on-device queue.</td>
</tr>
<tr>
<td>CL_DEVICE_DEVICE_ENQUEUE_CAPABILITIES</td>
<td></td>
</tr>
<tr>
<td>clSetDefaultDeviceCommandQueue</td>
<td>Returns CL_INVALID_OPERATION if device does not support a replaceable default on-device queue.</td>
</tr>
</tbody>
</table>

OpenCL C compilers supporting device-side enqueue and on-device queues will define the feature macro __opencl_c_device_enqueue. OpenCL C compilers that define the feature macro __opencl_c_device_enqueue must also define the feature macro __opencl_c_generic_address_space because some
OpenCL C functions for device-side enqueue accept pointers to the generic address space. OpenCL C compilers that define the feature macro `__opencl_c_device_enqueue` must also define the feature macro `__opencl_c_program_scope_global_variables` because an implementation of blocks may interact with program scope variables in global address space as part of ABI.

## Pipes

Pipe memory objects are optional for devices supporting OpenCL 3.0. When pipes are not supported:

<table>
<thead>
<tr>
<th>API</th>
<th>Behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>clGetDeviceInfo</code>, passing <code>CL_DEVICE_PIPE_SUPPORT</code></td>
<td>May return <code>CL_FALSE</code>, indicating that device does not support pipes.</td>
</tr>
<tr>
<td><code>clGetDeviceInfo</code>, passing <code>CL_DEVICE_MAX_PIPE_ARGS</code>, <code>CL_DEVICE_PIPE_MAX_ACTIVE_RESERVATIONS</code>, or <code>CL_DEVICE_PIPE_MAX_PACKET_SIZE</code></td>
<td>Returns 0 if device does not support pipes.</td>
</tr>
<tr>
<td><code>clCreatePipe</code></td>
<td>Returns <code>CL_INVALID_OPERATION</code> if no devices in context support pipes.</td>
</tr>
<tr>
<td><code>clGetPipeInfo</code></td>
<td>Returns <code>CL_INVALID_MEM_OBJECT</code> since pipe cannot be a valid pipe object.</td>
</tr>
</tbody>
</table>

OpenCL C compilers supporting pipes will define the feature macro `__opencl_c_pipes`. OpenCL C compilers that define the feature macro `__opencl_c_pipes` must also define the feature macro `__opencl_c_generic_address_space` because some OpenCL C functions for pipes accept pointers to the generic address space.

## Program Scope Global Variables

Program scope global variables are optional for devices supporting OpenCL 3.0. When program scope global variables are not supported:

<table>
<thead>
<tr>
<th>API</th>
<th>Behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>clGetDeviceInfo</code>, passing <code>CL_DEVICE_MAX_GLOBAL_VARIABLE_SIZE</code></td>
<td>May return 0, indicating that device does not support program scope global variables.</td>
</tr>
<tr>
<td><code>clGetDeviceInfo</code>, passing <code>CL_DEVICE_GLOBAL_VARIABLE_PREFERRED_TOTAL_SIZE</code></td>
<td>Returns 0 if device does not support program scope global variables.</td>
</tr>
<tr>
<td><code>clGetProgramBuildInfo</code>, passing <code>CL_PROGRAM_BUILD_GLOBAL_VARIABLE_TOTAL_SIZE</code></td>
<td>Returns 0 if device does not support program scope global variables.</td>
</tr>
</tbody>
</table>

OpenCL C compilers supporting program scope global variables will define the feature macro `__opencl_c_program_scope_global_variables`. 
Non-Uniform Work-groups

Support for non-uniform work-groups is optional for devices supporting OpenCL 3.0. When non-uniform work-groups are not supported:

<table>
<thead>
<tr>
<th>API</th>
<th>Behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td>clGetDeviceInfo, passing</td>
<td>May return CL_FALSE, indicating that device does not support non-uniform work-groups.</td>
</tr>
<tr>
<td>CL_DEVICE_NON_UNIFORM_WORK_GROUP_SUPPORT</td>
<td></td>
</tr>
<tr>
<td>clEnqueueNDRangeKernel</td>
<td>Behaves as though non-uniform work-groups were not enabled for kernel, if the device associated with command_queue does not support non-uniform work-groups.</td>
</tr>
</tbody>
</table>

Read-Write Images

Read-write images, that may be read from and written to in the same kernel, are optional for devices supporting OpenCL 3.0. When read-write images are not supported:

<table>
<thead>
<tr>
<th>API</th>
<th>Behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td>clGetDeviceInfo, passing</td>
<td>May return 0, indicating that device does not support read-write images.</td>
</tr>
<tr>
<td>CL_DEVICE_MAX_READ_WRITE_IMAGE_ARGS</td>
<td></td>
</tr>
<tr>
<td>clGetSupportedImageFormats, passing</td>
<td>Returns an empty set (such as num_image_formats equal to 0), indicating that no image formats are supported for reading and writing in the same kernel, if no devices in context support read-write images.</td>
</tr>
<tr>
<td>CL_MEM_KERNEL_READ_AND_WRITE</td>
<td></td>
</tr>
</tbody>
</table>

OpenCL C compilers supporting read-write images will define the feature macro __opencl_c_read_write_images.

Creating 2D Images From Buffers

Creating a 2D image from a buffer is optional for devices supporting OpenCL 3.0. When creating a 2D image from a buffer is not supported:

<table>
<thead>
<tr>
<th>API</th>
<th>Behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td>clGetDeviceInfo, passing</td>
<td>May return 0, indicating that device does not support creating a 2D image from a Buffer.</td>
</tr>
<tr>
<td>CL_DEVICE_IMAGE_PITCH_ALIGNMENT or CL_DEVICE_IMAGE_BASE_ADDRESS_ALIGNMENT</td>
<td></td>
</tr>
<tr>
<td>clGetDeviceInfo, passing</td>
<td>Will not describe support for the cl_khr_image2d_from_buffer extension if device does not support creating a 2D image from a buffer.</td>
</tr>
<tr>
<td>CL_DEVICE_EXTENSIONS</td>
<td></td>
</tr>
</tbody>
</table>
**API** | **Behavior**
---|---
`clCreateImage` or `clCreateImageWithProperties`, passing `image_type` equal to `CL_MEM_OBJECT_IMAGE2D` and `mem_object` not equal to `NULL` | Returns `CL_INVALID_OPERATION` if no devices in `context` support creating a 2D image from a buffer.

### sRGB Images

All of the sRGB image channel orders (such as `CL_sRGBA`) are optional for devices supporting OpenCL 3.0. When sRGB images are not supported:

**API** | **Behavior**
---|---
`clGetSupportedImageFormats` | Will not return any image formats with `image_channel_order` equal to an sRGB image channel order if no devices in `context` support sRGB images.

### Depth Images

The `CL_DEPTH` image channel order is optional for devices supporting OpenCL 3.0. When depth images are not supported:

**API** | **Behavior**
---|---
`clGetSupportedImageFormats` | Will not return any image formats with `image_channel_order` equal to `CL_DEPTH` if no devices in `context` support depth images.

### Device and Host Timer Synchronization

Synchronizing the device and host timers is optional for platforms supporting OpenCL 3.0. When device and host timer synchronization is not supported:

**API** | **Behavior**
---|---
`clGetPlatformInfo`, passing `CL_PLATFORM_HOST_TIMER_RESOLUTION` | May return 0, indicating that `platform` does not support device and host timer synchronization.

### Intermediate Language Programs

Creating programs from an intermediate language (such as SPIR-V) is optional for devices supporting OpenCL 3.0. When intermediate language programs are not supported:
<table>
<thead>
<tr>
<th>API</th>
<th>Behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td>clGetDeviceInfo, passing</td>
<td>May return an empty string and empty array, indicating that device does not support intermediate language programs.</td>
</tr>
<tr>
<td>CL_DEVICE_IL_VERSION or</td>
<td></td>
</tr>
<tr>
<td>CL_DEVICE_ILS_WITH_VERSION</td>
<td></td>
</tr>
<tr>
<td>clGetProgramInfo, passing</td>
<td>Returns an empty buffer (such as param_value_size_ret equal to 0) if no devices in the context associated with program support intermediate language programs.</td>
</tr>
<tr>
<td>CL_PROGRAM_IL</td>
<td></td>
</tr>
<tr>
<td>clCreateProgramWithIL</td>
<td>Returns CL_INVALID_OPERATION if no devices in context support intermediate language programs.</td>
</tr>
<tr>
<td>clSetProgramSpecializationConstant</td>
<td>Returns CL_INVALID_OPERATION if no devices associated with program support intermediate language programs.</td>
</tr>
<tr>
<td>clGetKernelSubGroupInfo, passing</td>
<td>Returns 0 if device does not support intermediate language programs, since there is currently no way to require a number of sub-groups per work-group for programs created from source.</td>
</tr>
<tr>
<td>CL_KERNEL_COMPILE_NUM_SUB_GROUPS</td>
<td></td>
</tr>
</tbody>
</table>

## Sub-groups

Sub-groups are optional for devices supporting OpenCL 3.0. When sub-groups are not supported:

<table>
<thead>
<tr>
<th>API</th>
<th>Behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td>clGetDeviceInfo, passing</td>
<td>May return 0, indicating that device does not support sub-groups.</td>
</tr>
<tr>
<td>CL_DEVICE_MAX_NUM_SUB_GROUPS</td>
<td></td>
</tr>
<tr>
<td>clGetDeviceInfo, passing</td>
<td>Returns CL_FALSE if device does not support sub-groups.</td>
</tr>
<tr>
<td>CL_DEVICE_SUB_GROUP_INDEPENDENT_FORWARD_PROGRESS</td>
<td></td>
</tr>
<tr>
<td>clGetDeviceInfo, passing</td>
<td>Will not describe support for the cl_khr_subgroups extension if device does not support sub-groups.</td>
</tr>
<tr>
<td>CL_DEVICE_EXTENSIONS</td>
<td></td>
</tr>
<tr>
<td>clGetKernelSubGroupInfo</td>
<td>Returns CL_INVALID_OPERATION if device does not support sub-groups.</td>
</tr>
</tbody>
</table>

OpenCL C compilers supporting sub-groups will define the feature macro `__opencl_c_subgroups`.

## Program Initialization and Clean-Up Kernels

Program initialization and clean-up kernels are not supported in OpenCL 3.0, and the APIs and queries for program initialization and clean-up kernels are deprecated in OpenCL 3.0. When program initialization and clean-up kernels are not supported:
### API Behavior

<table>
<thead>
<tr>
<th>API</th>
<th>Behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>clGetProgramInfo</strong>, passing</td>
<td>Returns <strong>CL_FALSE</strong> if no devices in the context associated with <em>program</em> support program initialization and clean-up kernels.</td>
</tr>
<tr>
<td>CL_PROGRAM_SCOPE_GLOBAL_CTORS_PRESENT</td>
<td></td>
</tr>
<tr>
<td>CL_PROGRAM_SCOPE_GLOBAL_DTORS_PRESENT</td>
<td></td>
</tr>
<tr>
<td><strong>clSetProgramReleaseCallback</strong></td>
<td>Returns <strong>CL_INVALID_OPERATION</strong> if no devices in the context associated with <em>program</em> support program initialization and clean-up kernels.</td>
</tr>
</tbody>
</table>

### 3D Image Writes

Kernel built-in functions for writing to 3D image objects are optional for devices supporting OpenCL 3.0. When writing to 3D image objects is not supported:

<table>
<thead>
<tr>
<th>API</th>
<th>Behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>clGetDeviceInfo</strong>, passing</td>
<td>Will not describe support for the <strong>cl_khr_3d_image_writes</strong> extension if <em>device</em> does not support writing to 3D image objects.</td>
</tr>
<tr>
<td>CL_DEVICE_EXTENSIONS</td>
<td></td>
</tr>
<tr>
<td><strong>clGetSupportedImageFormats</strong>, passing</td>
<td>Returns an empty set (such as <em>num_image_formats</em> equal to 0), indicating that no image formats are supported for writing to 3D image objects, if no devices in <em>context</em> support writing to 3D image objects.</td>
</tr>
<tr>
<td>CL_MEM_OBJECT_IMAGE3D and one of</td>
<td></td>
</tr>
<tr>
<td>CL_MEM_WRITE_ONLY,</td>
<td></td>
</tr>
<tr>
<td>CL_MEM_READ_WRITE,</td>
<td></td>
</tr>
<tr>
<td>CL_MEM_KERNEL_READ_AND_WRITE</td>
<td></td>
</tr>
</tbody>
</table>

OpenCL C compilers supporting writing to 3D image objects will define the feature macro `__opencl_c_3d_image_writes`.

### Work-group Collective Functions

Work-group collective functions for broadcasts, scans, and reductions are optional for devices supporting OpenCL 3.0. When work-group collective functions are not supported:

<table>
<thead>
<tr>
<th>API</th>
<th>Behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>clGetDeviceInfo</strong>, passing</td>
<td>May return <strong>CL_FALSE</strong>, indicating that <em>device</em> does not support work-group collective functions.</td>
</tr>
<tr>
<td>CL_DEVICE_WORK_GROUP_COLLECTIVE_FUNCTIONS_SUPPORT</td>
<td></td>
</tr>
</tbody>
</table>

OpenCL C compilers supporting work-group collective functions will define the feature macro `__opencl_c_work_group_collective_functions`.

### Generic Address Space

Support for the generic address space is optional for devices supporting OpenCL 3.0. When the generic address space is not supported:
<table>
<thead>
<tr>
<th>API</th>
<th>Behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td>clGetDeviceInfo, passing</td>
<td>May return <strong>CL_FALSE</strong>, indicating that <em>device</em> does not support the generic address space.</td>
</tr>
<tr>
<td>CL_DEVICE_GENERIC_ADDRESS_SPACE_SUPPORT</td>
<td></td>
</tr>
</tbody>
</table>

OpenCL C compilers supporting the generic address space will define the feature macro `__opencl_c_generic_address_space`.

**Language Features That Were Already Optional**

Some OpenCL C language features were already optional before OpenCL 3.0, the API mechanisms for querying these have not changed.

New feature macros for these optional features have been added to OpenCL C to provide a consistent mechanism for using optional features in OpenCL C 3.0. OpenCL C compilers supporting images will define the feature macro `__opencl_c_images`. OpenCL C compilers supporting the *double* type will define the feature macro `__opencl_c_fp64`. OpenCL C compilers supporting the *long*, *unsigned long* and *ulong* types will define the feature macro `__opencl_c_int64`, note that compilers for FULL_PROFILE devices must support these types and define the macro unconditionally.
Appendix I: OpenCL Extensions (Informative)

Extensions to the OpenCL API can be defined by authors, groups of authors, and the Khronos OpenCL Working Group. The online Registry of extensions is available at URL

https://registry.khronos.org/OpenCL

It is possible to generate versions of the API Specification incorporating different extensions. At present only a subset of defined extensions can be incorporated in this fashion.

The remainder of this appendix documents a set of extensions chosen when this document was built.

Extensions are grouped as Khronos khr, multivendor ext, and then alphabetically by author ID. Within each group, extensions are listed in alphabetical order by their names.

Provisional Extensions

Provisional OpenCL extensions described in this appendix have been Ratified under the Khronos Intellectual Property Framework. They are being made publicly available as provisional extensions to enable review and feedback from the community. While an extension is provisional, features may be added, removed, or changed in non-backward compatible ways.

If you have feedback on a provisional extension, please create an issue on the OpenCL-Docs repository.

Extension Dependencies

Extensions which have dependencies on specific core versions or on other extensions will list such dependencies.

All extensions implicitly require support for OpenCL 1.0.

List of Current Extensions

- cl_khr_3d_image_writes
- cl_khr_async_work_group_copy_fence
- cl_khr_byte_addressable_store
- cl_khr_create_command_queue
- cl_khr_d3d10_sharing
- cl_khr_d3d11_sharing
- cl_khr_depth_images
- cl_khr_device_enqueue_local_arg_types
• cl_khr_device_uuid
• cl_khr_dx9_media_sharing
• cl_khr_egl_event
• cl_khr_egl_image
• cl_khr_expect_assume
• cl_khr_extended_async_copies
• cl_khr_extended_bit_ops
• cl_khr_extended_versioning
• cl_khr_external_memory
• cl_khr_external_memory_dma_buf
• cl_khr_external_memory_opaque_fd
• cl_khr_external_memory_win32
• cl_khr_external_semaphore
• cl_khr_external_semaphore_opaque_fd
• cl_khr_external_semaphore_sync_fd
• cl_khr_fp16
• cl_khr_fp64
• cl_khr_gl_depth_images
• cl_khr_gl_event
• cl_khr_gl_msaa_sharing
• cl_khr_gl_sharing
• cl_khr_global_int32_base_atomics
• cl_khr_global_int32_extended_atomics
• cl_khr_icd
• cl_khr_il_program
• cl_khr_image2d_from_buffer
• cl_khr_initialize_memory
• cl_khr_int64_base_atomics
• cl_khr_int64_extended_atomics
• cl_khr_integer_dot_product
• cl_khr_local_int32_base_atomics
• cl_khr_local_int32_extended_atomics
• cl_khr_mipmap_image
• cl_khr_mipmap_image_writes
• cl_khr_pci_bus_info
• cl_khr_priority_hints
• cl_khr_select_fprounding_mode
• cl_khr_semaphore
• cl_khr_spirv_extended_debug_info
• cl_khr_spirv_linkonce_odr
• cl_khr_spirv_no_integer_wrap-decoration
• cl_khr_srgb_image_writes
• cl_khr_subgroup_ballot
• cl_khr_subgroup_clustered_reduce
• cl_khr_subgroup_extended_types
• cl_khr_subgroup_named_barrier
• cl_khr_subgroup_non_uniform_arithmetic
• cl_khr_subgroup_non_uniform_vote
• cl_khr_subgroup_rotate
• cl_khr_subgroup_shuffle
• cl_khr_subgroup_shuffle_relative
• cl_khr_subgroups
• cl_khr_suggested_local_work_size
• cl_khr_terminate_context
• cl_khr_throttle_hints
• cl_khr_work_group_uniform_arithmetic
cl_khr_3d_image_writes

Name String
cl_khr_3d_image_writes

Ratification Status
Ratified

Extension and Version Dependencies
None

Deprecation State
• Promoted to OpenCL 2.0

Other Extension Metadata

Last Modified Date
2020-04-21

IP Status
No known IP claims.

Description

cl_khr_3d_image_writes adds built-in OpenCL C functions that allow a kernel to write to 3D image objects in addition to 2D image objects.

See the 3D Image Writes section of the OpenCL C specification for more information.

Version History

• Revision 1.0.0, 2020-04-21
  ◦ First assigned version.

cl_khr_async_work_group_copy_fence

Name String
cl_khr_async_work_group_copy_fence

Ratification Status
Ratified

Extension and Version Dependencies
None

Other Extension Metadata

Last Modified Date
2021-11-10
IP Status
No known IP claims.

Description
`cl_khr_async_work_group_copy_fence` adds a new built-in OpenCL C function to establish a memory synchronization ordering of asynchronous copies.

See the Async Work-group Copy Fence section of the OpenCL C specification for more information.

Version History
- Revision 0.9.0, 2020-04-21
  - First assigned version (provisional).
- Revision 1.0.0, 2021-11-10
  - First non-provisional version.

`cl_khr_byte_addressable_store`

Name String
`cl_khr_byte_addressable_store`

Ratification Status
Ratified

Extension and Version Dependencies
None

Deprecation State
- Promoted to OpenCL 1.1

Other Extension Metadata

Last Modified Date
2020-04-21

Interactions and External Dependencies
- Promoted to OpenCL 1.1 core

IP Status
No known IP claims.

Description
`cl_khr_byte_addressable_store` relaxes restrictions on pointers to `char`, `uchar`, `char2`, `uchar2`, `short`, `ushort` and `half` that were present in Section 6.8m: Restrictions of the OpenCL 1.0 specification. With this extension, applications are able to read from and write to pointers to these types.
This extension became a core feature in OpenCL 1.1.

See the Byte-Addressable Storage section of the OpenCL C specification for more information.

Version History

- Revision 1.0.0, 2020-04-21
  - First assigned version.

**cl_khr_create_command_queue**

Name String

cl_khr_create_command_queue

Ratification Status
Ratified

Extension and Version Dependencies
None

Deprecation State
- Promoted to OpenCL 2.0

Other Extension Metadata

Last Modified Date
2020-04-21

IP Status
No known IP claims.

Description

cl_khr_create_command_queue allows OpenCL 1.x devices to support an equivalent of the clCreateCommandQueueWithProperties API that was added in OpenCL 2.0. This allows OpenCL 1.x devices to support other optional extensions or features that use the clCreateCommandQueueWithProperties API to specify additional command-queue properties that cannot be specified using the OpenCL 1.x clCreateCommandQueue API.

No new command-queue properties are required by this extension. Applications may use the existing CL_DEVICE_QUEUE_PROPERTIES query to determine command-queue properties that are supported by the device.

Newer OpenCL devices may support this extension for compatibility. In this scenario, the function added by this extension will have the same capabilities as the core clCreateCommandQueueWithProperties API. Applications that only target newer OpenCL devices should use the core clCreateCommandQueueWithProperties API instead of this extension API.
New Commands

- clCreateCommandQueueWithPropertiesKHR

New Types

- cl_queue_propertiesKHR

Version History

- Revision 1.0.0, 2020-04-21
  - First assigned version.

cl_khr_d3d10_sharing

Name String

cl_khr_d3d10_sharing

Ratification Status

Ratified

Extension and Version Dependencies

None

Other Extension Metadata

Last Modified Date

2020-04-21

IP Status

No known IP claims.

Description

cl_khr_d3d10_sharing provides interoperability between OpenCL and Direct3D 10.

New Commands

- clGetDeviceIDsFromD3D10KHR
- clCreateFromD3D10BufferKHR
- clCreateFromD3D10Texture2DKHR
- clCreateFromD3D10Texture3DKHR
- clEnqueueAcquireD3D10ObjectsKHR
- clEnqueueReleaseD3D10ObjectsKHR
New Types

- cl_d3d10_device_source_khr
- cl_d3d10_device_set_khr

New Enums

- cl_d3d10_device_source_khr
  - CL_D3D10_DEVICE_KHR
  - CL_D3D10_DXGI_ADAPTER_KHR
- cl_d3d10_device_set_khr
  - CL_PREFERRED_DEVICES_FOR_D3D10_KHR
  - CL_ALL_DEVICES_FOR_D3D10_KHR
- cl_context_properties
  - CL_CONTEXT_D3D10DEVICE_KHR
- cl_context_info
  - CL_CONTEXT_D3D10_PREFER_SHARED_RESOURCES_KHR
- cl_mem_info
  - CL_MEM_D3D10RESOURCE_KHR
- cl_image_info
  - CL_IMAGE_D3D10_SUBRESOURCE_KHR
- cl_command_type
  - CL_COMMAND_ACQUIRE_D3D10OBJECTS_KHR
  - CL_COMMAND_RELEASE_D3D10OBJECTS_KHR

New Error Codes

- CL_INVALID_D3D10DEVICE_KHR
- CL_INVALID_D3D10RESOURCE_KHR
- CL_D3D10RESOURCE_ALREADY_ACQUIRED_KHR
- CL_D3D10RESOURCE_NOT_ACQUIRED_KHR

Issues

1. Should this extension be KHR or EXT?

   **PROPOSED:** KHR. If this extension is to be approved by Khronos then it should be KHR, otherwise EXT. Not all platforms can support this extension, but that is also true of OpenGL interop.

   **RESOLVED:** KHR.

2. Requiring SharedHandle on ID3D10Resource
Requiring this can largely simplify things at the DDI level and make some implementations faster. However, the DirectX spec only defines the shared handle for a subset of the resources we would like to support:

- **D3D10_RESOURCE_MISC_SHARED** - Enables the sharing of resource data between two or more Direct3D devices. The only resources that can be shared are 2D non-mipmapped textures.

**PROPOSED:** A: Add wording to the spec about some implementations needing the resource setup as shared:

Some implementations may require the resource to be shared on the D3D10 side of the API.

If we do that, do we need another enum to describe this failure case?

**PROPOSED:** B: Require that all implementations support both shared and non-shared resources. The restrictions prohibiting multisample textures and the flag `D3D10_USAGE_IMMUTABLE` guarantee software access to all shareable resources.

**RESOLVED:** Require that implementations support both `D3D10_RESOURCE_MISC_SHARED` being set and not set. Add the query for `CL_CONTEXT_D3D10_PREFER_SHARED_RESOURCES_KHR` to determine on a per-context basis which method will be faster.

3. Texture1D support

There is not a matching CL type, so do we want to support this and map to buffer or Texture2D?

**RESOLVED:** We will not add support for ID3D10Texture1D objects unless a corresponding OpenCL 1D Image type is created.

4. CL/D3D10 queries

The GL interop has `clGetGLObjectInfo` and `clGetGLTextureInfo`. It is unclear if these are needed on the D3D10 interop side since the D3D10 spec makes these queries trivial on the D3D10 object itself. Also, not all of the semantics of the GL call map across.

**PROPOSED:** Add the `clGetMemObjectInfo` and `clGetImageInfo` parameter names `CL_MEM_D3D10RESOURCE_KHR` and `CL_IMAGE_D3D10_SUBRESOURCE_KHR` to query the D3D10 resource from which a `cl_mem` was created. From this data, any D3D10 side information may be queried using the D3D10 API.

**RESOLVED:** We will use `clGetMemObjectInfo` and `clGetImageInfo` to access this information.

### Version History

- Revision 1.0.0, 2020-04-21
  - First assigned version.

### cl_khr_d3d11_sharing

**Name String**

- `cl_khr_d3d11_sharing`
Ratification Status
   Ratified

Extension and Version Dependencies
   None

Other Extension Metadata

Last Modified Date
   2020-04-21

IP Status
   No known IP claims.

Description
   cl_khr_d3d11_sharing provides interoperability between OpenCL and Direct3D 11.

New Commands
   • clGetDeviceIDsFromD3D11KHR
   • clCreateFromD3D11BufferKHR
   • clCreateFromD3D11Texture2DKHR
   • clCreateFromD3D11Texture3DKHR
   • clEnqueueAcquireD3D11ObjectsKHR
   • clEnqueueReleaseD3D11ObjectsKHR

New Types
   • cl_d3d11_device_source_khr
   • cl_d3d11_device_set_khr

New Enums
   • cl_d3d11_device_source_khr
     ◦ CL_D3D11_DEVICE_KHR
     ◦ CL_D3D11_DXGI_ADAPTER_KHR
   • cl_d3d11_device_set_khr
     ◦ CL_PREFERRED_DEVICES_FOR_D3D11_KHR
     ◦ CL_ALL_DEVICES_FOR_D3D11_KHR
   • cl_context_properties
     ◦ CL_CONTEXT_D3D11_DEVICE_KHR
   • cl_context_info
- `CL_CONTEXT_D3D11_PREFER_SHARED_RESOURCES_KHR`

- `cl_mem_info`
  - `CL_MEM_D3D11RESOURCE_KHR`

- `cl_image_info`
  - `CL_IMAGE_D3D11_SUBRESOURCE_KHR`

- `cl_command_type`
  - `CL_COMMAND_ACQUIRE_D3D11OBJECTS_KHR`
  - `CL_COMMAND_RELEASE_D3D11OBJECTS_KHR`

- **New Error Codes**
  - `CL_INVALID_D3D11DEVICE_KHR`
  - `CL_INVALID_D3D11RESOURCE_KHR`
  - `CL_D3D11RESOURCE_ALREADY_ACQUIRED_KHR`
  - `CL_D3D11RESOURCE_NOT_ACQUIRED_KHR`

**Version History**

- Revision 1.0.0, 2020-04-21
  - First assigned version.

**cl_khr_depth_images**

**Name String**

`cl_khr_depth_images`

**Ratification Status**

Ratified

**Extension and Version Dependencies**

None

**Deprecation State**

- *Promoted* to OpenCL 2.0

**Other Extension Metadata**

**Last Modified Date**

2020-04-21

**IP Status**

No known IP claims.
Description

`cl_khr_depth_images` adds OpenCL C support for depth images.

See the Depth Images section of the OpenCL C specification for more information.

Version History

- Revision 1.0.0, 2020-04-21
  - First assigned version.

**cl_khr_device_enqueue_local_arg_types**

Name String

`cl_khr_device_enqueue_local_arg_types`

Ratification Status

 Ratified

Extension and Version Dependencies

None

Other Extension Metadata

Last Modified Date

2020-04-21

IP Status

No known IP claims.

Description

`cl_khr_device_enqueue_local_arg_types` allows arguments to blocks that are passed to the `enqueue_kernel` built-in OpenCL C function to be pointers to any type (built-in or user-defined) in local memory, instead of requiring arguments to blocks to be pointers to void in local memory.

See the Device Enqueue Local Argument Types section of the OpenCL C specification for more information.

Version History

- Revision 1.0.0, 2020-04-21
  - First assigned version.

**cl_khr_device_uuid**

Name String

`cl_khr_device_uuid`
Ratification Status
   Ratified

Extension and Version Dependencies
   None

Other Extension Metadata

Last Modified Date
   2020-08-27

IP Status
   No known IP claims.

Description

`cl_khr_device_uuid` adds the ability to query a universally unique identifier (UUID) for an OpenCL driver and OpenCL device. The UUIDs returned by the query may be used to identify drivers and devices across processes or APIs.

New Enums

Accepted value for the `param_name` parameter to `clGetDeviceInfo`:

- `cl_device_info`
  - `CL_DEVICE_UUID_KHR`
  - `CL_DRIVER_UUID_KHR`
  - `CL_DEVICE_LUID_VALID_KHR`
  - `CL_DEVICE_LUID_KHR`
  - `CL_DEVICE_NODE_MASK_KHR`

- Constants describing the size of the driver and device UUIDs, and the device LUID:
  - `CL_UUID_SIZE_KHR`
  - `CL_LUID_SIZE_KHR`

Version History

- Revision 1.0.0, 2020-08-27
  - First assigned version.

`cl_khr_dx9_media_sharing`

Name String

`cl_khr_dx9_media_sharing`
Ratification Status
Ratified

Extension and Version Dependencies
None

Other Extension Metadata

Last Modified Date
2020-04-21

IP Status
No known IP claims.

Description

cl_khr_dx9_media_sharing allows applications to use media surfaces as OpenCL memory objects. This allows efficient sharing of data between OpenCL and selected adapter APIs (only DX9 for now). If this extension is supported, an OpenCL image object can be created from a media surface and the OpenCL API can be used to execute kernels that read and/or write memory objects that are media surfaces. Note that OpenCL memory objects may be created from the adapter media surface if and only if the OpenCL context has been created from that adapter.

New Commands

• clGetDeviceIDsFromDX9MediaAdapterKHR
• clCreateFromDX9MediaSurfaceKHR
• clEnqueueAcquireDX9MediaSurfacesKHR
• clEnqueueReleaseDX9MediaSurfacesKHR

New Types

• cl_dx9_media_adapter_type_khr
• cl_dx9_media_adapter_set_khr

New Enums

• cl_dx9_media_adapter_type_khr
  ◦ CL_ADAPTER_D3D9_KHR
  ◦ CL_ADAPTER_D3D9EX_KHR
  ◦ CL_ADAPTER_DXVA_KHR
• cl_dx9_media_adapter_set_khr
  ◦ CL_PREFERRED_DEVICES_FOR_DX9_MEDIA_ADAPTER_KHR
  ◦ CL_ALL_DEVICES_FOR_DX9_MEDIA_ADAPTER_KHR
• cl_context_info
• CL_CONTEXT_ADAPTER_D3D9_KHR
• CL_CONTEXT_ADAPTER_D3D9EX_KHR
• CL_CONTEXT_ADAPTER_DXVA_KHR

• cl_mem_info
  • CL_MEM_DX9_MEDIA_ADAPTER_TYPE_KHR
  • CL_MEM_DX9_MEDIA_SURFACE_INFO_KHR

• cl_image_info
  • CL_IMAGE_DX9_MEDIA_PLANE_KHR

• cl_command_type
  • CL_COMMAND_ACQUIRE_DX9_MEDIA_SURFACES_KHR
  • CL_COMMAND_RELEASE_DX9_MEDIA_SURFACES_KHR

• New Error Codes
  • CL_INVALID_DX9_MEDIA_ADAPTER_KHR
  • CL_INVALID_DX9_MEDIA_SURFACE_KHR
  • CL_DX9_MEDIA_SURFACE_ALREADY_ACQUIRED_KHR
  • CL_DX9_MEDIA_SURFACE_NOT_ACQUIRED_KHR

Version History

• Revision 1.0.0, 2020-04-21
  • First assigned version.

cl_khr_egl_event

Name String
  cl_khr_egl_event

Ratification Status
  Ratified

Extension and Version Dependencies
  None

Other Extension Metadata

Last Modified Date
  2020-04-21

IP Status
  No known IP claims.
Description

`cl_khr_egl_event` allows creating OpenCL event objects linked to EGL fence sync objects, potentially improving efficiency of sharing images and buffers between the two APIs. The companion `EGL_KHR_cl_event` extension provides the complementary functionality of creating an EGL sync object from an OpenCL event object.

New Commands

- `clCreateEventFromEGLSyncKHR`

New Enums

- `cl_command_type`
  - `CL_COMMAND_EGL_FENCE_SYNC_OBJECT_KHR`

Issues

Most issues are shared with `cl_khr_gl_event` and are resolved as described in that extension.

1. Should we support implicit synchronization?

   **RESOLVED**: No, as this may be very difficult since the synchronization would not be with EGL, it would be with currently bound EGL client APIs. It would be necessary to know which client APIs might be bound, to validate that they're associated with the `EGLDisplay` associated with the OpenCL context, and to reach into each such context.

2. Do we need to have typedefs to use EGL handles in OpenCL?

   **RESOLVED** Using typedefs for EGL handles.

3. Should we restrict which CL APIs can be used with this `cl_event`?

   **RESOLVED** Use is limited to calls to acquire and release memory objects only.

4. What is the desired behavior for this extension when EGLSyncKHR is of a type other than `EGL_SYNC_FENCE_KHR`?

   **RESOLVED** This extension only requires support for `EGL_SYNC_FENCE_KHR`. Support of other types is an implementation choice, and will result in `CL_INVALID_EGL_OBJECT_KHR` if unsupported.

Version History

- Revision 1.0.0, 2020-04-21
  - First assigned version.

`cl_khr_egl_image`

Name String

`cl_khr_egl_image`
Ratification Status  
Ratified  

Extension and Version Dependencies  
None  

Other Extension Metadata  

Last Modified Date  
2020-04-21  

IP Status  
No known IP claims.  

Description  

cl_khr_egl_image provides a mechanism to creating OpenCL memory objects from from EGLImages.  

New Commands  

• clCreateFromEGLImageKHR  
• clEnqueueAcquireEGLObjectsKHR  
• clEnqueueReleaseEGLObjectsKHR  

New Enums  

• cl_command_type  
  ◦ CL_COMMAND_ACQUIRE_EGL_OBJECTS_KHR  
  ◦ CL_COMMAND_RELEASE_EGL_OBJECTS_KHR  

• New Error Codes  
  ◦ CL_EGL_RESOURCE_NOT_ACQUIRED_KHR  
  ◦ CL_INVALID_EGL_OBJECT_KHR  

Issues  

1. This extension does not support reference counting of the images, so the onus is on the application to behave sensibly and not release the underlying cl_mem object while the EGLImage is still being used.  

2. In order to ensure data integrity, the application is responsible for synchronizing access to shared CL/EGL image objects by their respective APIs. Failure to provide such synchronization may result in race conditions and other undefined behavior. This may be accomplished by calling clWaitForEvents with the event objects returned by any OpenCL commands which use the shared image object or by calling clFinish.  

3. Currently CL_MEM_READ_ONLY is the only supported flag for flags.  

**RESOLVED:** Implementation will now return an error if writing to a shared object that is not
supported rather than disallowing it entirely.

4. Currently restricted to 2D image objects.

5. What should happen for YUV color-space conversion, multi plane images, and chroma-siting, and channel mapping?

**RESOLVED:** YUV is no longer explicitly described in this extension. Before this removal the behavior was dependent on the platform. This extension explicitly leaves the YUV layout to the platform and **EGLImage** source extension (i.e. is implementation specific). Colorspace conversion must be applied by the application using a color conversion matrix.

The expected extension path if YUV color-space conversion is to be supported is to introduce a YUV image type and provide overloaded versions of the read_image built-in functions.

Getting image information for a YUV image should return the original image size (non quantized size) when all of Y U and V are present in the image. If the planes have been separated then the actual dimensionality of the separated plane should be reported. For example with YUV 4:2:0 (NV12) with a YUV image of 256x256, the Y only image would return 256x256 whereas the UV only image would return 128x128.

6. Should an attribute list be used instead?

**RESOLVED:** function has been changed to use an attribute list.

7. What should happen for **EGLImage** extensions which introduce formats without a mapping to an OpenCL image channel data type or channel order?

**RESOLVED:** This extension does not define those formats. It is expected that as additional EGL extensions are added to create EGL images from other sources, an extension to CL will be introduced where needed to represent those image types.

8. What are the guarantees to synchronization behavior provided by the implementation?

The basic portable form of synchronization is to use a **clFinish**, as is the case for GL interop. In addition implementations which support the synchronization extensions **cl_khr_egl_event** and **EGL_KHR_cl_event** can interoperates more efficiently as described in those extensions.

**Version History**

- Revision 1.0.0, 2020-04-21
  - First assigned version.

**cl_khr_expect_assume**

**Name String**

**cl_khr_expect_assume**

**Ratification Status**

Ratified
Extension and Version Dependencies

None

Other Extension Metadata

Last Modified Date

2021-11-10

Interactions and External Dependencies

The initial version of this extension extends the OpenCL SPIR-V environment to support new instructions. Please refer to the OpenCL SPIR-V Environment Specification that describes how this extension modifies the OpenCL SPIR-V environment.

IP Status

No known IP claims.

Description

`cl_khr_expect_assume` adds mechanisms to provide information to the compiler that may improve the performance of some kernels. Specifically, this extension adds the ability to:

- Tell the compiler the *expected* value of a variable.
- Allow the compiler to *assume* a condition is true.

These functions are not required for functional correctness.

The initial version of this extension extends the OpenCL SPIR-V environment to support new instructions for offline compilation tool chains. Similar functionality may be provided by some OpenCL C online compilation tool chains, but formal support in OpenCL C is not required by the initial version of the extension.

Sample Code

Although this extension does not formally extend OpenCL C, the ability to provide *expect* and *assume* information is supported by many OpenCL C compiler tool chains. The sample code below describes how to test for and provide *expect* and *assume* information to compilers based on Clang:

```c
// __has_builtin is an optional compiler feature that is supported by Clang.
// If this feature is not supported, we will assume the builtin is not present.
#ifndef __has_builtin
#define __has_builtin(x)  0
#endif

kernel void test(global int* dst, global int* src)
{
    int value = src[get_global_id(0)];

    // Tell the compiler that the most likely source value is zero.
    #if __has_builtin(__builtin_expect)

    #endif
```
value = __builtin_expect(value, 0);
#endif

// Tell the compiler that the source value is non-negative.
// Behavior is undefined if the source value is actually negative.
#if __has_builtin(__builtin_assume)
__builtin_assume(value >= 0);
#endif

dst[get_global_id(0)] = value % 4;

Version History

• Revision 1.0.0, 2021-11-10
  ◦ First assigned version.

cl_khr_extended_async_copies

Name String
  cl_khr_extended_async_copies

Ratification Status
  Ratified

Extension and Version Dependencies
  None

Other Extension Metadata

Last Modified Date
  2021-11-10

IP Status
  No known IP claims.

Description

cl_khr_extended_async_copies augments built-in OpenCL C asynchronous copy functions to support more patterns:

1. For async copy between 2D source and 2D destination.
2. For async copy between 3D source and 3D destination.

See the Extended Async Copy Functions section of the OpenCL C specification for more information.
Version History

- Revision 0.9.0, 2020-04-21
  - First assigned version (provisional).
- Revision 0.9.1, 2021-09-06
  - Elements-based proposal update.
- Revision 1.0.0, 2021-11-10
  - First non-provisional version.

**cl_khr_extended_bit_ops**

**Name String**

cl_khr_extended_bit_ops

**Ratification Status**

Ratified

**Extension and Version Dependencies**

None

**Other Extension Metadata**

**Last Modified Date**

2021-04-22

**IP Status**

No known IP claims.

**Description**

*cl_khr_extended_bit_ops* adds built-in OpenCL C functions for performing extended bit operations. Specifically, the following functions are added:

- bitfield insert: insert bits from one source operand into another source operand.
- bitfield extract: extract bits from a source operand, with sign- or zero-extension.
- bit reverse: reverse the bits of a source operand.

See the [Extended Bit Operations](#) section of the OpenCL C specification for more information.

**Version History**

- Revision 1.0.0, 2021-04-22
  - Initial version.
cl_khr_extended_versioning

Name String

cl_khr_extended_versioning

Ratification Status

Ratified

Extension and Version Dependencies

None

Deprecation State

• Promoted to OpenCL 3.0

Other Extension Metadata

Last Modified Date

2020-02-12

IP Status

No known IP claims.

Contributors

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Description

The cl_khr_extended_versioning extension introduces new platform and device queries that return detailed version information to applications. It makes it possible to return the exact revision of the specification or intermediate languages supported by an implementation. It also enables implementations to communicate a version number for each of the extensions they support and remove the requirement for applications to process strings to test for the presence of an extension or intermediate language or built-in kernel.

Extended versioning was promoted to a core feature in OpenCL 3.0. However, the query for CL_DEVICE_OPENCL_C_NUMERIC_VERSION_KHR was replaced by the query for CL_DEVICE_OPENCL_C_ALL_VERSIONS. With the exception of this query, all types, structures, enums, and macro names defined by this extension are equivalent to the corresponding core name (with the _KHR or _khr suffix removed).

The version number encoding scheme is described in the Versioning section.

New Types

• cl_version_khr
New Structures

- cl_name_version_khr
- CL_NAME_VERSION_MAX_NAME_SIZE_KHR

New Macro Names

- CL_VERSION_MAJOR_BITS_KHR
- CL_VERSION_MINOR_BITS_KHR
- CL_VERSION_PATCH_BITS_KHR
- CL_VERSION_MAJOR_MASK_KHR
- CL_VERSION_MINOR_MASK_KHR
- CL_VERSION_PATCH_MASK_KHR
- CL_VERSION_MAJOR_KHR
- CL_VERSION_MINOR_KHR
- CL_VERSION_PATCH_KHR
- CL_MAKE_VERSION_KHR

New Enums

- cl_device_info
  - CL_DEVICE_NUMERIC_VERSION_KHR
  - CL_DEVICE_OPENCL_C_NUMERIC_VERSION_KHR
  - CL_DEVICE_EXTENSIONS_WITH_VERSION_KHR
  - CL_DEVICE_ILS_WITH_VERSION_KHR
  - CL_DEVICE_BUILT_IN_KERNELS_WITH_VERSION_KHR
- cl_platform_info
  - CL_PLATFORM_NUMERIC_VERSION_KHR
  - CL_PLATFORM_EXTENSIONS_WITH_VERSION_KHR

Conformance Tests

1. Each of the new queries described in this extension must be attempted and succeed.
2. It must be verified that the information returned by all queries that extend existing queries is consistent with the information returned by existing queries.
3. Some of the queries introduced by this extension impose uniqueness constraints on the list of returned values. It must be verified that these constraints are satisfied.

Issues

1. What compatibility policy should we define? e.g. a revision has to be backwards-compatible with previous ones
**RESOLVED:** No general rules as that wouldn’t be testable. Here’s a recommended policy:

- Patch version bump: only clarifications and small/obvious bugfixes.
- Minor version bump: backwards-compatible changes only.
- Major version bump: backwards compatibility may break.

2. Do we want versioning for built-in kernels as returned by `CL_DEVICE_BUILT_IN_KERNELS`?

**RESOLVED:** No immediate use-case for versioning but being able to get a list of individual kernels without parsing a string is desirable. Adding `CL_DEVICE_BUILT_IN_KERNELS_WITH_VERSION_KHR`.

3. What is the behaviour of the queries that return an array of structures when there are no elements to return?

**RESOLVED:** The query succeeds and the size returned is zero.

4. What value should be returned when version information is not available?

**RESOLVED:** If a patch version is not available, it should be reported as 0. If no version information is available, 0.0.0 should be reported. These values have been chosen as they are guaranteed to be lower than or equal to any other version.

5. Should we add a query to report SPIR-V extended instruction sets?

**RESOLVED:** It is unlikely that we will introduce many SPIR-V extended instruction sets without an accompanying API extension. Decided not to do this.

6. Should the queries for which the old-style query doesn’t exist in a given OpenCL version be present (e.g. `CL_DEVICE_BUILT_IN_KERNELS_WITH_VERSION_KHR` prior to OpenCL 2.1 or without support for `cl_khr_il_program` or `CL_DEVICE_OPENCL_C_NUMERIC_VERSION_KHR` on OpenCL 1.0)?

**RESOLVED:** All the queries are always present. `CL_DEVICE_BUILT_IN_KERNELS_WITH_VERSION_KHR` returns an empty set when Intermediate Languages are not supported. `CL_DEVICE_OPENCL_C_NUMERIC_VERSION_KHR` always returns 1.0 on an OpenCL 1.0 platform.

7. Is reporting multiple Intermediate Languages with the same name and major/minor versions but differing patch versions allowed?

**RESOLVED:** No. This isn’t aligned with the intended use for patch versions and makes it harder for implementations to guarantee consistency with the existing IL queries.

**Version History**

- Revision 1.0.0, 2020-02-12
  - Initial version.

**cl_khr_external_memory**
cl_khr_external_memory defines a generic mechanism to share buffer and image objects between OpenCL and many other APIs, including:

- Optional properties to import external memory exported by other APIs into OpenCL for a set of
devices.

- Routines to explicitly hand off memory ownership between OpenCL and other APIs.

Other related extensions define specific external memory types that may be imported into OpenCL.

New Commands

- clEnqueueAcquireExternalMemObjectsKHR
- clEnqueueReleaseExternalMemObjectsKHR

New Types

- cl_external_memory_handle_type_khr

New Enums

- cl_platform_info
  - CL_PLATFORM_EXTERNAL_MEMORY_IMPORT_HANDLE_TYPES_KHR
- cl_device_info
  - CL_DEVICE_EXTERNAL_MEMORY_IMPORT_HANDLE_TYPES_KHR
  - CL_DEVICE_EXTERNAL_MEMORY_IMPORT_ASSUME_LINEAR_IMAGES_HANDLE_TYPES_KHR
- cl_mem_properties
  - CL_MEM_DEVICE_HANDLE_LIST_KHR
  - CL_MEM_DEVICE_HANDLE_LIST_END_KHR

- Return values from clGetEventInfo when param_name is cl_command_type:
  - CL_COMMAND_ACQUIRE_EXTERNAL_MEM_OBJECTS_KHR
  - CL_COMMAND_RELEASE_EXTERNAL_MEM_OBJECTS_KHR

Sample Code

Example for Creating a CL Buffer From an Exported External Buffer in a Single Device Context

This example also requires use of the cl_khr_external_memory_opaque_fd extension.

```c
// Get cl_devices of the platform.
clGetDeviceIDs(..., &devices, &deviceCount);

// Create cl_context with just first device
clCreateContext(..., 1, devices, ...);

// Obtain fd/win32 or similar handle for external memory to be imported
// from other API.
int fd = getFdForExternalMemory();

// Create extMemBuffer of type cl_mem from fd.
```
cl_mem_properties_khr extMemProperties[] =
{
    (cl_mem_properties_khr)CL_EXTERNAL_MEMORY_HANDLE_OPAQUE_FD_KHR,
    (cl_mem_properties_khr)fd,
    0
};

cl_mem extMemBuffer = clCreateBufferWithProperties(/*context*/clContext,
                                                 /*properties*/extMemProperties,
                                                 /*flags*/0,
                                                 /*size*/size,
                                                 /*host_ptr*/NULL,
                                                 /*errcode_ret*/&errcode_ret);

Example for Creating a CL Image From an Exported External Image for Single Device Usage in a Multi-Device Context

This example also requires use of the cl_khr_external_memory_opaque_fd extension.

// Get cl_devices of the platform.
clGetDeviceIDs(..., &devices, &deviceCount);

// Create cl_context with first two devices
clCreateContext(..., 2, devices, ...);

// Create img of type cl_mem usable only on devices[0]

// Create img of type cl_mem.
// Obtain fd/win32 or similar handle for external memory to be imported
// from other API.
int fd = getFdForExternalMemory();

// Set cl_image_format based on external image info
cl_image_format clImgFormat = { };
clImageFormat.image_channel_order = CL_RGBA;
clImageFormat.image_channel_data_type = CL_UNORM_INT8;

// Set cl_image_desc based on external image info
size_t clImageFormatSize = { };
cl_image_desc image_desc = { };
image_desc.image_type = CL_MEM_OBJECT_IMAGE2D_ARRAY;
image_desc.image_width = width;
image_desc.image_height = height;
image_desc.image_depth = depth;
image_desc.image_array_size = num_slices;
image_desc.image_row_pitch = width * 8 * 4; // May need alignment
image_desc.image_slice_pitch = image_desc.image_row_pitch * height;
image_desc.num_mip_levels = 1;
image_desc.num_samples = 0;
image_desc.buffer = NULL;

cl_mem_properties_khr extMemProperties[] = {
    (cl_mem_properties_khr)CL_EXTERNAL_MEMORY_HANDLE_OPAQUE_FD_KHR,
    (cl_mem_properties_khr)fd,
    (cl_mem_properties_khr)CL_MEM_DEVICE_HANDLE_LIST_KHR,
    (cl_mem_properties_khr)devices[0],
    CL_MEM_DEVICE_HANDLE_LIST_END_KHR,
    0
};

cl_mem img = clCreateImageWithProperties(/*context*/ clContext,
    /*properties*/ extMemProperties,
    /*flags*/ 0,
    /*image_format*/ &clImgFormat,
    /*image_desc*/ &image_desc,
    /*errcode_ret*/ &errcode_ret);

// Use clGetImageInfo to get cl_image_format details.
size_t clImageFormatSize;
clGetImageInfo(img,
    CL_IMAGE_FORMAT, sizeof(cl_image_format),
    &clImageFormat,
    &clImageFormatSize);

Example for Synchronization Using Wait and Signal

// Start the main rendering loop

// Create extSem of type cl_semaphore_khr using clCreateSemaphoreWithPropertiesKHR

// Create extMem of type cl_mem using clCreateBufferWithProperties or clCreateImageWithProperties

while (true) {
    // (not shown) Signal the semaphore from the other API

    // Wait for the semaphore in OpenCL, by calling clEnqueueWaitSemaphoresKHR on 'extSem'
    clEnqueueWaitSemaphoresKHR(/*command_queue*/ command_queue,
        /*num_sema_objects*/ 1,
        /*sema_objects*/ &extSem,
        /*sema_payload_list*/ NULL,
        /*num_events_in_wait_list*/ 0,
        /*event_wait_list*/ NULL,
        /*event*/ NULL);

    // Launch kernel that accesses extMem
    clEnqueueNDRangeKernel(command_queue, ...);
// Signal the semaphore in OpenCL
clEnqueueSignalSemaphoresKHR(/*command_queue*/         command_queue,
    /*num_sema_objects*/  1,
    /*sema_objects*/     &extSem,
    /*sema_payload_list*/ NULL,
    /*num_events_in_wait_list*/ NULL,
    /*event_wait_list*/   NULL,
    /*event*/            NULL);

// (not shown) Launch work in other API that waits on 'extSem'
}

Example With Memory Sharing Using Acquire/Release

// Create extSem of type cl_semaphore_khr using
// clCreateSemaphoreWithPropertiesKHR with CL_SEMAPHORE_HANDLE_*_KHR.
// Create extMem1 and extMem2 of type cl_mem using clCreateBufferWithProperties
// or clCreateImageWithProperties

while (true) {
    // (not shown) Signal the semaphore from the other API. Wait for the
    // semaphore in OpenCL, by calling clEnqueueWaitForSemaphore on extSem
    clEnqueueWaitSemaphoresKHR(/*command_queue*/         cq1,
        /*num_sema_objects*/  1,
        /*sema_objects*/     &extSem,
        /*sema_payload_list*/ NULL,
        /*num_events_in_wait_list*/ NULL,
        /*event_wait_list*/   NULL,
        /*event*/            NULL);

    // Get explicit ownership of extMem1
    clEnqueueAcquireExternalMemObjectsKHR(/*command_queue*/      cq1,
        /*num_mem_objects*/  1,
        /*mem_objects*/     extMem1,
        /*num_events_in_wait_list*/   NULL,
        /*event_wait_list*/  NULL,
        /*event*/           NULL);

    // Launch kernel that accesses extMem1 on cq1 on cl_device1
    clEnqueueNDRangeKernel(cq1, ... , &event1);

    // Launch kernel that accesses both extMem1 and extMem2 on cq2 on cl_device2
    // Migration of extMem1 and extMem2 handles through regular CL memory
    // migration.
    clEnqueueNDRangeKernel(cq2, ... , &event1, &event2);

    // Give up ownership of extMem1 before you signal the semaphore. Handle
    // memory migration here.
clEnqueueReleaseExternalMemObjectsKHR( /*command_queue*/ cq2,
    /*num_mem_objects*/ 1,
    /*mem_objects*/ &extMem1,
    /*num_events_in_wait_list*/ 0,
    /*event_wait_list*/ NULL,
    /*event*/ NULL);

// Signal the semaphore from OpenCL
clEnqueueSignalSemaphoresKHR( /*command_queue*/ cq2,
    /*num_sema_objects*/ 1,
    /*sema_objects*/ &extSem,
    /*sema_payload_list*/ NULL,
    /*num_events_in_wait_list*/ 0,
    /*event_wait_list*/ NULL,
    /*event*/ NULL);

// (not shown) Launch work in other API that waits on 'extSem'
// Other API accesses ext1, but not ext2 on device-1

// Issues

1. How should the import of images that are created in external APIs with non-linear tiling be robustly handled?

   UNRESOLVED

// Version History

• Revision 0.9.0, 2021-09-10
  ◦ Initial version (provisional).

• Revision 0.9.1, 2023-05-04
  ◦ Clarified device handle list enum cannot be specified without an external memory handle (provisional).

• Revision 0.9.2, 2023-08-01
  ◦ Changed device handle list enum to the memory-specific CL_MEM_DEVICE_HANDLE_LIST_KHR (provisional).

• Revision 0.9.3, 2023-08-29
  ◦ Added query for CL_DEVICE_EXTERNAL_MEMORY_IMPORT_ASSUME_LINEAR_IMAGES_HANDLE_TYPES_KHR (provisional).

• Revision 1.0.0, 2024-03-15
  ◦ First non-provisional version.

// cl_khr_external_memory_dma_buf
Name String
cl_khr_external_memory_dma_buf

Ratification Status
Ratified

Extension and Version Dependencies
OpenCL 3.0
and
cl_khr_external_memory

Other Extension Metadata

Last Modified Date
2024-03-15

IP Status
No known IP claims.

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Description
cl_khr_external_memory_dma_buf extends cl_external_memory_handle_type_khr to support Linux dma_buf as an external memory handle type that may be specified when creating a buffer or image
memory object.

New Enums

- cl_external_memory_handle_type_khr
  - CL_EXTERNAL_MEMORY_HANDLE_DMA_BUF_KHR

Version History

- Revision 0.9.0, 2021-09-10
  - Initial version (provisional).

- Revision 0.9.1, 2023-05-04
  - Clarified device handle list enum cannot be specified without an external memory handle (provisional).

- Revision 0.9.2, 2023-08-01
  - Changed device handle list enum to the memory-specific cl_mem_device_handle_list_khr (provisional).

- Revision 0.9.3, 2023-08-29
  - Added query for CL_DEVICE_EXTERNAL_MEMORY_IMPORT_ASSUME_LINEAR_IMAGES_HANDLE_TYPES_KHR (provisional).

- Revision 1.0.0, 2024-03-15
  - First non-provisional version.

cl_khr_external_memory_opaque_fd

Name String

- cl_khr_external_memory_opaque_fd

Ratification Status

- Ratified

Extension and Version Dependencies

- OpenCL 3.0
  - and
  - cl_khr_external_memory

Other Extension Metadata

Last Modified Date

- 2024-03-15

IP Status

- No known IP claims.
Contributors

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Description

`cl_khr_external_memory_opaque_fd` extends `cl_external_memory_handle_type_khr` to support a POSIX file descriptor handle as an external memory handle type that may be specified when creating a buffer or image memory object.

New Enums

- `cl_external_memory_handle_type_khr`
  - `CL_EXTERNAL_MEMORY_HANDLE_OPAQUE_FD_KHR`

Version History

- Revision 0.9.0, 2021-09-10
  - Initial version (provisional).
- Revision 0.9.1, 2023-05-04
  - Clarified device handle list enum cannot be specified without an external memory handle (provisional).
- Revision 0.9.2, 2023-08-01
  - Changed device handle list enum to the memory-specific `CL_MEM_DEVICE_HANDLE_LIST_KHR` (provisional).
• Revision 0.9.3, 2023-08-29
  ◦ Added query for `CL_DEVICE_EXTERNAL_MEMORY_IMPORT_ASSUME_LINEAR_IMAGES_HANDLE_TYPES_KHR` (provisional).
• Revision 1.0.0, 2024-03-15
  ◦ First non-provisional version.

`cl_khr_external_memory_win32`

**Name String**

`cl_khr_external_memory_win32`

**Ratification Status**

Ratified

**Extension and Version Dependencies**

- OpenCL 3.0
- and
- `cl_khr_external_memory`

**Other Extension Metadata**

**Last Modified Date**

2024-03-15

**IP Status**

No known IP claims.

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Description

cl_khr_external_memory_win32 extends cl_external_memory_handle_type_khr to support Windows handles as external memory handle types that may be specified when creating a buffer or image memory object.

New Enums

- cl_external_memory_handle_type_khr
  - CL_EXTERNAL_MEMORY_HANDLE_OPAQUE_WIN32_KHR
  - CL_EXTERNAL_MEMORY_HANDLE_OPAQUE_WIN32_KMT_KHR

Version History

- Revision 0.9.0, 2021-09-10
  - Initial version (provisional).
- Revision 0.9.1, 2023-05-04
  - Clarified device handle list enum cannot be specified without an external memory handle (provisional).
- Revision 0.9.2, 2023-08-01
  - Changed device handle list enum to the memory-specific CL_MEM_DEVICE_HANDLE_LIST_KHR (provisional).
- Revision 0.9.3, 2023-08-29
  - Added query for CL_DEVICE_EXTERNAL_MEMORY_IMPORT_ASSUME_LINEAR_IMAGES_HANDLE_TYPES_KHR (provisional).
- Revision 1.0.0, 2024-03-15
  - First non-provisional version.

cl_khr_external_semaphore

Name String

cl_khr_external_semaphore

Ratification Status

Ratified

Extension and Version Dependencies

OpenCL 1.2
and
cl_khr_semaphore
Other Extension Metadata

Last Modified Date

2024-03-15

Interactions and External Dependencies

- This extension requires OpenCL 1.2.
- The cl_khr_semaphore extension is required as it defines semaphore objects as well as for wait and signal operations on semaphores.
- For OpenCL to be able to import external semaphores from other APIs using this extension, the other API is required to provide below mechanisms:
  - Ability to export semaphore handles
  - Ability to query semaphore handle in the form of one of the handle type supported by OpenCL.
- The other APIs that want to use semaphore exported by OpenCL using this extension are required to provide below mechanism:
  - Ability to import semaphore handles using handle types exported by OpenCL.

IP Status

No known IP claims.

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Description

c_l_khr_semaphore introduced semaphores as a new type along with a set of APIs for create, release, retain, wait and signal operations on it. This extension defines APIs and mechanisms to share semaphores created in an external API by importing into and exporting from OpenCL.

This extension defines:

- New attributes that can be passed as part of cl_semaphore_properties_khr for specifying properties of external semaphores to be imported or exported.
- New attributes that can be passed as part of cl_semaphore_info_khr for specifying properties of external semaphores to be exported.
- An extension to clCreateSemaphoreWithPropertiesKHR to accept external semaphore properties allowing to import or export an external semaphore into or from OpenCL.
- Semaphore handle types required for importing and exporting semaphores.
- Modifications to Wait and Signal API behavior when dealing with external semaphores created from different handle types.
- API query exportable semaphores handles using specified handle type.

The layered extensions cl_khr_external_semaphore_dx_fence, cl_khr_external_semaphore_opaque_fd, cl_khr_external_semaphore_sync_fd, and cl_khr_external_semaphore_win32 define specific external semaphores that may be imported into or exported from OpenCL.

New Types

- cl_external_semaphore_handle_type_khr

New Enums

- cl_platform_info
  - CL_PLATFORM_SEMAPHORE_IMPORT_HANDLE_TYPES_KHR
  - CL_PLATFORM_SEMAPHORE_EXPORT_HANDLE_TYPES_KHR
- cl_device_info
  - CL_DEVICE_SEMAPHORE_IMPORT_HANDLE_TYPES_KHR
  - CL_DEVICE_SEMAPHORE_EXPORT_HANDLE_TYPES_KHR
- cl_semaphore_properties_khr and cl_semaphore_info_khr:
  - CL_SEMAPHORE_EXPORT_HANDLE_TYPES_KHR
  - CL_SEMAPHORE_EXPORT_HANDLE_TYPES_LIST_END_KHR
- cl_semaphore_info_khr
  - CL_SEMAPHORE_EXPORTABLE_KHR

Sample Code

The following examples use the cl_khr_external_semaphore_opaque_fd extension to obtain an
external semaphore. Similar code can be written using the other layered extensions.

Example for Importing a Semaphore Created by Another API in OpenCL in a Single-Device Context

```c
// Get cl_devices of the platform.
clGetDeviceIDs(..., &devices, &deviceCount);

// Create cl_context with just first device
clCreateContext(..., 1, devices, ...);

// Obtain fd/win32 or similar handle for external semaphore to be imported
// from the other API.
int fd = getFdForExternalSemaphore();

// Create clSema of type cl_semaphore_khr usable on the only available device
// assuming the semaphore was imported from the same device.

cl_semaphore_properties_khr_sema_props[] =
   {
      (cl_semaphore_properties_khr)CL_SEMAPHORE_TYPE_KHR,
      (cl_semaphore_properties_khr)CL_SEMAPHORE_TYPE_BINARY_KHR,
      (cl_semaphore_properties_khr)CL_SEMAPHORE_HANDLE_OPAQUE_FD_KHR,
      (cl_semaphore_properties_khr)fd,
      0};

int errcode_ret = 0;
cl_semaphore_khr clSema = clCreateSemaphoreWithPropertiesKHR(context,
   sema_props,
   &errcode_ret);
```

Example for Importing a Semaphore Created by Another API in OpenCL in a Multi-device Context for Single Device Usage

```c
// Get cl_devices of the platform.
clGetDeviceIDs(..., &devices, &deviceCount);

// Create cl_context with first two devices
clCreateContext(..., 2, devices, ...);

// Obtain fd/win32 or similar handle for external semaphore to be imported
// from the other API.
int fd = getFdForExternalSemaphore();

// Create clSema of type cl_semaphore_khr usable only on device 1
// assuming the semaphore was imported from the same device.

cl_semaphore_properties_khr_sema_props[] =
   {
      (cl_semaphore_properties_khr)CL_SEMAPHORE_TYPE_KHR,
      (cl_semaphore_properties_khr)CL_SEMAPHORE_TYPE_BINARY_KHR,
      (cl_semaphore_properties_khr)CL_SEMAPHORE_HANDLE_OPAQUE_FD_KHR,
      (cl_semaphore_properties_khr)fd,
```
Example for Synchronization Using a Semaphore Created by Another API and Imported in OpenCL

// Create clSema using one of the above examples of external semaphore creation.

int errcode_ret = 0;
cl_semaphore_khr clSema = clCreateSemaphoreWithPropertiesKHR(context,
    sema_props,
    &errcode_ret);

// Start the main loop

while (true) {
    // (not shown) Signal the semaphore from the other API

    // Wait for the semaphore in OpenCL
cEnqueueWaitSemaphoresKHR(command_queue, 1, clSema, 0, NULL, NULL);

    // Launch kernel
cEnqueueNDRangeKernel(command_queue, ...);

    // Signal the semaphore in OpenCL
cEnqueueSignalSemaphoresKHR(command_queue, 1, clSema, 0, NULL, NULL);

    // (not shown) Launch work in the other API that waits on 'clSema'
}

(\cl_semaphore_properties_khr) CL_SEMAPHORE_DEVICE_HANDLE_LIST_KHR,
    (\cl_semaphore_properties_khr) devices[1],
    CL_SEMAPHORE_DEVICE_HANDLE_LIST_END_KHR,
    0
    
};

int errcode_ret = 0;
cl_semaphore_khr clSema = clCreateSemaphoreWithPropertiesKHR(context,
    sema_props,
    &errcode_ret);
// Get cl_devices of the platform.
cGetDeviceIDs(..., &devices, &deviceCount);

// Create cl_context with first two devices
cCreateContext(..., 2, devices, ...);

// Create clSema of type cl_semaphore_khr usable only on device 1
cl_semaphore_properties_khr sema_props[] = {
    (cl_semaphore_properties_khr)CL_SEMAPHORE_TYPE_KHR,
    (cl_semaphore_properties_khr)CL_SEMAPHORE_TYPE_BINARY_KHR,
    (cl_semaphore_properties_khr)CL_SEMAPHORE_EXPORT_HANDLE_TYPES_KHR,
    (cl_semaphore_properties_khr)CL_SEMAPHORE_HANDLE_OPAQUE_FD_KHR,
    CL_SEMAPHORE_EXPORT_HANDLE_TYPES_LIST_END_KHR,
    (cl_semaphore_properties_khr)CL_SEMAPHORE_DEVICE_HANDLE_LIST_KHR,
    (cl_semaphore_properties_khr)devices[1],
    CL_SEMAPHORE_DEVICE_HANDLE_LIST_END_KHR,
    0
};

int errcode_ret = 0;
cl_semaphore_khr clSema = clCreateSemaphoreWithPropertiesKHR(context,
    sema_props,
    &errcode_ret);

// Application queries handle-type and the exportable handle associated with the
// semaphore.
cGetSemaphoreInfoKHR(clSema,
    CL_SEMAPHORE_EXPORT_HANDLE_TYPES_KHR,
    sizeof(cl_external_semaphore_handle_type_khr),
    &handle_type,
    &handle_type_size);

// The other API or process can use the exported semaphore handle
// to import
int fd = -1;
if (handle_type == CL_SEMAPHORE_HANDLE_OPAQUE_FD_KHR) {
    clGetSemaphoreHandleForTypeKHR(clSema,
        device,
        CL_SEMAPHORE_HANDLE_OPAQUE_FD_KHR,
        sizeof(int),
        &fd, NULL);
}

// Start the main rendering loop

while (true) {
    // (not shown) Signal the semaphore from the other API
}
// Wait for the semaphore in OpenCL
clEnqueueWaitSemaphoresKHR(command_queue, /*num_sema_objects*/ 1, /*sema_objects*/ &clSema, /*num_events_in_wait_list*/ 0, /*event_wait_list*/ NULL, /*event*/ NULL);

// Launch kernel
clEnqueueNDRangeKernel(command_queue, ...);

// Signal the semaphore in OpenCL
clEnqueueSignalSemaphoresKHR(command_queue, /*num_sema_objects*/ 1, /*sema_objects*/ &clSema, /*num_events_in_wait_list*/ 0, /*event_wait_list*/ NULL, /*event*/ NULL);

    // (not shown) Launch work in the other API that waits on 'clSema'

Version History

- Revision 0.9.0, 2021-09-10
  - Initial version (provisional).

- Revision 0.9.1, 2023-11-16
  - Added CL_SEMAPHORE_EXPORTABLE_KHR.

- Revision 0.9.2, 2023-11-21
  - Added re-import function call to cl_khr_external_semaphore_sync_fd

- Revision 1.0.0, 2024-03-15
  - First non-provisional version.

cl_khr_external_semaphore_opaque_fd

Name String
    cl_khr_external_semaphore_opaque_fd

Ratification Status
    Ratified

Extension and Version Dependencies
    OpenCL 1.2
    and
    cl_khr_semaphore
    and
cl_khr_external_semaphore

Other Extension Metadata

Last Modified Date
2024-03-15

IP Status
No known IP claims.

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Description
cl_khr_external_semaphore_opaque_fd supports importing and exporting a restricted POSIX file descriptor as an external semaphore using the APIs introduced by cl_khr_external_semaphore.

New Enums
• cl_khr_external_semaphore_opaque_fd
• cl_external_semaphore_handle_type_khr
  • CL_SEMAPHORE_HANDLE_OPAQUE_FD_KHR

Version History
• Revision 0.9.0, 2021-09-10
cl_khr_external_semaphore_sync_fd

Name String
cl_khr_external_semaphore_sync_fd

Ratification Status
Ratified

Extension and Version Dependencies
OpenCL 1.2
and
clkhr_semaphore
and
clkhr_external_semaphore

Other Extension Metadata

Last Modified Date
2024-03-15

IP Status
No known IP claims.

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Description

`cl_khr_external_semaphore_sync_fd` supports importing and exporting a POSIX file descriptor handle to a Linux Sync File or Android Fence object as an external semaphore using the APIs introduced by `cl_khr_external_semaphore`.

New Commands

• `clGetSemaphoreHandleForTypeKHR`

New Types

• `cl_semaphore_reimport_properties_khr`

New Enums

• `cl_external_semaphore_handle_type_khr`
  ◦ `CL_SEMAPHORE_HANDLE_SYNC_FD_KHR`

Version History

• Revision 0.9.0, 2021-09-10
  ◦ Initial version (provisional).
• Revision 0.9.1, 2023-11-16
  ◦ Added `CL_SEMAPHORE_EXPORTABLE_KHR`.
• Revision 0.9.2, 2023-11-21
  ◦ Added re-import function call to `cl_khr_external_semaphore_sync_fd`
• Revision 1.0.0, 2024-03-15
  ◦ First non-provisional version.

cl_khr_fp16

Name String

`cl_khr_fp16`

Ratification Status

Ratified

Extension and Version Dependencies

None
Other Extension Metadata

Last Modified Date
2020-04-21

IP Status
No known IP claims.

Description

`cl_khr_fp16` adds support to OpenCL C for half scalar and vector types as built-in types that can be used for arithmetic operations, conversions, etc.

See the Half-Precision Floating-Point section of the OpenCL C specification for more information.

New Enums

- `cl_device_info`
  - `CL_DEVICE_HALF_FP_CONFIG`

Version History

- Revision 1.0.0, 2020-04-21
  - First assigned version.

`cl_khr_fp64`

Name String

`cl_khr_fp64`

Ratification Status

Ratified

Extension and Version Dependencies

None

Deprecation State

- Promoted to OpenCL 1.2

Other Extension Metadata

Last Modified Date
2020-04-21

IP Status
No known IP claims.
Description

*cl_khr_fp64* adds support to OpenCL C for double-precision scalar and vector types as built-in types that can be used for arithmetic operations, conversions, etc.

See the Double-Precision Floating-Point section of the OpenCL C specification for more information.

New Enums

- cl_device_info
  - CL_DEVICE_DOUBLE_FP_CONFIG

Version History

- Revision 1.0.0, 2020-04-21
  - First assigned version.

**cl_khr_gl_depth_images**

Name String

*cl_khr_gl_depth_images*

Ratification Status

Ratified

Extension and Version Dependencies

- cl_khr_gl_sharing

Other Extension Metadata

Last Modified Date

2020-04-21

IP Status

No known IP claims.

Description

*cl_khr_gl_depth_images* extends OpenCL / OpenGL sharing defined by the *cl_khr_gl_sharing* extension to allow an OpenCL image to be created from an OpenGL depth or depth-stencil texture.

Depth images with an image channel order of CL_DEPTH_STENCIL can only be created using the *clCreateFromGLTexture* API.

New Enums

- cl_channel_order
  - CL_DEPTH_STENCIL
- cl_channel_type
**Version History**

- Revision 1.0.0, 2020-04-21
  - First assigned version.

**cl_khr_gl_event**

**Name String**

cl_khr_gl_event

**Ratification Status**

Ratified

**Extension and Version Dependencies**

cl_khr_gl_sharing

**Other Extension Metadata**

**Last Modified Date**

2020-04-21

**IP Status**

No known IP claims.

**Description**

cl_khr_gl_event allows creating OpenCL event objects linked to OpenGL fence sync objects, potentially improving efficiency of sharing images and buffers between the two APIs. The companion GL_ARB_cl_event extension provides the complementary functionality of creating an OpenGL sync object from an OpenCL event object.

In addition, this extension modifies the behavior of clEnqueueAcquireGLObjecTs and clEnqueueReleaseGLObjecTs to implicitly guarantee synchronization with an OpenGL context bound in the same thread as the OpenCL context.

**New Commands**

- clCreateEventFromGLsyncKHR

**New Enums**

- cl_command_type
  - CL_COMMAND_GL_FENCE_SYNC_OBJECT_KHR

**Issues**

1. How are references between CL events and GL syncs handled?
**PROPOSED:** The linked CL event places a single reference on the GL sync object. That reference is removed when the CL event is deleted. A more expensive alternative would be to reflect changes in the CL event reference count through to the GL sync.

2. How are linkages to synchronization primitives in other APIs handled?

**UNRESOLVED.** We will at least want to have a way to link events to EGL sync objects. There is probably no analogous DX concept. There would be an entry point for each type of synchronization primitive to be linked to, such as `clCreateEventFromEGLSyncKHR`.

An alternative is a generic `clCreateEventFromExternalEvent` taking an attribute list. The attribute list would include information defining the type of the external primitive and additional information (GL sync object handle, EGL display and sync object handle, etc.) specific to that type. This allows a single entry point to be reused.

These will probably be separate extensions following the API proposed here.

3. Should the `CL_EVENT_COMMAND_TYPE` correspond to the type of command (fence) or the type of the linked sync object?

**PROPOSED:** To the type of the linked sync object.

4. Should we support both explicit and implicit synchronization?

**PROPOSED:** Yes. Implicit synchronization is suitable when GL and CL are executing in the same application thread. Explicit synchronization is suitable when they are executing in different threads but the expense of `glFinish` is too high.

5. Should this be a platform or device extension?

**PROPOSED:** Platform extension. This may result in considerable under-the-hood work to implement the sync → event semantics using only the public GL API, however, when multiple drivers and devices with different GL support levels coexist in the same runtime.

6. Where can events generated from GL syncs be usable?

**PROPOSED:** Only with `clEnqueueAcquireGLObjects`, and attempting to use such an event elsewhere will generate an error. There is no apparent use case for using such events elsewhere, and possibly some cost to supporting it, balanced by the cost of checking the source of events in all other commands accepting them as parameters.

**Version History**

- Revision 1.0.0, 2020-04-21
  - First assigned version.

**cl_khr_gl_msaa_sharing**

**Name String**

cl_khr_gl_msaa_sharing
Ratification Status
Ratified

Extension and Version Dependencies
- `cl_khr_gl_depth_images`
- `cl_khr_gl_sharing`

Other Extension Metadata

Last Modified Date
2020-04-21

IP Status
No known IP claims.

Description
`cl_khr_gl_msaa_sharing` extends the `cl_khr_gl_sharing` extension to allow a shared OpenCL/OpenGL image object to be created from an OpenGL multi-sampled (“MSAA”) color or depth texture.

This extension adds multi-sample support to `clCreateFromGLTexture` and `clGetGLTextureInfo`, and allows passing multi-sample images to compute kernels.

This extension requires `cl_khr_gl_depth_images`.

See the `cl_khr_gl_msaa_sharing` section of the OpenCL C specification for more information.

New Enums
- `cl_gl_texture_info`
  - `CL_GL_NUM_SAMPLES`

Version History
- Revision 1.0.0, 2020-04-21
  - First assigned version.

`cl_khr_gl_sharing`

Name String
`cl_khr_gl_sharing`

Ratification Status
Ratified

Extension and Version Dependencies
None
Description

The `cl_khr_gl_sharing` extension allows use of OpenGL buffer, texture, and renderbuffer objects as OpenCL memory objects, referred to as “Shared OpenCL/OpenGL Memory Objects”.

An OpenCL context may be associated with an OpenGL context or share group object, using additional attributes described for `clCreateContext`.

An OpenCL image object may be created from an OpenGL texture or renderbuffer object as described for `clCreateFromGLTexture` and `clCreateFromGLRenderbuffer`, respectively.

An OpenCL buffer object may be created from an OpenGL buffer object using `clCreateFromGLBuffer`.

Any supported OpenGL object defined within the associated OpenGL context or share group object may be shared, with the exception of the default OpenGL objects (i.e. objects named zero), which may not be shared.

Additional information on the use of shared OpenCL/OpenGL memory objects is found in the Lifetime of Shared OpenCL/OpenGL Memory Objects, Acquiring, Releasing, and Synchronizing Access to Shared OpenCL/OpenGL Memory Objects and Querying Devices that Support Sharing with OpenGL sections.

An OpenGL implementation supporting buffer objects and sharing of texture and buffer object images with OpenCL is required by this extension.

New Commands

- `clGetGLContextInfoKHR`
- `clCreateFromGLBuffer`
- `clCreateFromGLTexture`
- `clCreateFromGLRenderbuffer`
- `clGetGLOBJECTINFO`
- `clGetGLOBJECTINFO`
- `clEnqueueAcquireGLObjects`
- `clEnqueueReleaseGLObjects`
New Types

- cl_gl_context_info
- cl_gl_object_type
- cl_gl_texture_info
- cl_gl_platform_info

New Enums

- cl_gl_context_info
  - CL_CURRENT_DEVICE_FOR_GL_CONTEXT_KHR
  - CL_DEVICES_FOR_GL_CONTEXT_KHR
- cl_context_properties
  - CL_GL_CONTEXT_KHR
  - CL_EGL_DISPLAY_KHR
  - CL_GLX_DISPLAY_KHR
  - CL_WGL_HDC_KHR
  - CL_CGL_SHAREGROUP_KHR
- cl_gl_object_type
  - CL_GL_OBJECT_BUFFER
  - CL_GL_OBJECT_TEXTURE2D
  - CL_GL_OBJECT_TEXTURE3D
  - CL_GL_OBJECT_RENDERBUFFER
  - CL_GL_OBJECT_TEXTURE2D_ARRAY
  - CL_GL_OBJECT_TEXTURE1D
  - CL_GL_OBJECT_TEXTURE1D_ARRAY
  - CL_GL_OBJECT_TEXTURE_BUFFER
- cl_gl_texture_info
  - CL_GL_TEXTURE_TARGET
  - CL_GL_MIPMAP_LEVEL

New Error Codes

- CL_INVALID_GL_SHAREGROUP_REFERENCE_KHR

Issues

1. How should the OpenGL context be identified when creating an associated OpenCL context?

   **RESOLVED**: by using a (display,context handle) attribute pair to identify an arbitrary OpenGL or OpenGL ES context with respect to one of the window-system binding layers EGL, GLX, or
WGL, or a share group handle to identify a CGL share group. If a context is specified, it need not be current to the thread calling clCreateContext*.

A previously suggested approach would use a single boolean attribute CL_USE_GL_CONTEXT_KHR to allow creating a context associated with the currently bound OpenGL context. This may still be implemented as a separate extension, and might allow more efficient acquire/release behavior in the special case where they are being executed in the same thread as the bound GL context used to create the CL context.

2. What should the format of an attribute list be?

After considerable discussion, we think we can live with a list of <attribute name,value> pairs terminated by zero. The list is passed as 'cl_context_properties *properties', where cl_context_properties is typedefed to be 'intptr_t' in cl.h.

This effectively allows encoding all scalar integer, pointer, and handle values in the host API into the argument list and is analogous to the structure and type of EGL attribute lists. NULL attribute lists are also allowed. Again as for EGL, any attributes not explicitly passed in the list will take on a defined default value that does something reasonable.

Experience with EGL, GLX, and WGL has shown attribute lists to be a sufficiently flexible and general mechanism to serve the needs of management calls such as context creation. It is not completely general (encoding floating-point and non-scalar attribute values is not straightforward), and other approaches were suggested such as opaque attribute lists with getter/setter methods, or arrays of varadic structures.

3. What’s the behavior of an associated OpenGL or OpenCL context when using resources defined by the other associated context, and that context is destroyed?

**RESOLVED:** OpenCL objects place a reference on the data store underlying the corresponding GL object when they’re created. The GL name corresponding to that data store may be deleted, but the data store itself remains so long as any CL object has a reference to it. However, destroying all GL contexts in the share group corresponding to a CL context results in implementation-dependent behavior when using a corresponding CL object, up to and including program termination.

4. How about sharing with D3D?

Sharing between D3D and OpenCL should use the same attribute list mechanism, though obviously with different parameters, and be exposed as a similar parallel OpenCL extension. There may be an interaction between that extension and this one since it’s not yet clear if it will be possible to create a CL context simultaneously sharing GL and D3D objects.

5. Under what conditions will context creation fail due to sharing?

**RESOLVED:** Several cross-platform failure conditions are described (GL context or CGL share group doesn’t exist, GL context doesn’t support types of GL objects, GL context implementation doesn’t allow sharing), but additional failures may result due to implementation-dependent reasons and should be added to this extension as such failures are discovered. Sharing between OpenCL and OpenGL requires integration at the driver internals level.
6. What command-queues can \texttt{clEnqueueAcquire/ReleaseGLObjects} be placed on?

\textbf{RESOLVED:} All command-queues. This restriction is enforced at context creation time. If any device passed to context creation cannot support shared OpenCL/OpenGL memory objects, context creation will fail with a \texttt{CL_INVALID_OPERATION} error.

7. How can applications determine which command-queue to place an Acquire/Release on?

\textbf{RESOLVED:} The \texttt{clGetGLContextInfoKHR} returns either the CL device currently corresponding to a specified GL context (typically the display it's running on), or a list of all the CL devices the specified context might run on (potentially useful in multiheaded / “virtual screen” environments). This command is not placed together with commands to create shared OpenCL/OpenGL memory objects because it relies on the same property-list method of specifying a GL context introduced by this extension.

If no devices are returned, it means that the GL context exists on an older GPU not capable of running OpenCL, but still capable of sharing objects between GL running on that GPU and CL running elsewhere.

8. What is the meaning of the \texttt{CL_DEVICES_FOR_GL_CONTEXT_KHR} query?

\textbf{RESOLVED:} The list of all CL devices that may ever be associated with a specific GL context. On platforms such as MacOS X, the “virtual screen” concept allows multiple GPUs to back a single virtual display. Similar functionality might be implemented on other windowing systems, such as a transparent heterogenous multiheaded X server. Therefore the exact meaning of this query is interpreted relative to the binding layer API in use.

9. What happened to the “\texttt{extension\"s cl_khr_gl_sharing\_context and cl_khr_gl_sharing\_memobjs} that were previously published?

\textbf{RESOLVED:} These were not actual extensions, but the result of splitting the \texttt{cl_khr_gl_sharing} extension language into two separate sections for publication. All extension language has now been integrated into the unified Specification and this distinction is not useful.

10. Where are the \texttt{clCreateFromGLTexture2D} and \texttt{clCreateFromGLTexture3D} functions described?

\textbf{PROPOSED:} These functions are present in \texttt{cl.xml}, listed as OpenCL 1.0 APIs that were deprecated in OpenCL 1.2, but the current extension language does not described them. Since OpenCL 1.2 itself is so old, it is not worth the effort to look back and determine the exact details of these APIs.

\textbf{Version History}

- Revision 1.0.0, 2020-04-21
  - First assigned version.

\textbf{cl_khr_global_int32_base_atomics}

\textbf{Name String}

\begin{verbatim}
 cl_khr_global_int32_base_atomics
\end{verbatim}
cl_khr_global_int32_base_atomics allows OpenCL C atomic operations to be performed on 32-bit signed and unsigned integers in global memory.

This extension became a core feature in OpenCL 1.1, with the built-in atomic function names changed to use the atomic_prefix instead of atom_.

See the Global 32-Bit Base Atomics section of the OpenCL C specification for more information.

Version History

• Revision 1.0.0, 2020-04-21
  ◦ First assigned version.

cl_khr_global_int32_extended_atomics

Name String

cl_khr_global_int32_extended_atomics

Ratification Status

Ratified

Extension and Version Dependencies

None

Deprecation State

• Promoted to OpenCL 1.1
Description

`cl_khr_global_int32_extended_atomics` allows OpenCL C extended atomic operations to be performed on 32-bit signed and unsigned integers in global memory.

This extension became a core feature in OpenCL 1.1, with the built-in atomic function names changed to use the `atomic_` prefix instead of `atom_`.

See the Global 32-Bit Extended Atomics section of the OpenCL C specification for more information.

Version History

- Revision 1.0.0, 2020-04-21
  - First assigned version.

`cl_khr_icd` describes a platform extension which defines a simple mechanism through which the Khronos OpenCL installable client driver loader (ICD Loader) may expose multiple separate vendor installable client drivers (Vendor ICDs) for OpenCL. An application written against the ICD Loader will be able to access all `cl_platform_ids` exposed by all vendor implementations with the ICD Loader acting as a demultiplexor.

This is a platform extension, so if this extension is supported by an implementation, the string
"cl_khr_icd" will be present in the CL_PLATFORM_EXTENSIONS string.

Source Code

The official source for the ICD Loader is available on github, at:

https://github.com/KhronosGroup/OpenCL-ICD-Loader

The complete _cl_icd_dispatch structure is defined in the header cl_icd.h, which is available as a part of the OpenCL headers.

Inferring Vendors From Function Call Arguments

At every OpenCL function call, the ICD Loader infers the vendor ICD function to call from the arguments to the function. An object is said to be ICD compatible if it is of the following structure:

```c
struct _cl_<object>
{
    struct _cl_icd_dispatch *dispatch;
    // ... remainder of internal data
};
```

<object> is one of platform_id, device_id, context, command_queue, mem, program, kernel, event, or sampler.

The structure _cl_icd_dispatch is a function pointer dispatch table which is used to direct calls to a particular vendor implementation. All objects created from ICD compatible objects must be ICD compatible.

The definition for _cl_icd_dispatch is provided along with the OpenCL headers. Existing members can never be removed from that structure but new members can be appended.

Functions which do not have an argument from which the vendor implementation may be inferred have been deprecated and may be ignored.

ICD Data

A Vendor ICD is defined by two pieces of data:

- The Vendor ICD library specifies a library which contains the OpenCL entry points for the vendor's OpenCL implementation. The vendor ICD's library file name should include the vendor name, or a vendor-specific implementation identifier.
- The Vendor ICD extension suffix is a short string which specifies the default suffix for extensions implemented only by that vendor. The vendor suffix string is optional.

ICD Loader Vendor Enumeration on Windows

To enumerate Vendor ICDs on Windows, the ICD Loader will first scan for REG_SZ string values in the "Display Adapter" and "Software Components" HKR registry keys. The exact registry keys to
scan should be obtained via PnP Configuration Manager APIs, but will look like:

For 64-bit ICDs:

HKLM\SYSTEM\CurrentControlSet\Control\Class\{Display Adapter GUID}\{Instance ID}\OpenCLDriverName, or
HKLM\SYSTEM\CurrentControlSet\Control\Class\{Software Component GUID}\{Instance ID}\OpenCLDriverName

For 32-bit ICDs:

HKLM\SYSTEM\CurrentControlSet\Control\Class\{Display Adapter GUID}\{Instance ID}\OpenCLDriverNameWoW, or
HKLM\SYSTEM\CurrentControlSet\Control\Class\{Software Component GUID}\{Instance ID}\OpenCLDriverNameWoW

These registry values contain the path to the Vendor ICD library. For example, if the registry contains the value:

[HKLM\SYSTEM\CurrentControlSet\Control\Class\{GUID}\{Instance}\]
"OpenCLDriverName"="c:\\vendor a\\vndra_ocl.dll"

Then the ICD Loader will open the Vendor ICD library:

c:\vendor a\vndra_ocl.dll

The ICD Loader will also scan for REG_DWORD values in the registry key:

HKLM\SOFTWARE\Khronos\OpenCL\Vendors

For each registry value in this key which has data set to 0, the ICD Loader will open the Vendor ICD library specified by the name of the registry value.

For example, if the registry contains the value:

[HKLM\SOFTWARE\Khronos\OpenCL\Vendors]
"c:\\vendor a\\vndra_ocl.dll"=dword:00000000

Then the ICD Loader will open the Vendor ICD library:

c:\vendor a\vndra_ocl.dll
ICD Loader Vendor Enumeration on Linux

To enumerate vendor ICDs on Linux, the ICD Loader scans the files in the path /etc/OpenCL/vendors. For each file in this path, the ICD Loader opens the file as a text file. The expected format for the file is a single line of text which specifies the Vendor ICD's library. The ICD Loader will attempt to open that file as a shared object using dlopen(). Note that the library specified may be an absolute path or just a file name.

For example, if the following file exists

```
/etc/OpenCL/vendors/VendorA.icd
```

and contains the text

```
libVendorAOpenCL.so
```

then the ICD Loader will load the library `libVendorAOpenCL.so`.

ICD Loader Vendor Enumeration on Android

To enumerate vendor ICDs on Android, the ICD Loader scans the files in the path /system/vendor/Khronos/OpenCL/vendors. For each file in this path, the ICD Loader opens the file as a text file. The expected format for the file is a single line of text which specifies the Vendor ICD's library. The ICD Loader will attempt to open that file as a shared object using dlopen(). Note that the library specified may be an absolute path or just a file name.

For example, if the following file exists

```
/system/vendor/Khronos/OpenCL/vendors/VendorA.icd
```

and contains the text

```
libVendorAOpenCL.so
```

then the ICD Loader will load the library `libVendorAOpenCL.so`.

Adding a Vendor Library

Upon successfully loading a Vendor ICD's library, the ICD Loader queries the following functions from the library: `clIcdGetPlatformIDsKHR`, `clGetPlatformInfo`, and `clGetExtensionFunctionAddress` (note: `clGetExtensionFunctionAddress` has been deprecated, but is still required for the ICD Loader). If any of these functions are not present then the ICD Loader will close and ignore the library.

Next the ICD Loader queries available ICD-enabled platforms in the library using `clIcdGetPlatformIDsKHR`. For each of these platforms, the ICD Loader queries the platform’s
extension string to verify that cl_khr_icd is supported, then queries the platform’s Vendor ICD extension suffix using clGetPlatformInfo with the value CL_PLATFORM_ICD_SUFFIX_KHR.

If any of these steps fail, the ICD Loader will ignore the Vendor ICD and continue on to the next.

**New Commands**

- clIcdGetPlatformIDsKHR

**New Enums**

Accepted as `param_name` to the function clGetPlatformInfo:

- CL_PLATFORM_ICD_SUFFIX_KHR

Returned by clGetPlatformIDs when no platforms are found:

- CL_PLATFORM_NOT_FOUND_KHR

**Issues**

1. Some OpenCL functions do not take an object argument from which their vendor library may be identified (e.g. clUnloadCompiler), how will they be handled?

   **RESOLVED:** Such functions will be a noop for all calls through the ICD Loader.

2. How are OpenCL extension to be handled?

   **RESOLVED:** Extension APIs must be queried using clGetExtensionFunctionAddressForPlatform.

3. How will the ICD Loader handle a NULL cl_platform_id?

   **RESOLVED:** The ICD will by default choose the first enumerated platform as the NULL platform.

4. There exists no mechanism to unload the ICD Loader, should there be one?

   **RESOLVED:** As there is no standard mechanism for unloading a vendor implementation, do not add one for the ICD Loader.

5. How will the ICD Loader handle NULL objects passed to the OpenCL functions?

   **RESOLVED:** The ICD Loader will check for NULL objects passed to the OpenCL functions without trying to dereference the NULL objects for obtaining the ICD dispatch table. On detecting a NULL object it will return one of the an invalid object error values (e.g. CL_INVALID_DEVICE) corresponding to the object in question.

**Version History**

- Revision 1.0.0, 2020-04-21
  - First assigned version.
**cl_khr_il_program**

**Name String**

`cl_khr_il_program`

**Ratification Status**

Ratified

**Extension and Version Dependencies**

None

**Deprecation State**

- Promoted to OpenCL 2.1

**Other Extension Metadata**

**Last Modified Date**

2020-04-21

**IP Status**

No known IP claims.

**Description**

`cl_khr_il_program` adds the ability to create programs with intermediate language (IL), usually SPIR-V. Further information about the format and contents of SPIR-V may be found in the SPIR-V Specification. Information about how SPIR-V modules behave in the OpenCL environment may be found in the OpenCL SPIR-V Environment Specification.

This functionality described by this extension is a core feature in OpenCL 2.1.

**New Commands**

- `clCreateProgramWithILKHR`

**New Enums**

- `cl_device_info`
  - `CL_DEVICE_IL_VERSION_KHR`
- `cl_platform_info`
  - `CL_PROGRAM_IL_KHR`

**Version History**

- Revision 1.0.0, 2020-04-21
  - First assigned version.
cl_khr_image2d_from_buffer

Name String
   cl_khr_image2d_from_buffer

Ratification Status
   Ratified

Extension and Version Dependencies
   None

Deprecation State
   • Promoted to OpenCL 2.0

Other Extension Metadata

Last Modified Date
   2020-04-21

IP Status
   No known IP claims.

Description
   cl_khr_image2d_from_buffer allows a 2D image to be created from an existing OpenCL buffer memory object.

This extension became a core feature in OpenCL 2.0.

Refer to the discussion of 2D images created from buffers in the Image Descriptor section for additional details.

New Enums
   • CL_DEVICE_IMAGE_PITCH_ALIGNMENT_KHR
   • CL_DEVICE_IMAGE_BASE_ADDRESS_ALIGNMENT_KHR

Version History
   • Revision 1.0.0, 2020-04-21
     ◦ First assigned version.

cl_khr_initialize_memory

Name String
   cl_khr_initialize_memory

Ratification Status
   Ratified
**Extension and Version Dependencies**
None

**Other Extension Metadata**

**Last Modified Date**
2020-04-21

**IP Status**
No known IP claims.

**Description**

`cl_khr_initialize_memory` adds OpenCL C support for initializing local and private memory before a kernel begins execution. This is accomplished by specifying a flag at context creation time affecting all such memory.

Memory is allocated in various forms in OpenCL both explicitly (global memory) or implicitly (local, private memory). This allocation so far does not provide a straightforward mechanism to initialize the memory on allocation. In other words what is lacking is the equivalent of `calloc` for the currently supported `malloc` like capability. This functionality is useful for a variety of reasons including ease of debugging, application controlled limiting of visibility to previous contents of memory and in some cases, optimization.

See the [Initializing Memory](#) section of the OpenCL C specification for more information.

**New Enums**

- `cl_context_properties`
  - `CL_CONTEXT_MEMORY_INITIALIZE_KHR`

- `cl_context_memory_initialize_khr`
  - `CL_CONTEXT_MEMORY_INITIALIZE_LOCAL_KHR`
  - `CL_CONTEXT_MEMORY_INITIALIZE_PRIVATE_KHR`

**Version History**

- Revision 1.0.0, 2020-04-21
  - First assigned version.

**cl_khr_int64_base_atomics**

**Name String**
`cl_khr_int64_base_atomics`

**Ratification Status**
Ratified
Extension and Version Dependencies
None

Other Extension Metadata

Last Modified Date
2020-04-21

IP Status
No known IP claims.

Description

cl_khr_int64_base_atomics adds built-in OpenCL functions supporting atomic operations to be performed on 64-bit signed and unsigned integers in global and local memory.

See the 64-Bit Base Atomics section of the OpenCL C specification for more information.

Version History

• Revision 1.0.0, 2020-04-21
  ◦ First assigned version.

cl_khr_int64_extended_atomics

Name String
cl_khr_int64_extended_atomics

Ratification Status
Ratified

Extension and Version Dependencies
None

Other Extension Metadata

Last Modified Date
2020-04-21

IP Status
No known IP claims.

Description

cl_khr_int64_extended_atomics adds built-in OpenCL functions supporting extended atomic operations to be performed on 64-bit signed and unsigned integers in global and local memory.

See the 64-Bit Extended Atomics section of the OpenCL C specification for more information.
Version History

- Revision 1.0.0, 2020-04-21
  - First assigned version.

cl_khr_integer_dot_product

Name String

cl_khr_integer_dot_product

Ratification Status

Ratified

Extension and Version Dependencies

None

Other Extension Metadata

Last Modified Date

2021-06-23

IP Status

No known IP claims.

Contributors

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Description

cl_khr_integer_dot_product adds support for SPIR-V instructions and OpenCL C built-in functions to compute the dot product of vectors of integers.

OpenCL C compilers supporting this extension will define the extension macro cl_khr_integer_dot_product, and may define corresponding feature macros __opencl_c_integer_dot_product_input_4x8bit and __opencl_c_integer_dot_product_input_4x8bit_packed depending on the reported capabilities.

See the Integer Dot Product section of the OpenCL C specification for more information.
New Structures

• cl_device_integer_dot_product_acceleration_properties_khr

New Types

• cl_device_integer_dot_product_capabilities_khr

New Enums

• cl_device_integer_dot_product_capabilities_khr
  ◦ CL_DEVICE_INTEGER_DOT_PRODUCT_INPUT_4x8BIT_KHR
  ◦ CL_DEVICE_INTEGER_DOT_PRODUCT_INPUT_4x8BIT_PACKED_KHR

• cl_device_info
  ◦ CL_DEVICE_INTEGER_DOT_PRODUCT_CAPABILITIES_KHR
  ◦ CL_DEVICE_INTEGER_DOT_PRODUCT_ACCELERATION_PROPERTIES_8BIT_KHR
  ◦ CL_DEVICE_INTEGER_DOT_PRODUCT_ACCELERATION_PROPERTIES_4x8BIT_PACKED_KHR

Version History

• Revision 1.0.0, 2021-06-17
  ◦ Initial version

• Revision 2.0.0, 2021-06-23
  ◦ 8-bit support is mandatory, added 8-bit acceleration properties.

cl_khr_local_int32_base_atomics

Name String

cl_khr_local_int32_base_atomics

Ratification Status

Ratified

Extension and Version Dependencies

None

Deprecation State

• Promoted to OpenCL 1.1

Other Extension Metadata

Last Modified Date

2020-04-21

IP Status

No known IP claims.
**Description**

`cl_khr_local_int32_base_atomics` allows OpenCL C atomic operations to be performed on 32-bit signed and unsigned integers in local memory.

This extension became a core feature in OpenCL 1.1, with the built-in atomic function names changed to use the `atomic_` prefix instead of `atom_`.

See the [Local 32-Bit Base Atomics](#) section of the OpenCL C specification for more information.

**Version History**

- Revision 1.0.0, 2020-04-21
  - First assigned version.

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**Description**

`cl_khr_local_int32_extended_atomics` allows OpenCL C extended atomic operations to be performed on 32-bit signed and unsigned integers in local memory.

This extension became a core feature in OpenCL 1.1, with the built-in atomic function names changed to use the `atomic_` prefix instead of `atom_`.

See the [Local 32-Bit Extended Atomics](#) section of the OpenCL C specification for more information.

**Version History**

- Revision 1.0.0, 2020-04-21
First assigned version.

**cl_khr_mipmap_image**

**Name String**

cl_khr_mipmap_image

**Ratification Status**

Ratified

**Extension and Version Dependencies**

None

**Other Extension Metadata**

**Last Modified Date**

2020-04-21

**IP Status**

No known IP claims.

**Description**

The `cl_khr_mipmap_image` extension adds the ability to create and access mipmapped images:

- `clCreateImage` is extended to create mipmapped images.
- `clCreateFromGLTexture` is extended to create a mipmapped image from a mipmapped GL texture.
- `clEnqueueReadImage`, `clEnqueueWriteImage`, `clEnqueueCopyImage`, `clEnqueueFillImage`, `clEnqueueCopyImageToBuffer`, `clEnqueueCopyBufferToImage`, and `clEnqueueMapImage` are extended to operate on regions of mipmapped images.
  - The [Specifying Mipmap Levels to Image Operations](#) section describes how mipmap levels are encoded in existing parameters to these commands.
- OpenCL C built-in functions are added to read from and query a mipmapped image.

See the [Mipmapped Image Reads and Queries](#) section of the OpenCL C specification for more information.

**Version History**

- Revision 1.0.0, 2020-04-21
  - First assigned version.

**cl_khr_mipmap_image_writes**

**Name String**

cl_khr_mipmap_image_writes
Ratification Status
   Ratified

Extension and Version Dependencies
   cl_khr_mipmap_image

Other Extension Metadata

Last Modified Date
   2020-04-21

IP Status
   No known IP claims.

Description
The cl_khr_mipmap_image_writes extension adds OpenCL C built-in functions to write to a mipmapped image.

If cl_khr_mipmap_image_writes is supported by the OpenCL device, the cl_khr_mipmap_image extension must also be supported.

See the Mipmapped Image Writes section of the OpenCL C specification for more information.

Version History
   • Revision 1.0.0, 2020-04-21
      ◦ First assigned version.

cl_khr_pci_bus_info

Name String
   cl_khr_pci_bus_info

Ratification Status
   Ratified

Extension and Version Dependencies
   None

Other Extension Metadata

Last Modified Date
   2021-04-19

IP Status
   No known IP claims.
The cl_khr_pci_bus_info extension adds a new query to obtain PCI bus information about an OpenCL device.

Not all OpenCL devices have PCI bus information, either due to the device not being connected to the system through a PCI interface or due to platform specific restrictions and policies. Thus this extension is only expected to be supported by OpenCL devices which can provide the information.

As a consequence, applications should always check for the presence of the extension string for each individual OpenCL device for which they intend to issue the new query for and should not have any assumptions about the availability of the extension on any given platform.

New Types

- cl_device_pci_bus_info_khr

New Enums

- cl_device_info
  - CL_DEVICE_PCI_BUS_INFO_KHR

Version History

- Revision 1.0.0, 2021-04-19
  - Initial version.

cl_khr_priorityHints

Name String
c_l_khr_priority_hints

Ratification Status
Ratified

Extension and Version Dependencies
None

Other Extension Metadata

Last Modified Date
2020-04-21

IP Status
No known IP claims.

Description
The cl_khr_priority_hints extension adds priority hints for OpenCL, but does not specify the
scheduling behavior or minimum guarantees. It is expected that the user guides associated with each implementation which supports this extension will describe the scheduling behavior guarantees.

Note that the priority hint is orthogonal to functionality defined in the `cl_khr_throttle_hints` extension. For example, a task may have high priority (`CL_QUEUE_PRIORITY_HIGH_KHR`) but should at the same time be executed at an optimized throttle setting (`CL_QUEUE_THROTTLE_LOW_KHR`).

**New Types**

- `cl_queue_priority_khr`

**New Enums**

- `cl_queue_properties`
  - `CL_QUEUE_PRIORITY_KHR`
- `cl_queue_priority_khr`
  - `CL_QUEUE_PRIORITY_HIGH_KHR`
  - `CL_QUEUE_PRIORITY_MED_KHR`
  - `CL_QUEUE_PRIORITY_LOW_KHR`

**Version History**

- Revision 1.0.0, 2020-04-21
  - First assigned version.

---

**cl_khr_select_fprounding_mode**

**Name String**

`cl_khr_select_fprounding_mode`

**Ratification Status**

Ratified

**Extension and Version Dependencies**

None

**Deprecation State**

- *Obsoleted by OpenCL 1.1*

**Other Extension Metadata**

**Last Modified Date**

2020-04-21

**IP Status**

No known IP claims.
Description

c_l_khr_select_fprounding_mode allows an application to specify the rounding mode for an instruction or group of instructions in the OpenCL C program source.

This extension was deprecated in OpenCL 1.1, and its use is not recommended.

See the Select Floating-Point Rounding Mode section of the OpenCL C specification for more information.

Version History

• Revision 1.0.0, 2020-04-21
  ◦ First assigned version.

cl_khr_semaphore

Name String

cl_khr_semaphore

Ratification Status

Ratified

Extension and Version Dependencies

OpenCL 1.2

Other Extension Metadata

Last Modified Date

2024-03-15

IP Status

No known IP claims.

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Description

OpenCL provides cl_event as a primary mechanism of synchronization between host and device as well as across devices. While events can be waited on or can be passed as dependencies across work-submissions, they suffer from following limitations:

- They are immutable.
- They are not reusable.

cl_khr_semaphore introduces a new type of synchronization object to represent semaphores that can be reused, waited on, and signaled multiple times by OpenCL work-submissions.

In particular, this extension defines:

- a new type called cl_semaphore_khr to represent the semaphore objects.
- A new type called cl_semaphore_properties_khr to specify metadata associated with semaphores.
- Functions to create, retain, and release semaphores.
- Functions to wait on and signal semaphore objects.
- Functions to query the properties of semaphore objects.

New Commands

- clCreateSemaphoreWithPropertiesKHR
- clEnqueueWaitSemaphoresKHR
- clEnqueueSignalSemaphoresKHR
- clGetSemaphoreInfoKHR
- clReleaseSemaphoreKHR
- clRetainSemaphoreKHR

New Types

- cl_semaphore_khr
- cl_semaphore_properties_khr
New Enums

- `cl_platform_info`
  - `CL_PLATFORM_SEMAPHORE_TYPES_KHR`

- `cl_device_info`
  - `CLDEVICE_SEMAPHORE_TYPES_KHR`

- `cl_semaphore_type_khr`
  - `CL_SEMAPHORE_TYPE_BINARY_KHR`

- `cl_semaphore_info_khr`
  - `CL_SEMAPHORE_CONTEXT_KHR`
  - `CL_SEMAPHORE_REFERENCE_COUNT_KHR`
  - `CL_SEMAPHORE_PROPERTIES_KHR`
  - `CL_SEMAPHORE_PAYLOAD_KHR`

- `cl_semaphore_info_khr` or `cl_semaphore_properties_khr`
  - `CL_SEMAPHORE_TYPE_KHR`
  - `CL_SEMAPHORE_DEVICE_HANDLE_LIST_KHR`
  - `CL_SEMAPHORE_DEVICE_HANDLE_LIST_END_KHR`

- `cl_command_type`
  - `CL_COMMAND_SEMAPHORE_WAIT_KHR`
  - `CL_COMMAND_SEMAPHORE_SIGNAL_KHR`

New Error Codes

- `CL_INVALID_SEMAPHORE_KHR`

Sample Code

**Example for Semaphore Creation in a Single Device Context**

```c
// Get cl_devices of the platform.
clGetDeviceIDs(..., &devices, &deviceCount);

// Create cl_context with just first device
context = clCreateContext(..., 1, devices, ...);

// Create clSema of type cl_semaphore_khr usable on single device in the context
cl_semaphore_properties_khr sema_props[] =
{((cl_semaphore_properties_khr)CL_SEMAPHORE_TYPE_KHR,
```
Example for Semaphore Creation for a Single Device in a Multi-Device Context

```
// Get cl devices of the platform.
clGetDeviceIDs(..., &devices, &deviceCount);

// Create cl_context with first two devices
clCreateContext(..., 2, devices, ...);

// Create clSema of type cl_semaphore_khr usable only on device 0
cl_semaphore_properties_khr sema_props[] = {
    (cl_semaphore_properties_khr)CL_SEMAPHORE_TYPE_KHR,
    (cl_semaphore_properties_khr)CL_SEMAPHORE_TYPE_BINARY_KHR,
    (cl_semaphore_properties_khr)CL_SEMAPHORE_DEVICE_HANDLE_LIST_KHR,
    (cl_semaphore_properties_khr)devices[0],
    CL_SEMAPHORE_DEVICE_HANDLE_LIST_END_KHR,
    0
};

int errcode_ret = 0;

cl_semaphore_khr clSema = clCreateSemaphoreWithPropertiesKHR(context,
    sema_props,
    &errcode_ret);
```

Example for Synchronization Using Wait and Signal

```
// clSema is created using clCreateSemaphoreWithPropertiesKHR
// using one of the examples for semaphore creation.

cl_semaphore_khr clSema = clCreateSemaphoreWithPropertiesKHR(context,
    sema_props,
    &errcode_ret);

// Start the main loop

while (true) {
    // (not shown) Signal the semaphore from other work

    // Wait for the semaphore in OpenCL
    // by calling clEnqueueWaitSemaphoresKHR on 'clSema'
```
clEnqueueWaitSemaphoresKHR(command_queue, 1, &clSema, NULL, 0, NULL, NULL);

// Launch kernel that accesses extMem
clEnqueueNDRangeKernel(command_queue, ...);

// Signal the semaphore in OpenCL
clEnqueueSignalSemaphoresKHR(command_queue, 1, &clSema, NULL, 0, NULL, NULL);

// (not shown) Launch other work that waits on 'clSema'

Example for clGetSemaphoreInfoKHR

// clSema is created using clCreateSemaphoreWithPropertiesKHR
// using one of the examples for semaphore creation.

cl_semaphore_khr clSema = clCreateSemaphoreWithPropertiesKHR(context, sema_props, &errcode_ret);

// Start the main rendering loop

while (true) {
    // (not shown) Signal the semaphore from other work

    // Wait for the semaphore in OpenCL, by calling clEnqueueWaitSemaphoresKHR on 'clSema'
    clEnqueueWaitSemaphoresKHR(command_queue, 1, &clSema, NULL, 0, NULL, NULL);

    // Launch kernel in OpenCL
    clEnqueueNDRangeKernel(command_queue, ...);
// Signal the semaphore in OpenCL
clEnqueueSignalSemaphoresKHR(command_queue, 1, &clSema, NULL, 0, NULL);

// Query type of clSema
clGetSemaphoreInfoKHR(clSema, CL_SEMAPHORE_TYPE_KHR, sizeof(cl_semaphore_type_khr), &clSemaType, &clSemaTypeSize);

if (clSemaType == CL_SEMAPHORE_TYPE_BINARY_KHR) {
    // Do something
}
else {
    // Do something else
}

// (not shown) Launch other work that waits on 'clSema'

Version History

- Revision 0.9.0, 2021-09-10
  - Initial version (provisional).
- Revision 0.9.1, 2023-08-01
  - Changed device handle list enum to the semaphore-specific CL_SEMAPHORE_DEVICE_HANDLE_LIST_KHR (provisional).
- Revision 1.0.0, 2024-03-15
  - First non-provisional version.

cl_khr_spirv_extended_debug_info

Name String
cl_khr_spirv_extended_debug_info

Ratification Status
Ratified

Extension and Version Dependencies
None
Other Extension Metadata

Last Modified Date
2020-04-21

IP Status
No known IP claims.

Description

`cl_khr_spirv_extended_debug_info` allows use of the SPIR-V `OpenCL.DebugInfo.100` extended instruction set.

See the `cl_khr_spirv_extended_debug_info` section of the OpenCL SPIR-V Environment specification for more information.

Version History

- Revision 1.0.0, 2020-04-21
  - First assigned version.

**cl_khr_spirv_linkonce_odr**

Name String

`cl_khr_spirv_linkonce_odr`

Ratification Status

Ratified

Extension and Version Dependencies

None

Other Extension Metadata

Last Modified Date
2020-04-21

IP Status

No known IP claims.

Description

`cl_khr_spirv_linkonce_odr` allows use of the SPIR-V extension `SPV_KHR_linkonce_odr`.

See the `cl_khr_spirv_linkonce_odr` section of the OpenCL SPIR-V Environment specification for more information.
cl_khr_spirv_no_integer_wrap_decoration

Name String
cl_khr_spirv_no_integer_wrap_decoration

Ratification Status
Ratified

Extension and Version Dependencies
None

Other Extension Metadata

Last Modified Date
2020-04-21

IP Status
No known IP claims.

Description
cl_khr_spirv_no_integer_wrap_decoration allows use of the SPIR-V extension SPV_KHR_no_integer_wrap_decoration, which adds new decorations to indicate that a given instruction does not cause integer wrapping to occur.

See the cl_khr_spirv_no_integer_wrap_decoration section of the OpenCL SPIR-V Environment specification for more information.

Version History

• Revision 1.0.0, 2020-04-21
  ◦ First assigned version.

cl_khr_srgb_image_writes

Name String
cl_khr_srgb_image_writes

Ratification Status
Ratified

Extension and Version Dependencies
None
Other Extension Metadata

Last Modified Date
2020-04-21

IP Status
No known IP claims.

Description

cl_khr_srgb_image_writes enables OpenCL C kernels to write to sRGB images using the write_imagef built-in function. The sRGB image formats that may be written to will be returned by clGetSupportedImageFormats.

When the image is an sRGB image, the write_imagef built-in function will perform the linear to sRGB conversion. Only the R, G, and B components are converted from linear to sRGB; the A component is written as-is.

See the sRGB Image Write Functions section of the OpenCL C specification for more information.

Version History

- Revision 1.0.0, 2020-04-21
  - First assigned version.

cl_khr_subgroup_ballot

Name String
cl_khr_subgroup_ballot

Ratification Status
Ratified

Extension and Version Dependencies
None

Other Extension Metadata

Last Modified Date
2020-12-15

IP Status
No known IP claims.

Description

cl_khr_subgroup_ballot adds built-in OpenCL C functions with the ability to collect and operate on ballots from work items in a sub-group.
See the **Sub-Group Ballots** section of the OpenCL C specification for more information.

**Summary of New OpenCL C Functions**

```c
// These functions are available to devices supporting cl_khr_subgroup_ballot:

gentype sub_group_non_uniform_broadcast( gentype value, uint index )
gentype sub_group_broadcast_first( gentype value )

uint4 sub_group_ballot( int predicate )
int sub_group_inverse_ballot( uint4 value )
int sub_group_ballot_bit_extract( uint4 value, uint index )
uint sub_group_ballot_bit_count( uint4 value )
uint sub_group_ballot_inclusive_scan( uint4 value )
uint sub_group_ballot_exclusive_scan( uint4 value )
uint sub_group_ballot_find_lsb( uint4 value )
uint sub_group_ballot_find_msb( uint4 value )

uint4 get_sub_group_eq_mask()
uint4 get_sub_group_ge_mask()
uint4 get_sub_group_gt_mask()
uint4 get_sub_group_le_mask()
uint4 get_sub_group_lt_mask()
```

**Version History**

- Revision 1.0.0, 2020-12-15
  - First assigned version.

**cl_khr_subgroup_clustered_reduce**

**Name String**

`cl_khr_subgroup_clustered_reduce`

**Ratification Status**

Ratified

**Extension and Version Dependencies**

None

**Other Extension Metadata**

**Last Modified Date**

2020-12-15

**IP Status**

No known IP claims.
Description

`cl_khr_subgroup_clustered_reduce` adds built-in OpenCL functions for clustered reductions that operate on a subset of work items in the sub-group.

See the Clustered Reductions section of the OpenCL C specification for more information.

Summary of New OpenCL C Functions

```c
// These functions are available to devices supporting
// cl_khr_subgroup_clustered_reduce:

gentype  sub_group_clustered_reduce_add( gentype value, uint clustersize )
gentype  sub_group_clustered_reduce_mul( gentype value, uint clustersize )
gentype  sub_group_clustered_reduce_min( gentype value, uint clustersize )
gentype  sub_group_clustered_reduce_max( gentype value, uint clustersize )
gentype  sub_group_clustered_reduce_and( gentype value, uint clustersize )
gentype  sub_group_clustered_reduce_or( gentype value, uint clustersize )
gentype  sub_group_clustered_reduce_xor( gentype value, uint clustersize )
int      sub_group_clustered_reduce_logical_and( int predicate, uint clustersize )
int      sub_group_clustered_reduce_logical_or( int predicate, uint clustersize )
int      sub_group_clustered_reduce_logical_xor( int predicate, uint clustersize )
```

Version History

- Revision 1.0.0, 2020-12-15
  - First assigned version.

`cl_khr_subgroup_extended_types`

Name String

- `cl_khr_subgroup_extended_types`

Ratification Status

- Ratified

Extension and Version Dependencies

- None

Other Extension Metadata

Last Modified Date

- 2020-12-15

IP Status

- No known IP claims.
Description

`cl_khr_subgroup_extended_types` adds additional supported OpenCL C data types to the existing sub-group broadcast, scan, and reduction functions.

See the Sub-Group Extended Types section of the OpenCL C specification for more information.

Summary of New OpenCL C Functions

```c
// These functions are available to devices supporting
// cl_khr_subgroup_extended_types:

// Note: Existing functions supporting additional data types.

gentype sub_group_broadcast( gentype value, uint index )

gentype sub_group_reduce_add( gentype value )
gentype sub_group_reduce_min( gentype value )
gentype sub_group_reduce_max( gentype value )

gentype sub_group_scan_inclusive_add( gentype value )
gentype sub_group_scan_inclusive_min( gentype value )
gentype sub_group_scan_inclusive_max( gentype value )

gentype sub_group_scan_exclusive_add( gentype value )
gentype sub_group_scan_exclusive_min( gentype value )
gentype sub_group_scan_exclusive_max( gentype value )
```

Version History

- Revision 1.0.0, 2020-12-15
  - First assigned version.

`cl_khr_subgroup_named_barrier`

Name String

`cl_khr_subgroup_named_barrier`

Ratification Status

Ratified

Extension and Version Dependencies

None

Other Extension Metadata

Last Modified Date

2020-04-21
IP Status
No known IP claims.

Description
c_khr_subgroup_named_barrier adds barrier operations that cover subsets of an OpenCL workgroup. Only the OpenCL API changes are described in this section. Please refer to the SPIR-V specification for information about using sub-group named barriers in the SPIR-V intermediate representation, and to the OpenCL C++ specification for descriptions of the sub-group named barrier built-in functions in the OpenCL C++ kernel language.

New Enums
- cl_device_info
  - CL_DEVICE_MAX_NAMED_BARRIER_COUNT_KHR

Version History
- Revision 1.0.0, 2020-04-21
  - First assigned version.

c_khr_subgroup_non_uniform_arithmetic

Name String
c_khr_subgroup_non_uniform_arithmetic

Ratification Status
Ratified

Extension and Version Dependencies
None

Other Extension Metadata

Last Modified Date
2020-12-15

IP Status
No known IP claims.

Description
c_khr_subgroup_non_uniform_arithmetic adds built-in OpenCL C functions providing the ability to use some sub-group functions within non-uniform flow control, including additional scan and reduction operators.

See the Built-in Non-Uniform Arithmetic Functions for Sub-Groups section of the OpenCL C specification for more information.
Summary of New OpenCL C Functions

// These functions are available to devices supporting cl_khr_subgroup_non_uniform_arithmetic:

gentype sub_group_non_uniform_reduce_add(gentype value)
gentype sub_group_non_uniform_reduce_mul(gentype value)
gentype sub_group_non_uniform_reduce_min(gentype value)
gentype sub_group_non_uniform_reduce_max(gentype value)
gentype sub_group_non_uniform_reduce_and(gentype value)
gentype sub_group_non_uniform_reduce_or(gentype value)
gentype sub_group_non_uniform_reduce_xor(gentype value)
int sub_group_non_uniform_reduce_logical_and(int predicate)
int sub_group_non_uniform_reduce_logical_or(int predicate)
int sub_group_non_uniform_reduce_logical_xor(int predicate)

gentype sub_group_non_uniform_scan_inclusive_add(gentype value)
gentype sub_group_non_uniform_scan_inclusive_mul(gentype value)
gentype sub_group_non_uniform_scan_inclusive_min(gentype value)
gentype sub_group_non_uniform_scan_inclusive_max(gentype value)
gentype sub_group_non_uniform_scan_inclusive_and(gentype value)
gentype sub_group_non_uniform_scan_inclusive_or(gentype value)
gentype sub_group_non_uniform_scan_inclusive_xor(gentype value)
int sub_group_non_uniform_scan_inclusive_logical_and(int predicate)
int sub_group_non_uniform_scan_inclusive_logical_or(int predicate)
int sub_group_non_uniform_scan_inclusive_logical_xor(int predicate)

gentype sub_group_non_uniform_scan_exclusive_add(gentype value)
gentype sub_group_non_uniform_scan_exclusive_mul(gentype value)
gentype sub_group_non_uniform_scan_exclusive_min(gentype value)
gentype sub_group_non_uniform_scan_exclusive_max(gentype value)
gentype sub_group_non_uniform_scan_exclusive_and(gentype value)
gentype sub_group_non_uniform_scan_exclusive_or(gentype value)
gentype sub_group_non_uniform_scan_exclusive_xor(gentype value)
int sub_group_non_uniform_scan_exclusive_logical_and(int predicate)
int sub_group_non_uniform_scan_exclusive_logical_or(int predicate)
int sub_group_non_uniform_scan_exclusive_logical_xor(int predicate)

Version History

• Revision 1.0.0, 2020-12-15
  ◦ First assigned version.

cl_khr_subgroup_non_uniform_vote

Name String
  cl_khr_subgroup_non_uniform_vote
Ratification Status
   Ratified

Extension and Version Dependencies
   None

Other Extension Metadata

Last Modified Date
   2020-12-15

IP Status
   No known IP claims.

Description

**cl_khr_subgroup_non_uniform_vote** adds built-in OpenCL C functions with the ability to elect a single work item from a sub-group to perform a task and to hold votes among work items in a sub-group.

See the [Built-in Non-Uniform Vote and Election Functions for Sub-Groups](#) section of the OpenCL C specification for more information.

Summary of New OpenCL C Functions

```c
// These functions are available to devices supporting
// cl_khr_subgroup_non_uniform_vote:

int sub_group_elect()

int sub_group_non_uniform_all( int predicate )
int sub_group_non_uniform_any( int predicate )
int sub_group_non_uniform_all_equal( genotype value )
```

Version History

- Revision 1.0.0, 2020-12-15
  - First assigned version.

**cl_khr_subgroup_rotate**

Name String
   cl_khr_subgroup_rotate

Ratification Status
   Ratified
Extension and Version Dependencies
None

Other Extension Metadata

Last Modified Date
2022-04-22

IP Status
No known IP claims.

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Description
cl_khr_subgroup_rotate adds built-in OpenCL C functions with support for a new sub-group data
exchange operation that makes it possible to rotate values through the work items in a sub-group.

See the Sub-Group Rotation section of the OpenCL C specification for more information.

Version History
• Revision 1.0.0, 2022-04-22
  ◦ Initial version.

cl_khr_subgroup_shuffle

Name String
cl_khr_subgroup_shuffle

Ratification Status
Ratified

Extension and Version Dependencies
None

Other Extension Metadata

Last Modified Date
2020-12-15
**IP Status**
No known IP claims.

**Description**

`cl_khr_subgroup_shuffle` adds built-in OpenCL C functions providing additional ways to exchange data among work items in a sub-group.

See the General Purpose Shuffles section of the OpenCL C specification for more information.

**Summary of New OpenCL C Functions**

```c
// These functions are available to devices supporting
// cl_khr_subgroup_shuffle:

gentype sub_group_shuffle( gentype value, uint index )
gentype sub_group_shuffle_xor( gentype value, uint mask )
```

**Version History**

- Revision 1.0.0, 2020-12-15
  - First assigned version.

**cl_khr_subgroup_shuffle_relative**

**Name String**

`cl_khr_subgroup_shuffle_relative`

**Ratification Status**

Ratified

**Extension and Version Dependencies**

None

**Other Extension Metadata**

**Last Modified Date**

2020-12-15

**IP Status**

No known IP claims.

**Description**

`cl_khr_subgroup_shuffle_relative` adds built-in OpenCL C functions providing specialized ways to exchange data among work items in a sub-group that may perform better on some implementations.
See the Relative Shuffles section of the OpenCL C specification for more information.

Summary of New OpenCL C Functions

```c
// These functions are available to devices supporting
// cl_khr_subgroup_shuffle_relative:

gentype sub_group_shuffle_up( gentype value, uint delta )
gentype sub_group_shuffle_down( gentype value, uint delta )
```

Version History

- Revision 1.0.0, 2020-12-15
  - First assigned version.

**cl_khr_subgroups**

**Name String**

`cl_khr_subgroups`

**Ratification Status**

Ratified

**Extension and Version Dependencies**

None

**Deprecation State**

- Promoted to OpenCL 2.1

**Other Extension Metadata**

**Last Modified Date**

2020-04-21

**IP Status**

No known IP claims.

**Description**

`cl_khr_subgroups` adds support for implementation-controlled groups of work items, known as sub-groups. Sub-groups behave similarly to work-groups and have their own sets of built-ins and synchronization primitives. Sub-groups within a work-group are independent, may make forward progress with respect to each other, and may map to optimized hardware structures where that makes sense.

Sub-groups were promoted to a core feature in OpenCL 2.1. However, note that:

- The sub-group OpenCL C built-in functions described by this extension must still be accessed as
an OpenCL C extension in OpenCL 2.1.

• Sub-group independent forward progress is an optional device property in OpenCL 2.1, see `CL_DEVICE_SUB_GROUP_INDEPENDENT_FORWARD_PROGRESS`.

See the Sub-Groups section of the OpenCL C specification for more information.

New Commands

• `clGetKernelSubGroupInfoKHR`

New Types

• `cl_kernel_sub_group_info`

New Enums

• `cl_kernel_sub_group_info`
  ◦ `CL_KERNEL_MAX_SUB_GROUP_SIZE_FOR_NDRANGE_KHR`
  ◦ `CL_KERNEL_SUB_GROUP_COUNT_FOR_NDRANGE_KHR`

Version History

• Revision 1.0.0, 2020-04-21
  ◦ First assigned version.

**cl_khr_suggested_local_work_size**

Name String

`cl_khr_suggested_local_work_size`

Ratification Status

Ratified

Extension and Version Dependencies

None

Other Extension Metadata

Last Modified Date

2021-04-22

IP Status

No known IP claims.

Description

`cl_khr_suggested_local_work_size` adds the ability to query a suggested local work-group size for a kernel running on a device for a specified global work size and global work offset. The suggested
local work-group size will match the work-group size that would be chosen if the kernel were enqueued with the specified global work size and global work offset and a NULL local work size.

By using the suggested local work-group size query an application has greater insight into the local work-group size chosen by the OpenCL implementation, and the OpenCL implementation need not re-compute the local work-group size if the same kernel is enqueued multiple times with the same parameters.

New Commands

- clGetKernelSuggestedLocalWorkSizeKHR

Version History

- Revision 1.0.0, 2021-04-22
  - Initial version.

cl_khr_terminate_context

Name String

cl_khr_terminate_context

Ratification Status

Ratified

Extension and Version Dependencies

None

Other Extension Metadata

Last Modified Date

2020-04-21

IP Status

No known IP claims.

Description

The cl_khr_terminate_context extension provides a new query to check whether a device can terminate an OpenCL context, and adds an API to terminate a context.

Today, OpenCL provides an API to release a context. This operation is done only after all queues, memory object, programs and kernels are released, which in turn might wait for all ongoing operations to complete. However, there are cases in which a fast release is required, or release operation cannot be done, as commands are stuck in mid execution. An example of the first case can be program termination due to exception, or quick shutdown due to low power. Examples of the second case are when a kernel is running too long, or gets stuck, or it may result from user action which makes the results of the computation unnecessary.
In many cases, the driver or the device is capable of speeding up the closure of ongoing operations when the results are no longer required in a much more expedient manner than waiting for all previously enqueued operations to finish.

**New Commands**
- clTerminateContextKHR

**New Types**
- cl_device_terminate_capability_khr

**New Enums**
- cl_device_info
  - CL_DEVICE_TERMINATE_CAPABILITY_KHR
- cl_context_properties
  - CL_CONTEXT_TERMINATE_KHR
- cl_device_terminate_capability_khr
  - CL_DEVICE_TERMINATE_CAPABILITY_CONTEXT_KHR
- New Error codes
  - CL_CONTEXT_TERMINATED_KHR

**Version History**
- Revision 1.0.0, 2020-04-21
  - First assigned version.

**cl_khr_throttle_hints**

**Name String**
- cl_khr_throttle_hints

**Ratification Status**
- Ratified

**Extension and Version Dependencies**
- None

**Other Extension Metadata**

**Last Modified Date**
- 2020-04-21

**IP Status**
- No known IP claims.
Description

The `cl_khr_throttle_hints` extension adds throttle hints for OpenCL, but does not specify the throttling behavior or minimum guarantees. It is expected that the user guide associated with each implementation which supports this extension will describe the throttling behavior guarantees.

Note that the throttle hint is orthogonal to functionality defined in `cl_khr_priority_hints` extension. For example, a task may have high priority (`CL_QUEUE_PRIORITY_HIGH_KHR`) but should at the same time be executed at an optimized throttle setting (`CL_QUEUE_THROTTLE_LOW_KHR`).

New Types

- `cl_queue_throttle_khr`

New Enums

- `cl_queue_properties`
  - `CL_QUEUE_THROTTLE_KHR`
- `cl_queue_throttle_khr`
  - `CL_QUEUE_THROTTLE_HIGH_KHR`
  - `CL_QUEUE_THROTTLE_MED_KHR`
  - `CL_QUEUE_THROTTLE_LOW_KHR`

Version History

- Revision 1.0.0, 2020-04-21
  - First assigned version.

`cl_khr_work_group_uniform_arithmetic`

Name String

`cl_khr_work_group_uniform_arithmetic`

Ratification Status

Ratified

Extension and Version Dependencies

None

Other Extension Metadata

Last Modified Date

2022-04-29

IP Status

No known IP claims.
Contributors

- Kevin Petit, Arm Ltd.
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Description

c_l_k_h_r_w_o_r_k_g_r_o_u_p_u_n_i_f_o_r_m_a_r_i_t_h_m_e_t_i_c adds additional built-in work-group collective functions to OpenCL C. Specifically, this extension adds support for work-group scans and reductions for the following operators:

- Logical operations (and, or, and xor).
- Bitwise operations (and, or, and xor).
- Integer multiplication (mul).
- Floating-point multiplication (mul).

See the Work-group Collective Uniform Arithmetic Functions section of the OpenCL C specification for more information.

Issues

1. For these built-in functions, do we only want to support the types supported by the existing work-group collective functions, or do we want to support the types supported by the sub-group collective functions?

   **RESOLVED:** The extension will require the same types as the existing work-group collective functions.

   The difference are the 8-bit and 16-bit types: char, uchar, short, and ushort. Note that half is already supported, if half-precision is supported.

Version History

- Revision 1.0.0, 2022-04-29
  - Initial version.

List of Provisional Extensions

- cl_khr_command_buffer
- cl_khr_command_buffer_multi_device
- cl_khr_command_buffer_mutable_dispatch
- cl_khr_external_memory_dx
- cl_khr_external_semaphore_dx_fence
- cl_khr_external_semaphore_win32
- cl_khr_kernel_clock
**cl_khr_command_buffer**

**Name String**

`cl_khr_command_buffer`

**Ratification Status**

Ratified

**Extension and Version Dependencies**

OpenCL 1.2

- This is a *provisional* extension and must be used with caution. See the description of provisional header files for enablement and stability details.

**API Interactions**

- Interacts with CL_VERSION_2_0

**Other Extension Metadata**

**Last Modified Date**

2023-03-31

**IP Status**

No known IP claims.

**Contributors**

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**Description**

*cl_khr_command_buffer* adds the ability to record and replay buffers of OpenCL commands.

Command-buffers enable a reduction in overhead when enqueuing the same workload multiple times. By separating the command-queue setup from dispatch, the ability to replay a set of previously created commands is introduced.

Device-side *cl_sync_point_khr* synchronization-points can be used within command-buffers to define command dependencies. This allows the commands of a command-buffer to execute out-of-order on a single compatible command-queue. The command-buffer itself has no inherent in-order/out-of-order property, this ordering is inferred from the command-queue used on command recording. Out-of-order enqueues without event dependencies of both regular commands, such as *clEnqueueFillBuffer*, and command-buffers are allowed to execute concurrently, and it is up to the user to express any dependencies using events.

The command-queues a command-buffer will be executed on can be set on replay via parameters to *clEnqueueCommandBufferKHR*, provided they are compatible with the command-queues used on command-buffer recording.

**Background**

On embedded devices where building a command stream accounts for a significant expenditure of resources and where workloads are often required to be pipelined, a solution that minimizes driver overhead can significantly improve the utilization of accelerators by removing a bottleneck in repeated command stream generation.

An additional motivator is lowering task execution latency, as devices can be kept occupied with work by repeated submissions, without having to wait on the host to construct commands again for a similar workload.

**Rationale**

The command-buffer abstraction over the generation of command streams is a proven approach which facilitates a significant reduction in driver overhead in existing real-world applications with repetitive pipelined workloads which are built on top of Vulkan, DirectX 12, and Metal.

A primary goal is for a command-buffer to avoid any interaction with application code after being enqueued until all recorded commands have completed. As such, any command which maps or migrates memory objects; reads or writes memory objects; or enqueues a native kernel, is not available for command-buffer recording. Finally commands recorded into a command buffer do not wait for or return event objects, these are instead replaced with device-side synchronization-point identifiers which enable out-of-order execution when enqueued on compatible command-queues.

Adding new entry-points for individual commands, rather than recording existing command-queue APIs with begin/end markers was a design decision made for the following reasons:

- Individually specified entry points makes it clearer to the user what's supported, as opposed to adding a large number of error conditions throughout the specification with all the restrictions.
• Prevents code forking in existing entry points for the implemenetor, as otherwise separate paths in each entry point need to be maintained for both the recording and normal cases.

• Allows the definition of a new device-side synchronization primitive rather than overloading `cl_event`. As use of `cl_event` in individual commands allows host interaction from callback and user-events, as well as introducing complexities when a command-buffer is enqueued multiple times regarding profiling and execution status.

• New entry points facilitate returning handles to individual commands, allowing those commands to be modified between enqueues of the command buffer. Not all command handles are used in this extension, but providing them facilitates other extensions layered on top to take advantage of them to provide additional mutable functionality.

Simultaneous Use

The optional simultaneous use capability was added to the extension so that vendors can support pipelined workflows, where command-buffers are repeatedly enqueued without blocking in user code. However, simultaneous use may result in command-buffers being more expensive to enqueue than in a sequential model, so the capability is optional to enable optimizations on command-buffer recording.

Interactions With Other Extensions

The introduction of the command-buffer abstraction enables functionality beyond what the `cl_khr_command_buffer` extension currently provides, i.e. the recording of immutable commands to a single queue which can then be executed without commands synchronizing outside the command-buffer. Extra functionality expanding on this is provided as layered extensions on top of `cl_khr_command_buffer`. The layered extensions that currently exist are:

- `cl_khr_command_buffer_multi_device`
- `cl_khr_command_buffer_mutable_dispatch`

Having `cl_khr_command_buffer` as a minimal base specification means that the API defines mechanisms for functionality that is not enabled by this extension, these are described in the following sub-sections. `cl_khr_command_buffer` will retain its provisional extension status until other layered extensions are released, as these may reveal modifications needed to the base specification to support their intended use cases.

ND-range Kernel Command Properties

The `clCommandNDRangeKernelKHR` entry-point defines a `properties` parameter of new type `cl_ndrange_kernel_command_properties_khr`. No properties are defined in `cl_khr_command_buffer`, but the parameter enables layered extensions like `cl_khr_command_buffer_mutable_dispatch` to define properties that inform the characteristics of the kernel command.

Command Handles

All command recording entry-points define a `cl_mutable_command_khr` output parameter which provides a handle to the specific command being recorded. Use of these output handles is not enabled by the `cl_khr_command_buffer` extension, but the handles allow individual commands in a command-buffer to be referenced by the user.
Use of these handles is enabled in `cl_khr_command_buffer_mutable_dispatch` to give the capability for an application to use the handles to modify commands between enqueues of a command-buffer.

List of Queues

Only a single command-queue can be associated with a command-buffer in the `cl_khr_command_buffer` extension, but the API is designed so that the layered `cl_khr_command_buffer_multi_device` extension can relax this constraint to allow commands to be recorded across multiple queues in the same command-buffer, providing replay of heterogeneous task graphs.

Using multiple queue functionality will result in an error without `cl_khr_command_buffer_multi_device` to relax usage of the following API features:

- When a command-buffer is created the API enables passing a list of queues that the command-buffer will record commands to. Only a single queue is permitted in `cl_khr_command_buffer`.
- Individual command recording entry-points define a `cl_command_queue` parameter for which of the queues set on command-buffer creation that command should be record to. This must be passed as NULL in `cl_khr_command_buffer`.
- `clEnqueueCommandBufferKHR` takes a list of queues for command-buffer execution, correspond to those set on creation. Only a single queue is permitted in `cl_khr_command_buffer`.

New Commands

- `clCreateCommandBufferKHR`
- `clRetainCommandBufferKHR`
- `clReleaseCommandBufferKHR`
- `clFinalizeCommandBufferKHR`
- `clEnqueueCommandBufferKHR`
- `clCommandBarrierWithWaitListKHR`
- `clCommandCopyBufferKHR`
- `clCommandCopyBufferRectKHR`
- `clCommandCopyBufferToImageKHR`
- `clCommandCopyImageKHR`
- `clCommandCopyImageToBufferKHR`
- `clCommandFillBufferKHR`
- `clCommandFillImageKHR`
- `clCommandNDRangeKernelKHR`
- `clGetCommandBufferInfoKHR`

The following SVM entry points are supported only with at least OpenCL 2.0, and starting from version 0.9.4 of this extension

- `clCommandSVMMemcpyKHR`
- `clCommandSVMMemFillKHR`
New Types

- `cl_device_command_buffer_capabilities_khr`
- `cl_command_buffer_khr`
- `cl_sync_point_khr`
- `cl_command_buffer_info_khr`
- `cl_command_buffer_state_khr`
- `cl_command_buffer_properties_khr`
- `cl_command_buffer_flags_khr`
- `cl_ndrange_kernel_command_properties_khr`
- `cl_mutable_command_khr`

New Enums

- `cl_device_info`
  - `CL_DEVICE_COMMAND_BUFFER_CAPABILITIES_KHR`
  - `CL_DEVICE_COMMAND_BUFFER_REQUIRED_QUEUE_PROPERTIES_KHR`
- `cl_device_command_buffer_capabilities_khr`
  - `CL_COMMAND_BUFFER_CAPABILITY_KERNEL_PRINTF_KHR`
  - `CL_COMMAND_BUFFER_CAPABILITY_DEVICE_SIDE_ENQUEUE_KHR`
  - `CL_COMMAND_BUFFER_CAPABILITY_SIMULTANEOUS_USE_KHR`
  - `CL_COMMAND_BUFFER_CAPABILITY_OUT_OF_ORDER_KHR`
- `cl_command_buffer_properties_khr`
  - `CL_COMMAND_BUFFER_FLAGS_KHR`
- `cl_command_buffer_flags_khr`
  - `CL_COMMAND_BUFFER_SIMULTANEOUS_USE_KHR`
- `cl_command_buffer_info_khr`
  - `CL_COMMAND_BUFFER_QUEUES_KHR`
  - `CL_COMMAND_BUFFER_NUM_QUEUES_KHR`
  - `CL_COMMAND_BUFFER_REFERENCE_COUNT_KHR`
  - `CL_COMMAND_BUFFER_STATE_KHR`
  - `CL_COMMAND_BUFFER_PROPERTIES_ARRAY_KHR`
  - `CL_COMMAND_BUFFER_CONTEXT_KHR`
- `cl_command_buffer_state_khr`
  - `CL_COMMAND_BUFFER_STATE_RECORDING_KHR`
  - `CL_COMMAND_BUFFER_STATE_EXECUTABLE_KHR`
  - `CL_COMMAND_BUFFER_STATE_PENDING_KHR`
• cl_command_type
  ◦ CL_COMMAND_COMMAND_BUFFER_KHR

• New Error Codes
  ◦ CL_INVALID_COMMAND_BUFFER_KHR
  ◦ CL_INVALID_SYNC_POINT_WAIT_LIST_KHR
  ◦ CL_INCOMPATIBLE_COMMAND_QUEUE_KHR

Sample Code

```c
#define CL_CHECK(ERROR)                             
  if (ERROR) {                                      
    std::cerr << "OpenCL error: " << ERROR << "\n"; 
    return ERROR;                                   
  }

int main() { 
  cl_platform_id platform; 
  CL_CHECK(clGetPlatformIDs(1, &platform, nullptr)); 
  cl_device_id device; 
  CL_CHECK(clGetDeviceIDs(platform, CL_DEVICE_TYPE_ALL, 1, &device, nullptr));

  cl_int error; 
  cl_context context = 
    clCreateContext(nullptr, 1, &device, nullptr, nullptr, &error); 
  CL_CHECK(error);

  const char* code = R"OpenCLC(" 
  kernel void vector_addition(global int* tile1, global int* tile2, 
      global int* res) { 
    size_t index = get_global_id(0); 
    res[index] = tile1[index] + tile2[index]; 
} 
)OpenCLC";
  const size_t length = std::strlen(code);

  cl_program program = 
    clCreateProgramWithSource(context, 1, &code, &length, &error); 
  CL_CHECK(error);

  CL_CHECK(clBuildProgram(program, 1, &device, nullptr, nullptr, nullptr));

  cl_kernel kernel = clCreateKernel(program, "vector_addition", &error); 
  CL_CHECK(error);

  constexpr size_t frame_count = 60; 
  constexpr size_t frame_elements = 1024; 
  constexpr size_t frame_size = frame_elements * sizeof(cl_int);
```

constexpr size_t tile_count = 16;
constexpr size_t tile_elements = frame_elements / tile_count;
constexpr size_t tile_size = tile_elements * sizeof(cl_int);

cl_mem buffer_tile1 =
    clCreateBuffer(context, CL_MEM_READ_ONLY, tile_size, nullptr, &error);
CL_CHECK(error);
cl_mem buffer_tile2 =
    clCreateBuffer(context, CL_MEM_READ_ONLY, tile_size, nullptr, &error);
CL_CHECK(error);
cl_mem buffer_res =
    clCreateBuffer(context, CL_MEM_WRITE_ONLY, tile_size, nullptr, &error);
CL_CHECK(error);

CL_CHECK(clSetKernelArg(kernel, 0, sizeof(buffer_tile1), &buffer_tile1));
CL_CHECK(clSetKernelArg(kernel, 1, sizeof(buffer_tile2), &buffer_tile2));
CL_CHECK(clSetKernelArg(kernel, 2, sizeof(buffer_res), &buffer_res));

cl_command_queue command_queue =
    clCreateCommandQueue(context, device,
    CL_QUEUE_OUT_OF_ORDER_EXEC_MODE_ENABLE, &error);
CL_CHECK(error);

cl_command_buffer_khr command_buffer =
    clCreateCommandBufferKHR(1, &command_queue, nullptr, &error);
CL_CHECK(error);

cl_mem buffer_src1 =
    clCreateBuffer(context, CL_MEM_READ_ONLY, frame_size, nullptr, &error);
CL_CHECK(error);
cl_mem buffer_src2 =
    clCreateBuffer(context, CL_MEM_READ_ONLY, frame_size, nullptr, &error);
CL_CHECK(error);
cl_mem buffer_dst =
    clCreateBuffer(context, CL_MEM_WRITE_ONLY, frame_size, nullptr, &error);
CL_CHECK(error);

cl_sync_point_khr tile_sync_point = 0;
for (size_t tile_index = 0; tile_index < tile_count; tile_index++) {
    std::array<cl_sync_point_khr, 2> copy_sync_points;
    CL_CHECK(clCommandCopyBufferKHR(command_buffer,
        command_queue, buffer_src1, buffer_tile1, tile_index * tile_size, 0,
        tile_size, tile_sync_point ? 1 : 0,
        tile_sync_point ? &tile_sync_point : nullptr, &copy_sync_points[0]),
        nullptr);
    CL_CHECK(clCommandCopyBufferKHR(command_buffer,
        command_queue, buffer_src2, buffer_tile2, tile_index * tile_size, 0,
        tile_size, tile_sync_point ? 1 : 0,
        tile_sync_point ? &tile_sync_point : nullptr, &copy_sync_points[1]),
        nullptr);
CL_SYNC_POINT_KHR

CL_CHECK(clCommandNDRangeKernelKHR(command_buffer,
    command_queue, nullptr, kernel, 1, nullptr, &tile_elements, nullptr,
    copy_sync_points.size(), copy_sync_points.data(), &nd_sync_point,
    nullptr));

CL_CHECK(clCommandCopyBufferKHR(command_buffer,
    command_queue, buffer_res, buffer_dst, 0, tile_index * tile_size,
    tile_size, 1, &nd_sync_point, &tile_sync_point, nullptr));

CL_CHECK(clFinalizeCommandBufferKHR(command_buffer));

std::random_device random_device;
std::mt19937 random_engine(random_device);
std::uniform_int_distribution<cl_int> random_distribution{
    0, std::numeric_limits<cl_int>::max() / 2};
auto random_generator = [8]() { return random_distribution(random_engine); };

for (size_t frame_index = 0; frame_index < frame_count; frame_index++) {
    std::vector<cl_event, 2> write_src_events;
    std::vector<cl_int> src1(frame_elements);
    std::generate(src1.begin(), src1.end(), random_generator);
    CL_CHECK(clEnqueueWriteBuffer(command_queue, buffer_src1, CL_FALSE, 0,
        frame_size, src1.data(), 0, nullptr,
        &write_src_events[0]));
    std::vector<cl_int> src2(frame_elements);
    std::generate(src2.begin(), src2.end(), random_generator);
    CL_CHECK(clEnqueueWriteBuffer(command_queue, buffer_src2, CL_FALSE, 0,
        frame_size, src2.data(), 0, nullptr,
        &write_src_events[1]));

    CL_CHECK(clEnqueueCommandBufferKHR(0, NULL, command_buffer, 2,
        write_src_events.data(), nullptr));

    CL_CHECK(clFinish(command_queue));

    CL_CHECK(clReleaseEvent(write_src_event[0]));
    CL_CHECK(clReleaseEvent(write_src_event[1]));
}

CL_CHECK(clReleaseCommandBufferKHR(command_buffer));
CL_CHECK(clReleaseCommandQueue(command_queue));

CL_CHECK(clReleaseMemObject(buffer_src1));
CL_CHECK(clReleaseMemObject(buffer_src2));
CL_CHECK(clReleaseMemObject(buffer_dst));

CL_CHECK(clReleaseMemObject(buffer_tile1));
CL_CHECK(clReleaseMemObject(buffer_tile2));
CL_CHECK(clReleaseMemObject(buffer_res));
CL_CHECK(clReleaseKernel(kernel));
CL_CHECK(clReleaseProgram(program));
CL_CHECK(clReleaseContext(context));

return 0;
}

Issues

1. Introduce a `clCloneCommandBufferKHR` entry-point for cloning a command-buffer.
   
   **UNRESOLVED**

2. Enable detached command-buffer execution, where command-buffers are executed on their own internal queue to prevent locking user created queues for the duration of their execution.
   
   **UNRESOLVED**

Version History

- Revision 0.9.0, 2021-11-10
  - First assigned version (provisional).
- 0.9.1, 2022-08-24
  - Specify an error if a command-buffer is finalized multiple times (provisional).
- 0.9.2, 2023-03-31
  - Introduce context query `CL_COMMAND_BUFFER_CONTEXT_KHR` (provisional).
- 0.9.3, 2023-04-04
  - Remove Invalid command-buffer state (provisional).
- 0.9.4, 2023-05-11
  - Add `clCommandSVMMemcpyKHR` and `clCommandSVMMemFillKHR` command entries (provisional).

**cl_khr_command_buffer_multi_device**

**Name String**

`cl_khr_command_buffer_multi_device`

**Ratification Status**

Ratified

**Extension and Version Dependencies**

`cl_khr_command_buffer`

- This is a *provisional* extension and must be used with caution. See the description of provisional header files for enablement and stability details.
Other Extension Metadata

Last Modified Date
2023-04-30

IP Status
No known IP claims.

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Description

The cl_khr_command_buffer extension separates command construction from enqueue by providing a mechanism to record a set of commands which can then be repeatedly enqueued. However, the commands in a command-buffer can only be recorded to a single command-queue specified on command-buffer creation.

cl_khr_command_buffer_multi_device extends the scope of a command-buffer to allow commands to be recorded across multiple queues in the same command-buffer, providing execution of heterogeneous task graphs from command-queues associated with different devices.

The ability for a user to deep copy an existing command-buffer so that the commands target a different device is also made possible by cl_khr_command_buffer_multi_device. Depending on platform support the mapping of commands to the new target device can be done either explicitly by the user, or automatically by the OpenCL runtime.

New Commands
- clRemapCommandBufferKHR
New Types

Bitfield for querying command-buffer capabilities of an OpenCL Platform with `clGetPlatformInfo`, see the platform queries table:

- `cl_platform_command_buffer_capabilities_khr`

New Enums

Enums for querying device command-buffer capabilities with `clGetDeviceInfo`, see the device queries table:

- `cl_device_info`
  - `CL_DEVICE_COMMAND_BUFFER_NUM_SYNC_DEVICES_KHR`
  - `CL_DEVICE_COMMAND_BUFFER_SYNC_DEVICES_KHR`
- `cl_device_command_buffer_capabilities_khr`
  - `CL_COMMAND_BUFFER_CAPABILITY_MULTIPLE_QUEUE_KHR`
- `cl_command_buffer_flags_khr`
  - `CL_COMMAND_BUFFER_DEVICE_SIDE_SYNC_KHR`
- `cl_platform_info`
  - `CL_PLATFORM_COMMAND_BUFFER_CAPABILITIES_KHR`
- `cl_platform_command_buffer_capabilities_khr`
  - `CL_COMMAND_BUFFER_PLATFORM_UNIVERSAL_SYNC_KHR`
  - `CL_COMMAND_BUFFER_PLATFORM_REMAP_QUEUES_KHR`
  - `CL_COMMAND_BUFFER_PLATFORM_AUTOMATIC_REMAP_KHR`

Sample Code

```c
#define CL_CHECK(ERROR)                                                                
  if (ERROR) {                                                                        
    std::cerr << "OpenCL error: " << ERROR << "\n";                                 
    return ERROR;                                                                    
  }

int main() {
  cl_platform_id platform;
  CL_CHECK(clGetPlatformIDs(1, &platform, nullptr));
  cl_platform_command_buffer_capabilities_khr platform_caps;
  CL_CHECK(clGetPlatformInfo(platform,
                              CL_PLATFORM_COMMAND_BUFFER_CAPABILITIES_KHR,
                              sizeof(platform_caps), &platform_caps, NULL));
  if (!(platform_caps & CL_COMMAND_BUFFER_PLATFORM_AUTOMATIC_REMAP_KHR)) {
    std::cerr << "Command-buffer remapping not supported but used in example," "\n" "skipping\n";
    return 0;
  }
```

576
...
clCreateBuffer(context, CL_MEM_READ_ONLY, tile_size, NULL, &error);
CL_CHECK(error);

cl_mem buffer_tile2 =
    clCreateBuffer(context, CL_MEM_READ_ONLY, tile_size, NULL, &error);
CL_CHECK(error);

cl_mem buffer_res =
    clCreateBuffer(context, CL_MEM_WRITE_ONLY, tile_size, NULL, &error);
CL_CHECK(error);

CL_CHECK(clSetKernelArg(kernel, 0, sizeof(buffer_tile1), &buffer_tile1));
CL_CHECK(clSetKernelArg(kernel, 1, sizeof(buffer_tile2), &buffer_tile2));
CL_CHECK(clSetKernelArg(kernel, 2, sizeof(buffer_res), &buffer_res));

cl_command_buffer_khr original_cmdbuf =
    clCreateCommandBufferKHR(num_devices, queues.data(), nullptr, &error);
CL_CHECK(error);

cl_mem buffer_src1 =
    clCreateBuffer(context, CL_MEM_READ_ONLY, frame_size, NULL, &error);
CL_CHECK(error);

cl_mem buffer_src2 =
    clCreateBuffer(context, CL_MEM_READ_ONLY, frame_size, NULL, &error);
CL_CHECK(error);

cl_mem buffer_dst =
    clCreateBuffer(context, CL_MEM_READ_WRITE, frame_size, NULL, &error);
CL_CHECK(error);

cl_sync_point_khr tile_sync_point = 0;
for (size_t tile_index = 0; tile_index < tile_count; tile_index++) {
    cl_sync_point_khr copy_sync_points[2];
    CL_CHECK(clCommandCopyBufferKHR(
        original_cmdbuf, queues[tile_index % num_devices], buffer_src1,
        buffer_tile1, tile_index * tile_size, 0, tile_size,
        tile_sync_point ? 1 : 0, tile_sync_point ? &tile_sync_point : NULL,
        &copy_sync_points[0], NULL));

    CL_CHECK(clCommandCopyBufferKHR(
        original_cmdbuf, queues[tile_index % num_devices], buffer_src2,
        buffer_tile2, tile_index * tile_size, 0, tile_size,
        tile_sync_point ? 1 : 0,
        tile_sync_point ? &tile_sync_point : nullptr,
        &copy_sync_points[1], NULL));

    cl_sync_point_khr nd_sync_point;
    CL_CHECK(clCommandNDRangeKernelKHR(
        original_cmdbuf, queues[tile_index % num_devices], NULL, kernel, 1,
        NULL, &tile_elements, NULL, 2, copy_sync_points, &nd_sync_point, NULL));
CL_CHECK(clCommandCopyBufferKHR(
    original_cmdbuf, queues[tilde_index % num_devices], buffer_res,
    buffer_dst, 0, tile_index * tile_size, tile_size, 1, &nd_sync_point,
    &tile_sync_point, NULL));
}
CL_CHECK(clFinalizeCommandBufferKHR(original_cmdbuf));

std::random_device random_device;
std::mt19937 random_engine{random_device};
std::uniform_int_distribution<cl_int> random_distribution{
    0, std::numeric_limits<cl_int>::max() / 2};
auto random_generator = [8]() { return random_distribution(random_engine); }

auto enqueue_frame = [8](cl_command_buffer_khr command_buffer) {
    for (size_t frame_index = 0; frame_index < frame_count; frame_index++) {
        std::array<cl_event, 3> enqueue_events;
        std::vector<cl_int> src1(frame_elements);
        std::generate(src1.begin(), src1.end(), random_generator);
        CL_CHECK(clEnqueueWriteBuffer(queues[0], buffer Src1, CL_FALSE, 0,
            frame_size, src1.data(), 0, nullptr,
            &enqueue_events[0]));
        std::vector<cl_int> src2(frame_elements);
        std::generate(src2.begin(), src2.end(), random_generator);
        CL_CHECK(clEnqueueWriteBuffer(queues[0], buffer Src2, CL_FALSE, 0,
            frame_size, src2.data(), 0, nullptr,
            &enqueue_events[1]));
        CL_CHECK(clEnqueueCommandBufferKHR(0, NULL, command_buffer, 2,
            enqueue_events.data(),
            &enqueue_events[2]));
        CL_CHECK(clWaitForEvents(1, enqueue_events[2]));
        for (auto e : enqueue_events) {
            CL_CHECK(clReleaseEvent(e));
        }
    }
    return 0;
};

error = enqueue_frame(original_cmdbuf);
CL_CHECK(error);

// Remap from N queues to 1 queue and run again
cl_command_buffer_khr remapped_cmdbuf = clRemapCommandBufferKHR(
    original_cmdbuf, CL_TRUE, 1, queues.data(), 0, NULL, NULL, &error);
CL_CHECK(error);

error = enqueue_frame(remapped_cmdbuf);
CL_CHECK(error);

for (unsigned i = 0; i < num_devices; ++i) {
    CL_CHECK(clReleaseCommandQueue(queues[i]));
}

CL_CHECK(clReleaseMemObject(buffer_src1));
CL_CHECK(clReleaseMemObject(buffer_src2));
CL_CHECK(clReleaseMemObject(buffer_dst));

CL_CHECK(clReleaseMemObject(buffer_tile1));
CL_CHECK(clReleaseMemObject(buffer_tile2));
CL_CHECK(clReleaseMemObject(buffer_res));

CL_CHECK(clReleaseCommandBufferKHR(original_cmdbuf));
CL_CHECK(clReleaseCommandBufferKHR(remapped_cmdbuf));

CL_CHECK(clReleaseKernel(kernel));
CL_CHECK(clReleaseProgram(program));
CL_CHECK(clReleaseContext(context));

return 0;

---

**Issues**

1. In `cl_event` profiling info for a command-buffer running across the queues for several devices, how do we know what the first & last commands executed are if there is concurrent execution across devices.

   **RESOLVED:** Allowed an implementation to fallback to `CL_PROFILING_COMMAND_SUBMIT` and `CL_PROFILING_COMMAND_COMPLETE` when reporting `CL_PROFILING_COMMAND_START` & `CL_PROFILING_COMMAND_END`.

2. Is an atomic constraint required? This would forbid regular `clEnqueue*` commands, from interleaving execution on a queue which a command-buffer is being executed on.

   **RESOLVED:** This behavior can block parallelism, and constraint is expressible by the user through existing synchronization mechanisms if they require it.

3. It is currently an error if a set of command-queues passed to `clEnqueueCommandBufferKHR` aren’t compatible with those set on recording. Should we relax this as an optional capability that allows an implementation to do a more expensive command-buffer enqueue for this case?

   **RESOLVED:** Added as an optional feature.

**Version History**

- Revision 0.9.0, 2023-04-14
  - First assigned version (provisional).
Revision 0.9.1, 2023-04-30

- Added clCommandSVMMemcpyKHR and clCommandSVMMemFillKHR as affected functions (provisional).

**cl_khr_command_buffer_mutable_dispatch**

**Name String**

- cl_khr_command_buffer_mutable_dispatch

**Ratification Status**

- Ratified

**Extension and Version Dependencies**

- cl_khr_command_buffer

  - This is a *provisional* extension and must be used with caution. See the description of provisional header files for enablement and stability details.

**Other Extension Metadata**

**Last Modified Date**

- 2022-08-31

**IP Status**

- No known IP claims.

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Description

The `cl_khr_command_buffer` extension separates command construction from enqueue by providing a mechanism to record a set of commands which can then be repeatedly enqueued. However, the commands recorded to the command-buffer are immutable between enqueues.

`cl_khr_command_buffer_mutable_dispatch` removes this restriction. In particular, this extension allows the configuration of a kernel execution command in a command-buffer, called a `mutable-dispatch`, to be modified. This allows inputs and outputs to the kernel, as well as work-item sizes and offsets, to change without having to re-record the entire command sequence in a new command-buffer.

Interactions With Other Extensions

The `cl_command_buffer_structure_type_khr` type has been added to this extension for the purpose of allowing expansion of mutable functionality in future extensions layered on top of `cl_khr_command_buffer_mutable_dispatch`. Any parameter that is a structure containing a `void* next` member must have a value of `next` that is either `NULL`, or is a pointer to a valid structure defined by `cl_khr_command_buffer_mutable_dispatch` or an extension layered on top. To be a valid structure in the pointer chain the first member of the structure must be a `cl_command_buffer_structure_type_khr` identifier for the structure being iterated through, and the second member a `void* next` pointer to the next structure in the chain.

This approach is based on structure pointer chains in Vulkan, for more details see the “Valid Usage for Structure Pointer Chains” section of the Vulkan specification.

This is designed so that another extension layered on `cl_khr_command_buffer_mutable_dispatch` could allow modification of commands recorded to a command-buffer other than kernel execution commands. As all command recording entry-points return a `cl_mutable_command_khr` handle, and aspects like which `cl_mem` object a command uses could also be updated between enqueues of the command-buffer.

New Commands

- `clUpdateMutableCommandsKHR`
- `clGetMutableCommandInfoKHR`

New Types

- `cl_mutable_dispatch_fields_khr`
- `cl_mutable_command_info_khr`
- `cl_command_buffer_structure_type_khr`
- `cl_mutable_base_config_khr`
- `cl_mutable_dispatch_asserts_khr`
- `cl_mutable_dispatch_config_khr`
- `cl_mutable_dispatch_exec_info_khr`
• **cl Mutable dispatch arg khr**

**New Enums**

• **cl device info**
  ◦ **CL DEVICE MUTABLE DISPATCH CAPABILITIES KHR**

• **cl ndrange kernel command properties khr**
  ◦ **CL MUTABLE DISPATCH ASSERTS KHR**
  ◦ **CL MUTABLE DISPATCH UPDATABLE FIELDS KHR**

• **cl mutable dispatch asserts khr**
  ◦ **CL MUTABLE DISPATCH ASSERT NO_ADDITIONAL_WORK_GROUPS KHR**

• **cl mutable dispatch fields khr**
  ◦ **CL MUTABLE DISPATCH GLOBAL OFFSET KHR**
  ◦ **CL MUTABLE DISPATCH GLOBAL SIZE KHR**
  ◦ **CL MUTABLE DISPATCH LOCAL SIZE KHR**
  ◦ **CL MUTABLE DISPATCH ARGUMENTS KHR**
  ◦ **CL MUTABLE DISPATCH EXEC_INFO KHR**

• **cl mutable command info khr**
  ◦ **CL MUTABLE COMMAND COMMAND QUEUE KHR**
  ◦ **CL MUTABLE COMMAND COMMAND BUFFER KHR**
  ◦ **CL MUTABLE DISPATCH PROPERTIES ARRAY KHR**
  ◦ **CL MUTABLE DISPATCH KERNEL KHR**
  ◦ **CL MUTABLE DISPATCH DIMENSIONS KHR**
  ◦ **CL MUTABLE DISPATCH GLOBAL WORK OFFSET KHR**
  ◦ **CL MUTABLE DISPATCH GLOBAL WORK SIZE KHR**
  ◦ **CL MUTABLE DISPATCH LOCAL WORK SIZE KHR**
  ◦ **CL MUTABLE COMMAND COMMAND TYPE KHR**

• **cl command buffer flags khr**
  ◦ **CL COMMAND BUFFER MUTABLE KHR**

• **cl command buffer properties khr**
  ◦ **CL COMMAND BUFFER MUTABLE DISPATCH ASSERTS KHR**

• **cl command buffer structure type khr**
  ◦ **CL STRUCTURE TYPE MUTABLE BASE CONFIG KHR**
  ◦ **CL STRUCTURE TYPE MUTABLE DISPATCH CONFIG KHR**

**New Error Codes**

• **CL INVALID_MUTABLE_COMMAND KHR**
#define CL_CHECK(ERROR)                             
  if (ERROR) {                                      
    std::cerr << "OpenCL error: " << ERROR << "\n"; 
    return ERROR;                                   
  } 

int main() { 
  cl_platform_id platform; 
  CL_CHECK(clGetPlatformIDs(1, &platform, nullptr)); 
  cl_device_id device; 
  CL_CHECK(clGetDeviceIDs(platform, CL_DEVICE_TYPE_ALL, 1, &device, nullptr)); 

  cl_mutable_dispatch_fields_khr mutable_capabilities; 
  CL_CHECK(clGetDeviceInfo(device, CL_DEVICE_MUTABLE_DISPATCH_CAPABILITIES_KHR, 
                                 sizeof(mutable_capabilities), &mutable_capabilities, nullptr)); 

  if (!mutable_capabilities & CL_MUTABLE_DISPATCH_ARGUMENTS_KHR) { 
    std::cerr 
                << "Device does not support update arguments to a mutable-dispatch, " 
                << "skipping example.\n"; 
    return 0; 
  } 

  cl_int error; 
  cl_context context = 
    clCreateContext(nullptr, 1, &device, nullptr, nullptr, &error); 
  CL_CHECK(error); 

  const char* code = R"OpenCLC(kernel void vector_addition(global int* tile1, global int* tile2, 
                                 global int* res) { 
                      size_t index = get_global_id(0); 
                      res[index] = tile1[index] + tile2[index]; 
                  } )OpenCLC"; 
  const size_t length = std::strlen(code); 

  cl_program program = 
    clCreateProgramWithSource(context, 1, &code, &length, &error); 
  CL_CHECK(error); 

  CL_CHECK(clBuildProgram(program, 1, &device, nullptr, nullptr, nullptr)); 

  cl_kernel kernel = clCreateKernel(program, "vector_addition", &error); 
  CL_CHECK(error); 

  // Set the parameters of the frames
constexpr size_t iterations = 60;
constexpr size_t elem_size = sizeof(cl_int);
constexpr size_t frame_width = 32;
constexpr size_t frame_count = frame_width * frame_width;
constexpr size_t frame_size = frame_count * elem_size;

cl_mem input_A_buffers[2] = {nullptr, nullptr};
cl_mem input_B_buffers[2] = {nullptr, nullptr};
cl_mem output_buffers[2] = {nullptr, nullptr};

// Create the buffer to swap between even and odd kernel iterations
for (size_t i = 0; i < 2; i++) {
    input_A_buffers[i] = 
        clCreateBuffer(context, CL_MEM_READ_ONLY, frame_size, nullptr, &error);
    CL_CHECK(error);
    input_B_buffers[i] = 
        clCreateBuffer(context, CL_MEM_READ_ONLY, frame_size, nullptr, &error);
    CL_CHECK(error);
    output_buffers[i] = 
        clCreateBuffer(context, CL_MEM_WRITE_ONLY, frame_size, nullptr, &error);
    CL_CHECK(error);
}

cl_command_queue command_queue = 
    clCreateCommandQueue(context, device, 0, &error);
CL_CHECK(error);

// Create command-buffer with mutable flag so we can update it
cl_command_buffer_properties_khr properties[3] = {
    CL_COMMAND_BUFFER_FLAGS_KHR, CL_COMMAND_BUFFER_MUTABLE_KHR, 0};
cl_command_buffer_khr command_buffer = 
    clCreateCommandBufferKHR(1, &command_queue, properties, &error);
CL_CHECK(error);

CL_CHECK(clSetKernelArg(kernel, 0, sizeof(cl_mem), &input_A_buffers[0]));
CL_CHECK(clSetKernelArg(kernel, 1, sizeof(cl_mem), &input_B_buffers[0]));
CL_CHECK(clSetKernelArg(kernel, 2, sizeof(cl_mem), &output_buffers[0]));

// Instruct the nd-range command to allow for mutable kernel arguments
cl_ndrange_kernel_command_properties_khr mutable_properties[] = {
    CL_MUTABLE_DISPATCH_UPDATABLE_FIELDS_KHR,
    CL_MUTABLE_DISPATCH_ARGUMENTS_KHR, 0};

// Create command handle for mutating nd-range command
cl_mutable_command_khr command_handle = nullptr;

// Add the nd-range kernel command
error = clCommandNDRangeKernelKHR(
    command_buffer, command_queue, mutable_properties, kernel, 1, nullptr,
&frame_count, nullptr, 0, nullptr, nullptr, &command_handle);
CL_CHECK(error);

CL_CHECK(clFinalizeCommandBufferKHR(command_buffer));

// Prepare for random input generation
std::random_device random_device;
std::mt19937 random_engine{random_device};
std::uniform_int_distribution<cl_int> random_distribution{
  std::numeric_limits<cl_int>::min() / 2,
  std::numeric_limits<cl_int>::max() / 2};

// Iterate over each frame
for (size_t i = 0; i < iterations; i++) {
  // Set the buffers for the current frame
  cl_mem input_A_buffer = input_A_buffers[i % 2];
  cl_mem input_B_buffer = input_B_buffers[i % 2];
  cl_mem output_buffer = output_buffers[i % 2];

  // Generate input A data
  std::vector<cl_int> input_a(frame_count);
  std::generate(std::begin(input_a), std::end(input_a),
                [i]() { return random_distribution(random_engine); });

  // Write the generated data to the input A buffer
  error =
    clEnqueueWriteBuffer(command_queue, input_A_buffer, CL_FALSE, 0,
                         frame_size, input_a.data(), 0, nullptr, nullptr);
  CL_CHECK(error);

  // Generate input B data
  std::vector<cl_int> input_b(frame_count);
  std::generate(std::begin(input_b), std::end(input_b),
                [i]() { return random_distribution(random_engine); });

  // Write the generated data to the input B buffer
  error =
    clEnqueueWriteBuffer(command_queue, input_B_buffer, CL_FALSE, 0,
                         frame_size, input_b.data(), 0, nullptr, nullptr);
  CL_CHECK(error);

  // If not executing the first frame
  if (i != 0) {
    // Configure the mutable configuration to update the kernel arguments
    cl_mutable_dispatch_arg_khr arg_0{0, sizeof(cl_mem), &input_A_buffer};
    cl_mutable_dispatch_arg_khr arg_1{1, sizeof(cl_mem), &input_B_buffer};
    cl_mutable_dispatch_arg_khr arg_2{2, sizeof(cl_mem), &output_buffer};
    cl_mutable_dispatch_arg_khr args[] = {arg_0, arg_1, arg_2};
    cl_mutable_dispatch_config_khr dispatch_config{
      CL_STRUCTURE_TYPE_MUTABLE_DISPATCH_CONFIG_KHR,
      nullptr,
      ...}
  }
}
command_handle, 
3 /* num_args */,
0 /* num_svm_arg */,
0 /* num_exec_infos */,
0 /* work_dim - 0 means no change to dimensions */,
args /* arg_list */,
nullptr /* arg_svm_list - nullptr means no change*/,
nullptr /* exec_info_list */,
nullptr /* global_work_offset */,
nullptr /* global_work_size */,
nullptr /* local_work_size */};

c1 mutable_base_config_khr mutable_config{
  CL_STRUCTURE_TYPE_MUTABLE_BASE_CONFIG_KHR, nullptr, 1,
  &dispatch_config};

// Update the command buffer with the mutable configuration
error = clUpdateMutableCommandsKHR(command_buffer, &mutable_config);
CL_CHECK(error);
}

// Enqueue the command buffer
error = clEnqueueCommandBufferKHR(0, nullptr, command_buffer, 0, nullptr,
                                   nullptr);
CL_CHECK(error);

// Allocate memory for the output data
std::vector<cl_int> output(frame_count);

// Read the output data from the output buffer
error = clEnqueueReadBuffer(command_queue, output_buffer, CL_TRUE, 0,
                             frame_size, output.data(), 0, nullptr, nullptr);
CL_CHECK(error);

// Flush and execute the read buffer
error = clFinish(command_queue);
CL_CHECK(error);

// Verify the results of the frame
for (size_t i = 0; i < frame_count; ++i) {
  const cl_int result = input_a[i] + input_b[i];
  if (output[i] != result) {
    std::cerr << "Error: Incorrect result at index " << i << " - Expected "
              << output[i] << " was " << result << std::endl;
    std::exit(1);
  }
}
}

std::cout << "Result verified\n";
CL_CHECK(clReleaseCommandBufferKHR(command_buffer));
for (size_t i = 0; i < 2; i++) {
    CL_CHECK(clReleaseMemObject(input_A_buffers[i]));
    CL_CHECK(clReleaseMemObject(input_B_buffers[i]));
    CL_CHECK(clReleaseMemObject(output_buffers[i]));
}
CL_CHECK(clReleaseCommandQueue(command_queue));
CL_CHECK(clReleaseKernel(kernel));
CL_CHECK(clReleaseProgram(program));
CL_CHECK(clReleaseContext(context));
CL_CHECK(clReleaseDevice(device));
return 0;
}

Issues

1. Include simpler, more user friendly, entry-points for updating kernel arguments?

    **RESOLVED**: Can be implemented in the ecosystem as a layer on top, if that layer proves popular then can be introduced, possibly as another extension on top.

2. Add a command-buffer clone entry-point for deep copying a command-buffer? Arguments could then be updated and both command-buffers used. Useful for techniques like double buffering.

    **RESOLVED**: In the use-case we're targeting a user would only have a handle to the original command-buffer, but not the clone, which may limit the usefulness of this capability. Additionally, an implementation could be complicated by non-trivial deep copying of the underlying objects contained in the command-buffer. As a result of this new entry-point being an additive change to the specification it is omitted, and if its functionality has demand later, it may be a introduced as a stand alone extension.

Version History

- Revision 0.9.0, 2022-08-31
  - First assigned version (provisional).
- Revision 0.9.1, 2023-11-07
  - Add type `cl.mutable_dispatch AssertsKHR` and its possible values (provisional).

**cl_khr_external_memory_dx**

Name String

`cl_khr_external_memory_dx`

Ratification Status

Ratified

Extension and Version Dependencies

OpenCL 3.0
and

\textit{cl\_khr\_external\_memory}

- This is a \textit{provisional} extension and must be used with caution. See the description of provisional header files for enablement and stability details.

Other Extension Metadata

Last Modified Date

2023-08-29

IP Status

No known IP claims.

Contributors

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Description

\texttt{cl\_khr\_external\_memory\_dx} extends \texttt{cl\_external\_memory\_handle\_type\_khr} to support Windows handles referring to Direct 3D resources as external memory handle types that may be specified when creating a buffer or image memory object.

New Enums

- \texttt{cl\_external\_memory\_handle\_type\_khr}
° CL_EXTERNAL_MEMORY_HANDLE_D3D11_TEXTURE_KHR
° CL_EXTERNAL_MEMORY_HANDLE_D3D11_TEXTURE_KMT_KHR
° CL_EXTERNAL_MEMORY_HANDLE_D3D12_HEAP_KHR
° CL_EXTERNAL_MEMORY_HANDLE_D3D12_RESOURCE_KHR

Version History

• Revision 0.9.0, 2021-09-10
  ○ Initial version (provisional).

• Revision 0.9.1, 2023-05-04
  ○ Clarified device handle list enum cannot be specified without an external memory handle (provisional).

• Revision 0.9.2, 2023-08-01
  ○ Changed device handle list enum to the memory-specific CL_MEM_DEVICE_HANDLE_LIST_KHR (provisional).

• Revision 0.9.3, 2023-08-29
  ○ Added query for CL_DEVICE_EXTERNAL_MEMORY_IMPORT_ASSUME_LINEAR_IMAGES_HANDLE_TYPES_KHR (provisional).

cl_khr_external_semaphore_dx_fence

Name String

cl_khr_external_semaphore_dx_fence

Ratification Status

Ratified

Extension and Version Dependencies

OpenCL 1.2
and
cl_khr_semaphore
and
cl_khr_external_semaphore

• This is a provisional extension and must be used with caution. See the description of provisional header files for enablement and stability details.

Other Extension Metadata

Last Modified Date

2021-09-10

IP Status

No known IP claims.
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Description

**cl_khr_external_semaphore_dx_fence** supports importing and exporting a D3D12 fence as an external semaphore using the APIs introduced by **cl_khr_external_semaphore**.

New Enums

- **cl_external_semaphore_handle_type_khr**
  - **CL_SEMAPHORE_HANDLE_D3D12_FENCE_KHR**

Version History

- Revision 0.9.0, 2021-09-10
  - Initial version (provisional).

**cl_khr_external_semaphore_win32**

Name String

**cl_khr_external_semaphore_win32**

Ratification Status

Ratified
Extension and Version Dependencies

- OpenCL 1.2
- cl_khr_semaphore
- cl_khr_external_semaphore

- This is a provisionally extension and must be used with caution. See the description of provisional header files for enablement and stability details.

Other Extension Metadata

Last Modified Date
2021-09-10

IP Status
No known IP claims.

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Description

cl_khr_external_semaphore_win32 supports importing and exporting an NT handle or global share handle as an external semaphore using the APIs introduced by cl_khr_external_semaphore.
New Enums

- cl_external_semaphore_handle_type_khr
  - CL_SEMAPHORE_HANDLE_OPAQUE_WIN32_KHR
  - CL_SEMAPHORE_HANDLE_OPAQUE_WIN32_KMT_KHR

Version History

- Revision 0.9.0, 2021-09-10
  - Initial version (provisional).

cl_khr_kernel_clock

Name String
cl_khr_kernel_clock

Ratification Status
Ratified

Extension and Version Dependencies
None

- This is a provisional extension and must be used with caution. See the description of provisional header files for enablement and stability details.

Other Extension Metadata

Last Modified Date
2024-03-25

IP Status
No known IP claims.

Contributors

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Description

cl_khr_kernel_clock adds the ability for a kernel to sample the value from one of three clocks provided by compute units.
OpenCL C compilers supporting this extension will define the extension macro `cl_khr_kernel_clock`, and may define corresponding feature macros `__opencl_c_kernel_clock_scope_device`, `__opencl_c_kernel_clock_scope_work_group`, and `__opencl_c_kernel_clock_scope_sub_group` depending on the reported capabilities.

See the Kernel Clock section of the OpenCL C specification for more information.

**Interactions With Other Extensions**

On devices that implement the EMBEDDED profile, the `cles_khr_int64` extension is required for the `clock_read_device`, `clock_read_work_group` and `clock_read_sub_group` functions to be present.

Support for sub-groups is required for the `clock_read_sub_group` and `clock_read_hilo_sub_group` functions to be present.

**New Types**

- `cl_device_kernel_clock_capabilities_khr`

**New Enums**

- `cl_device_info`
  - `CL_DEVICE_KERNEL_CLOCK_CAPABILITIES_KHR`
- `cl_device_kernel_clock_capabilities_khr`
  - `CL_DEVICE_KERNEL_CLOCK_SCOPE_DEVICE_KHR`
  - `CL_DEVICE_KERNEL_CLOCK_SCOPE_WORK_GROUP_KHR`
  - `CL_DEVICE_KERNEL_CLOCK_SCOPE_SUB_GROUP_KHR`

**Version History**

- Revision 0.9.0, 2024-03-25
  - First assigned version (provisional).

**List of Deprecated Extensions**

- `cl_khr_spir`
**cl_khr_spir**

Name String

*cl_khr_spir*

Ratification Status

Ratified

Extension and Version Dependencies

None

Deprecation State

- *Obsoleted* by *cl_khr_il_program* extension
  - Which in turn was *promoted* to OpenCL 2.1

Other Extension Metadata

Last Modified Date

2020-04-21

IP Status

No known IP claims.

Description

*cl_khr_spir* adds the ability to create an OpenCL program object from a Standard Portable Intermediate Representation (SPIR) instance. A SPIR instance is a vendor-neutral non-source representation for OpenCL C programs.

See the [SPIR Compilation Options](#) for information on compiling SPIR binaries.

*cl_khr_spir* has been superseded by the SPIR-V intermediate representation, which is supported by the *cl_khr_il_program* extension, and is a core feature in OpenCL 2.1.

New Enums

- *cl_device_info*
  - `CL_DEVICE_SPIR_VERSIONS`
- *cl_program_binary_type*
  - `CL_PROGRAM_BINARY_TYPE_INTERMEDIATE`

Version History

- Revision 1.0.0, 2020-04-21
  - First assigned version.
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